

### **the link of Tinkercad:**

[https://www.tinkercad.com/things/kZmsslUOjyB?sharecode=O5EO\\_ljw0UPu\\_J\\_-bhRsB6P\\_-L63lKxq-\\_k4VovPyUg](https://www.tinkercad.com/things/kZmsslUOjyB?sharecode=O5EO_ljw0UPu_J_-bhRsB6P_-L63lKxq-_k4VovPyUg)

### **Serial Communication between two Arduino:**

#### **Arduino with Pushbutton (Sender):**

```
const int buttonPin = 2; // Connect the pushbutton to digital pin 2
```

```
void setup() {  
  pinMode(buttonPin, INPUT_PULLUP);  
  Serial.begin(9600);  
}
```

```
void loop() {  
  int buttonState = digitalRead(buttonPin);  
  if (buttonState == LOW) {  
    Serial.write('1'); // Send a character '1' to indicate button press  
    delay(1000); // Delay to debounce the button  
  }  
}
```

#### **Arduino with LED (Receiver):**

```
const int ledPin = 13; // Connect the LED to digital pin 13
```

```
void setup() {  
  pinMode(ledPin, OUTPUT);  
  Serial.begin(9600);  
}
```

```
void loop() {  
  if (Serial.available() > 0) {  
    char receivedChar = Serial.read();  
    if (receivedChar == '1') {  
      digitalWrite(ledPin, HIGH);  
      delay(1000);  
      digitalWrite(ledPin, LOW);  
    }  
  }  
}
```