Training Documentation

Traffic Sign Classification using ResNet-18 on GTSRB Dataset

Project Overview:

This project involves training a **ResNet-18** model to classify German traffic signs using the **GTSRB** (**German Traffic Sign Recognition Benchmark**) dataset.

The system processes traffic sign images, learns patterns, and predicts the correct traffic sign category with high accuracy.

Dataset Information:

- Dataset Name: GTSRB German Traffic Sign Recognition Benchmark
- Files Used:
 - o Train.csv Training data with image paths and labels
 - Test.csv Validation data with image paths and labels
- Image Labels: Traffic sign class IDs ranging from 0 to 42 (43 classes total).

Project Dependencies:

- Libraries Used:
 - torch
 - torchvision
 - o PIL (Pillow)
 - o pandas
- Pretrained Model:
 - ResNet-18 (from torchvision.models)

Training Steps Explained:

1. Device Configuration

device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')

- Checks for GPU availability (CUDA).
- Falls back to CPU if a GPU is not found.

2. Image Transformations

```
transform = transforms.Compose([
    transforms.Resize((224, 224)),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.485, 0.456, 0.406],
        std=[0.229, 0.224, 0.225]),
])
```

- Resize: All images are resized to 224×224 pixels (ResNet-18 input requirement).
- **Normalization:** Images are normalized with ImageNet dataset means and standard deviations (since the pretrained ResNet-18 was trained on ImageNet).

3. Custom Dataset Class

class TrafficDataset(Dataset):

...

- Custom PyTorch Dataset to load the GTSRB dataset.
- Reads the CSV files (Train.csv, Test.csv), loads corresponding images, and applies transformations.
- Returns a tuple (image tensor, label) for each sample.

4. Data Loading

```
train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)
valid_loader = DataLoader(valid_dataset, batch_size=32, shuffle=False)
```

- Batch size: 32 images per batch.
- **Shuffle:** Enabled for training data to improve generalization.

5. Model Preparation

```
model = models.resnet18(pretrained=True)
num_classes = len(set(train_dataset.data['ClassId']))
model.fc = nn.Linear(model.fc.in_features, num_classes)
model = model.to(device)
```

• Base Model: Pretrained ResNet-18.

- **Modification:** Final fully connected layer (fc) adjusted for 43 output classes (instead of default 1000).
- Transfer Learning: We leverage pretrained features and fine-tune the model for traffic signs.

6. Loss Function & Optimizer

criterion = nn.CrossEntropyLoss()

optimizer = optim.Adam(model.parameters(), Ir=1e-4)

- Loss Function: Cross Entropy Loss (standard for multi-class classification).
- **Optimizer:** Adam Optimizer with a learning rate of 0.0001.

7. Training Loop

for epoch in range(3):

•••

- Epochs: 3 (each epoch represents a full pass over the training set).
- Steps Per Epoch:
 - o Set model to training mode.
 - Forward pass: Images \rightarrow Model \rightarrow Predictions.
 - Loss computation.
 - o Backward pass: Gradients are computed.
 - Parameters updated via the optimizer.
 - o Metrics collected: Running Loss, Accuracy.

Training Results:

• **Epoch 1:** Loss: 0.1907 | Accuracy: 95.86%

• Epoch 2: Loss: 0.0089 | Accuracy: 99.82%

• **Epoch 3:** Loss: 0.0077 | Accuracy: 99.82%

8. Validation Loop

model.eval()

with torch.no_grad():

...

• Model is switched to **evaluation mode** (no dropout, no batch norm update).

- No gradient calculation (torch.no_grad() improves speed and reduces memory usage).
- Predictions are made on the validation dataset.

Validation Result:

• Validation Accuracy: 99.14%

Final Model Performance:

Phase **Accuracy**

Training (Epoch 3) 99.82%

Validation 99.14%

Key Highlights:

- **Pretrained Model:** Leveraging ResNet-18 significantly boosts training speed and accuracy.
- **Custom Dataset Loader:** Flexibility to work with CSV file structures.
- Excellent Accuracy: >99% accuracy in just 3 epochs due to fine-tuning on powerful ResNet features.

Potential Improvements:

- Fine-tune more layers of ResNet-18 (not just fc layer).
- Use data augmentation (random rotation, horizontal flip, color jitter) for better robustness.
- Try advanced schedulers like CosineAnnealingLR for dynamic learning rate adjustments.
- Train for more epochs for even finer learning.
- Save the best model using torch.save(model.state_dict(), 'traffic_sign_model.pth').