Numerical Methods and Optimization

Topic 1:

Introduction to Numerical Methods

Lectures 1-4:

Lecture 1 Introduction to Numerical Methods

- What are NUMERICAL METHODS?
- Why do we need them?
- Topics covered in NMO.

Reading Assignment: Pages 3-10 of textbook

Numerical Methods

Numerical Methods:

Algorithms that are used to obtain numerical solutions of a mathematical problem.

Why do we need them?

- 1. No analytical solution exists,
- 2. An analytical solution is difficult to obtain or not practical.

What do we need?

Basic Needs in the Numerical Methods:

- Practical:
 - Can be computed in a reasonable amount of time.
- Accurate:
 - Good approximate to the true value,
 - Information about the approximation error (Bounds, error order,...).

Outlines of the Course

- Number Representation
- Approximate solution of nonlinear Equations
- Solution of linear Equations (Direct methods)
- Solution of linear Equations (Iterative methods)
- Polynomial Interpolation
- Least Squares approximation
- Numerical Integration

Solution of Nonlinear Equations

Some simple equations can be solved analytically:

$$x^2 + 4x + 3 = 0$$

Analytic solution
$$roots = \frac{-4 \pm \sqrt{4^2 - 4(1)(3)}}{2(1)}$$

$$x = -1$$
 and $x = -3$

Many other equations have no analytical solution:

$$x^{9} - 2x^{2} + 5 = 0$$

$$x = e^{-x}$$
 No analytic solution

Methods for Solving Nonlinear Equations

Bisection Method

Newton-Raphson Method

Secant Method

Solution of Systems of Linear Equations

$$x_1 + x_2 = 3$$

$$x_1 + 2x_2 = 5$$

We can solve it as:

$$x_1 = 3 - x_2$$
, $3 - x_2 + 2x_2 = 5$

$$\Rightarrow x_2 = 2, x_1 = 3 - 2 = 1$$

What to do if we have

1000 equations in 1000 unknowns.

Cramer's Rule is Not Practical

Cramer's Rule can be used to solve the system:

$$x_{1} = \frac{\begin{vmatrix} 3 & 1 \\ 5 & 2 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 1, \quad x_{2} = \frac{\begin{vmatrix} 1 & 3 \\ 1 & 5 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 2$$

But Cramer's Rule is not practical for large problems.

To solve N equations with N unknowns, we need (N+1)(N-1)N! multiplications.

To solve a 30 by 30 system, 2.3×10^{35} multiplications are needed.

A super computer needs more than 10^{20} years to compute this.

Methods for Solving Systems of Linear Equations

Naive Gaussian Elimination

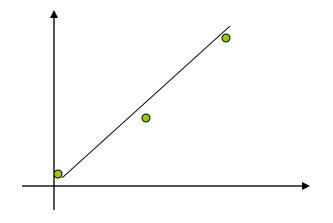
 Gaussian Elimination with Scaled Partial Pivoting

 Algorithm for Tri-diagonal Equations

Curve Fitting

Given a set of data:

X	0	1	2
y	0.5	10.3	21.3

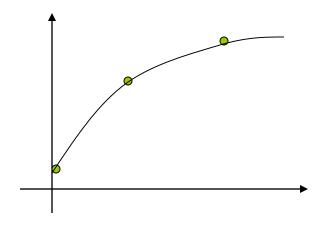


Select a curve that best fits the data. One choice is to find the curve so that the sum of the square of the error is minimized.

Polynomial Interpolation

Given a set of data:

Xi	0	1	2	
y _i	0.5	10.3	15.3	



Find a polynomial P(x) whose graph passes through all tabulated points.

$$y_i = P(x_i)$$
 if x_i is in the table

Methods for Curve Fitting

- Least Squares
 - Linear Regression
 - Nonlinear Least Squares Problems
- Interpolation
 - Newton Polynomial Interpolation
 - Lagrange Interpolation

Integration

Some functions can be integrated analytically:

$$\int_{1}^{3} x dx = \frac{1}{2} x^{2} \Big|_{1}^{3} = \frac{9}{2} - \frac{1}{2} = 4$$

But many functions have no analytical solutions:

$$\int_{0}^{a} e^{-x^2} dx = ?$$

Methods for Numerical Integration

Upper and Lower Sums

Trapezoid Method

Romberg Method

Gauss Quadrature

Summary

- Numerical Methods:
 - Algorithms that are used to obtain numerical solution of a mathematical problem.
- We need them when No analytical solution exists or it is difficult to obtain it.

Topics Covered in the Course

- Solution of Nonlinear Equations
- Solution of Linear Equations
- Curve Fitting
 - Least Squares
 - Interpolation
- Numerical Integration

Lecture 2 Number Representation and Accuracy

- Number Representation
- Normalized Floating Point Representation
- Significant Digits
- Accuracy and Precision
- Rounding and Chopping

Reading Assignment: Chapter 3

Representing Real Numbers

You are familiar with the decimal system:

$$312.45 = 3 \times 10^{2} + 1 \times 10^{1} + 2 \times 10^{0} + 4 \times 10^{-1} + 5 \times 10^{-2}$$

- □ Decimal System: Base = 10, Digits (0,1,...,9)
- Standard Representations:

Normalized Floating Point Representation

Normalized Floating Point Representation:

$$\pm \underline{d. f_1 f_2 f_3 f_4} \times 10^{\pm n}$$

sign mantissa exponent

$$d \neq 0$$
, $\pm n$: signed exponent

- Scientific Notation: Exactly one non-zero digit appears before decimal point.
- Advantage: Efficient in representing very small or very large numbers.

Binary System

□ Binary System: Base = 2, Digits {0,1}

$$\pm 1. f_1 f_2 f_3 f_4 \times 2^{\pm n}$$

sign mantissa signed exponent

$$(1.101)_2 = (1+1\times2^{-1}+0\times2^{-2}+1\times2^{-3})_{10} = (1.625)_{10}$$

Fact

Numbers that have a finite expansion in one numbering system may have an infinite expansion in another numbering system:

$$(1.1)_{10} = (1.000110011001100...)_2$$

You can never represent 1.1 exactly in binary system.

IEEE 754 Floating-Point Standard

- Single Precision (32-bit representation)
 - 1-bit Sign + 8-bit Exponent + 23-bit Fraction

```
S Exponent<sup>8</sup> Fraction<sup>23</sup>
```

- Double Precision (64-bit representation)
 - 1-bit Sign + 11-bit Exponent + 52-bit Fraction

S	Exponent ¹¹	Fraction ⁵²		
(continued)				

Significant Digits

- Significant digits are those digits that can be used with confidence.
- Single-Precision: 7 Significant Digits
 1.175494... × 10⁻³⁸ to 3.402823... × 10³⁸
- Double-Precision: 15 Significant Digits
 2.2250738... × 10⁻³⁰⁸ to 1.7976931... × 10³⁰⁸

Remarks

- Numbers that can be exactly represented are called machine numbers.
- Difference between machine numbers is not uniform
- Sum of machine numbers is not necessarily a machine number

Calculator Example

Suppose you want to compute:

3.578 * 2.139

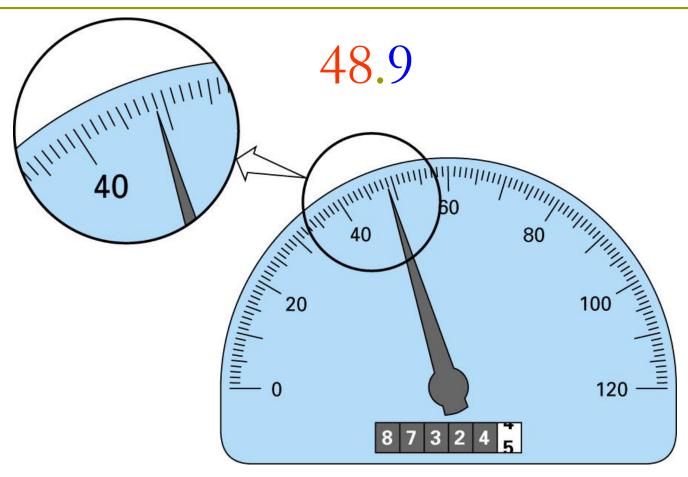
using a calculator with two-digit fractions

3.57 * 2.13 = 7.60

True answer:

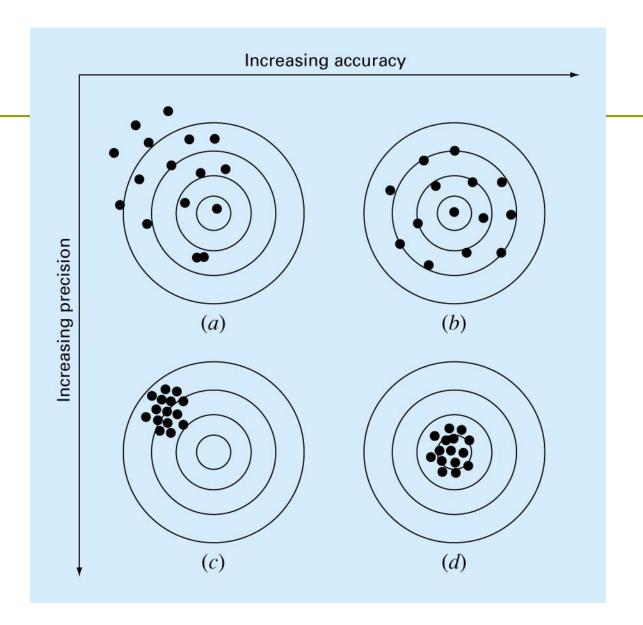
7.653342

Significant Digits - Example



Accuracy and Precision

- Accuracy is related to the closeness to the true value.
- Precision is related to the closeness to other estimated values.

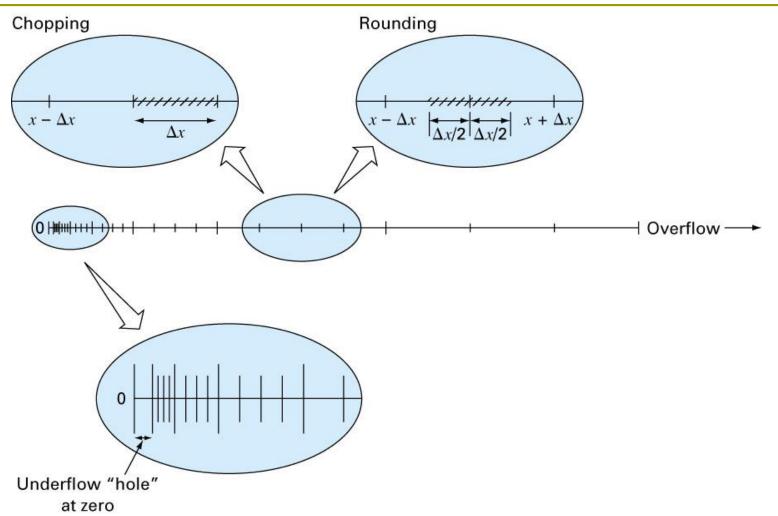


Rounding and Chopping

Rounding: Replace the number by the nearest machine number.

Chopping: Throw all extra digits.

Rounding and Chopping



Error Definitions — True Error

Can be computed if the true value is known:

Absolute True Error

$$E_t = |$$
 true value – approximation |

Absolute Percent Relative Error

$$\varepsilon_{\rm t} = \left| \frac{\text{true value - approximation}}{\text{true value}} \right| *100$$

Error Definitions — Estimated Error

When the true value is not known:

Estimated Absolute Error

$$E_a = |$$
 current estimate $-$ previous estimate $|$

Estimated Absolute Percent Relative Error

$$\varepsilon_a = \left| \frac{\text{current estimate} - \text{previous estimate}}{\text{current estimate}} \right| *100$$

Notation

We say that the estimate is correct to *n* decimal digits if:

$$| \text{Error } | \leq 10^{-n}$$

We say that the estimate is correct to *n* decimal digits **rounded** if:

$$\left| \text{Error } \right| \le \frac{1}{2} \times 10^{-n}$$

Summary

Number Representation

Numbers that have a finite expansion in one numbering system may have an infinite expansion in another numbering system.

Normalized Floating Point Representation

- Efficient in representing very small or very large numbers,
- Difference between machine numbers is not uniform,
- Representation error depends on the number of bits used in the mantissa.