

Team name:	Hyperion (Brisbane Boys' Co
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#	Component	Part name
1	Custom made Omni-wheels	Wheel Frame (ABS print filament, 9.3 grams)
2		Silicone-coated steel rollers (custom made)
3	Robot Frame (custom made)	Aluminium-6061 plates (mid and base plates) (935g)
4		3D printed components (PLA+ print filament, 186g)
5		Various fasteners (nuts, screws, etc.)
6		Various aluminium standoffs (M3, 10mm to 50mm)
7	Mirror System (custom made)	Reflective mirror foil
8		Acrylic tube (65mm length, Ø55)
9	Camera	Open MV Cam H7 Plus
10	Battery	Turnigy 11.1V 1300mAh 3S 45-90C Lipo Pack
11	Drive Motors	DCX19 9V Maxon Motor (second hand)
12	Microcontroller	Teensy 4.1
13	Assorted Wires	22 AWG Wire, jumper wires, FFC
14	Switches	Rocker Switch
15	Bluetooth Module	Bluetooth Module (HC-05)
16	Compass	9-DOF Absolute Orientation IMU BNO055 AHRS
17	Custom made Main PCB with Electrical Components	Main PCB board
18		All Electrical Components for Main PCB
19	Custom made Light Sensor PCB with Electrical Components	Light Sensor PCB Board
20		All Electrical Components for Light Sensor PCB
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Team name:	Hyperion (Brisbane Boys' College)
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#	Name	Software's Tool/Library	Description
1	Visual Studio Code	Software Tool	Used for developing the software on the ro
2	Platformio.io	Software Tool	Used as a compiler for the robot to upload
3	AdafruitBNO055	Library	Used for reading the compass
4	Adafruit Sensor	Library	Used for reading the compass
5	PID	Library	Used for tuning movement and direction ba
6	Timer	Library	Used to create timer based on instances in
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