

Relaxation for Efficient Asynchronous Queues

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1 Introduction

This paper proposes a new algorithm for implementing a standard FIFO queue in a fully asynchronous message passing mode. To our knowledge we have not encountered any previous work that suggested a queue algorithm for this specific model. Our algorithm utilizes vector clock timestamps that allow individual processes to hold some view of the time steps of other processes have taken at points of communication. Using this technique to timestamp invocations of the two operations of the queue, then linearizing all of the queue invocations based on the ascending lexicographic order of these timestamps creates a valid permutation that meets the specifications of a FIFO Queue. The goal of establishing this queue method is to design a system with full replication. There are existing systems that handle the asynchronous queue (server client model), but are incapable of replication. With replication, and (INSERT THE CITATION TO THE PAPER HERE) we hope that this queue algorithm can be used in fault tolerant systems in the future.

1.1 Related Work

2 Model and Definitions

2.1 Asynchronous System Model

We assume a fully asynchronous message passing model, with a set of n processes $\Pi = [p_0, \dots, p_{n-1}]$ modeled as state machines. These state machines are time-free, meaning that their output is only described through their input and state transitions without any specific time bound. All inter-process communication is assumed to be reliable i.e any message that is sent will always be received at its destination process. Additionally, communication channels between processes are considered to be treated as FIFO, in that any message sent from process A to process B will be processed prior to any other message from the same pair sent later in an execution. This can be accomplished by assuming that each process has an incoming buffer for each other process, and that inter-process messages are marked numerically, and out of order messages are stored in the buffer until they can be retrieved in order. We also assume no processes crash, and none of the processes have access to a hardware clock.

2.2 Queue Definitions

We introduce the definition for a standard FIFO Queue abstract data type. We will use the special character \perp to represent an empty queue.

► **Definition 1.** A Queue over a set of values V is a data type with two operations:



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23:2 Asynchronous Relaxed Queues

- 42 ■ *Enqueue(val, -)* adds the value X to the queue
- 43 ■ *Dequeue(-, val)* returns the oldest value in the queue.

44 A sequence of queue operations is legal iff it satisfies the following conditions. The empty
45 sequence is a legal sequence. Each Enqueue value is unique. Once a value has been enqueued
46 to the queue once, it can not be enqueued again. If ρ is a legal sequence of operation instances,
47 then $\rho \cdot \text{Dequeue}(-, val), val \neq \perp$ is legal iff *Enqueue(val, -)* is the first Enqueue instance in ρ
48 that does not already have a matching *Dequeue(-, val)* in ρ . Furthermore, $\rho \cdot \text{Dequeue}(-, \perp)$
49 is legal iff every *Enqueue(val, -)* in ρ has a matching *Dequeue(-, val)* in ρ .

3 Asynchronous FIFO Queues

3.1 Description

52 Each process stores a vector clock timestamp that holds its local view of the clocks at all
53 other processes. Thus the vector clock timestamp at v_i , dictating the vector clock view of
54 process i is an array of size n (number of processes in this system) that is initially 0 at all
55 indices. At the point when a process starts an *Enqueue()* or *Dequeue()* invocation, that
56 process will increment their own index in the local clock timestamp, which marks a step
57 or clock tick. Processes also update the local view of the vector clocks when they receive
58 a message containing a timestamp from another process. This occurs each Enqueue and
59 Dequeue invocation and response, as as a part of the payload of each of these messages,
60 the timestamp at the point in which it was invoked is included. This results in processes
61 regularly updating the local views of their clocks, resulting in processes being as updated as
62 possible. To update the local vector clock, values at corresponding indexes in the local clock
63 and message clock are compared, and the larger of the two values is set to the local view. By
64 adjusting each of these indices, this guarantees that a local clock will have the largest of the
65 two indices at all indices in the local clock, and therefore has the most advanced possible clock
66 at that point in the execution. For any two vector timestamps v_i and v_j , such that $v_i \prec v_j$,
67 states that v_i is a strictly smaller timestamp than v_j , if $v_i[x] < v_j[x], \forall x \in [0, \dots, n-1]$. If
68 this is not true, there is some index k , the first element that is different between the two
69 vector timestamps v_i and v_j i.e. for $x = 0$ to $k-1, v_i[k] < v_j[x]$ but at index $k, v_i[k] \geq v_j[k]$.
70 Then we say that v_i is lexicographically smaller than $v_j, v_i \ll v_j$ if $v_i[i] < v_j[i]$. Notice that
71 $v_i \prec v_j$ implies that $v_i \ll v_j$ but not the opposite.

72 Within each process there is a local version of an augmented minimum priority queue
73 keyed on lexicographic timestamp order. This priority queue can perform three operations:
74 *insert(value, vclock)*, *get(position)*, *remove(value)*. The insert operation adds the value to
75 the queue based on the vclock as a priority. The *get(position)* function allows the user to
76 peek into the element at the passed position without removing a value from the queue. The
77 *remove(value)* function removes the specific value passed to it from the queue which can
78 be at any location in the queue. Ordering elements in FIFO order is not a straight-faced
79 task in a distributed setting since defining which invocation happened first is not as clear as
80 in a linear setup. Consequently using a priority queue keyed on lexicographic timestamp
81 order allows us to ensure some order locally to guarantee FIFO consistency to the user once
82 linearized.

3.1.1 Confirmation Lists

84 The main structure of this algorithm it to utilize a structure we will define called a *Con-*
85 *firmation List* to track the responses for a given dequeue locally for each process. Upon

receiving a dequeue request message, a given process will either declare that dequeue "safe" or "unsafe" if that process is or isn't in the active process of dequeuing an element. If a process will declare that message safe, it sends a message confirming that to the process that invoked the dequeue, and if it will declare the message unsafe, it sends a message stating that to all processes in the system. Both safe and unsafe messages will be marked with the invoking process, the responding process, and the invoking dequeue vector clock.

Upon hearing about a dequeue request, which are sent globally, a process will instantiate a Confirmation List in its local memory, indexed by the timestamp of the invoking processes dequeue. For the dequeue invoking process, the confirmation list will fill by receiving messages from the other processes in the system with a corresponding timestamp. A safe message will be marked as a 1 in the corresponding index of the process in the Confirmation List and an unsafe will be marked as a 2. Once the Confirmation List has no undefined indices, the number of 2's within the list will be counted, and the queue will be accessed at that index, and the element removed.

For processes that are not the invoking process, only the unsafe messages are received, and marked as 2 in the local Confirmation Lists. To fill the rest of the list, messages with timestamps strictly greater than the invoking timestamp will be treated as implicit "safe" messages, as there cannot be an unsafe message that has not been received from that process. Thus, with the same number of unsafe messages, the non-invoking processes will naturally come to the same conclusion and remove the same element as the invoking processes. Confirmation lists, like enqueue requests are sorted by timestamp order, as when they are created, the invoking dequeue timestamp is included. The general structure of a of conf list is as follows [[Flags for responses from a given process][Invoking Process ID][Timestamp of invocation]]

3.2 Algorithm

3.3 Correctness

3.4 Complexity

4 Asynchronous Out-of-Order Queues

4.1 Description

4.2 Algorithm

4.3 Correctness

4.4 Complexity

5 Conclusion

■ **Algorithm 1** Code for each process p_i to implement a Queue with out-of-order k -relaxed *Dequeue*, where $k \geq n$ and $l = \lceil k/n \rceil$

```

1: function ENQUEUE( $val$ )
2:    $EnqCount = 0$ 
3:    $updateTS(v_i)$ 
4:    $enq\_timestamp = v_i$ 
5:   send ( $EnqReq, val, i, enq\_timestamp$ ) to all processes
6: end function
7: function RECEIVE( $EnqReq, val, j, enq\_timestamp$ ) from  $p_j$ 
8:    $updateTS(v_i, v_j)$ 
9:   if  $enq\_timestamp$  not in Pending_Enqueues then
10:     $Pending\_Enqueues.insertByTS(enq\_timestamp, val)$ 
11:   end if
12:   send ( $EnqAck, i$ ) to  $p_j$ 
13: end function
14: function RECEIVE( $EnqAck$  from  $p_j$ )
15:    $EnqCount++ = 1$ 
16:   if  $EnqCount == n$  then
17:     if  $localQueue.size < k$  then
18:       send ( $EnqConfirm, enq\_timestamp$ ) to all processes
19:     end if
20:   end if
21:   return  $EnqResponse$ 
22: end function
23: function RECEIVE( $EnqConfirm, enq\_timestamp$  from  $p_j$ )
24:    $localQueue.insertByTS(Pending\_Enqueues.getByTS(enq\_timestamp))$ 
25:   if  $clean == true$  and  $localQueue.size() \leq k$  then  $\triangleright$  localQueues agree by this point
26:     let  $procNum = (localQueue.size() - 1 \bmod n)$ 
27:      $localQueue.label(p_{procNum}, localQueue.tail)$   $\triangleright$  I may have mangled this line
28:   end if
29: end function

```

Algorithm 2 Continued, part 2

```

1: function DEQUEUE
2:    $v_i + = 1$ 
3:   let  $Deq_{ts} = v_i$ 
4:   if  $localQueue.peekByLabel(p_i) \neq \perp$  then           ▷ Check that I didn't change this
5:     let  $ret = localQueue.deqByLabel(p_i)$ 
6:     send ( $Deq_f, ret, Deq_{ts}$ ) to all processes
7:   else
8:     send ( $Deq_s, null, Deq_{ts}$ ) to all processes
9:   end if
10: end function
11: function RECEIVE( $deq_f, val, Deq_{ts}$ ) from  $p_j$ )
12:   if  $j \neq i$  then  $localQueue.remove(val)$ 
13:   end if
14: end function
15: function RECEIVE( $deq_s, val, Deq_{ts}$  from  $p_j$ )
16:    $UpdateTs(v_i, Deq_{ts})$ 
17:   if  $Deq_{ts}$  is not in  $PendingDequeues$  then
18:      $PendingDequeues.insertByTs(createList(Deq_{ts}, p_{invoker}))$            ▷ Check line
19:   end if
20:   let  $p_{invoker} = p_j$  ▷ This doesn't make sense to me? What are you doing on this line?
21:   if  $Deq_{ts} \neq 0$  and  $Deq_{ts} < v_i$  then
22:     send ( $Unsafe, Deq_{ts}, i, p_{invoker}$ ) to all processes
23:   else
24:     send ( $Safe, Deq_{ts}, i, p_{invoker}$ ) to all processes
25:   end if
26: end function

```

Algorithm 3 Continued, part 3

```

1: function RECEIVE(Safe/Unsafe,  $Deq_{ts}$ ,  $j$ ,  $p_{invoker}$ )
2:   if  $Deq_{ts}$  not in PendingDequeues then
3:     PendingDequeues.insertByTs(createList( $Deq_{ts}$ ,  $p_{invoker}$ ))
4:   end if
5:   for confirmationList in PendingDequeues do
6:     if confirmationList.ts ==  $Deq_{ts}$  then
7:       if Unsafe then
8:         response = 2
9:       else
10:        response = 1
11:      end if
12:      confirmationList.list[j] = response
13:    end if
14:    propagateEarlierResponses(PendingDequeues)
15:  end for
16:  for (index, confirmationList) in PendingDequeues do
17:    if not confirmationList.contains(0) and not confirmationList.handled then
18:      pos = 0
19:      for response in confirmationList.list do
20:        if response == 2 then
21:          pos++ = 1
22:        end if
23:      end for
24:      confirmationList.handled = True
25:      updateUnsafes(Lists, index)
26:      ret = localQueue.deqByIndex(pos)
27:      labelElements( $p_{invoker}$ )
28:      if  $i == p_{invoker}$  then
29:        return ret
30:      end if
31:    end if
32:  end for
33: end function

```

▷ Not sure I left the nesting right on these.