Recap

Direct Execution

Kernel/User modes => Restrict Direct Execution

Context switch needed for mode switch

System call => Restricted User Process can attain its functional goals

Timer Interrupt => OS can regain control periodically and can switch processes

Context switch needed for process switch

Xv6 code flows

Kernel from beginning: entry.S

- -> start() in start.c
- -> main() in main.c
- -> userinit() to start the first user process (user/init.c)
- -> run scheduler() loop (in proc.c)

Handling trap:uservec in trampoline.S

- -> usertrap() in trap.c
- -> (for system call) syscall() in syscall.c -> ...->...
- -> usertrapret() in trap.c
- -> userret in trampoline.S

L4: Scheduling

(Based on Chapter 7)

Scheduling

The workload of a system consists of many processes with often different and conflicting requirements and user expectations

- Some processes just want a lot of CPU time (CPU bound)
- Others require a quick response to I/O (I/O bound)
- Users expect applications to be responsive (Interactive)

What **scheduling policies** will best meet user expectations?

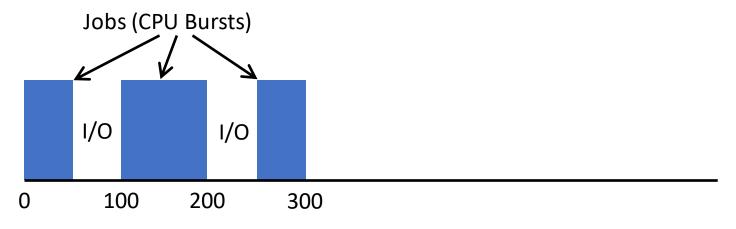
Jobs

Real processes alternate between needing CPU time and waiting for I/O

We call time when process needs CPU time a job (or CPU burst)

The time when process needs to wait is an I/O burst

Example: An OS that has only a single process looks like this



Jobs With Time-Sharing

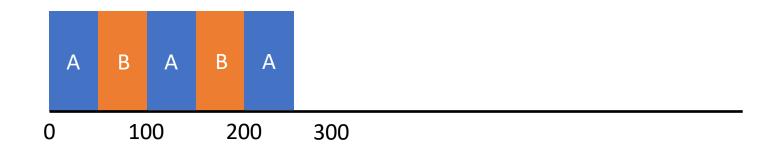
A scheduler may not let a process complete its job in one run on the CPU

On time-sharing systems, the scheduler may *preempt* a process, swapping it with a different process before it has completed its job

Example:

Process A has a CPU burst of 150ms

Process B has a CPU burst of 100ms



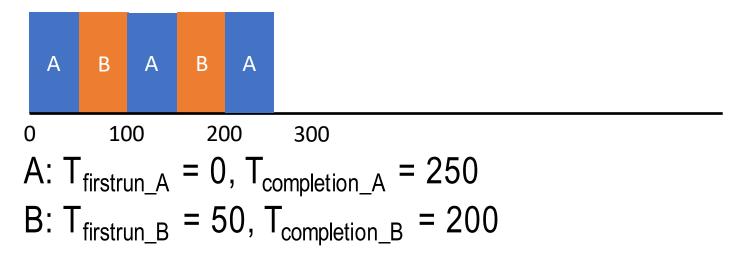
Metrics

T_{arrival} - time when job fist enters ready state

T_{completion} - time when job finishes

T_{firstrun} - time when job starts its first run on the CPU

Example: Suppose jobs A and B both arrive at time 0 and execute as shown

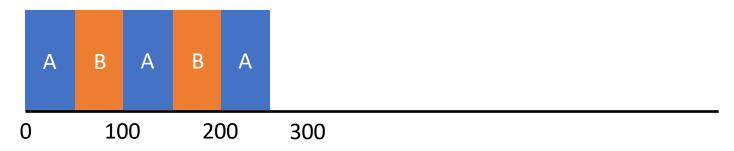


Metric: Turnaround Time

The time to complete a job

$$T_{turnaround} = T_{completion} - T_{arrival}$$

Example: Suppose jobs A and B both arrive at time 0 and execute as shown



A: $T_{turnaround_A} = 250 - 0 = 250$

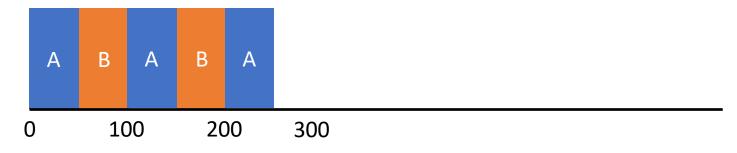
B: $T_{turnaround B} = 200 - 0 = 200$

Metric: Response Time

The time to first execution on CPU

$$T_{response} = T_{firstrun} - T_{arrival}$$

Example: Suppose jobs A and B both arrive at time 0 and execute as shown



A: $T_{response_A} = 0 - 0 = 0$

B: $T_{response_B} = 50 - 0 = 50$

Why Different Metrics?

Turnaround time tells time to complete jobs, good for *CPU bound* processes, where getting enough CPU runtime is the main concern

Response time tells how long to respond to I/O, good for I/O bound (interactive) processes, which have short CPU bursts and frequent I/O

There are other metrics, later we will look at *fairness*

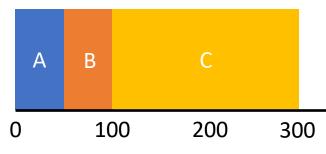
Policy: FIFO

Implementation: FIFO queue

Preemption: None

Advantage: Easy to implement

	T _{arrival}	Runtime
Α	0	50
В	0	50
С	0	200



$$T_{average_turnaround} = (50 + 100 + 300) / 3 = 150$$

 $T_{average_response} = (0 + 50 + 100) / 3 = 50$

$$T_{\text{average response}} = (0 + 50 + 100) / 3 = 50$$

Problem with FIFO

Example: Jobs arrive in the order A, B and C

	T _{arrival}	Runtime
Α	0	200
В	0	50
С	0	50



$$T_{average_turnaround} = (200 + 250 + 300) / 3 = 250$$

$$T_{average_response} = (0 + 200 + 250) / 3 = 150$$

Performance depends on arrival order, large upfront CPU burst can hurt turnaround and response time

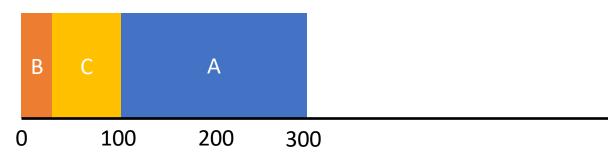
Policy: Shortest Job First (SJF)

Implementation: Priority queue sorted by job length (shortest first)

Preemption: None

Advantage: Optimal average turnaround time when all jobs arrive at same time

	T _{arrival}	Runtime
Α	0	200
В	0	25
С	0	75



$$T_{average_turnaround} = (25 + 100 + 300) / 3 = 142$$

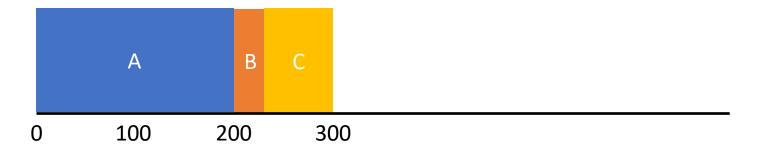
 $T_{average_response} = (0 + 25 + 100) / 3 = 42$

$$T_{\text{average response}} = (0 + 25 + 100) / 3 = 42$$

Problem with SJF

What happens if short jobs arrive after starting a long job? Back to high turnaround and response times Example:

	T _{arrival}	Runtime
Α	0	200
В	5	25
С	10	75



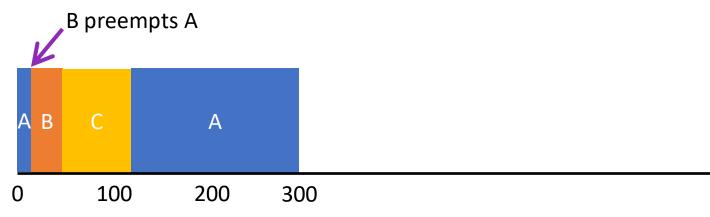
$$T_{average_turnaround} = ((200 - 0) + (225 - 5) + (300 - 10)) / 3 = 210$$

 $T_{average_response} = ((0 - 0) + (200 - 5) + (225 - 10)) / 3 = 136.7$

Policy: Shortest Time-to-Completion First (STCF)

Implementation: Priority queue sorted by time to completion (shortest first) Preemption: If new job arrives with a shorter time to completion, it preempts Advantage: Short jobs don't need to wait for a long job to complete

	T _{arrival}	Runtime
Α	0	200
В	5	25
С	10	75



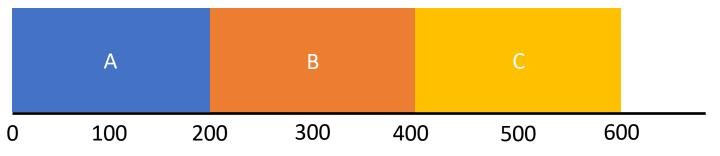
$$T_{average_turnaround} = ((300-0) + (30-5) + (105-10)) / 3 = 140$$

 $T_{average_response} = (0 + 0 + (30-10)) / 3 = 6.67$

Problem with STCF

Preemption gives STCF better response time in some cases, but there are still cases where response time can be poor

	T _{arrival}	Runtime
Α	0	200
В	0	200
С	0	200



$$T_{average_turnaround} = (200 + 400 + 600) / 3 = 400$$

$$T_{average_response} = (0 + 200 + 400) / 3 = 200$$

Policy: Round Robin (RR)

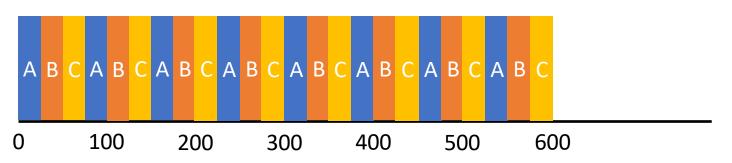
Implementation: FIFO queue

Preemption: Job on CPU gets *time-slice*, preempt when time expired

Advantage: Low response time

Example: Jobs arrive in the order A, B and C; time-slice is 25

	T _{arrival}	Runtime
Α	0	200
В	0	200
С	0	200



$$T_{average_turnaround} = (550 + 575 + 600) / 3 = 575$$

 $T_{average_response} = (0 + 25 + 50) / 3 = 25$

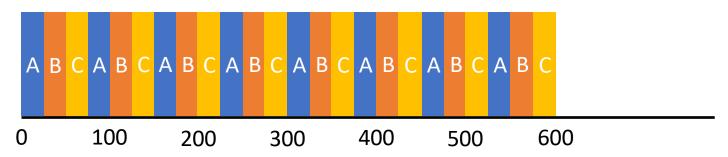
Pro and Con of RR

Pro: RR has great response time with guarenteed upper bound worst_case_response_time = time_slice x (num_jobs - 1)

Con: Bad average turnaround time, frequent context switches reduce CPU efficiency

Example: Jobs arrive in the order A, B and C; time-slice is 25

	T _{arrival}	Runtime
Α	0	200
В	0	200
С	0	200



$$T_{average_turnaround} = (550 + 575 + 600) / 3 = 575$$

 $T_{worst_case_response} = 25 \times (3 - 1) = 50$

$$T_{\text{worst_case_response}} = 25 \text{ x } (3-1) = 50$$

Another Problem with SJF and STCF: Oracle

Scheduler doesn't know how long it will take for a job to complete

SJF and STCF require an *oracle*, the ability to see into the future!

How can we get the benefits of STCF in a real system?