

SOEN331: Introduction to Formal Methods  
for Software Engineering  
Assignment 2 on Extended Finite State Machines

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# 1 Driver-less car system formal specification

The EFSM of the driver-less car system is the tuple  $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$ , where

$$Q = \{idle, parked\ mode, manual\ mode, cruise\ mode, marked\ mode, panic\ mode\}$$

$$\Sigma_1 = \{start, cruise\ signal, switch, arrived, unforeseen, panic\ off, off\}$$

$$\Sigma_2 = \{lock, unlock, beep\}$$

$$q_0 : idle$$

$$V : destination = \{set, no\}$$

$\Lambda$ : Transition specifications

1.  $\rightarrow idle$
2.  $idle \xrightarrow{start} parkedmode$
3.  $parked\ mode \xrightarrow{off} off?$
4.  $parked\ mode \xrightarrow{cruise\ signal\ [no\ dest]} manual\ mode$
5.  $parked\ mode \xrightarrow{cruise\ signal\ [set\ dest]\ /\ beep} cruise\ mode$
6.  $manual\ mode \xrightarrow{cruise\ signal\ [set\ dest]} cruise\ mode$
7.  $cruise\ mode \xrightarrow{switch} manual\ mode$
8.  $cruise\ mode \xrightarrow{arrived} parked\ mode$
9.  $cruise\ mode \xrightarrow{unforeseen} panic\ mode$
10.  $manual\ mode \xrightarrow{stop} marked\ mode$
11.  $panic\ mode \xrightarrow{panic\ off\ /\ hazard\ off} manual\ mode$

The Manual mode is a composite state, it is the tuple  $S = (Q, \Sigma_1, \Sigma_2, q_0, \Lambda)$ , where

$$Q = \{running, fast, slower, break\ mode\}$$

$$\Sigma_1 = \{accelerate, decelerate, break\}$$

$$\Sigma_2 = \{increase\ speed, decrease\ speed, 0 - speed\}$$

$$q_0 : running$$

$\Lambda$ : Transition specifications

1.  $\rightarrow running$

2. *running*  $\xrightarrow{\text{accelerate / increase speed}}$  *faster*
3. *running*  $\xrightarrow{\text{decelerate / decrease speed}}$  *slower*
4. *running*  $\xrightarrow{\text{break / 0-speed}}$  *breakmode*
5. *breakmode*  $\xrightarrow{\text{accelerate / increase speed}}$  *running*
6. *faster*  $\xrightarrow{\text{accelerate / increase speed}}$  *faster*
7. *faster*  $\xrightarrow{\text{decelerate / decrease speed}}$  *slower*
8. *slower*  $\xrightarrow{\text{decelerate / decrease speed}}$  *slower*

The UML state diagram is shown in Figure ??.

## 2 UML state diagrams

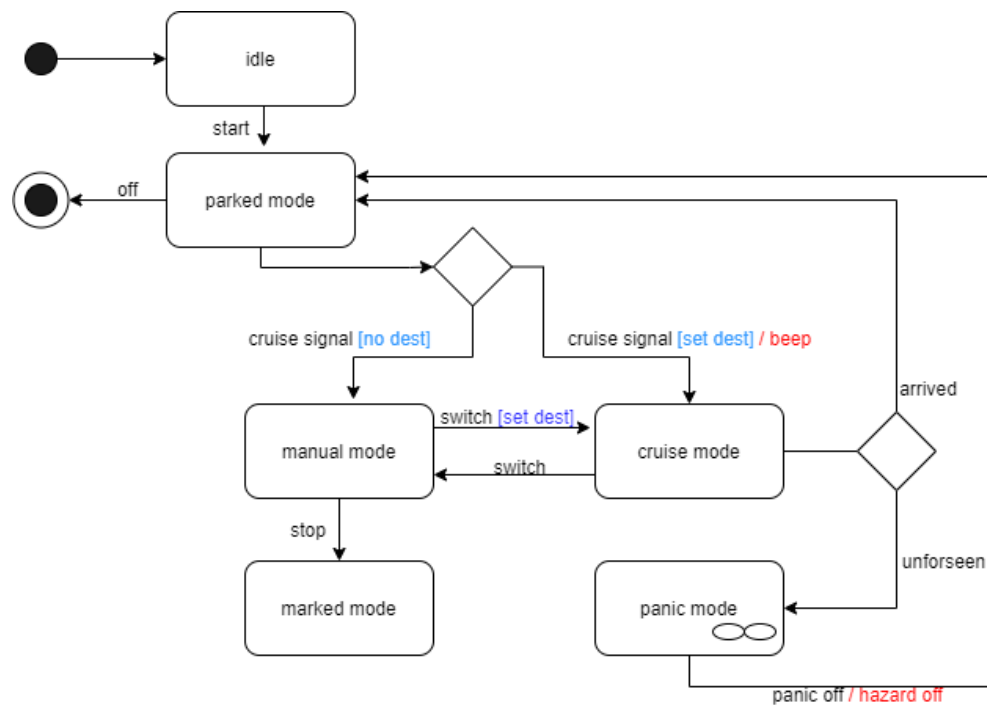


Figure 1: Main System.

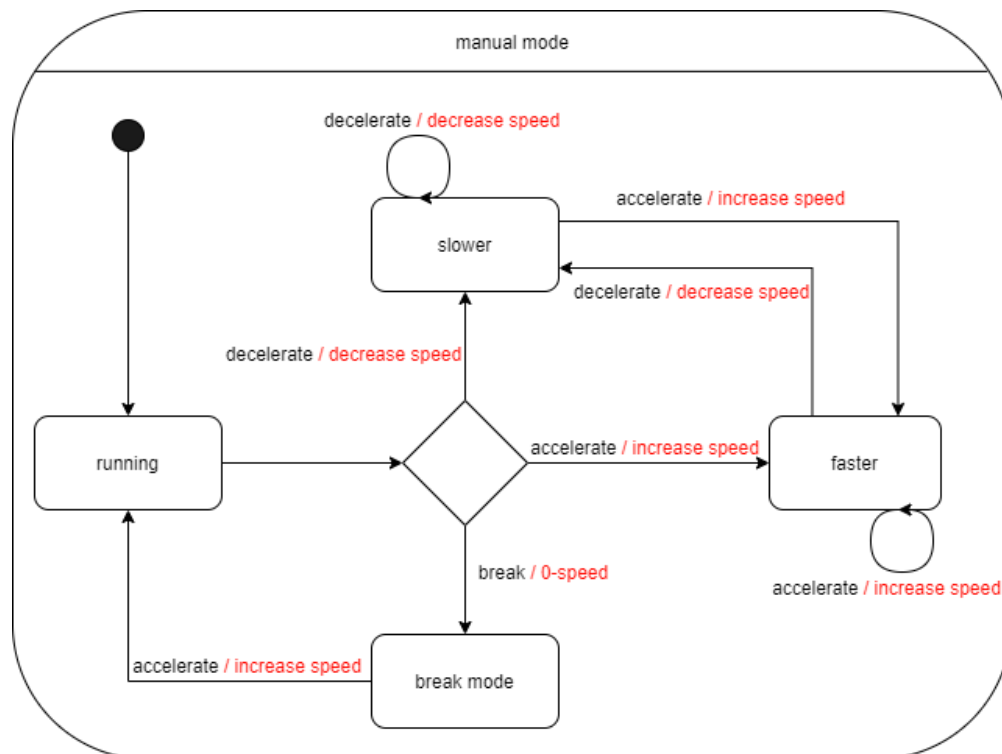


Figure 2: Manual Mode.