

11)

$$mg \sin \theta = kx \left( 1 - \frac{L}{\sqrt{x^2 + a^2}} \right)$$

To reduce to form :

$$1 - \frac{h}{u} = \frac{R}{\sqrt{1+u^2}}$$

$$\Rightarrow 1 - \frac{mg \sin \theta}{k} \left( \frac{1}{x} \right) = \frac{L}{a \sqrt{1 + \left( \frac{x}{a} \right)^2}}$$

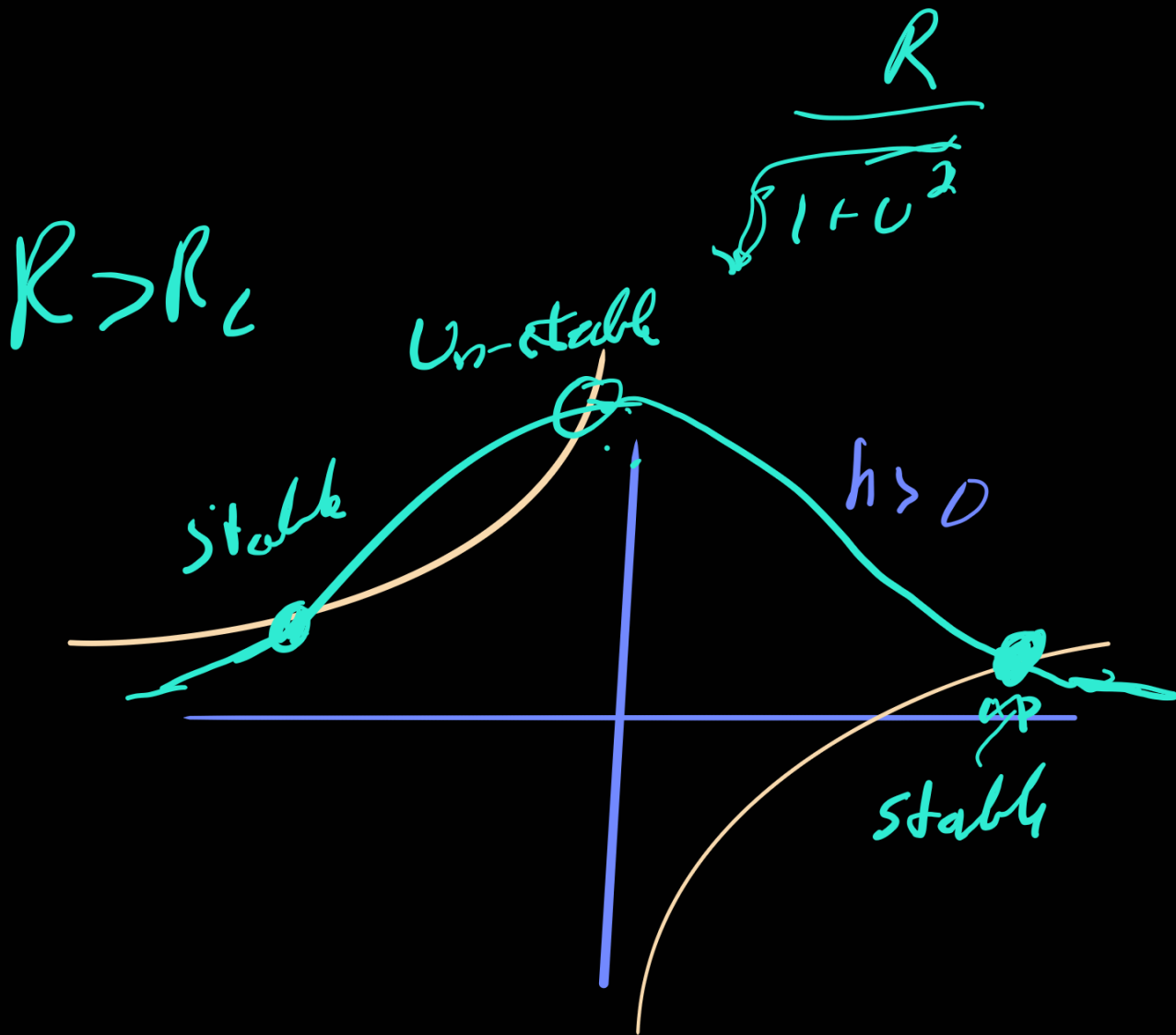
$$\Rightarrow 1 - \frac{mg \sin \theta}{ak} \left( \frac{a}{x} \right) = \frac{(L/a)}{\sqrt{1 + \left( \frac{x}{a} \right)^2}}$$

Let  $\frac{x}{a} = u$ ,  $\frac{mg \sin \theta}{ak} = h$ ,  $\frac{L}{a} = R$

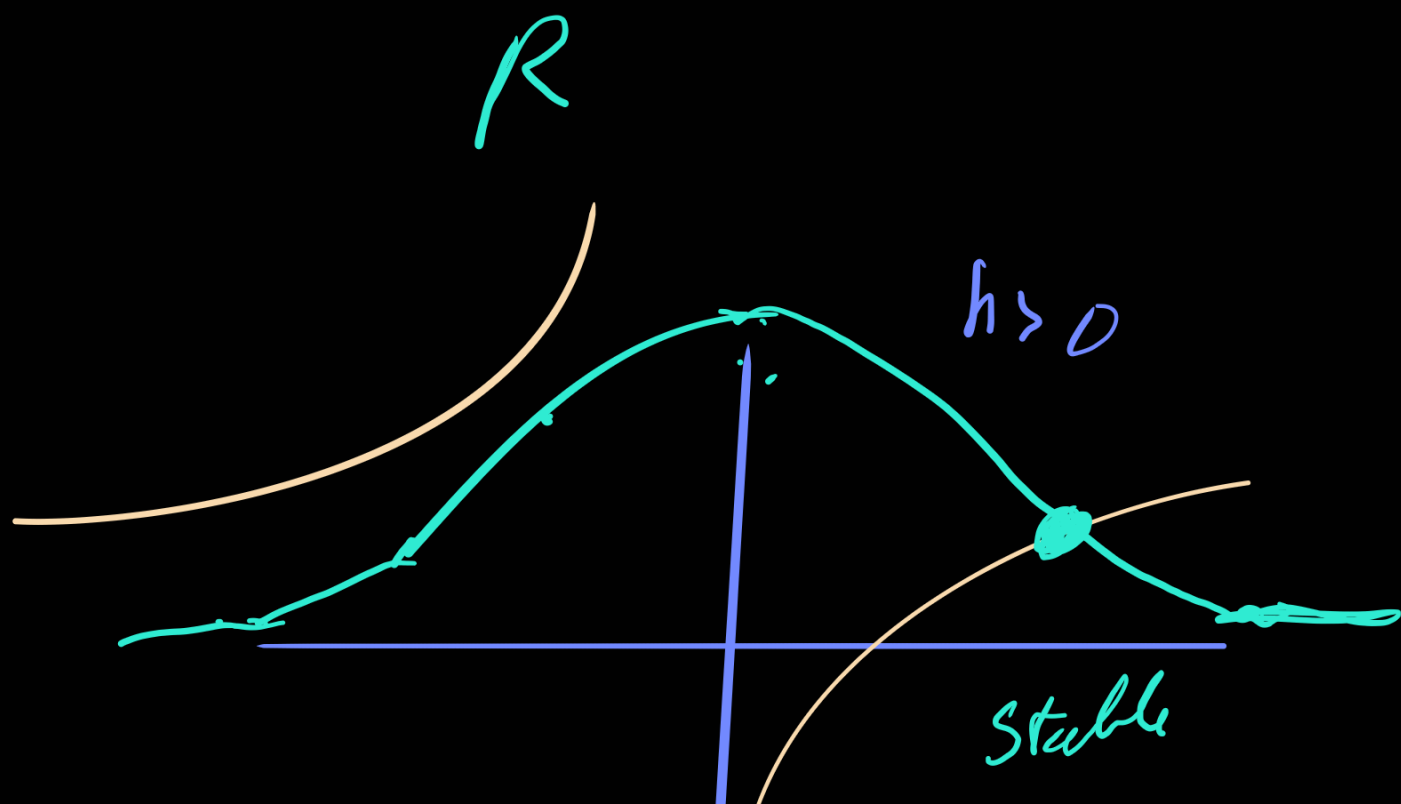
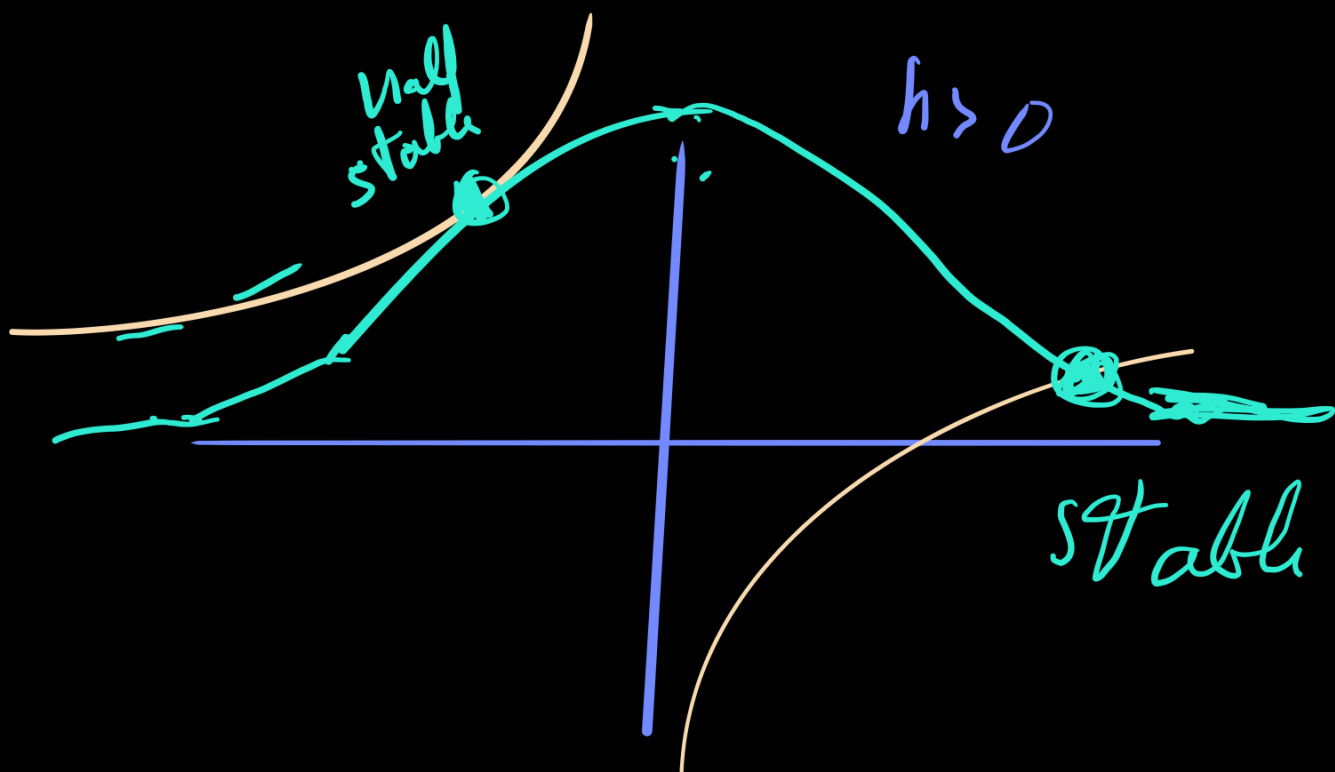
$$\Rightarrow 1 - \frac{h}{v} = \frac{R}{\sqrt{1+u^2}}$$

b)

Graph of  $1 - \frac{h}{v}$  vs

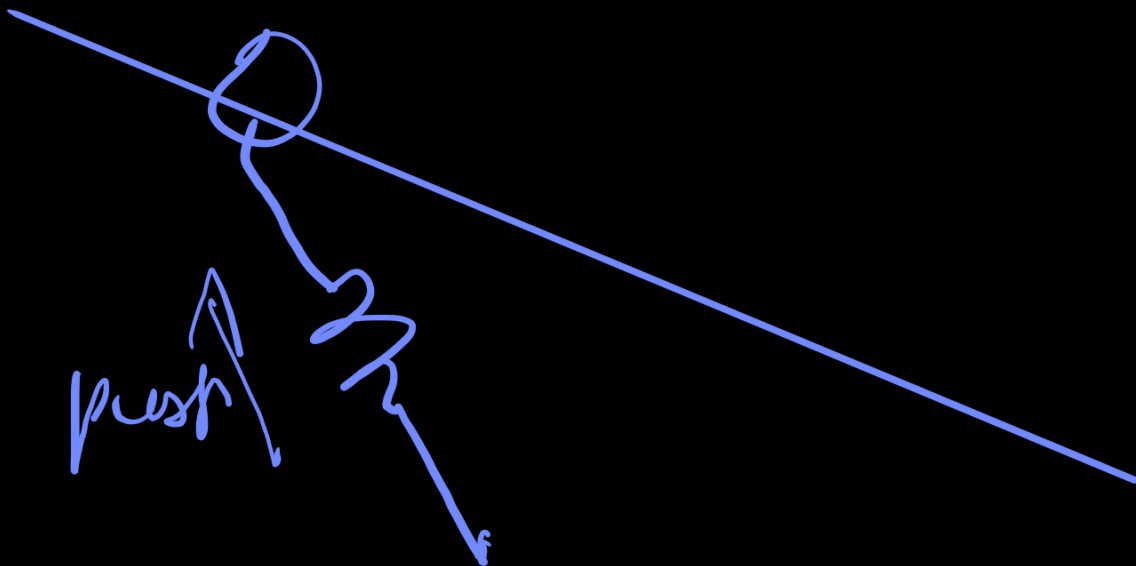


$$R = R_c$$



c) Graphs attached

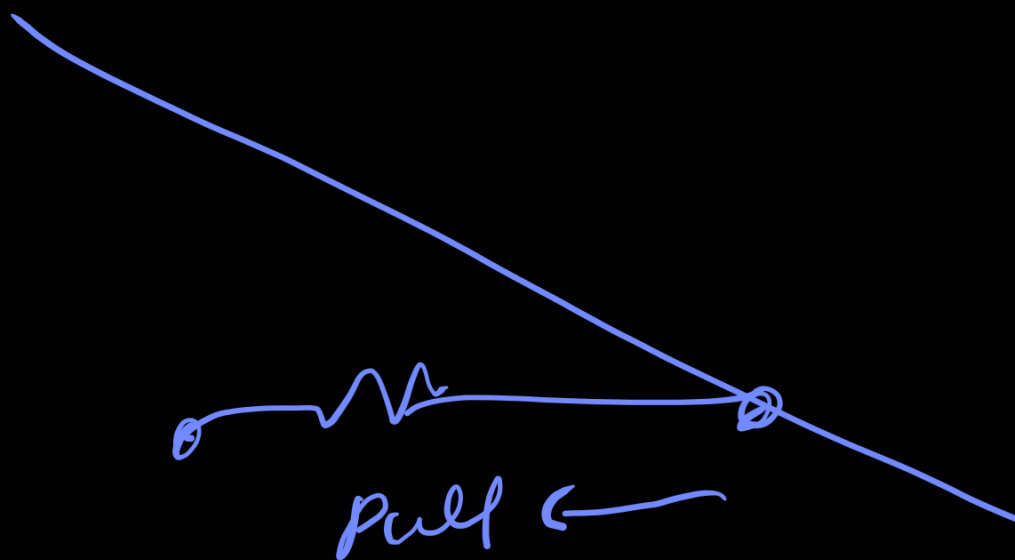
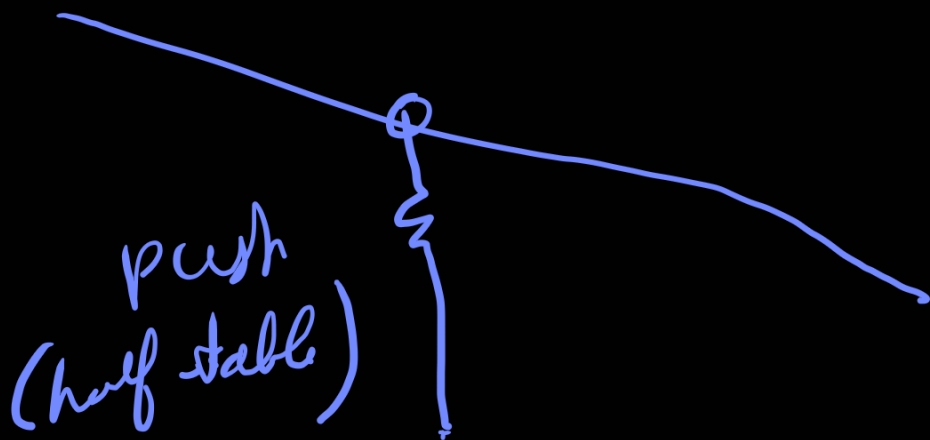
Case 1) Three f.p



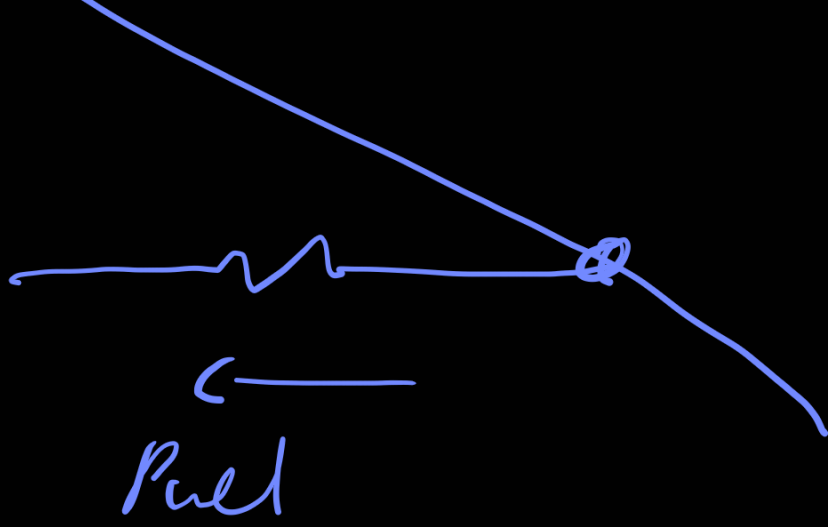
push  
- bad angle



(Case 2)



(case 3)



(Q)

Equation :

$$b\dot{\Theta} + mgl\sin\Theta = \Gamma$$

To reduce to:

$$\Theta' = \gamma - \sin\Theta$$

$$\Rightarrow \frac{b}{mgl} \dot{\Theta} + \sin\Theta = \frac{\Gamma}{mgl}$$

$$\frac{b}{mgl} \frac{d\Theta}{dt} = \frac{\Gamma}{mgl} - \sin\Theta$$

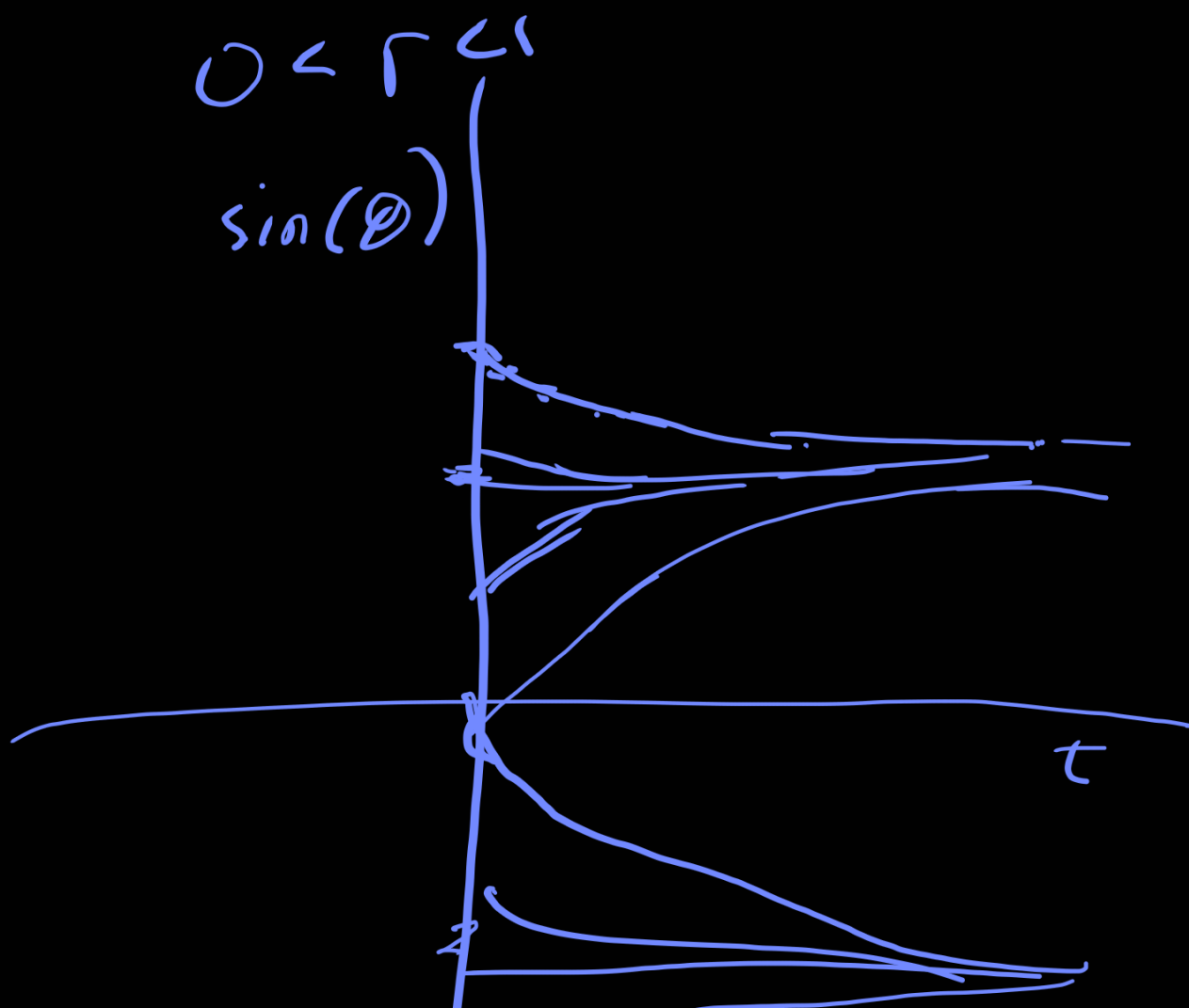
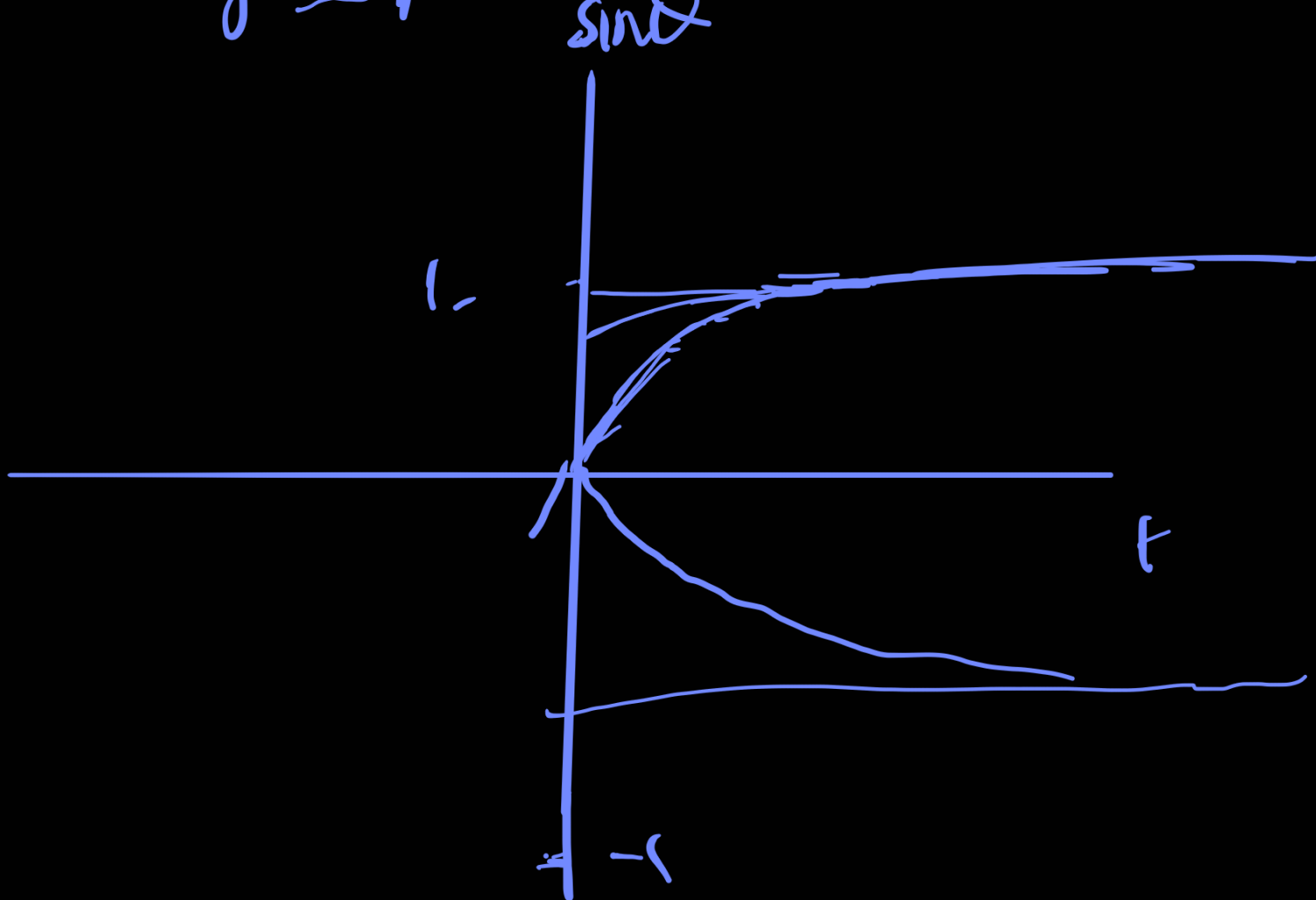
$$\text{Take: } z = \frac{mgl}{b} t, \quad \gamma = \frac{\Gamma}{mgl}$$

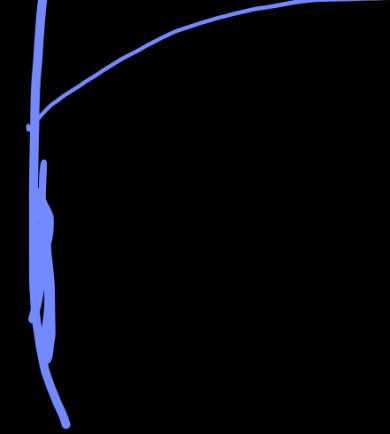
$$\Rightarrow \frac{d\Theta}{dz} = \gamma - \sin\Theta$$



(b)

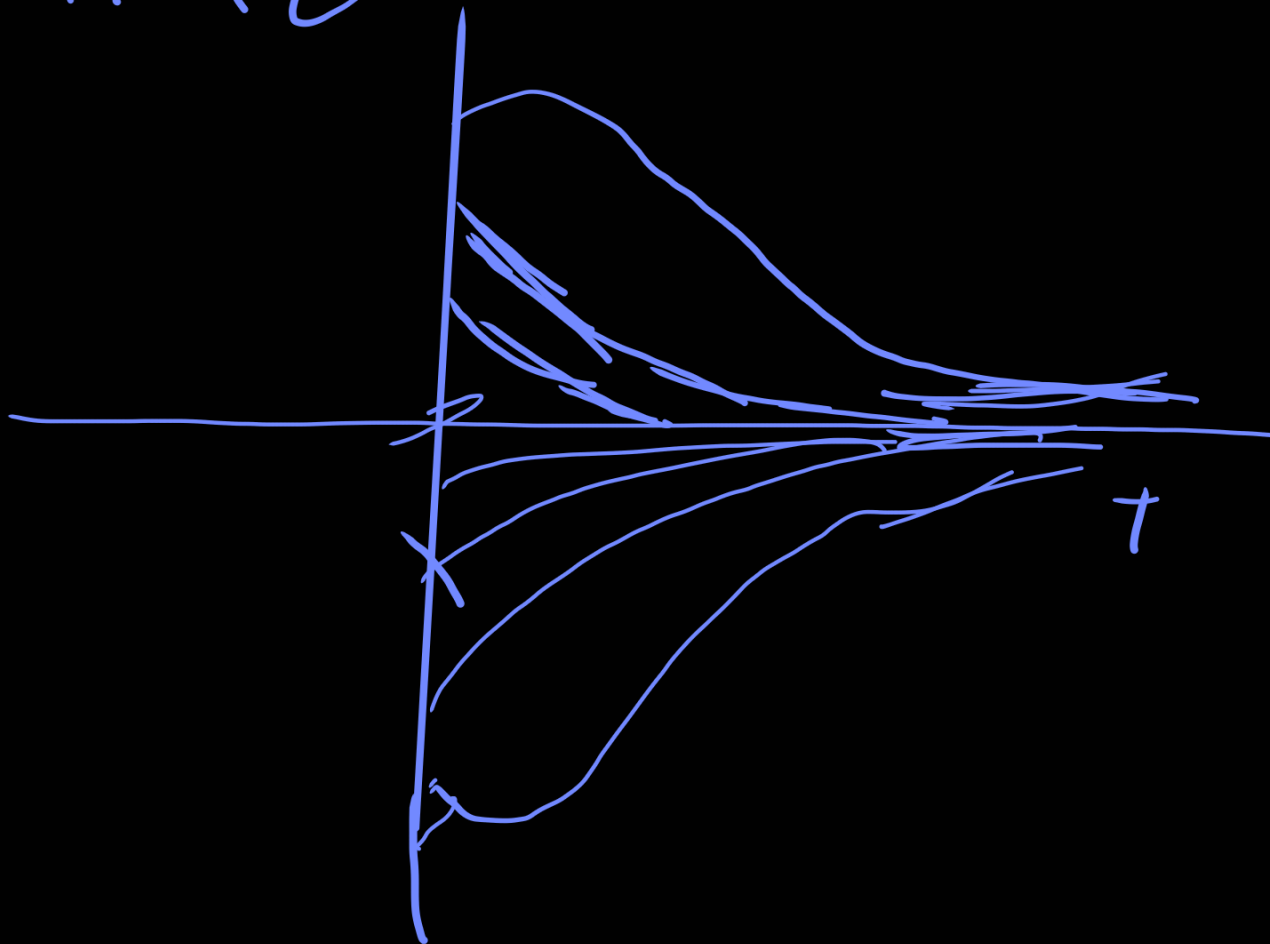
$x \approx 1$  and





$$y < 1$$

$$\sin(\theta)$$

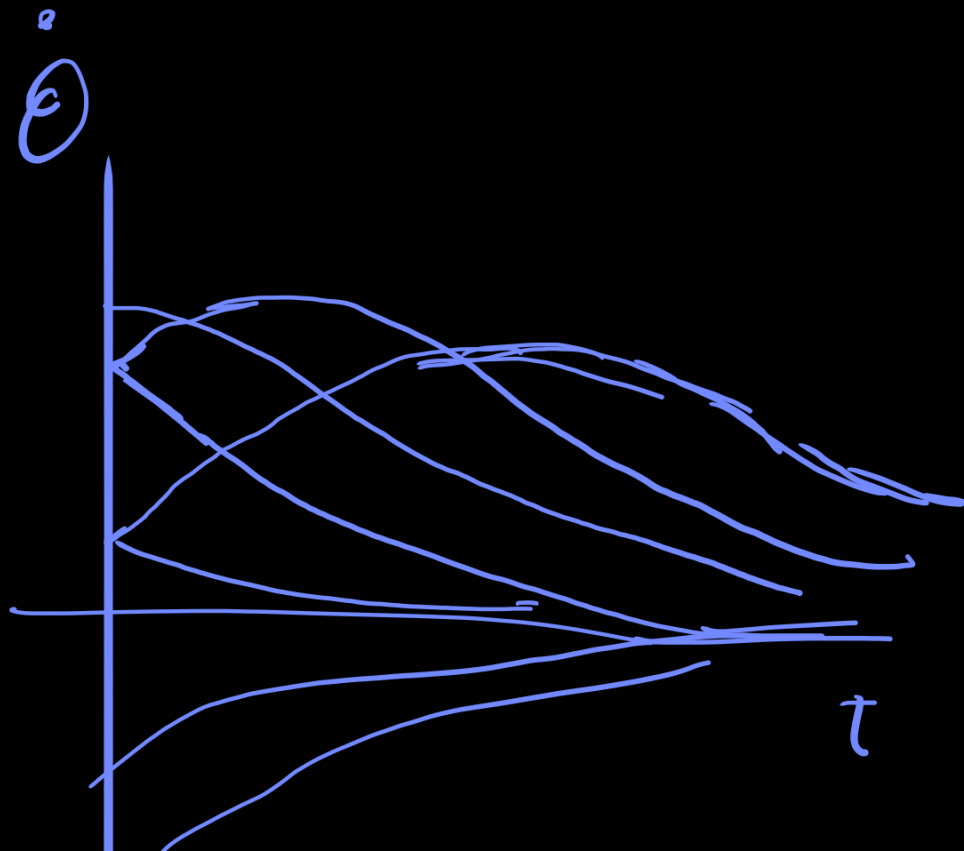


c) Torque due to gravity  
is proportional to  $\sin \theta$

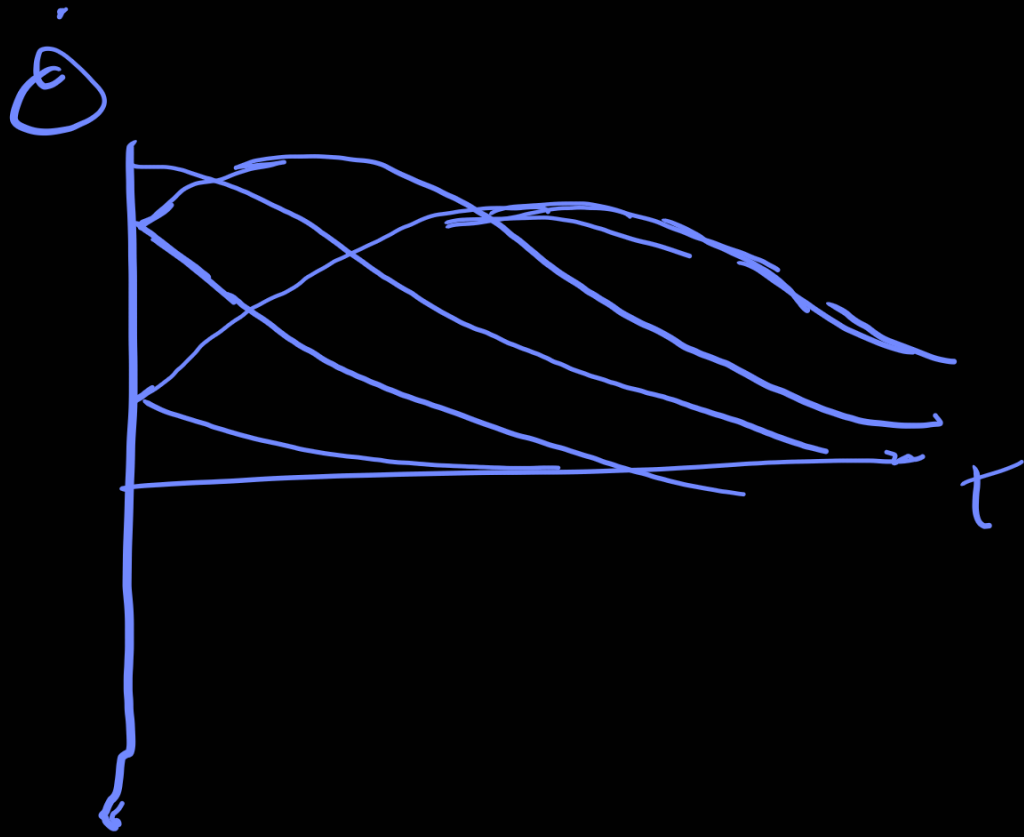
d)

For  $\dot{\theta}$  vs  $t$

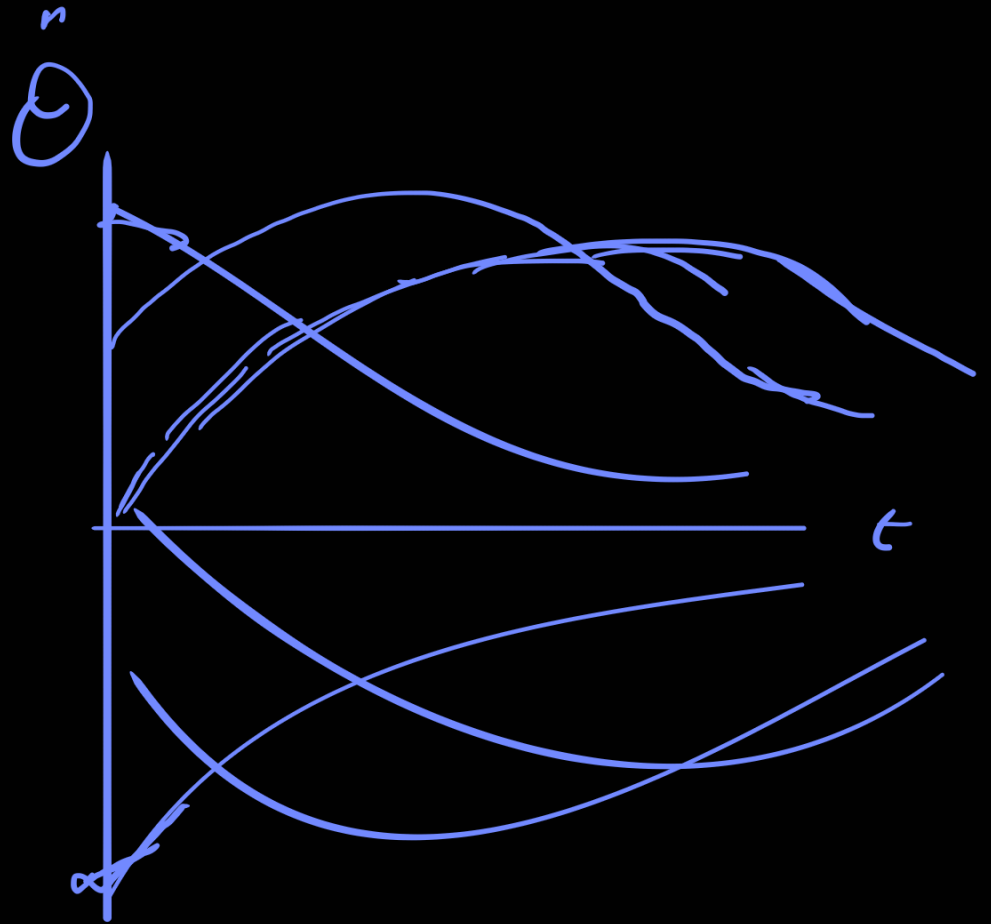
$$l > r > 0$$



$$\gamma \approx 1$$



12218

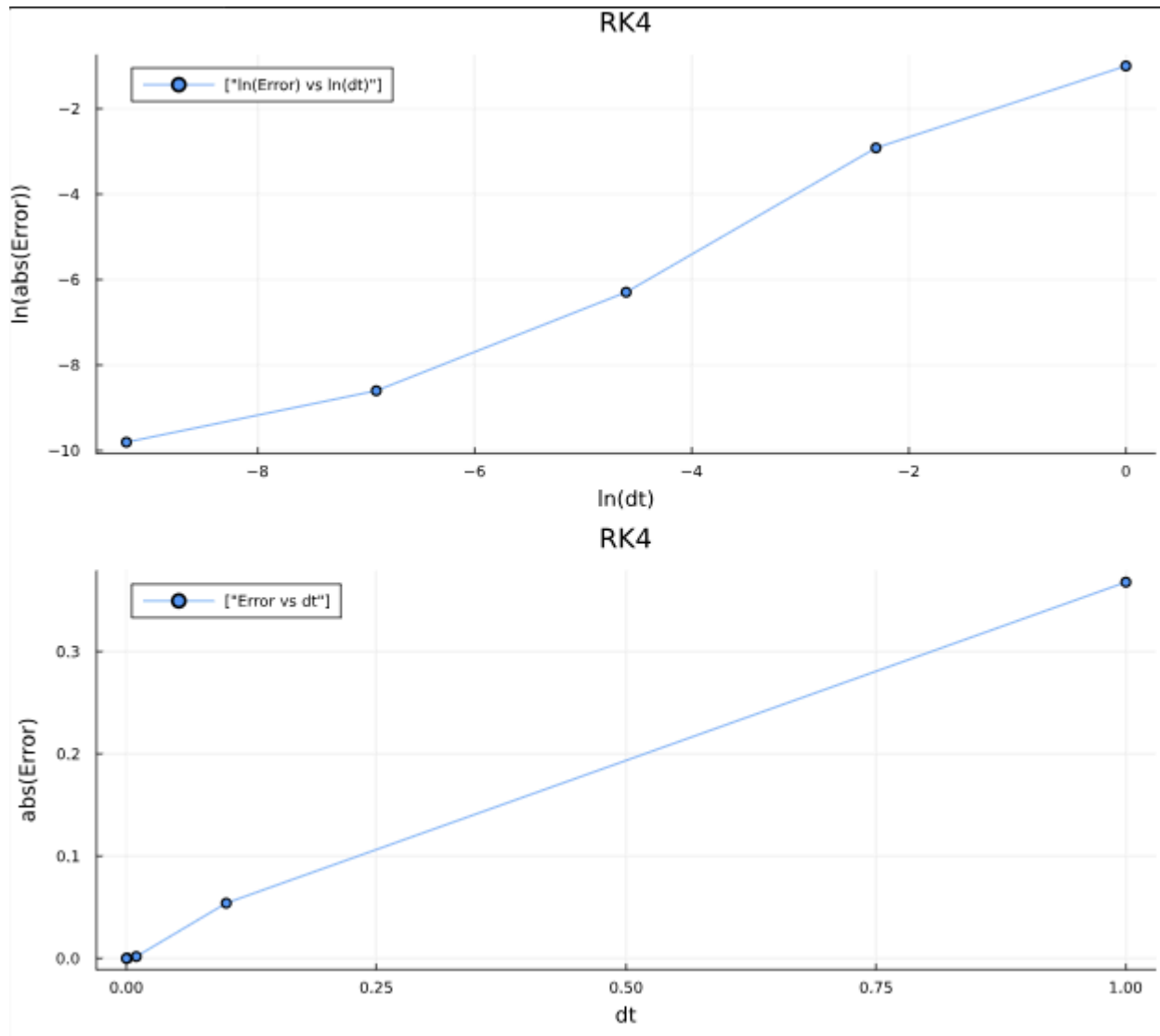


# Tut1\_Pictures

## 1

Exact value is  $\exp(-1)$

## Simple Euler



```
For time: 1.0    x(1): 0.0
For time: 0.1    x(1): 0.31381059609
For time: 0.01   x(1): 0.3660323412732295
For time: 0.001  x(1): 0.36769542477096373
For time: 0.0001 x(1): 0.36782426032828575
Actual answer is: 0.36787944117144233
```

○ julia> █

For time: 1.0 x(1): 0.0

For time: 0.1 x(1): 0.31381059609

For time: 0.01 x(1): 0.3660323412732296

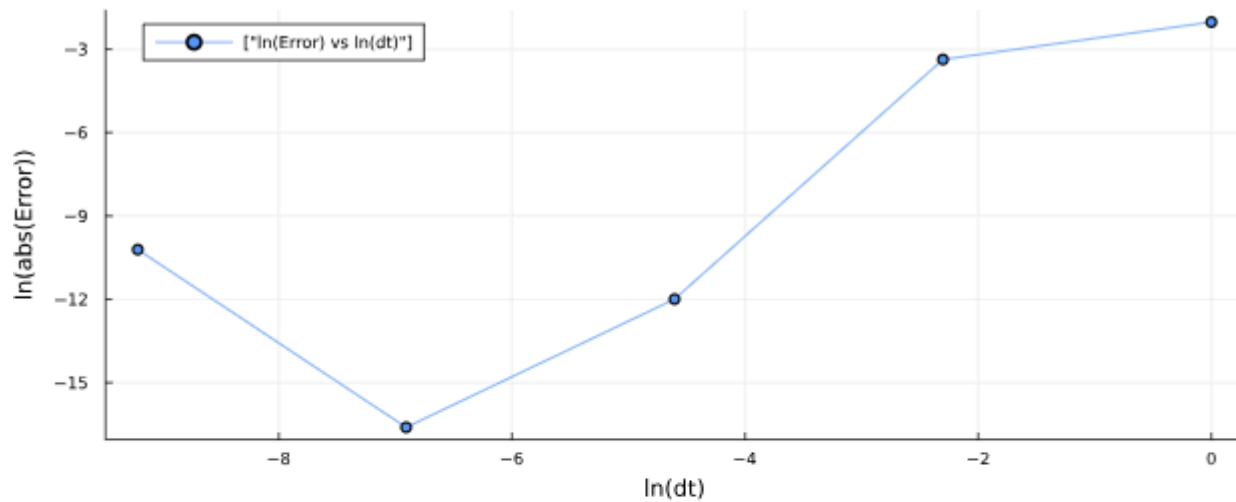
For time: 0.001 x(1): 0.36769542477096373

For time: 0.0001 x(1): 0.36782426032828575

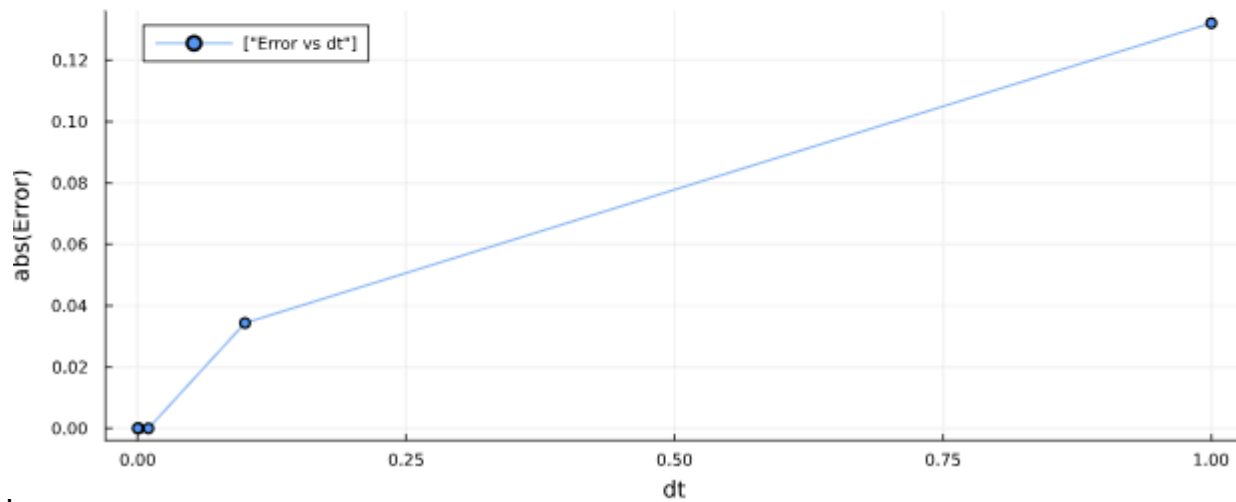
Actual answer is: 0.36787944117144233

# Improved Euler

Improved Euler



Improved Euler



```
For time: 1.0 x(1): 0.5
For time: 0.1 x(1): 0.33352959127436443
For time: 0.01 x(1): 0.367885618716192
For time: 0.001 x(1): 0.36787950253069096
For time: 0.0001 x(1): 0.3678426556798375
Actual answer is: 0.36787944117144233
```

julia

For time: 1.0 x(1): 0.5

For time: 0.1 x(1): 0.33352959127436443

For time: 0.01 x(1): 0.367885618716192

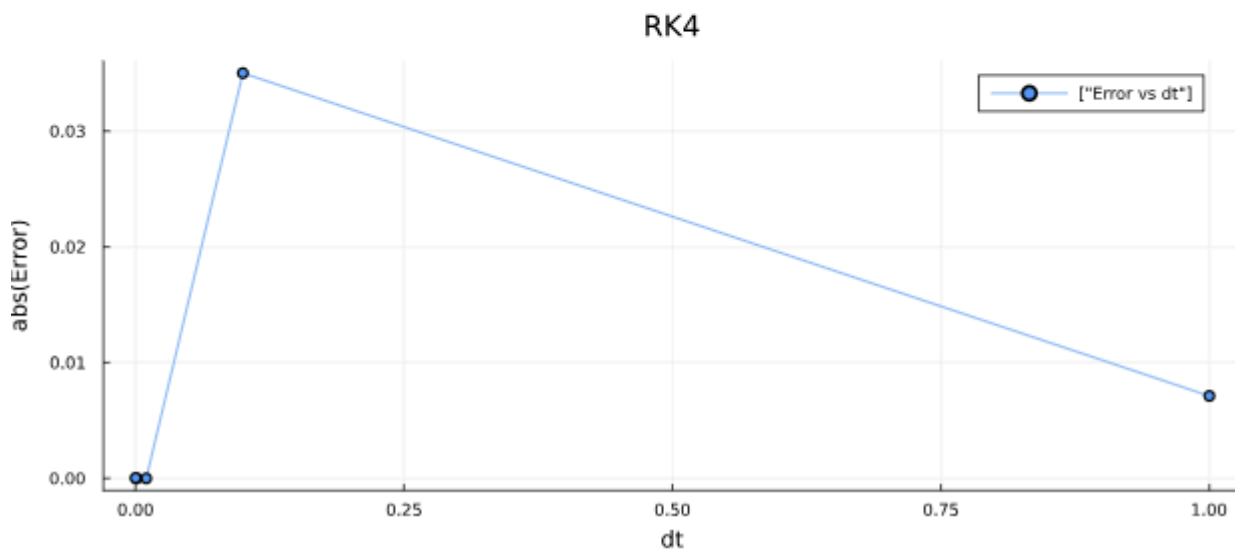
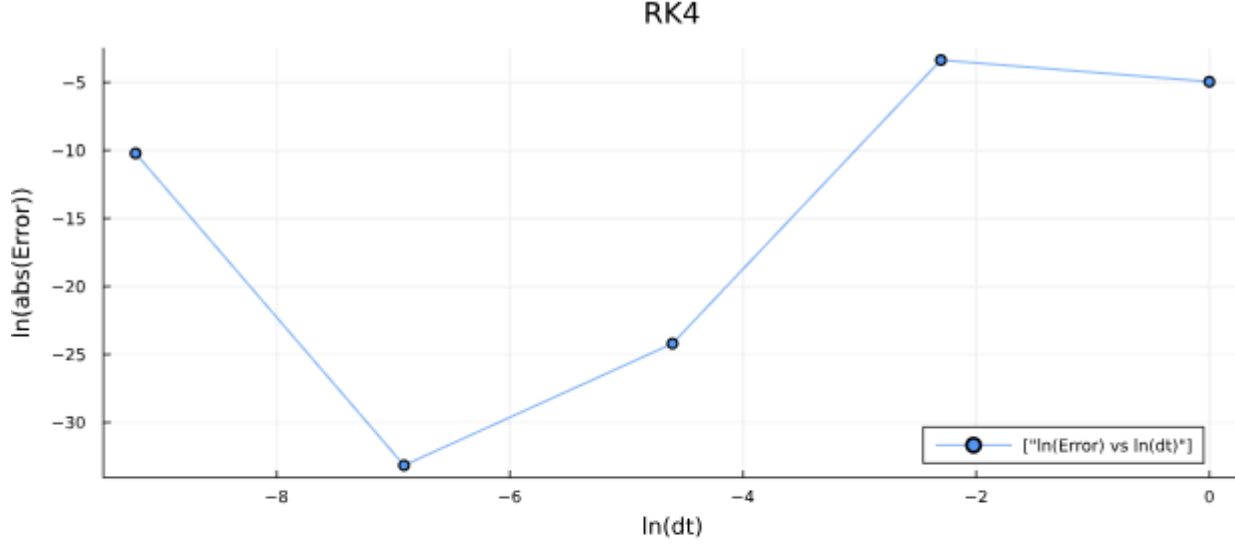
For time: 0.001 x(1): 0.36787950253069096

For time: 0.0001 x(1): 0.3678426556798375

Actual answer is: 0.36787944117144233

## Rk4





```

For time: 1.0   x(1): 0.375
For time: 0.1  x(1): 0.332871415379969
For time: 0.01 x(1): 0.3678794412023554
For time: 0.001 x(1): 0.36787944117144633
For time: 0.0001 x(1): 0.36784265506666375
Actual answer is: 0.36787944117144233

```

○ julia> █

For time: 1.0 x(1): 0.375

For time: 0.1 x(1): 0.332871415379969

For time: 0.01 x(1): 0.3678794412023554

For time: 0.001 x(1): 0.36787944117144633

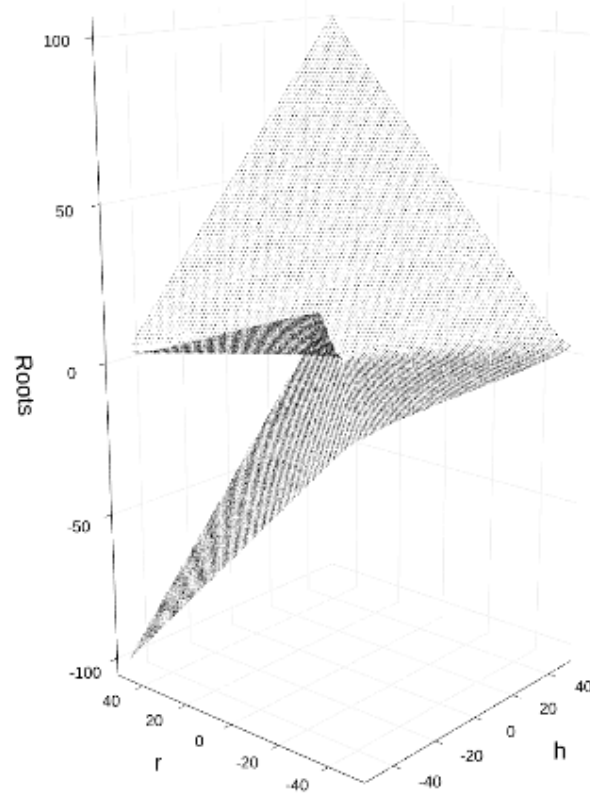
For time: 0.0001 x(1): 0.36784265506666375

Actual answer is: 0.36787944117144233

2

Below is the Catastrophe surface

Catastrophe Surface



The interactive HTML can be found in the github repo

Heatmap corresponds to the number of fixed points

