molsim tutorial

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1   Introduction

molsim is a GNU Octave/Matlab toolbox for molecular dynamics simulation library. molsim supports simulations of

- standard Lennard-Jones systems,

- molecular systems with bond, angle, and torsion potentials,

- confined flow systems, eg., Couette and Poiseuille flows,

- charged systems using shifted force and Wolf methods,

- dissipative particle dynamics systems,

- and more . . .

The package also supports a series of run-time sampling functionalities.

molsim is basically a wrapper for the seplib library, which is a light-weight flexible molecular dynamics simulation library written in ISO-C99. The library is CPU-based and offers shared memory parallisation; this parallisaton is supported by the molsim package. The algorithms used in seplib is based on the books by Allen & Tildesley, Rapaport, Frenkel & Smith, and R. Sadus, see Ref. [**?**].

In this text

```
>>
```

symbolises the GNU Octave/Matlab command prompt. This

```
$
```

symbolises the shell prompt.

Example scripts to simulate different systems can be found under the package tests directory.

2 Installation

2.1 GNU Octave

GNU Octave's package manager offers a very easy installation. From

`https://github.com/jesperschmidthansen/molsim/`

download and save the current release `molsim-<version>.tar.gz` in a directory of your choice. Start GNU Octave and if needed change directory to the directory where the file is saved.
Then type

```
>> pkg install molsim-<version>.tar.gz
```

to install the package. Check contact by

```
>> molsim('hello')
Hello.
```

In case this fails, check the path where molsim is install by

```
>> pkg list molsim
```

If the path is not in your GNU Octave search path add this using the `addpath` command.

2.2 Matlab

From

`https://github.com/jesperschmidthansen/seplib/`

download and save the current release `seplib-<version>.tar.gz` in a directory of your choice. Unpack, configure and build the library

```
$ tar zxvf seplib-<version>.tar.gz
$ cd seplib
$ ./configure
$ make
$ cd octave
```

To build the mex-file enter Matlab

```
$ matlab -nodesktop
```

Then build the

```
>> buildmex
```

Depending on the system this will build a molsim.mex¡archtype¿ file. You can copy this file to a directory in your Matlab search path.

3   First quick example: The Lennard-Jones liquid

In general, the `molsim` interface is on the form

```
molsim(<action>, <specifier>, <arguments>);
```

where the action can be any particular action the user wishes to perform, for example, `get`, `calcforce`, `load`, and so on. The action is further specified by the second argumen; say `lj` specifies that action `calcforce` should apply the pair-wise Lennard-Jones force. The specifier arguments are given as the final input.

Listing 1 shows the simplest script simulating a standard Lennard-Jones (LJ) system in the micro-canonical ensemble where number of particles, volume, and total energy is conserved.

Listing 1

```
% Specify the LJ paramters
cutoff = 2.5; epsilon = 1.0; sigma = 1.0; aw=1.0;

% Set init. position and velocities 10x10x10 particles
% in box with lengths 12x12x12. Velocities set to default.
% Configuration stored in start.xyz.
molsim('set', 'lattice', [10 10 10], [12 12 12]);

% Load the configuration file
molsim('load', 'xyz', 'start.xyz');

% Main mol. simulation loop - 10 thousand time steps
for n=1:10000
```

```
  % Reset everything
  molsim('reset');

  % Calculate force between particles of type A (default type)
  molsim('calcforce', 'lj', 'AA', cutoff, sigma, epsilon, aw);

  % Integrate forward in time - use leapfrog alogrithm
  molsim('integrate', 'leapfrog');

end

% Free memory allocated
molsim('clear');
```

—

In Listing 1 information is printed or saved. Inside the main loop you can add the command

```
if rem(n,100)==0
  molsim('print');
end
```

to print current iteration number, potential energy per particle, kinetic energy per particle, total energy per particle, kinetic temperature, and total momentum to screen every 100 time step.

Information can also be stored into variables for further analysis. For example, to get the system energies and pressure

```
[ekin, epot] = molsim('get', 'energies');
press = molsim('get', 'pressure');
```

and particle positions and velocities

```
x = molsim('get', 'positions');
v = molsim('get', 'velocities');
```

3.1   NVT and NPT simulations

Often you will not perform simulations in the microcanonical ensemble, but under a desired temperature and/or pressure. One way to achieve this with molsim is to use simple relaxation algorithms. To simulate at temperature, say 2.2, you call the action 'thermostate' with specifier 'relax' after the integration step

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```
molsim('thermostate', 'relax', 2.2, 0.01);
```

The last argument is the relaxation parameter; the higher value the faster relaxation. Notice that too large values makes the system unrealistically stiff. The best value is optimed via trail-and-error.

To simulate at pressure, say 0.9, you call the action 'barostate' after the integration step,

```
molsim('barostate', 'relax', 0.9, 0.01);
```

The choice of relaxation parameter is again a matter of the system. The barostate works by changing the system box length in the z-direction only (an-isotropic scaling); this is practical when doing sampling as two directions are fixed. You can use the barostate and the thermostate relaxation actions in the same simulation mimicking an NPT system.

4   The molsim force field

molsim supports simulations of confined, charged, and molecular systems. In general, the interaction molsim force field is defined from the potential functional form

$$U(\mathbf{r}_i, r_{ij}, \ldots) = U_{\text{lattice}} + U_{\text{vWaals}} + U_{\text{coloumb}} + U_{\text{bonds}} + U_{\text{angles}} + U_{\text{torsion}} \quad (1)$$

The first term allows for a simulation of a fictitious fixed crystal arrangement, where the particles/atoms are tethered around a pre-set lattice site. The potential function is a harmonic spring type

$$U_{\text{lattice}} = \sum_{\text{sites}} \frac{1}{2} k_0 (\mathbf{r}_i - \mathbf{r}_0)^2 \quad (2)$$

where k_0 is the spring constant, $\mathbf{r}_i$ is the position of particle/atom i, and $\mathbf{r}_0$ is the lattice site. The default lattice site positions are the initial particle positions.

The short ranged van der Waals pair interaction is given via the standard Lennard-Jones potential

$$U_{\text{vWaals}} = \sum_{i,j \text{ pairs}} 4\epsilon \left[\left(\frac{\sigma}{r_{ij}} \right)^{12} - a_w \left(\frac{\sigma}{r_{ij}} \right)^6 \right]. \quad (3)$$

Here r_{ij} is the particle distance, ϵ and σ define the characteristic energy and length scales. The parameter a_w determines the weight of the attractive second term in the potential function.

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The Coulomb potential is

$$U_{\text{coloumb}} = \sum_{i,j \text{ pairs}} \frac{q_i q_j}{r_{ij}} . \tag{4}$$

This long ranged interaction is evaluated using approximative shifted-force or Wolf methods; this can be specified. These two implementations do not apply to confined systems.

Particle bonds are model via the harmonic spring potential

$$U_{\text{bonds}} = \sum_{\text{bonds}} \frac{1}{2} k_s (r_{ij} - l_0)^2 \tag{5}$$

k_s is the spring constant and l_0 is the zero force bond length. Note, currently molsim does not support rigid bonds.

The angle potential is the cosine squared potential

$$U_{\text{angles}} = \frac{1}{2} \sum_{\text{angles}} k_\theta (\cos(\theta) - \cos(\theta_0))^2 , \tag{6}$$

where k_θ is the force amplitude, and the zero-force angle θ_0. See Fig. 1 for the angle definition.
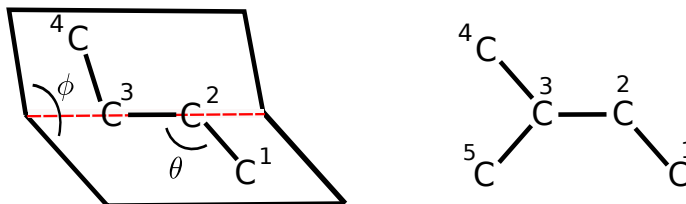

Figure 1: Illustration of the angle and torsion angle.

Finally, the torsion angle potential is the Ryckaert-Belleman potential

$$U_{\text{dihedral}} = \sum_{\text{dihedrals}} \sum_{n=0}^{5} c_n \cos^n(\pi - \phi) . \tag{7}$$

Here c_n are the six Ryckaert-Belleman coefficients, and ϕ is the torsion angle, see Fig. 1. Two illustrative examples are when $c_n = 0$ except for $n = 1$:

1. If $c_1 > 0$ then the minimum energy torsion angle is $\phi = 0$; this is illustrated in the right-hand figure in Fig. 1 with torsion angle defined by the 1-2-3-5 bonds. Useful for closed molecular ring structures.

2. If $c_1 < 0$ then the minimum torsion angle is $\phi = \pi$; this is illustrated in the right-hand figure in Fig. 1 with torsion defined by the 1-2-3-4 bonds. Useful for branched molecular structures.

Below a more complex example is given.

Importantly, you can have different types of particles with different charges, different bonds, angles, and torsion angles, all determined from the interaction parameters. It is thus possible to simulate mixtures, highly complex molecules, etc.

5 Molecular systems: Toluene

This example shows how to setup a simulation of model liquid toluene. The model of the molecule is a united atomic unit (UAU) model. This means that each carbon group is represented by a single Lennard-Jones particle, thus, the toluene molecule is composed of seven Lennard-Jones particles, six forming the phenyl ring structure (index 2-7) and one representing the -CH$_3$ group (index 1), see Fig. 2.
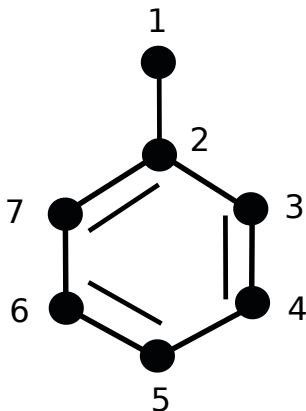

Figure 2: United atomic unit representation of toluene.

The intra-molecular interactions are given through bond, angle, and torsion angle potentials; Lennard-Jones interactions between carbon groups in same molecule are excluded. The model is further simplifed by using only two bonds and one angle interaction. There are two different torsion angles, eg., 1-2-3-4 form one type of torsion angle, $\phi = \pi$, whereas 7-2-3-4 is an example of the other torsion angle with $\phi = 0$. We define the molecular model in two files; one with extension .xyz giving UAU positions for

the molecule and one with extension `.top` defining bonds and angles in the molecule. You can find examples of these two files for different molecules under the `resources` directory. To setup the entire system (i.e. the ensemble of molecules) we copy the single molecule `.xyz` and `.top` to the current directory and use the `set` action; for example to simulate 500 molecules

```
>> molsim('set', 'molconfig', 'toluene.xyz', 'toluene.top', ...
   500, 0.05, 42)
```

The two last arguments are the molecular number density (keep very low initially and compress the system afterwards), and a seed for the random number generator. This generates a system `start.xyz` file and `start.top` file.

We now only need the parameter values for the interaction potentials and we will simply take what is available in the literature and convert them into MD reduced units. Listing 2 shows the resulting script

Listing 2

```
% Simulation parameters
temp0 = 4.0; dens0 = 1.95; dt  = 0.001; nloops = 200000;

% Intra-molecular parameters
bondlength_0 = 0.4; bondlength_1 = 0.38; springconstant = 48910;
bondangle = 2.09; angleconstant = 1173;

torsionparam_0 = [0.0, 133.0, 0.0 0.0 0.0];
torsionparam_1 = [0.0, -133.0, 0.0 0.0 0.0];

% Load positions, set temp, remove intra-molecular pair-interaction etc
molsim('load', 'xyz', 'start.xyz');
molsim('load', 'top', 'start.top');

molsim('set','timestep', dt);
molsim('set', 'temperature', temp0);
molsim('set', 'exclusion', 'molecule');

% Main loop
for n=1:nloops
  molsim('reset')
```

```
    molsim('calcforce', 'lj', 'CC', 2.5, 1.0, 1.0, 1.0);

    molsim('calcforce', 'bond', 0, bondlength_0, springconstant);
    molsim('calcforce', 'bond', 1, bondlength_1, springconstant);

    molsim('calcforce', 'angle', 0, bondangle, angleconstant);

    molsim('calcforce', 'torsion', 0, torsionparam_0);
    molsim('calcforce', 'torsion', 1, torsionparam_1);

    molsim('thermostate', 'nosehoover', 'C', temp0, 10.0);
    molsim('integrate', 'leapfrog');

    molsim('compress', dens0);

end
```

—

Note, the bond and angle types are specified through the third argument.

6 Sampling

The user can access the system configuration through the `get` action and from this perform data analysis via GNU Octave's or Matlab's built-in tools. molsim also offers some runtime data sampling. The different samplers can be initialised before the main loop using the `sample` action

```
molsim('sample', <sample specifier>, <arguments>);
```

For example, to sample the stress autocorrelation function with 200 sample points and over a sample time span window of 5.0 we write

```
molsim('sample', 'sacf', 200, 5.0);
```

The actual sampling is carried out by the specifier `do`, and in the main loop there must be the call

```
molsim('sample', 'do');
```

Typically this call is done just after the integration call. Check the reference sheet for the list of available samplers.

7 The two parallisation paradigms

molsim offers two types of sheared memory parallisation methods, namely,

- Loop parallisation n in force calculations

- Task-block parallisation

To use the first method simply use the `set` action

```
molsim('set', 'omp', <nthreads>);
```

where `nthreads` is the number of threads you will use. The call is placed anywhere before the main loop. Be aware that depending on your hardware and the particular system the parallelisation efficiency quickly drop as function of number of threads. Fig. **??** shows an example of a benchmark for a simple Lennard-Jones system.

Action	Specifier	Arguments	Output
load	`xyz`	file name	
	`top`	file name	
save		1: type names	
		2: file name	
set	`timestep`	time step (0.005)	
	`temperature`	temperature (1.0)	
	`cutoff`	Max. cut-off (2.5)	
	`omp`	No. of threads	
	`exclusion`	'bonded' or 'molecule'	
	`temperaturerelax`	relaxation time (0.01)	
	`compressionfactor`	compress factor	
	`types`	particles types (vector string)	
	`skin`	buffer-skin neighblist	
	`charges`	atom charges (vector)	
	`lattice`	1: array N_x, N_y, N_z	
		2: array L_x, L_y, L_z	