# sheet03 Rename

November 11, 2024

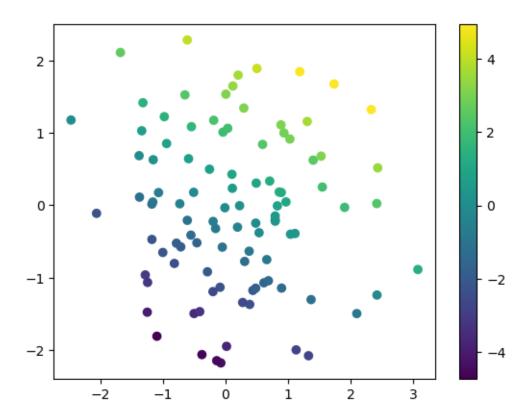
From Oliver Sange, Elias Huber and Sam Rouppe van der Voort

```
[]: import numpy as np
from matplotlib import pyplot as plt
from sklearn.linear_model import LinearRegression
```

## 0.1 3 Visualize Regularization Contours

```
[25]: # load the data
data = np.load('data/linreg.npz')
x = data['X']
y = data['Y']
print(f'x.shape: {x.shape}, "y.shape:" {y.shape}')
plt.scatter(*x, c=y);
plt.colorbar()
plt.show()
```

```
x.shape: (2, 100), "y.shape:" (1, 100)
```



```
[26]: # create a grid of points in the parameter space
b1, b2 = np.linspace(-1, 3, 101), np.linspace(-1, 3, 101)
bs = np.stack(np.meshgrid(b1, b2, indexing='ij'), axis=-1)
bs.shape
```

[26]: (101, 101, 2)

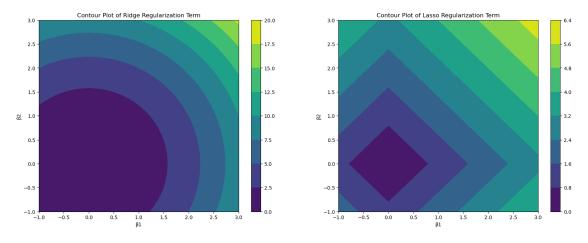
### 0.1.1 (a)

```
[27]: ridge_term = bs[..., 0]**2 + bs[..., 1]**2
lasso_term = np.abs(bs[..., 0]) + np.abs(bs[..., 1])

# Plotting
fig, ax = plt.subplots(1, 2, figsize=(20, 7))

# Ridge regression
contour1 = ax[0].contourf(bs[..., 0], bs[..., 1], ridge_term, cmap='viridis')
fig.colorbar(contour1, ax=ax[0])
ax[0].set_title('Contour Plot of Ridge Regularization Term')
ax[0].set_xlabel(' 1')
ax[0].set_ylabel(' 2')
```

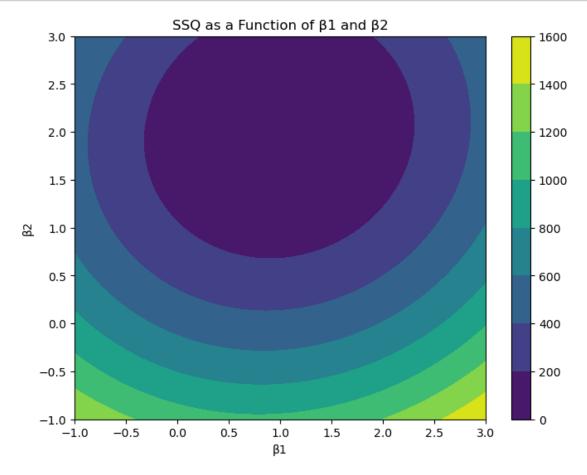
```
# Lasso regression
contour2 = ax[1].contourf(bs[..., 0], bs[..., 1], lasso_term, cmap='viridis')
fig.colorbar(contour2, ax=ax[1])
ax[1].set_title('Contour Plot of Lasso Regularization Term')
ax[1].set_xlabel('1')
ax[1].set_ylabel('2')
plt.show()
```



#### 0.1.2 (b)

```
[28]: # Reshape bs
      b1_vals = bs[..., 0]
      b2_vals = bs[..., 1]
      # Compute predictions
      y_pred_grid = b1_vals[:, :, np.newaxis] * x[0] + b2_vals[:, :, np.newaxis] *_u
       ∽x[1]
      # Compute residuals
      residuals = y - y_pred_grid
      # Compute SSQ
      SSQ = np.sum(residuals**2, axis=-1)
      # Plot
      fig, ax = plt.subplots(figsize=(8, 6))
      contour = ax.contourf(b1_vals, b2_vals, SSQ, cmap='viridis')
      fig.colorbar(contour, ax=ax)
      ax.set_title('SSQ as a Function of 1 and 2')
      ax.set_xlabel('1')
```

```
ax.set_ylabel('2')
plt.show()
```

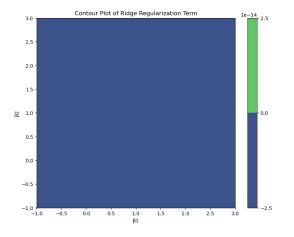


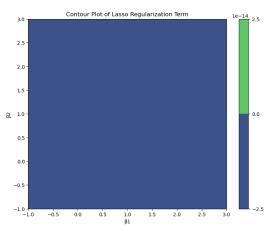
### 0.1.3 (c)

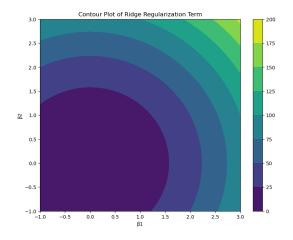
```
fig.colorbar(contour1, ax=ax[0])
  ax[0].set_title('Contour Plot of Ridge Regularization Term')
  ax[0].set_xlabel(' 1')
  ax[0].set_ylabel(' 2')

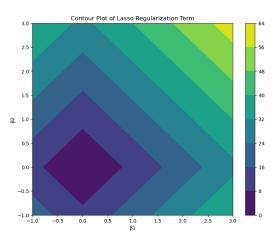
# Lasso regression
  contour2 = ax[1].contourf(bs[..., 0], bs[..., 1], lasso_term,
cmap='viridis')
  fig.colorbar(contour2, ax=ax[1])
  ax[1].set_title('Contour Plot of Lasso Regularization Term')
  ax[1].set_xlabel(' 1')
  ax[1].set_ylabel(' 2')

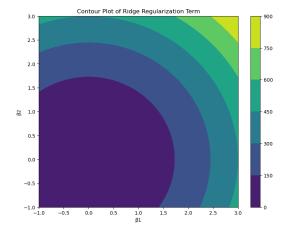
plt.show()
```

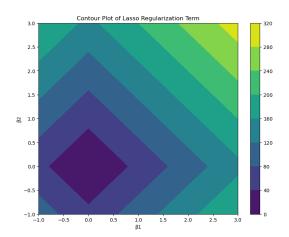


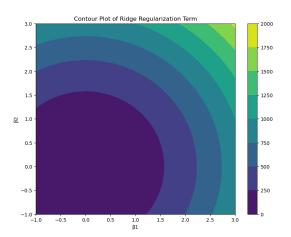


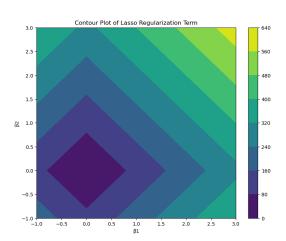


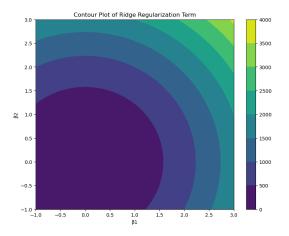


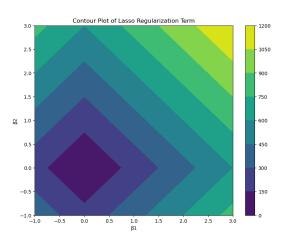


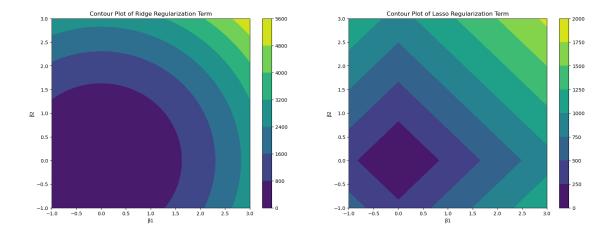












For a larger , the colorbar will extend to higher values. This means that the colors in the plot will represent a stronger penalty, and the "cost" of larger coefficients beta1 and beta2 becomes more pronounced in the optimization.

#### 0.2 4 CT Reconstruction

First, set up the design matrix. (Run this once to save it to the disk)

```
[15]: # create design matrix
      # don't change any of this, just run it once to create and save the design_{\sqcup}
       \hookrightarrow matrix
      import os
      n_parallel_rays = 70
      n_{\text{ray}} = 30
      res = (99, 117)
      print("Number of pixels in the 2d image:", np.prod(res))
      print("Total number of rays:", n_parallel_rays * n_ray_angles)
      def rot_mat(angle):
          c, s = np.cos(angle), np.sin(angle)
          return np.stack([np.stack([c, s], axis=-1), np.stack([-s, c], axis=-1)],
       \Rightarrowaxis=-1)
      kernel = lambda x: np.exp(-x**2/sigma**2/2)
      if not os.path.exists('data/design_matrix.npy'):
          xs = np.arange(0, res[1]+1) - res[1]/2 # np.linspace(-1, 1, res[1] + 1)
          ys = np.arange(0, res[0]+1) - res[0]/2 # np.linspace(-1, 1, res[0] + 1)
          # rays are defined by origin and direction
          ray offset range = [-res[1]/1.5, res[1]/1.5]
```

```
n_rays = n_parallel_rays * n_ray_angles
    ray_angles = np.linspace(0, np.pi, n_ray_angles, endpoint=False) + np.pi/
  # offsets for ray angle = 0, i.e. parallel to x-axis
    ray_0_offsets = np.stack([np.zeros(n_parallel_rays), np.
  →linspace(*ray_offset_range, n_parallel_rays)], axis=-1)
    ray_0_directions = np.stack([np.ones(n_parallel_rays), np.
 ⇔zeros(n_parallel_rays)], axis=-1)
    ray_rot_mats = rot_mat(ray_angles)
    ray_offsets = np.einsum('oi,aij->aoj', ray_0_offsets, ray_rot_mats).
  \rightarrowreshape(-1, 2)
    ray_directions = np.einsum('oi,aij->aoj', ray_0_directions, ray_rot_mats).
  \rightarrowreshape(-1, 2)
    sigma = 1
    xsc = (xs[1:] + xs[:-1]) / 2
    ysc = (ys[1:] + ys[:-1]) / 2
    b = np.stack(np.meshgrid(xsc, ysc), axis=-1).reshape(-1, 2)
    a = ray_offsets
    v = ray_directions
    v = v / np.linalg.norm(v, axis=-1, keepdims=True)
    p = ((b[None] - a[:, None]) * v[:, None]).sum(-1, keepdims=True) * v[:, u]
 →None] + a[:, None]
    d = np.linalg.norm(b - p, axis=-1)
    d = kernel(d)
    design_matrix = d.T
    np.save('data/design_matrix.npy', design_matrix)
    print(f'created and saved design matrix of shape {design_matrix.shape} at ⊔

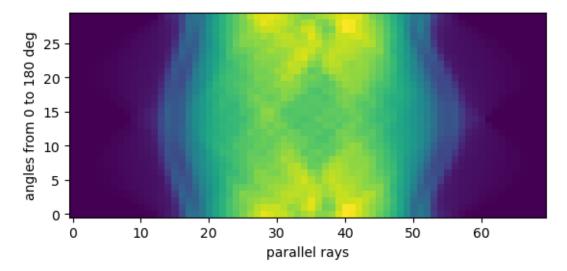
¬data/design_matrix.npy')
Number of pixels in the 2d image: 11583
```

Total number of rays: 2100

```
[16]: sino = np.load('data/sino.npy')
      print(f'sino shape: {sino.shape}')
      # visualize sinogram as image
      n_parallel_rays = 70
      n_angles = 30
```

```
plt.imshow(sino.reshape(n_angles, n_parallel_rays), origin='lower')
# plt.colorbar()
plt.xlabel('parallel rays')
plt.ylabel('angles from 0 to 180 deg')
plt.show();
```

sino shape: (1, 2100)



#### 0.2.1 (a)

```
[17]: design_matrix = np.load('data/design_matrix.npy')
    numbers = np.random.randint(0,design_matrix.shape[1],size = 4)
    print(f"shape design matrix: {design_matrix.shape}")

image1 = design_matrix[:,numbers[0]].reshape(res)
    image2 = design_matrix[:,numbers[1]].reshape(res)
    image3 = design_matrix[:,numbers[2]].reshape(res)
    image4 = design_matrix[:,numbers[3]].reshape(res)

plt.imshow(image1, origin='lower')
    plt.show()
    plt.imshow(image2, origin='lower')
    plt.show()
    plt.imshow(image3, origin='lower')
    plt.show()
    plt.imshow(image4, origin='lower')
    plt.show()
```

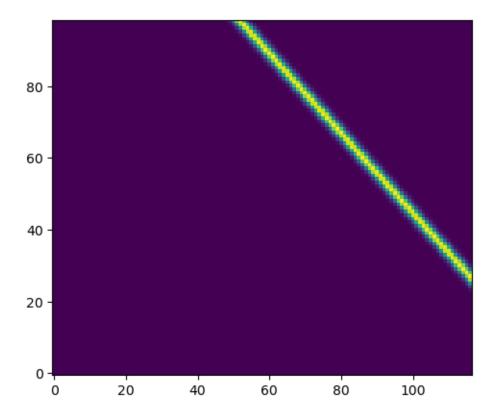
```
# Each image shows the trajectory and its corresponding intensity through the

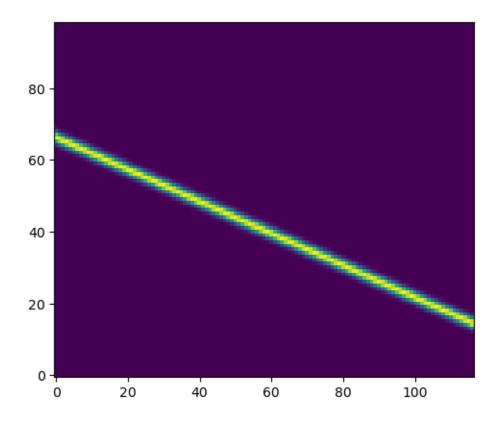
→ final image

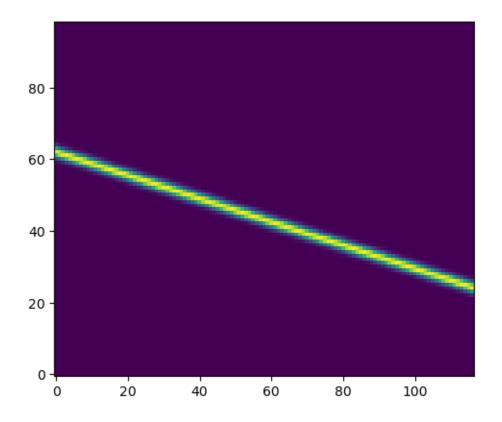
# TODO: visualize four random columns as images, using an image shape of (99,

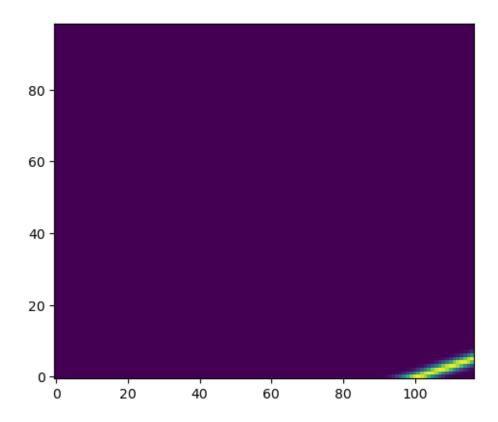
→117)
```

shape design matrix: (11583, 2100)









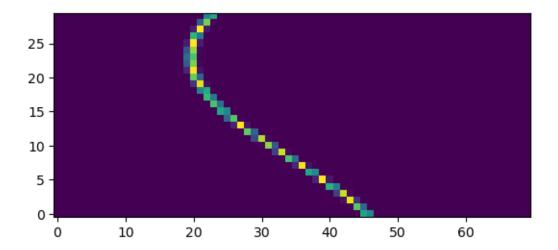
### 0.2.2 (b)

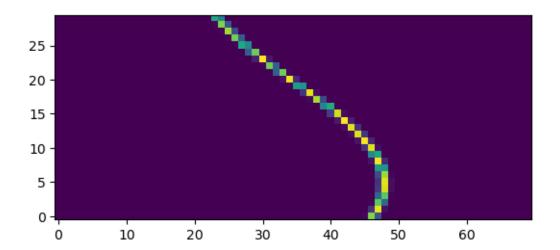
```
[18]: # TODO: visualize four random rows as images, using an images
   numbers = np.random.randint(0,design_matrix.shape[0],size = 4)
   res2 = (30,70)

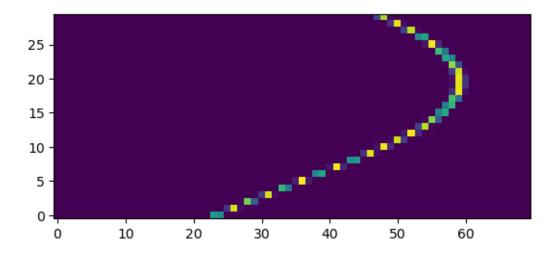
image1 = design_matrix[numbers[0]].reshape(res2)
   image2 = design_matrix[numbers[1]].reshape(res2)
   image3 = design_matrix[numbers[2]].reshape(res2)
   image4 = design_matrix[numbers[3]].reshape(res2)

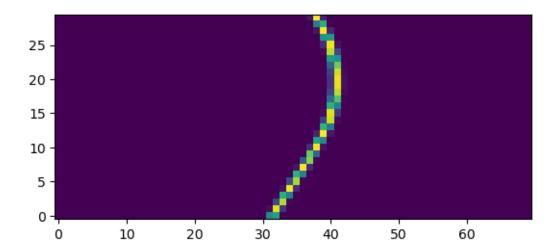
plt.imshow(image1, origin='lower')
   plt.show()
   plt.imshow(image2, origin='lower')
   plt.show()
   plt.imshow(image3, origin='lower')
   plt.show()
   plt.imshow(image4, origin='lower')
```

plt.show() 
# The images map the readout intensity of a detector to the corresponding ray 
and angle









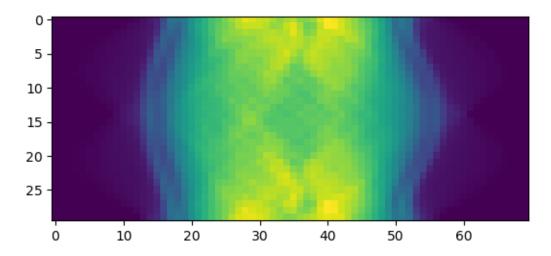
### 0.2.3 (c)

```
[19]: # TODO: solve the reconstruction with linear regression and visualize the result
print(f"shapes: sino {sino.shape} design_matrix: {design_matrix.shape}")
    # project components onto sino
    Y = sino.squeeze()
    reg = LinearRegression().fit(design_matrix.T, Y)
    print(reg.score(design_matrix.T,Y))
    prediction = reg.predict(design_matrix.T)
    new_sino = prediction.reshape((30,70))
    plt.imshow(new_sino)
    plt.show()
    # double check if sinogram fits
```

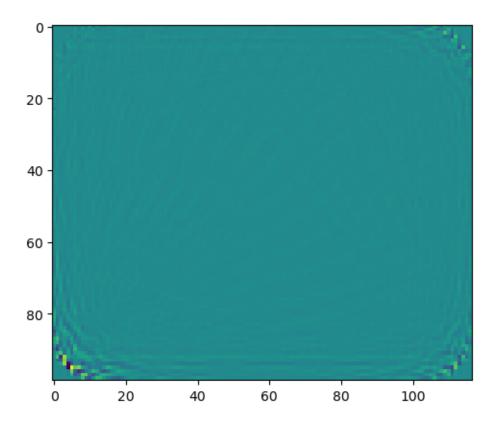
```
image = reg.coef_.reshape(res)
plt.imshow(image)

# we observe that the reconstructed image is not interpretable
```

shapes: sino (1, 2100) design\_matrix: (11583, 2100)
0.999999900717896



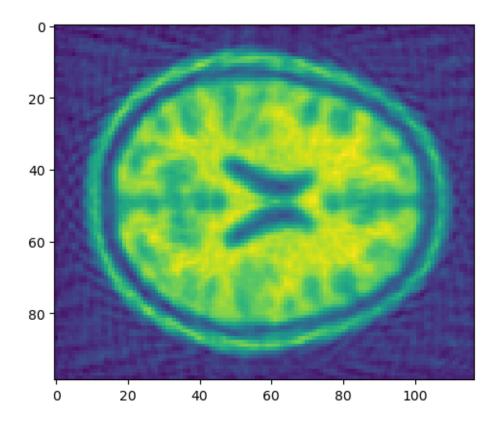
[19]: <matplotlib.image.AxesImage at 0x7f5ce8aa6e80>



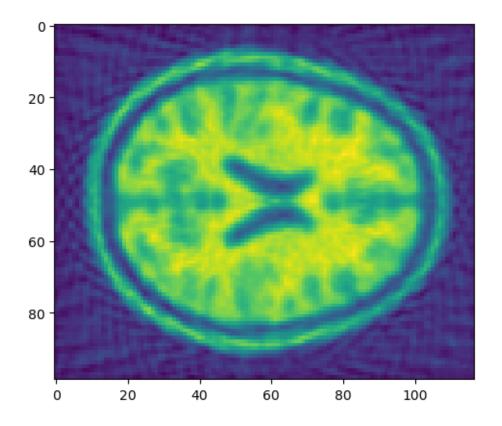
```
[11]: # TODO: solve the reconstruction with ridge regression and visualize the result
      # Optional: try out different regularization strengths and observe the influence
      from sklearn.linear_model import Ridge
      reg = Ridge(alpha=0.1).fit(design_matrix.T, Y)
      print(reg.score(design_matrix.T,Y))
      prediction = reg.predict(design_matrix.T)
      image = reg.coef_.reshape(res)
      plt.imshow(image)
      plt.show()
      reg = Ridge(alpha=1).fit(design_matrix.T, Y)
      print(reg.score(design_matrix.T,Y))
      prediction = reg.predict(design_matrix.T)
      image = reg.coef_.reshape(res)
      plt.imshow(image)
      plt.show()
      reg = Ridge(alpha=10).fit(design_matrix.T, Y)
      print(reg.score(design_matrix.T,Y))
      prediction = reg.predict(design_matrix.T)
      image = reg.coef_.reshape(res)
```

plt.imshow(image)
plt.show()

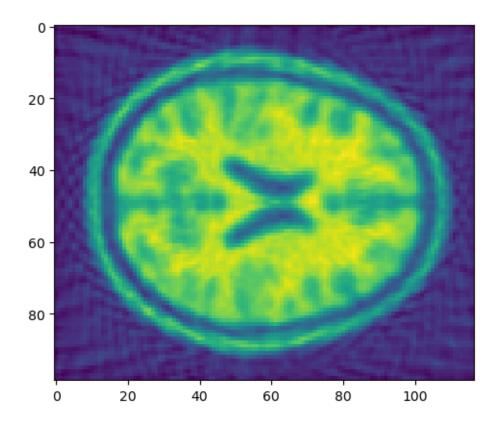
### 0.9999999710587341



#### 0.9999997054099179



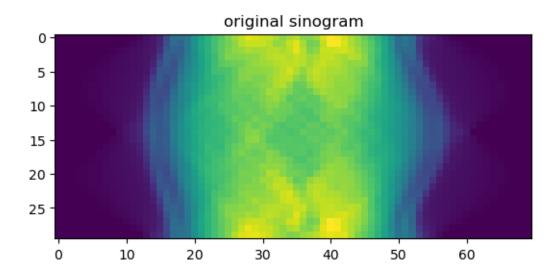
# 0.9999783629561321

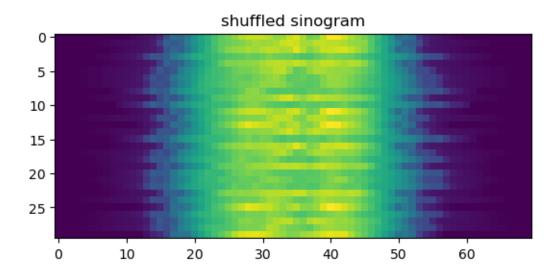


# 0.3 5 Bonus: X-Ray Free-Electron Lasers

```
[9]: sino = np.load('data/sino.npy').reshape(n_angles, n_parallel_rays)
plt.imshow(sino)
plt.title('original sinogram')
plt.show()

order = np.arange(n_angles)
np.random.shuffle(order)
sino_shuffled = sino[order]
plt.imshow(sino_shuffled)
plt.title('shuffled sinogram')
plt.show()
```





[]:

Machine learning and Physics Short OS @ a) Bridge = argmin | 1y-xTp/12+ X/1p/2 = argnan 5 (4:-(B.+BX,+BX,+BX))+ X(B.+B2+B2) We then get Bridge = (XXT+ XI) Xy
-> Since the regularitation primistres sony value of B:, This tesults in a bics for the intercept for towards when close to O. b) We nothing & Bridge and = armin 11y-XTB112+X11B12-1Bo to remove the punishment of the B. component. c) Since we remove the dependency on so of the penalty term, The total pently losses read: 1(Bi+Bi) (r b) and A(Bi+Bi+Bi) for a). If he now asome we find a minind which, the restriction contair (others of pargheters will some value) then a solve the equation 1 (Bi+ Bi) = L for b) and 1 (Bi+ Bi+ Bi) for a). We this have the Statece of an sphere for a) and ale surface of a cylinder for b). (Since for all whiles of By we have the sake penalty),

$$\hat{\beta} = \underset{\beta}{\operatorname{argmax}} \times \underset{\beta=1}{\overset{\vee}{\sum}} |_{G_{S}} \mathcal{N}(y_{n} | \mathcal{B}^{T} X_{\beta}^{2})$$

$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta=1}{\overset{\vee}{\sum}} |_{G_{S}} \mathcal{N}(y_{n} | \mathcal{B}^{T} X_{\beta}^{2})$$

$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta=1}{\overset{\vee}{\sum}} |_{G_{S}} \underbrace{\underset{\beta}{\operatorname{cyn-x}}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta=1}{\overset{\vee}{\sum}} |_{G_{S}} \underbrace{\underset{\beta}{\operatorname{cyn-x}}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

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$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta}{\overset{\vee}{\sum}} |_{G_{S}} \underbrace{\underset{\beta}{\operatorname{cyn-x}}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta}{\overset{\vee}{\sum}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

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$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta}{\overset{\vee}{\sum}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

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$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta}{\overset{\vee}{\sum}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta}{\overset{\vee}{\sum}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

$$= \underset{\beta}{\operatorname{argmax}} \times \underset{\beta}{\overset{\vee}{\sum}} |_{G_{S}} (y_{n} - x^{2}\beta) / G^{2}$$

$$= \underset{\beta}{\operatorname{argmax$$