## Notes for MAT1341A Fall 2023 Part II

Chapter 11 & 12 - Solving systems of linear equations

A linear equation is an equation of the from

$$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$$

Here,  $a_i$  and b are scalars (real numbers),  $x_i$  are **unknowns** or **variables** or **in-determinants**.

$$2x + 3y = 1$$

this is a linear equation with unknowns.

A linear system is a collection of linear equations.

$$x_1 - x_2 + x_3 = 4 \qquad (1)$$

$$2x_2 - x_3 = 1 \qquad (2)$$

is a linear system of \_\_\_\_\_ equations and \_\_\_\_ unknowns.

A **solution** to a linear system is a solution to **all** equations of the system simultaneously.

Notice that, (4,0,0) is a solution to equation (1), but not (2), so this is not a solution to the system.

**Definition** (11.1.2). The *general solution* to a linear system is the set of all solutions.

**Definition** (11.1.6). A linear system is *consistent* if there exists at last one solution. Otherwise, the system is *inconsistent*.

[E.g.] Determine if the following system is consistent.

$$\begin{aligned} x+y &= 1 \\ y+z &= 2 \\ x+2y+z &= -1 \end{aligned}$$

**Definition** (11.1.7). A linear system is *homogeneous* if all the constant terms are 0. Otherwise, the system is *inhomogeneous*.

[E.g.] Determine if the following system is homogeneous.

$$x + 2y = 0$$

$$2y + z = 0$$

**Fact.** Homogeneous linear systems are always consistent.

**Theorem** (11.1.9). If a linear system is consistent, then it admits either

- a unique solution
- infinitely many solutions

We will see why this is true by learning how to solve linear systems systematically. The method is called **Gaussian elimination** (or **elementary row operations**).

We first put the coefficients of a linear system in **an augmented matrix**, which is a rectangular grid that looks like this:

$$2x + y = 3$$

$$x - y = 5 \qquad \boxed{}$$

We can carry out the following operations on an augmented matrix:

- 1. Add a multiple of one row to another.
- 2. Exchange two rows.
- 3. Multiply a row by a nonzero scalar.

[E.g.] Perform the elementary row operations to the following augmented matrix and find the solution.

$$\left[\begin{array}{ccc|c}
1 & -2 & 1 & 0 \\
2 & -1 & 1 & 2 \\
1 & 0 & -5 & -4
\end{array}\right]$$

**Definition** (11.3.1). A matrix is in row echelon form or *REF* if

- 1. All zero rows (if any) are at the bottom
- 2. The first nonzero entry in each row is a 1 (called a leading one or a pivot).
- 3. Each leading 1 is to the right of the leading 1s in the rows above.

A matrix is in reduced row echelon form or RREF if it is in REF and pivot is the only nonzero entry in its column.

[E.g.] Determine if the following matrices are in REF. How about RREF?

$$\left[\begin{array}{cc|cc} 2 & 0 & 2 & 3 \\ 0 & 1 & 1 & 1 \end{array}\right]$$

$$\left[ \begin{array}{cc|c}
1 & 2 & 3 \\
0 & 1 & 8 \\
0 & 0 & 0
\end{array} \right]$$

$$\begin{bmatrix}
2 & 0 & 2 & | & 3 \\
0 & 1 & 1 & | & 1
\end{bmatrix} \qquad \begin{bmatrix}
1 & 2 & | & 3 \\
0 & 1 & | & 8 \\
0 & 0 & | & 0
\end{bmatrix} \qquad \begin{bmatrix}
1 & 0 & 0 & | & 1 \\
0 & 1 & 0 & | & 1 \\
0 & 0 & 1 & | & 1
\end{bmatrix}$$

**Theorem** (12.0.4). Any matrix can be turned into RREF via elementary row operations. Furthermore, the RREF we get is *unique*.

[E.g.] Find the general solution to the linear system with following augmented matrix.

$$\left[ 
\begin{array}{ccc|c}
1 & -3 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0
\end{array}
\right]$$

Whenever we have a system given by augmented matrix in RREF and there is a variable that gives a column that contains no leading 1, then this variable will give us a parameter in the general solution. In particular, this gives infinitely many solutions.

[E.g.] Show that the following system is inconsistent.

$$\left[ 
\begin{array}{ccc|c}
1 & -3 & 0 & 0 \\
0 & 0 & 1 & 0 \\
1 & -3 & 2 & 0
\end{array}
\right]$$

[E.g.] Solve the following linear system.

$$\left[\begin{array}{ccc|ccc|c}
0 & 1 & 0 & -2 & 6 \\
0 & 0 & 0 & 1 & -4 \\
1 & 2 & 3 & 0 & -3 \\
1 & -2 & 3 & 0 & 5
\end{array}\right]$$

**Definition** (12.0.1). We say that two linear systems are *equivalent* if they have the same general solution.

**Fact.** Every matrix is row equivalent to a matrix in RREF.

**Definition** (12.0.3). Two matrices A is row equivalent to B, written  $A \sim B$  if B can be obtained from A by elementary row operations.

**Definition** (12.4.1). The rank of a matrix A, denoted rank(A), is the number of leading 1 (pivots) in any REF of A.

**Remark:** In the Gaussian Algorithm, the passage from the REF to the RREF does not change the number of leading ones.

$$B = \left[ \begin{array}{ccc|c} 1 & 0 & 3 & 0 & 1 \\ 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & 0 & 1 & -4 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Then, we have  $rank(B) = \underline{\hspace{1cm}}$ .

If we have a linear system described by an augmented matrix:

$$B = [A \mid \mathbf{b}]$$
a matrix
a column vector

What do the ranks of A and B tell us about the linear system?

We always have  $rank(B) \ge rank(A)$ .

If rank(B) > rank(A), then the system is inconsistent. For example:

$$B = \left[ \begin{array}{ccc|ccc|c} 1 & 0 & 3 & 0 & 1 \\ 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

rank(B) = rank(A) =

If rank(B) = rank(A), then the system is consistent. There are two sub-cases.

If rank(A) = # of unknowns, then we have a unique solution.

$$B = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

rank(B) = rank(A) =

If rank(A) < # of unknowns, then we have infinitely many solutions.

$$B = \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 1 \\ 0 & 1 & 0 & -2 & 1 & -2 \\ 0 & 0 & 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

rank(B) = rank(A) =

We always have  $rank(A) \le \#$  of unknowns