

Magnetovision 2D 256: Hall Array for Tokamak Field Imaging

Sam Shelton, January 2025

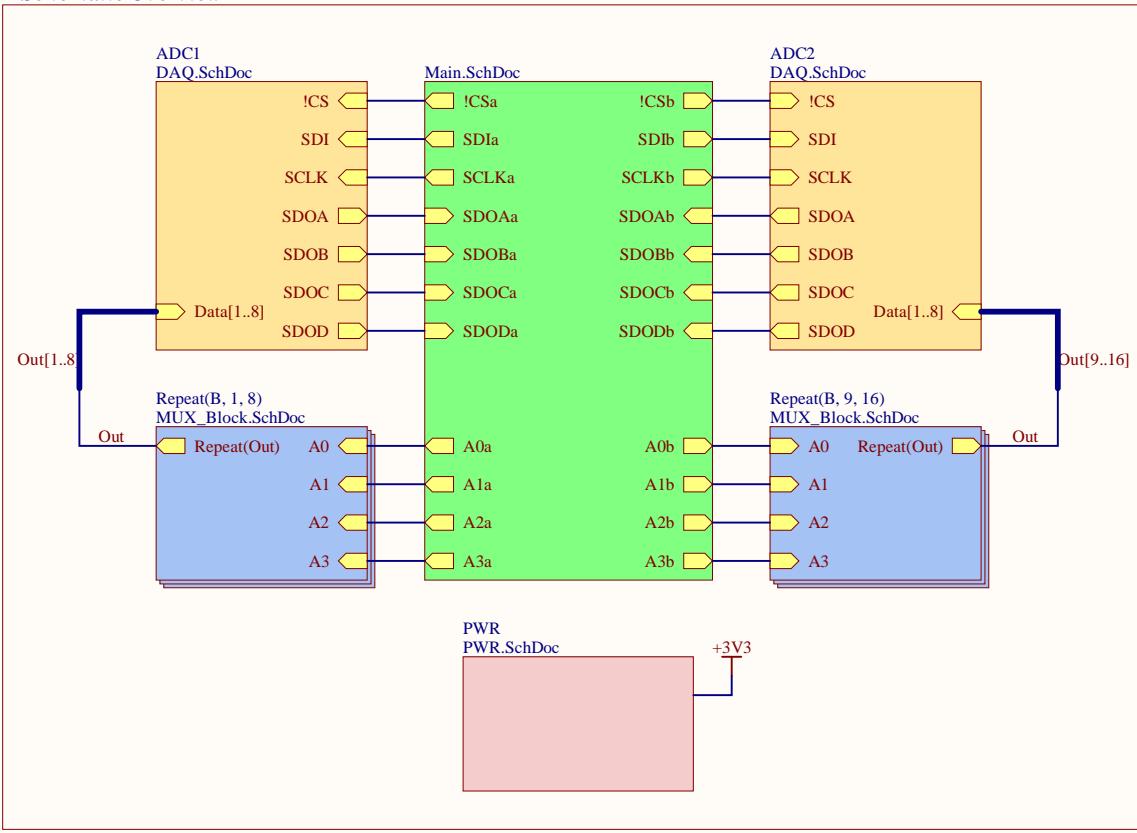
An array of 256 off-the-shelf Hall Effect sensors capable of measuring to ± 169 mT at 40 kSPS, to be used to image the field of UNSW's Tokamak

This PCB contains the sensors, filters and ADCs, as well as an LDO for power. It interfaces with another control board using level shifters and a SYZYGY FPGA Connector.

Two ADCs sample from 8 lots of 16 MUX'd sensors, allowing for simultaneous sampling of 8 sensors at a time to achieve 40 kSPS. An FPGA is required to get the full sampling rate, but a microcontroller can drive up to 4 kSPS. The sensor can operate a 60 SPS in 'real-time' mode, and use hardware oversampling and/or averaging to reduce noise.

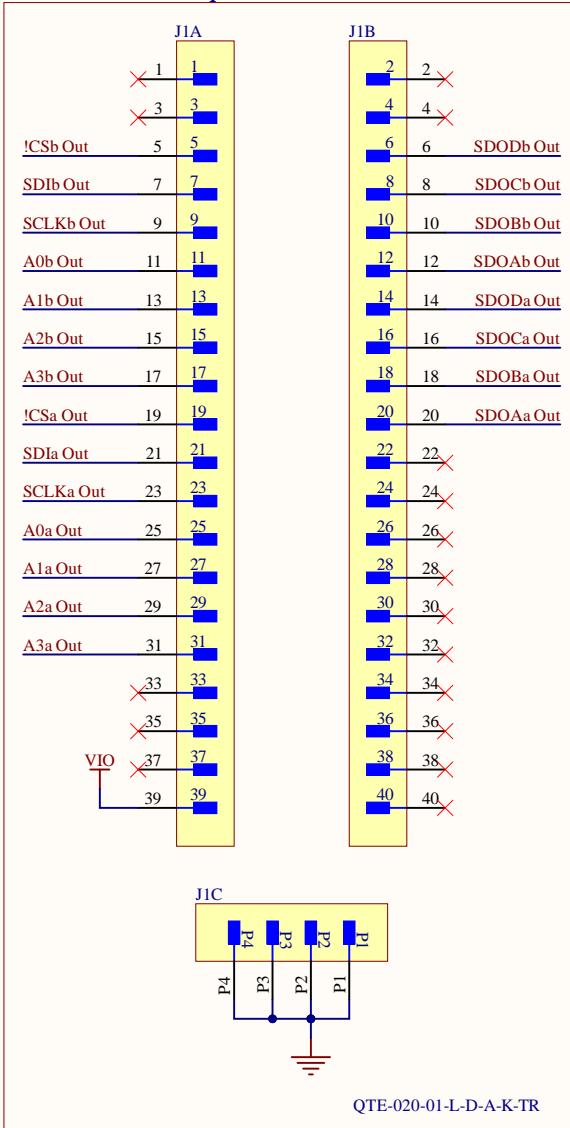
The PCB is a 6-layer board designs to use JLCPCB's advanced PCB product. It heavily uses via-in-pad and benefits from the ENIG finish. The board has SMD parts on both sides.

Schematic Overview

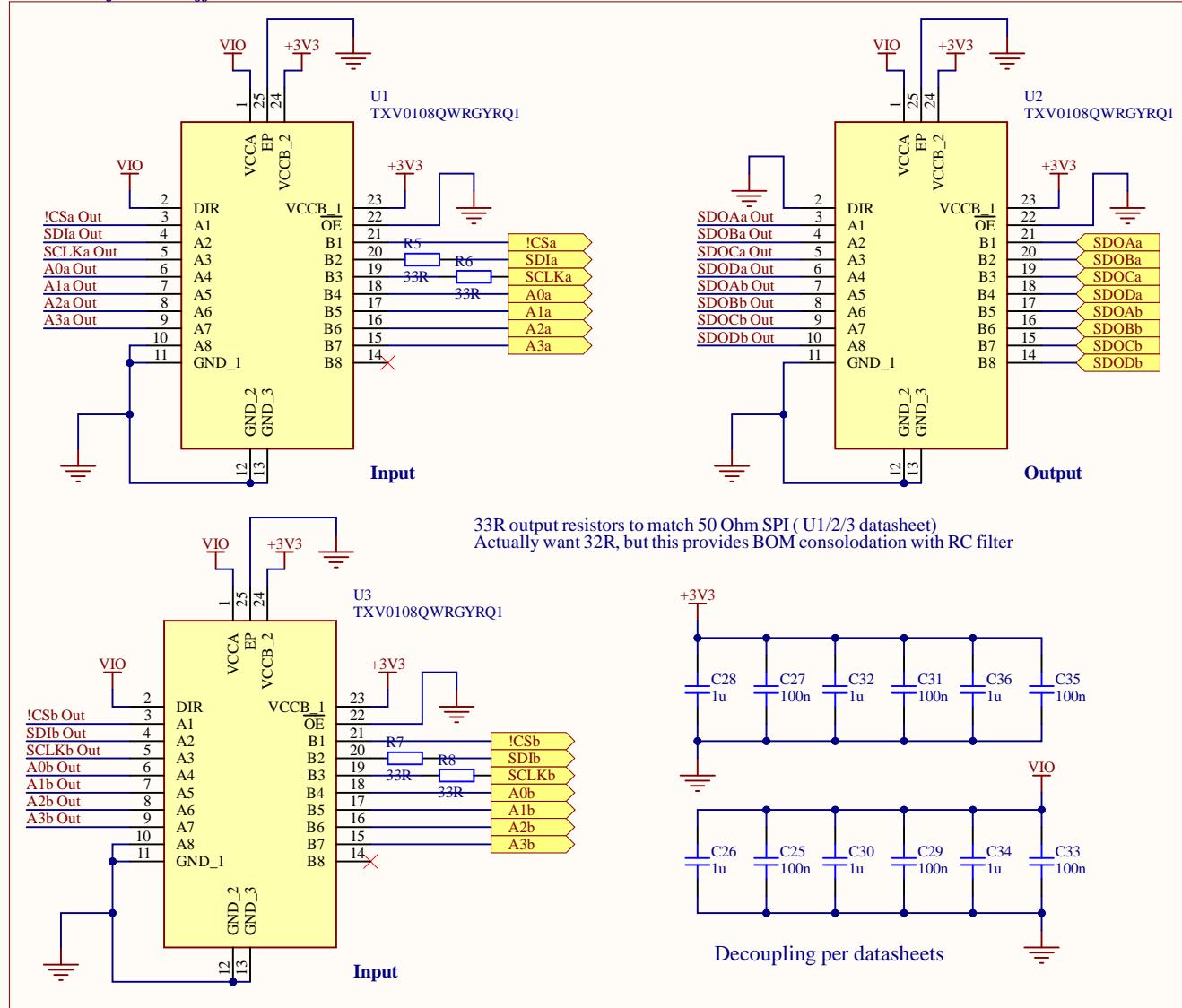


Title		
Magnetovision 2D 256: Overview		Revision
Size	Number	Final
A4		
Date:	6/16/2025	Sheet 1 of 7
File:	C:\Users\...\Master.SchDoc	Drawn By: Samsh

SYZYGY STD Peripheral FPGA Connector



Level Shifters + Buffers

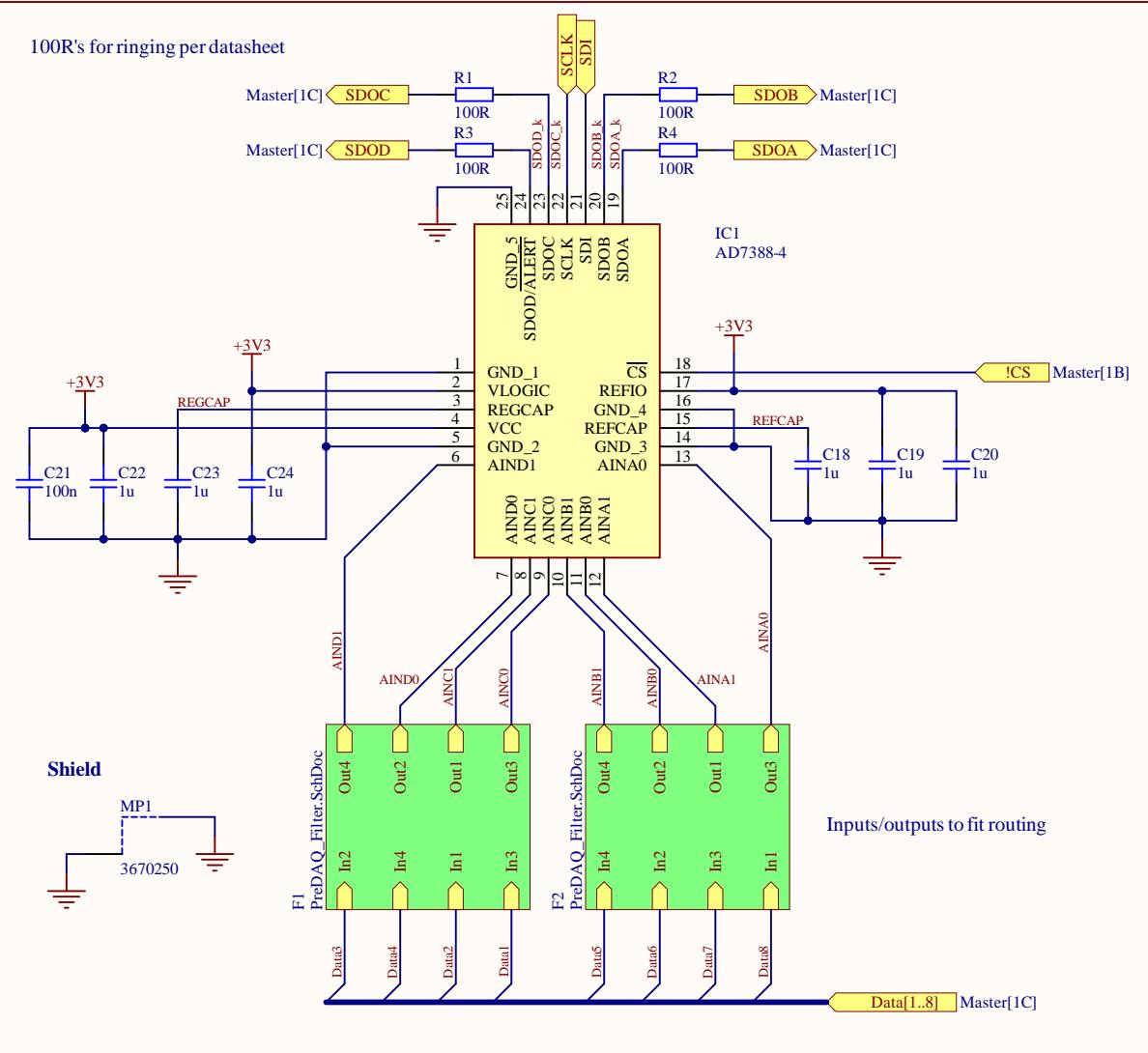


The buffers/level shifters allow more logic levels to be used (think FPGAs) as well as buffer the relatively high-capacitance MUX control busses, allowing them to be effectively driven by potentially wimpy digital logic signals.

Title Magnetovision 2D 256: MCU and I/O

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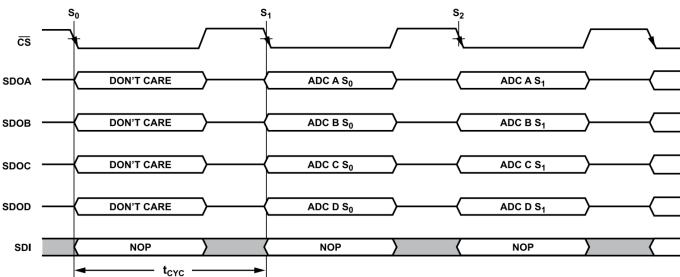
ADC and Related



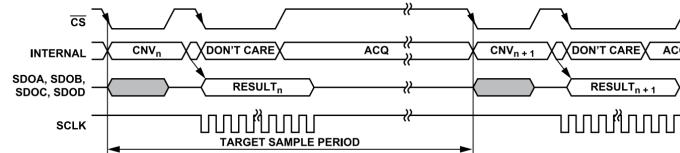
The AD7388-4 is a 12-bit part, this could be substituted for the 14 or 16 bit parts if desired (the AD7387-4 and AD7376-4 respectively - same datasheet!). These higher bits cost more, and there is diminishing returns as they just quantise noise. These parts support hardware oversampling for a +2 bit resolution boost. This family of parts was selected because of simultaneous nature, high sample rate and support for an external reference $V_{ref} = V_{cc}$. Note that the SPI behaviour of the AD7388-4 part does not quite match the behaviour of the AD7386-4 described in the datasheet. It takes 48 SCLKs to transmit all data.

In observations, RMS noise is about 0.07 mT with P2P noise of about 0.5 mT, when operating in 60 Hz mode with 8-measurement averaging.

SPI Behaviour 1-Wire mode (MCU)



SPI Behaviour 4-Wire mode (FPGA)



Low Latency Mode (Realtime Operation)

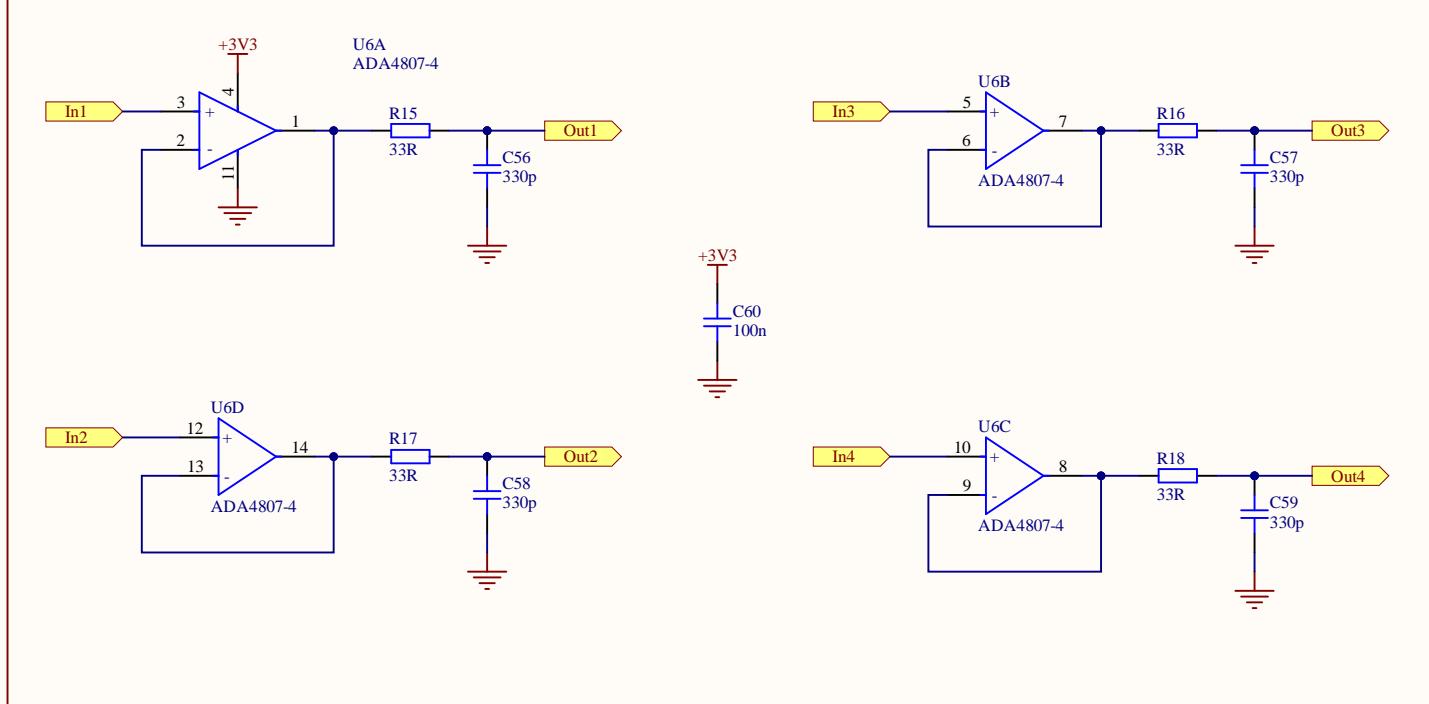
SPI Note - IMPORTANT!

Note that you need to use separate SPI busses for each ADC on the separate control board. This is because the level converters/buffers are not open drain/collector: they cause collisions. This is trivial to implement on a Teensy MCU, but still a bit annoying.

Title Magnetovision 2D 256: ADC and Related		
Size A4	Number	Revision Final
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File: C:\Users\...\DAQ.SchDoc	Drawn By: Samsh	

A

A

ADC Driver with RC Filter

The RC here is simply from the ADC datasheet. This is using the same (recommended) Op-Amp as the other filter, but here in a quad package to fit inside the shielding can.

We can calculate $f_{-3dB} = 1/(2 \pi R C) = 14.6 \text{ MHz}$

B

B

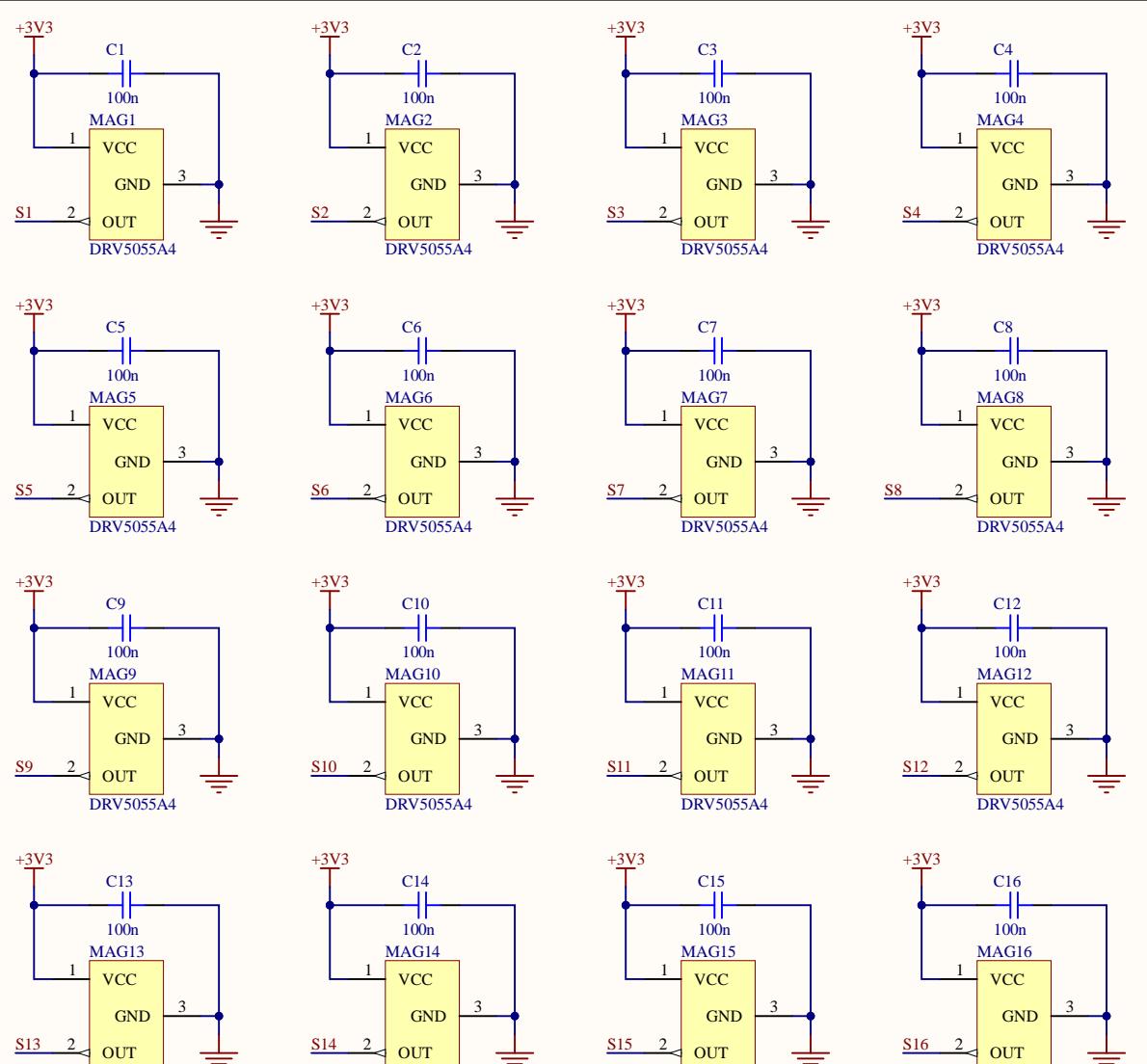
C

C

D

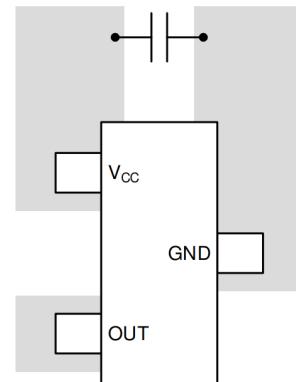
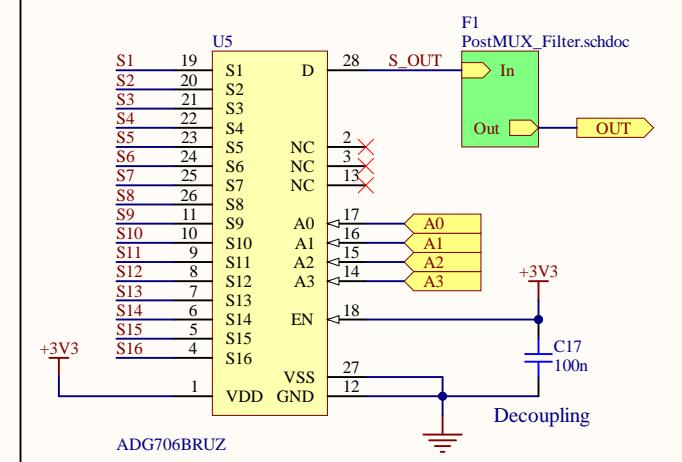
D

Title Magnetovision 2D 256: Pre-ADC Filter		
Size A4	Number	Revision Final
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File: C:\Users\...\PreDAQ_Filter.SchDoc		Drawn By: Samsh

x16 Magnetometer Array

Atomcraft has $B_{max} = 0.125$ T, requiring the X4 SKU, choose A4 for temperature drift compensation

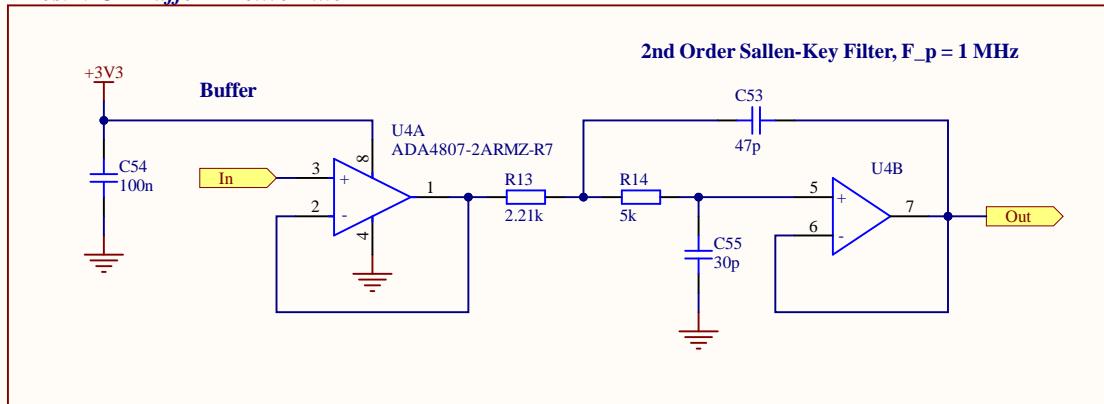
$$V_{out} = VCC/2 + \sim B, \text{ so between } VCC/2 \text{ and } VCC \text{ for positive } B$$

Datasheet Layouts**MUX and Related**

20 KHz Sensing Bandwidth

Title		Magnetovision 2D 256: x16 Sensor Array and MUX	
Size	Number	Revision	
A4		Final	
Date:	6/16/2025		Sheet 5 of 7
File:	C:\Users...\MUX_Block.SchDoc		Drawn By: Samsh

Post-MUX Buffer + Active Filter



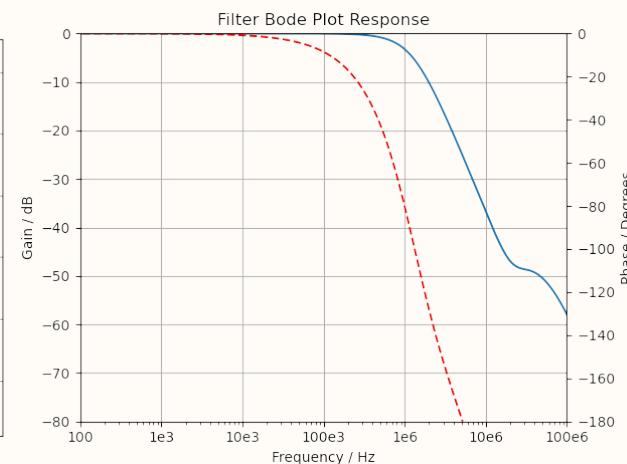
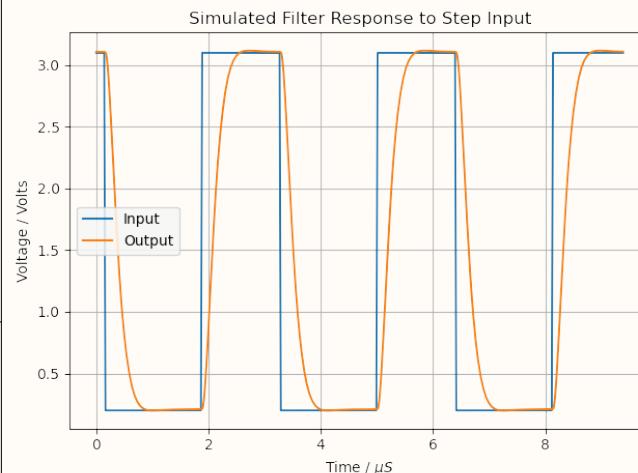
MAX ADC Speed is 2MSPS (when MUXed), so set stopband at Nyquist 1 MHz (-3db). Used AD Filter design tool, set for Bessel topology. Adjusted R/C for manufacturing.

This particular Op-Amp is high-bandwidth AND rail-to-rail. It was the only 'recommended' Op-Amp to be stable in Spice simulations.

While Nyquist was a concern, the primary focus was filter settling time. This design allows 5 tau to be achieved for all samples at 40 kSPS overall sampling. This is just about the 'strictest filter' that meets this condition with this number of stages. More stages would have likely added more noise and introduced delay, for only mildly reduced settling time.

Filter Behaviour Simulation Results & Notes

The filter was simulated in LTSpice extensively. Analysis with an oscilloscope confirmed appropriate filter behaviour in testing.



Filter Model

U1 ADA4807-2

U2 ADA4807-1

U3 ADA4807-1

U4 ADA4807-1

V1 3.3

V2 PULSE(0 3.3 0 0 1.5625u 3.225 20)

A1 ADG706

A2 ADG706

C1 20p

C2 47p

C3 330p

R1 2.21k

R2 5k

R3 33

S1-S16

.tran 50u

EN

Vdd

Vss

GND

Title

Magnetovision 2D 256: Post MUX Filter

Size

A4

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File: C:\Users...\PostMUX_Filter.SchDoc

Drawn By: Samsh

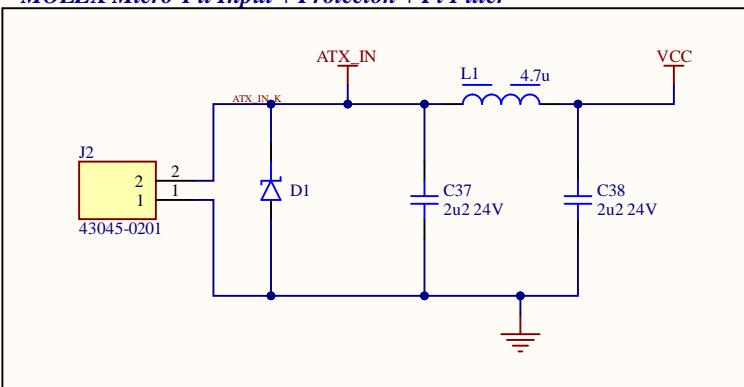
1

2

3

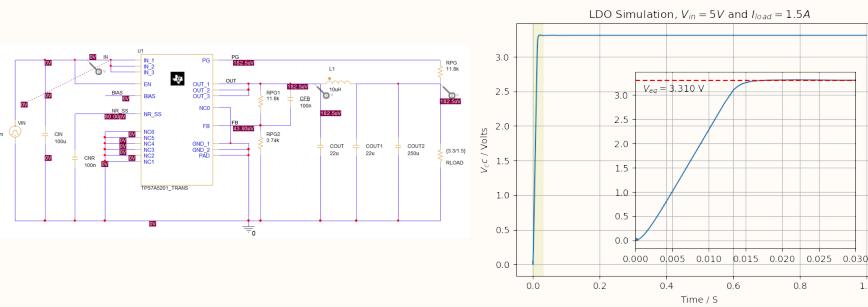
4

MOLEX Micro-Fit Input + Protection + Pi Filter

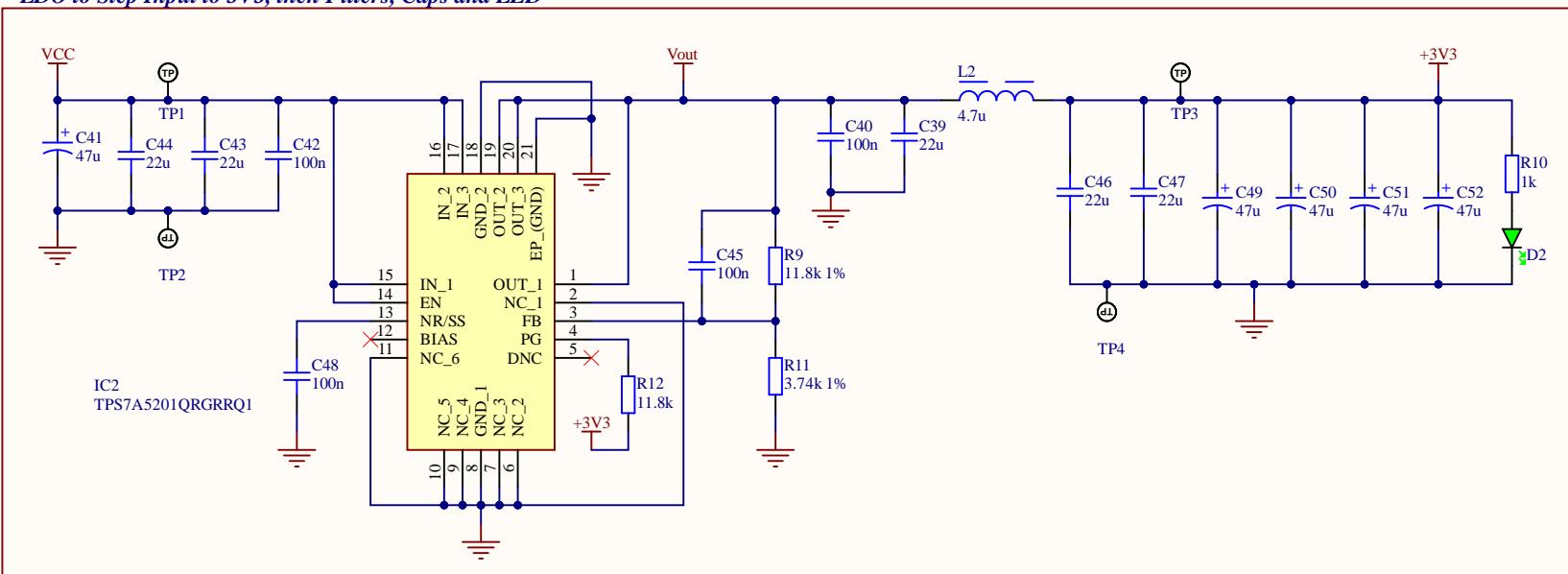


Notes on Power Consumption & Behaviour

The device consumes about 1.5 A (running from 4V) and produced a fair amount of heat. It should be allowed to sit for ~20 minutes to thermally equilibrate before calibration. The filters seem OK at removing high frequency switching noise, but 50 Hz bleeds through. It is recommended to power from 4V/Linear lab PSU, although 5V is acceptable as well.



LDO to Step Input to 3V3, then Filters, Caps and LED

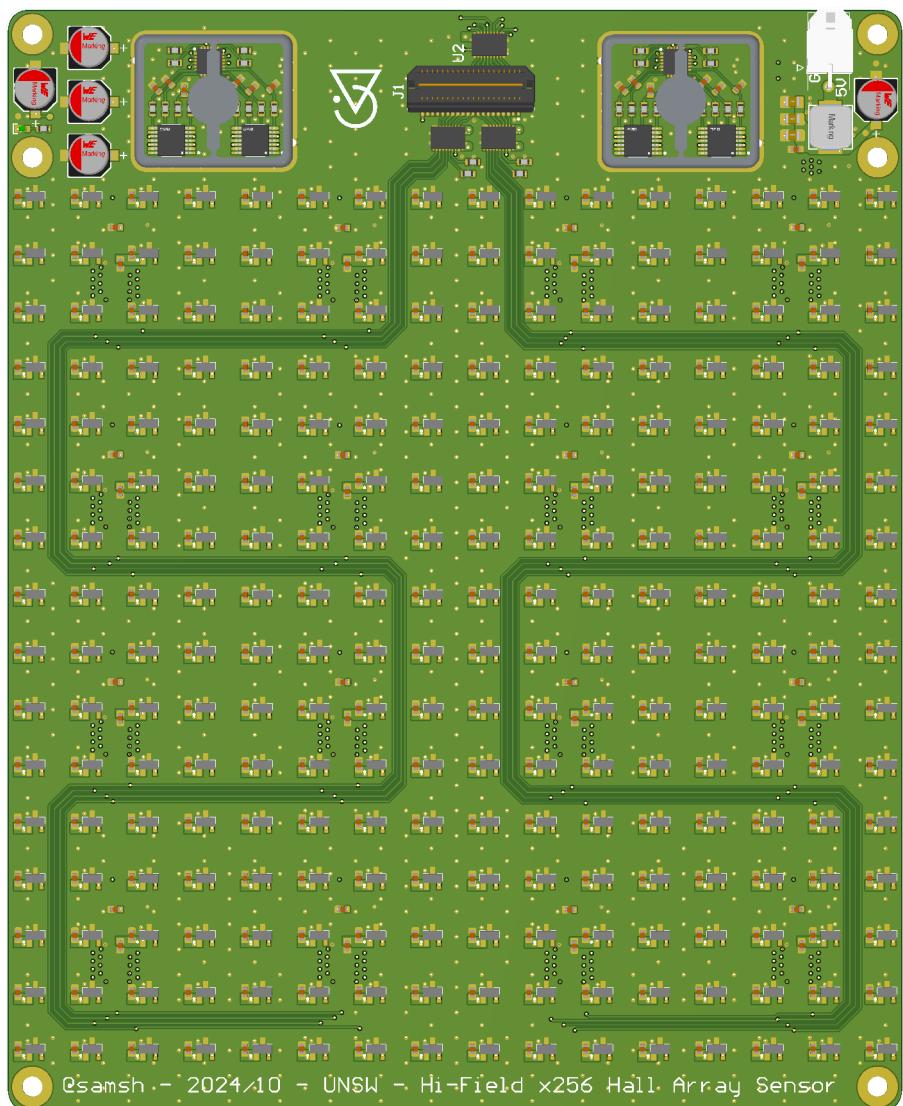
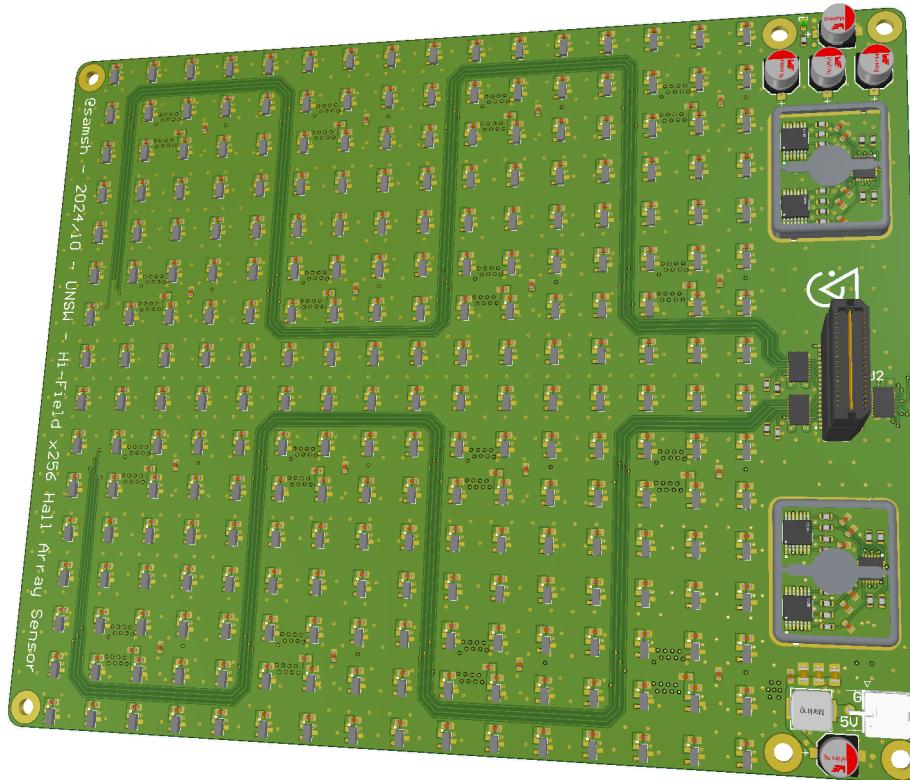


Title Magnetovision 2D 256: Power Supply

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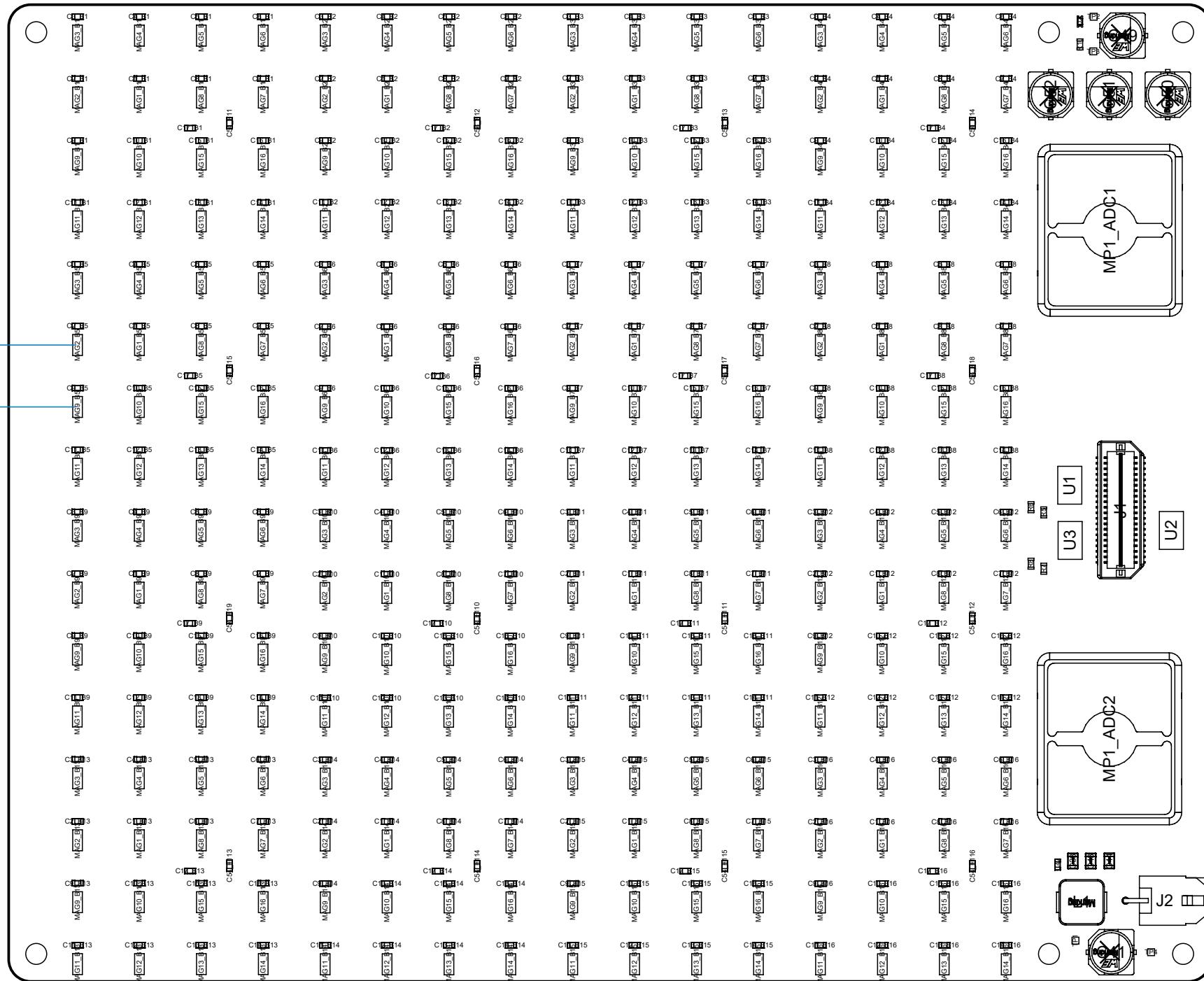
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Sam Shelton, January 2025

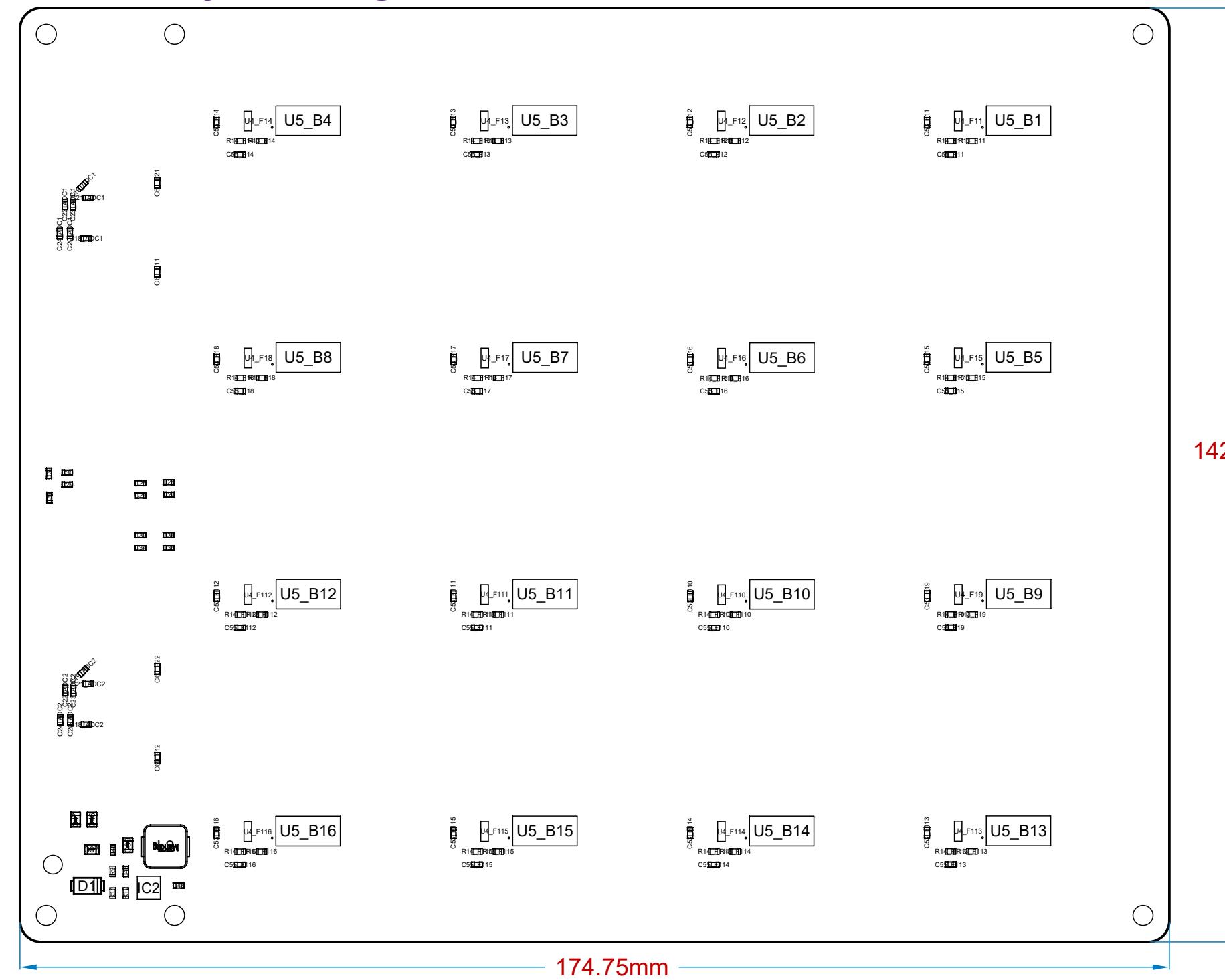


MANUFACTURING AND DISPLAY DRAWINGS

Assembly Drawing: Top View



Assembly Drawing: Bottom View



A

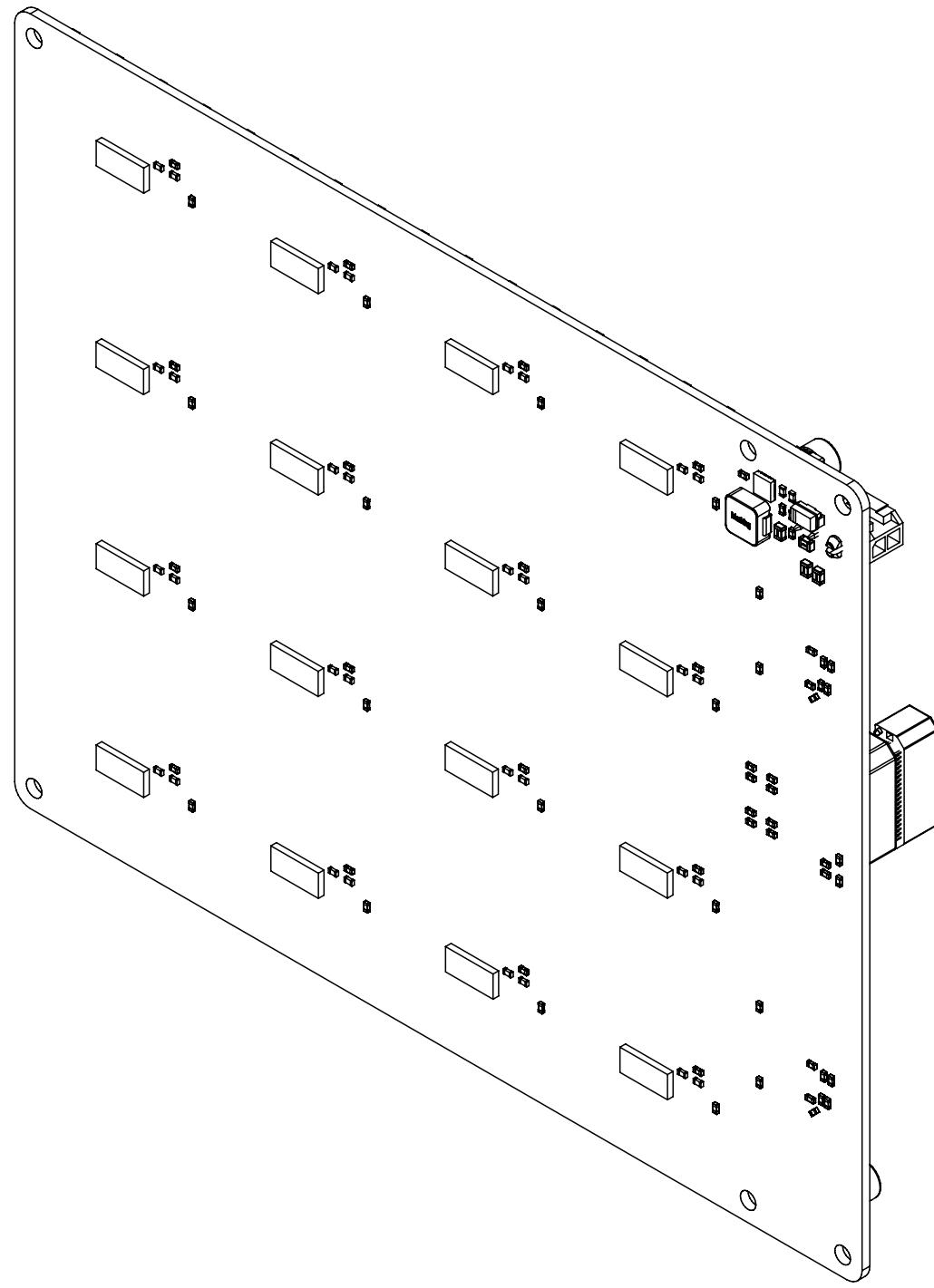
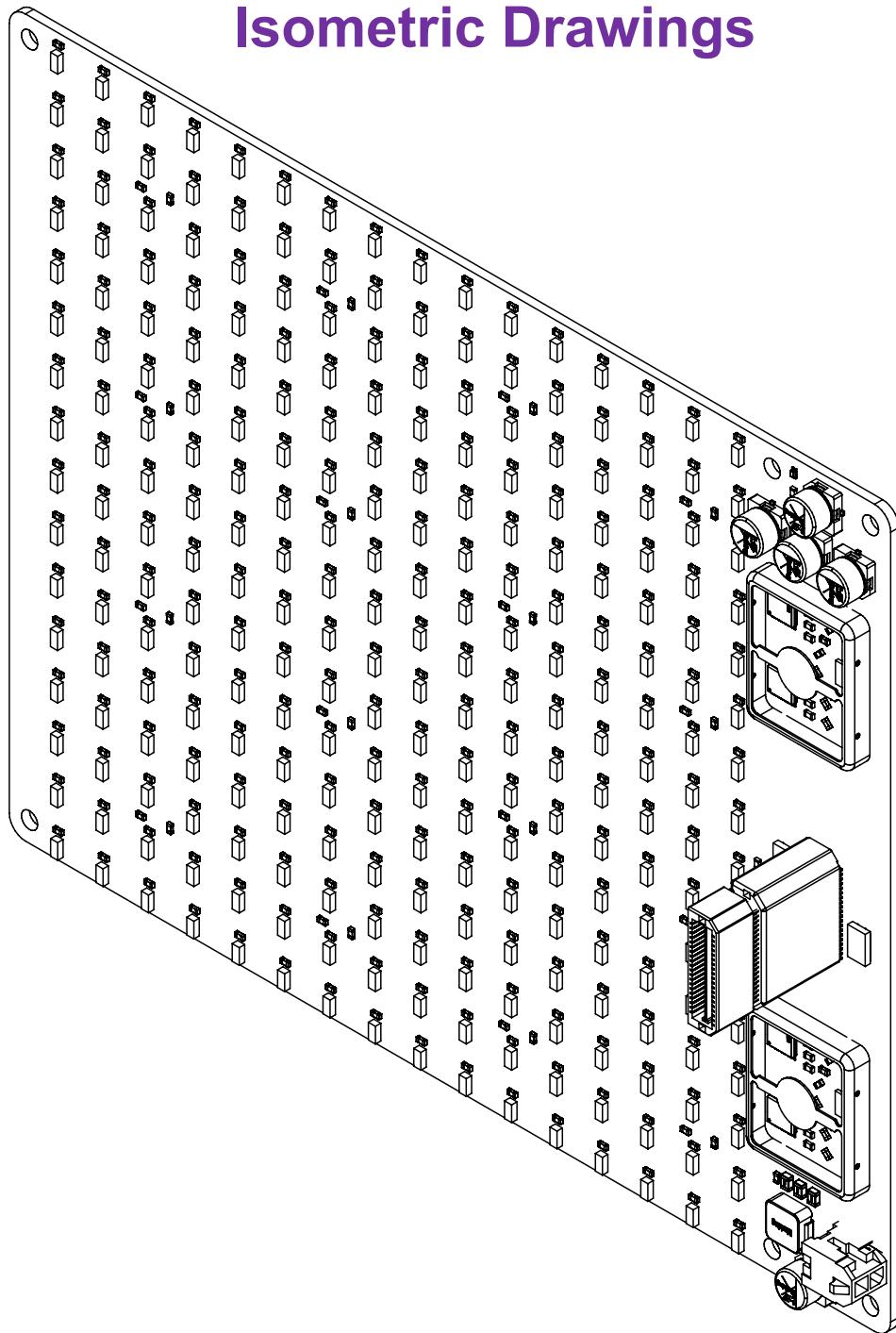
B

C

D

E

Isometric Drawings



A

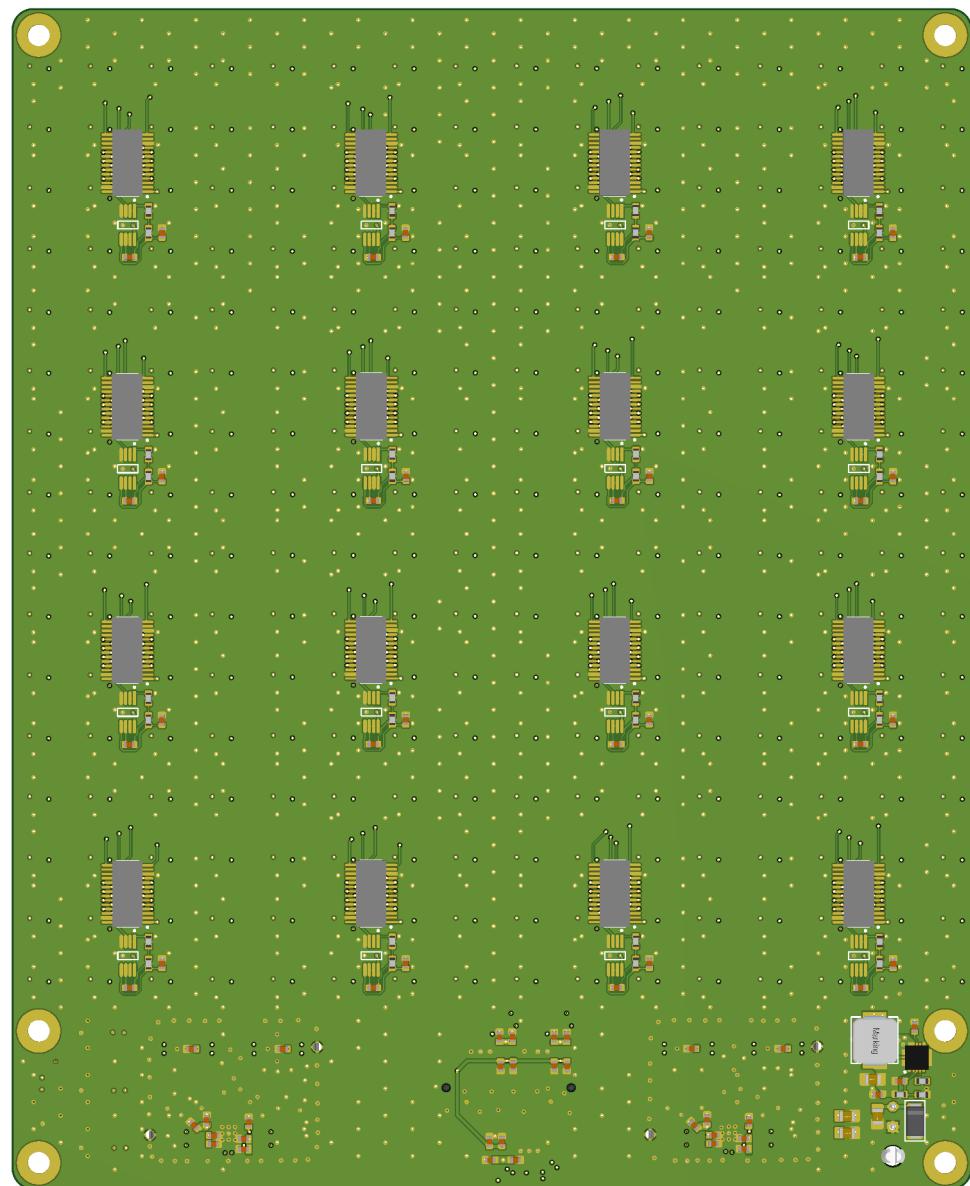
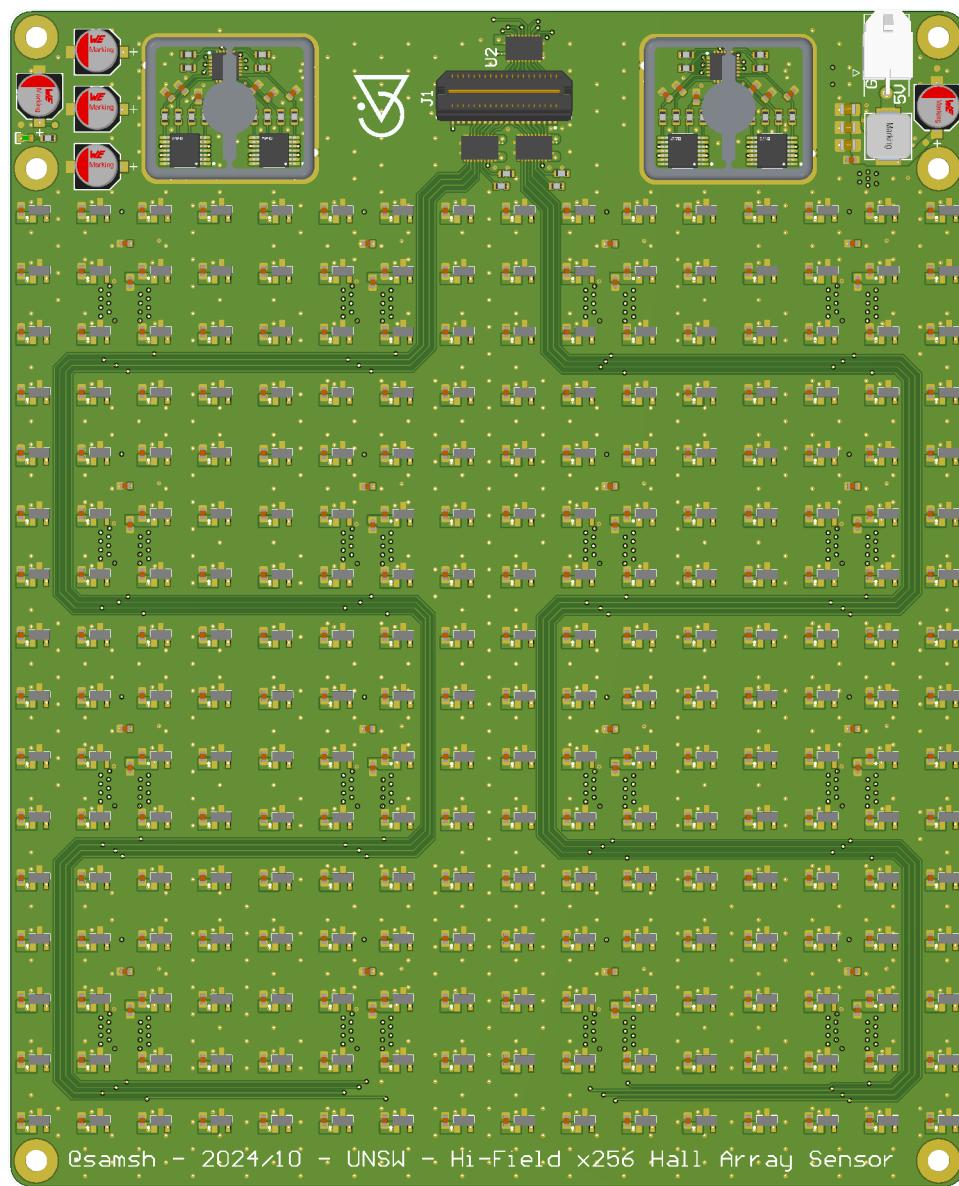
B

C

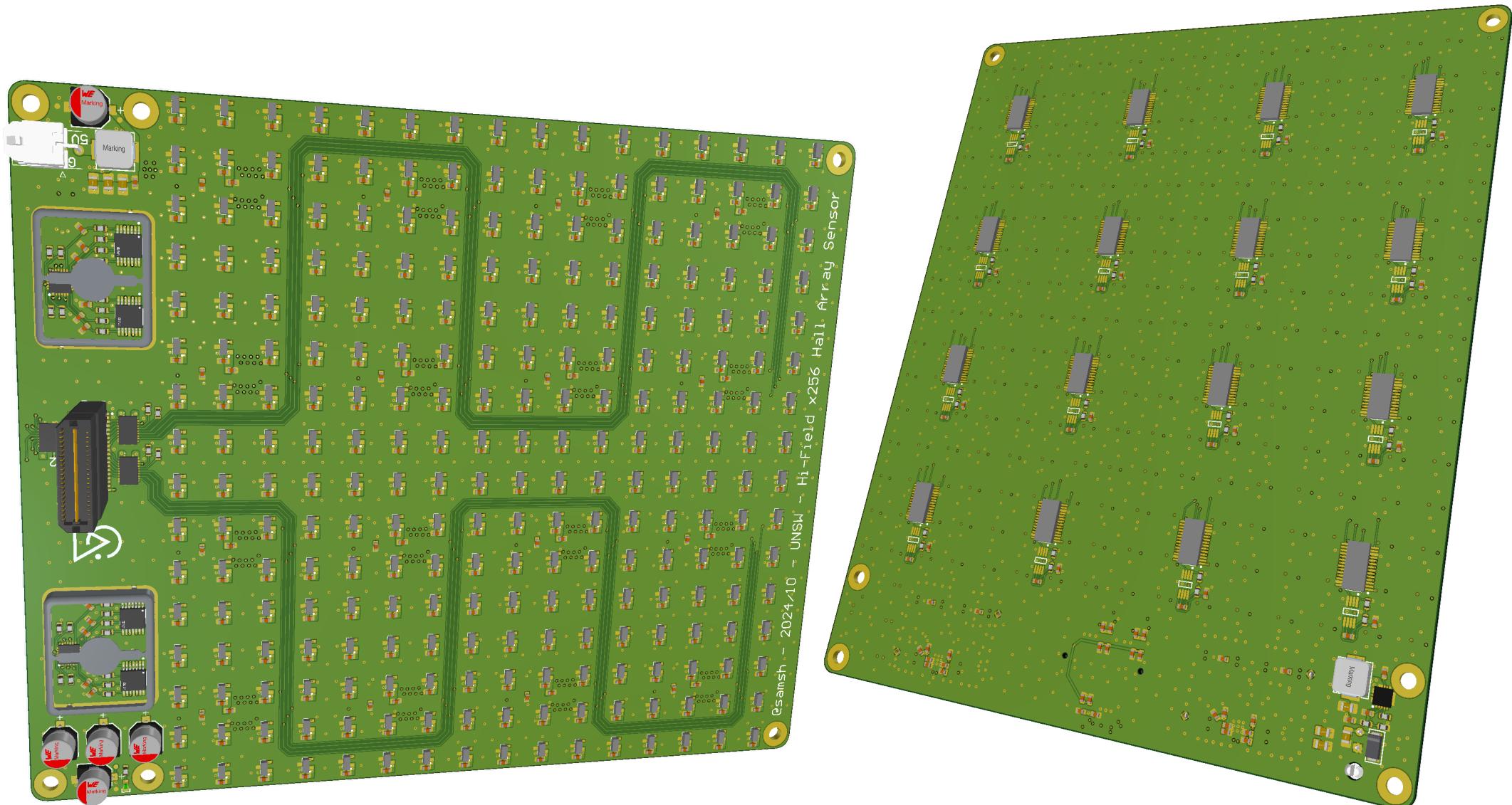
D

E

Realistic Face Drawings

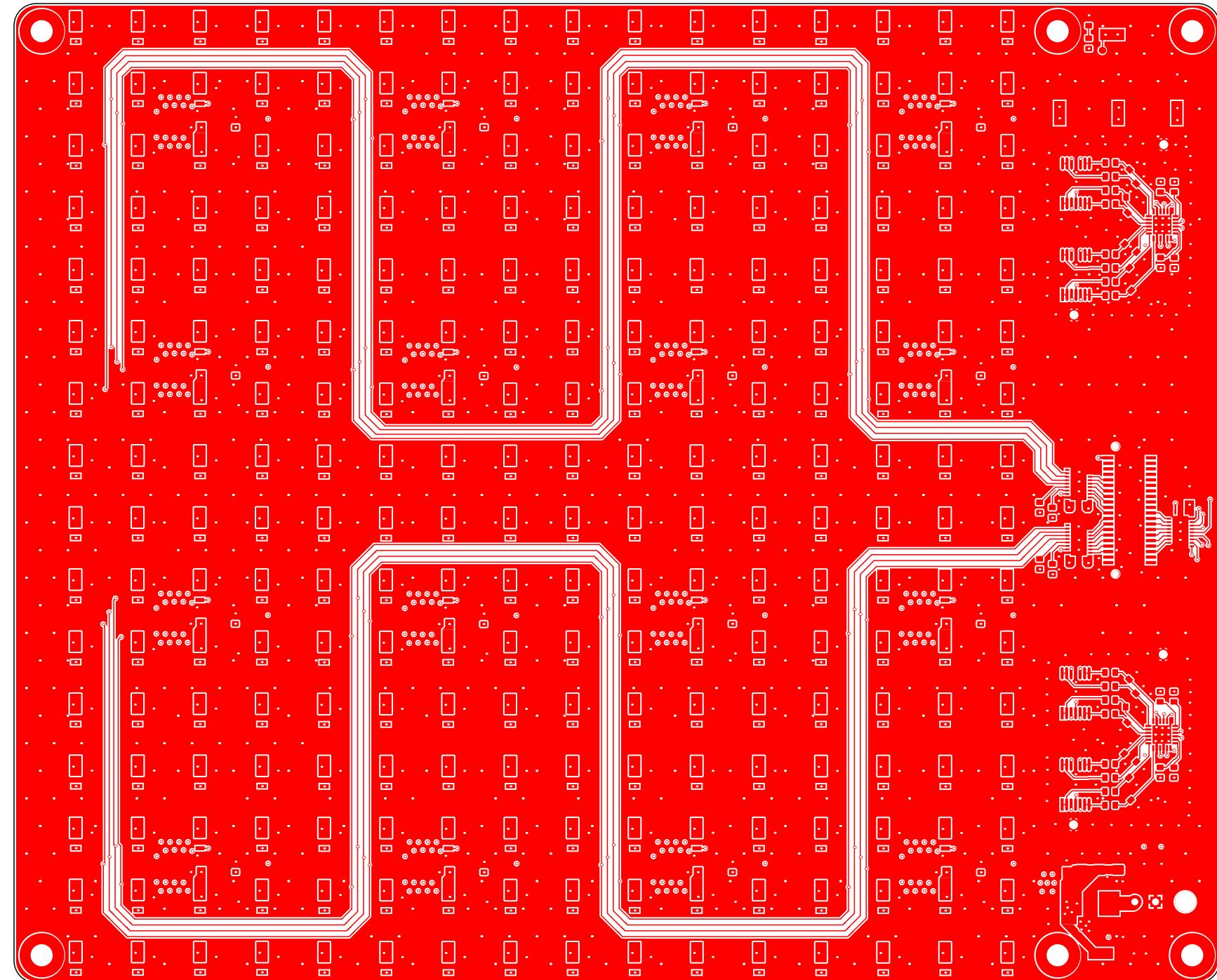


Realistic Isometric Drawings



A	B	C	D	E
<h1>Stackup - Standard JLCPCB without Impedance Control</h1>				
1				
	Material	Layer	Thickness	Dielectric Material
		Top Overlay		
	Surface Material	Top Mask	0.02mm	Solder Resist
	Copper	L1 (SIG)	0.04mm	
	Prepreg		0.10mm	2313
	Copper	L2 (GND)	0.02mm	
	Core		0.57mm	FR-4
2				<i>Dielectric</i>
	Copper	L3 (SIG)	0.02mm	
	Prepreg		0.13mm	2116
	Copper	L4 (GND)	0.02mm	
	Core		0.57mm	FR-4
3				<i>Dielectric</i>
	Copper	L5 (PWR)	0.02mm	
	Prepreg		0.10mm	2313
	Copper	L6 (SIG)	0.04mm	
	Surface Material	Bottom Mask	0.02mm	Solder Resist
		Bottom Overlay		
4				
	Total thickness: 1.63mm			

L1 (SIG) Layer



A

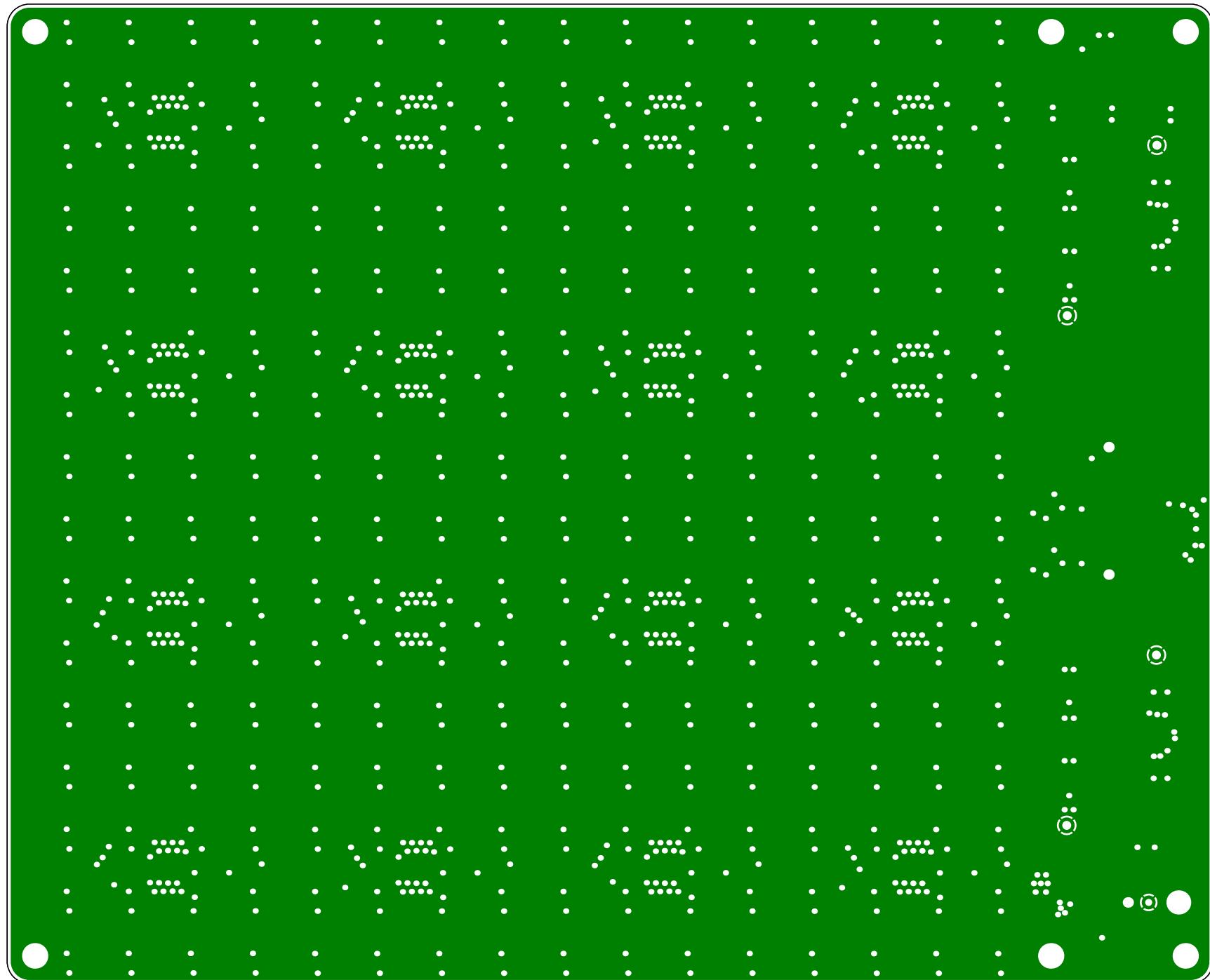
B

C

D

E

L2 (GND) Layer



A

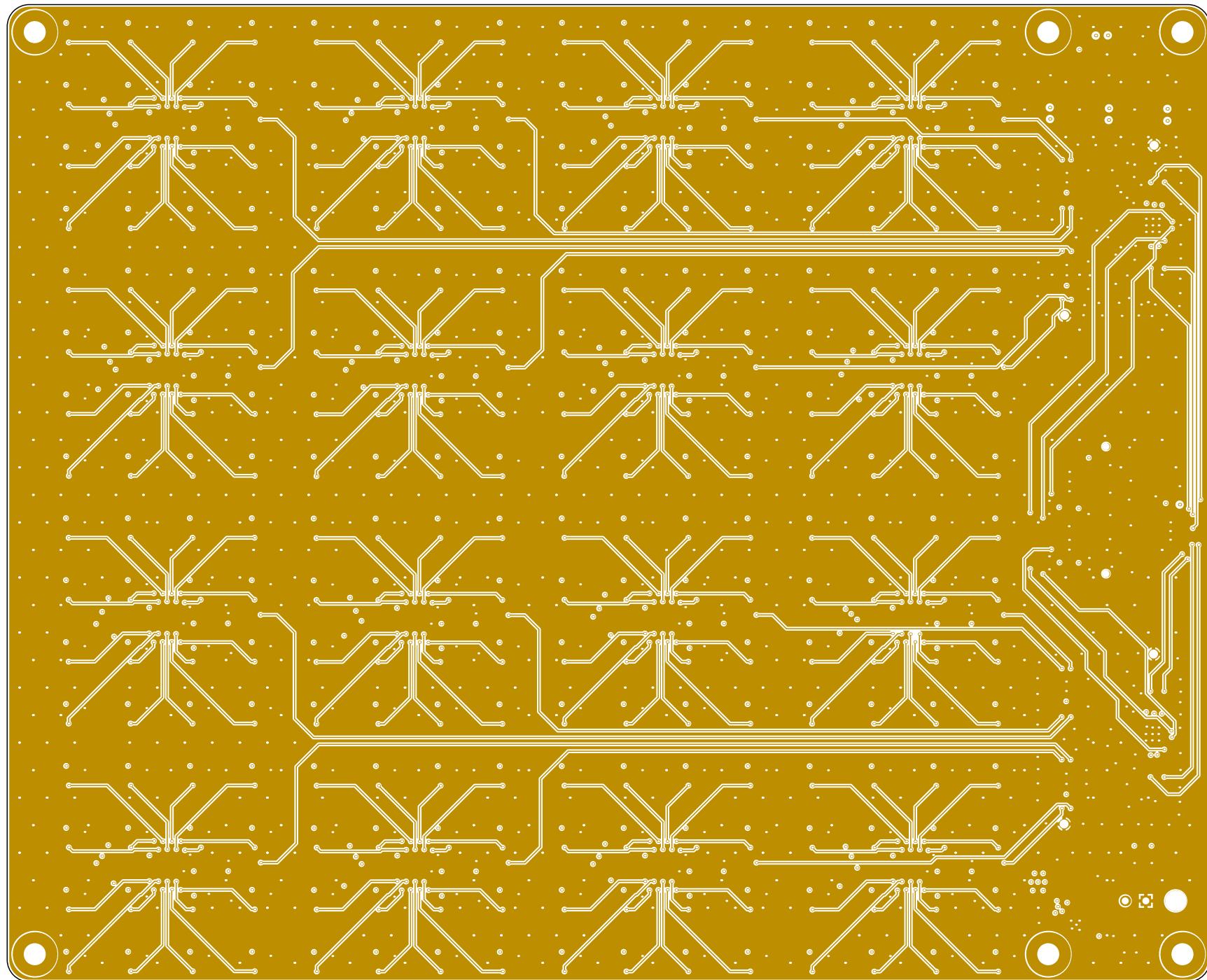
B

C

D

E

L3 (SIG) Layer



A

B

C

D

E

A

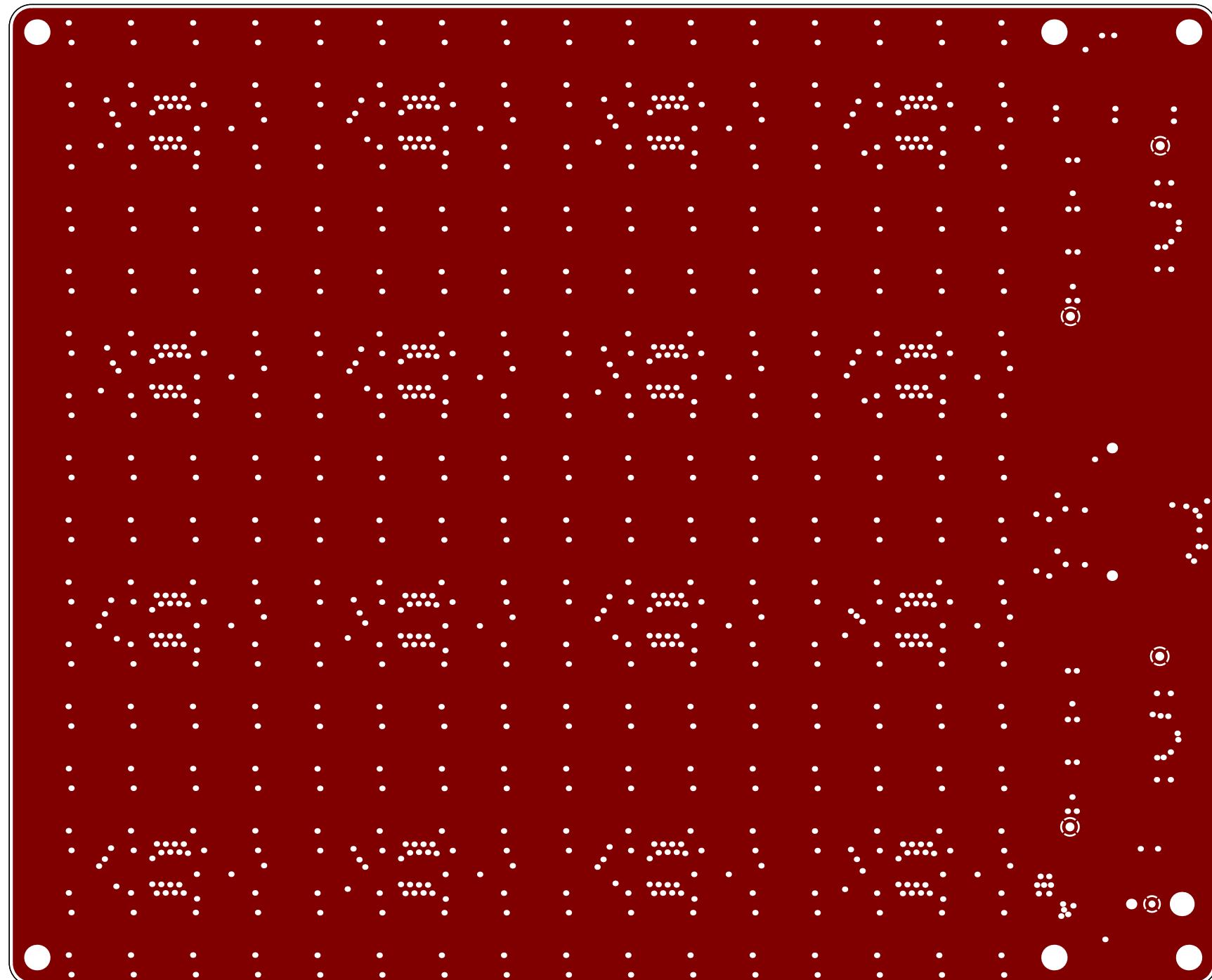
B

C

D

E

L4 (GND) Layer



A

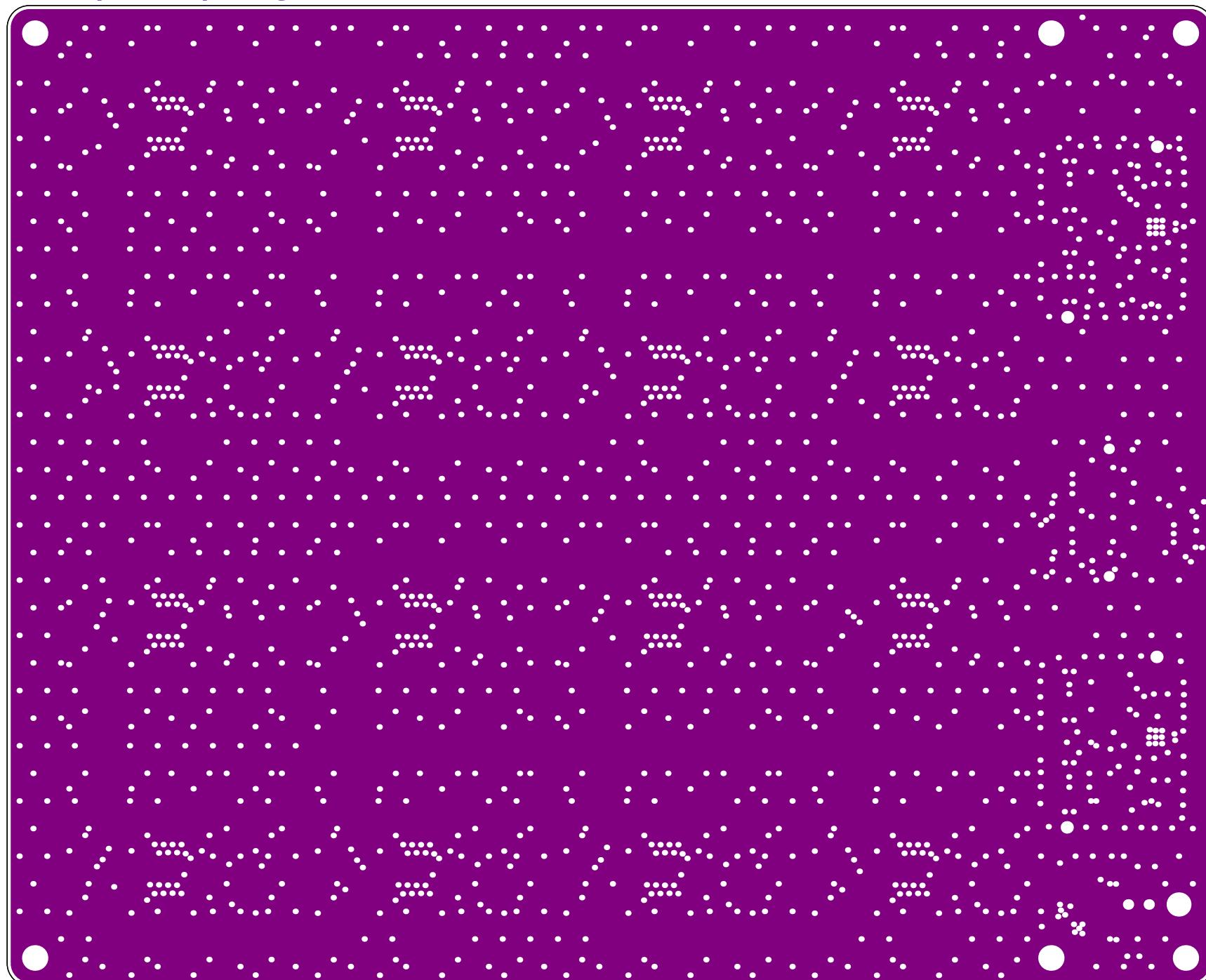
B

C

D

E

L5 (PWR) Layer



1

2

3

4

1

2

3

4

A

B

C

D

E

A

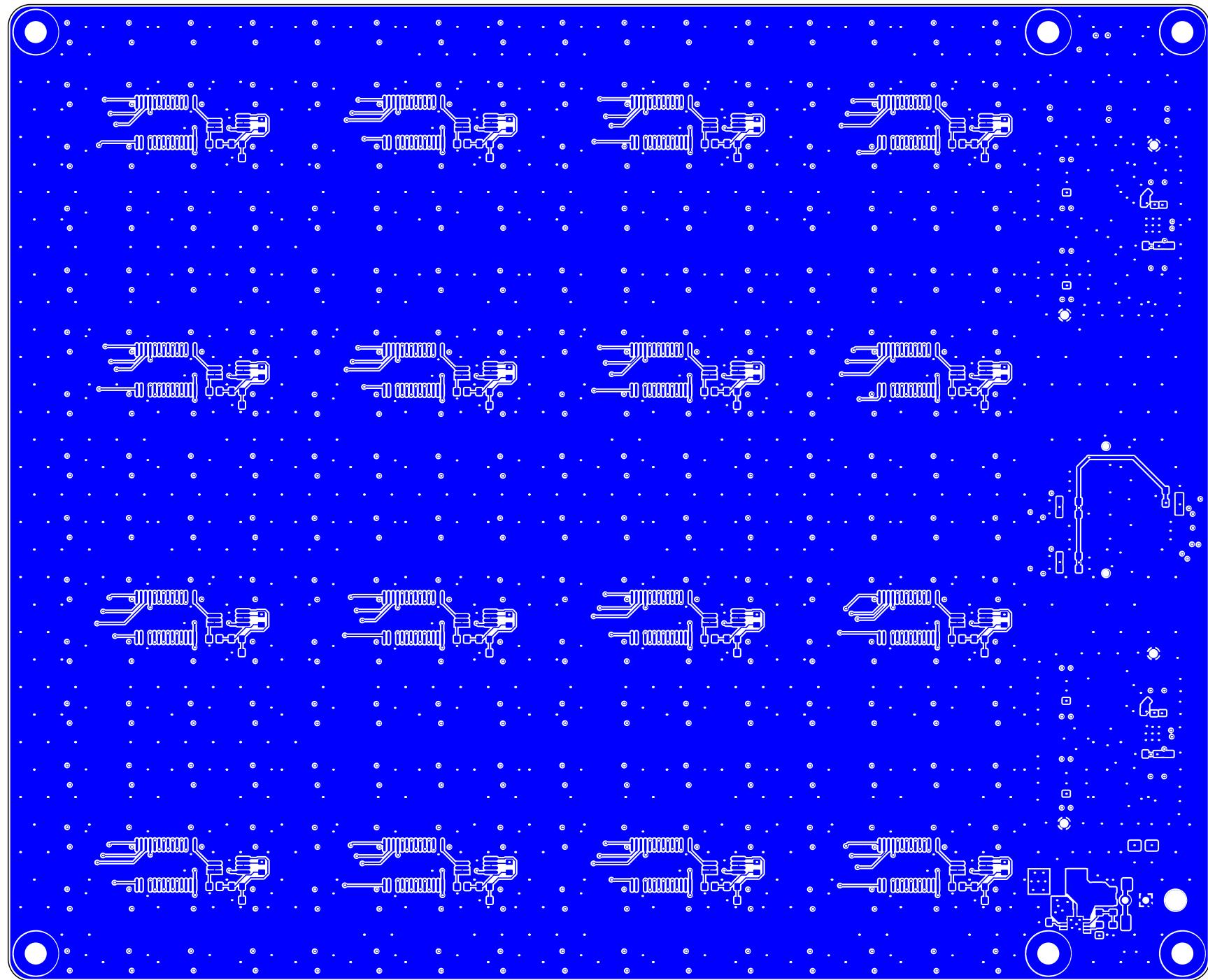
B

C

D

E

L6 (SIG) Layer



1

2

3

4

1

2

3

4

A

B

C

D

E