ns-3 Installation

- The ns-3 simulator is a discrete-event network simulator.
- ns-3 is designed as a set of libraries that can be combined together and also with other external software libraries. While some simulation platforms provide users with a single, integrated graphical user interface environment in which all tasks are carried out, ns-3 is more modular in this regard. Several external animators and data analysis and visualization tools can be used with ns-3. However, users should expect to work at the command line and with C++ and/or Python software development tools.
- Website and Documentation
 - The main web site is located at https://www.nsnam.org and provides access to basic information about the ns-3 system. Detailed documentation is available through the main web site at https://www.nsnam.org/documentation/.
- Installation page https://www.nsnam.org/wiki/Installation
- Tools
 - o VMware, https://my.vmware.com/en/web/vmware/downloads/details?downloadGroup=PLAYER-1610&productId=1039&rPId=55792
 - Ubuntu (highly compatible with ns-3) https://ubuntu.com/#download
 (Ubuntu Desktop 20.04 LTS)
 - \circ ns-3
 - Any C++/Python IDE to be used as an editor (VS Code or Eclipse)
- Ubuntu Installation into VMware, (Recommended 4GB RAM and 25GB Hard Disk)
 - o https://www.youtube.com/watch?v=9rUhGWijf9U

• ns-3 download and building:

Open a new terminal window and run the following commands (Do Not copy the \$):

\$ cd Desktop

\$ sudo apt-get update

\$ sudo apt-get upgrade

\$ sudo apt install build-essential

\$ sudo apt-get install gcc g++ python python-dev mercurial bzr gdb valgrind gsl-bin libgsl0-dev libgsl23

\$ sudo apt-get install flex bison tcpdump sqlite sqlite3 libsqlite3-dev libxml2 libxml2-dev

\$ sudo apt-get install libgtk2.0-0 libgtk2.0-dev uncrustify doxygen graphviz imagemagick texlive texlive-latex-extra texlive-xetex

\$ sudo apt-get install texinfo dia texlive texlive-latex-extra texlive-extrautils texi2html

\$ sudo apt-get install gir1.2-goocanvas-2.0 python-gi python-gi-cairo python3-gi python3-gi-cairo gir1.2-gtk-3.0 python3-pygraphviz python3-pygccxml

\$ sudo apt-get install openmpi-bin openmpi-common openmpi-doc libopenmpi-dev

\$ sudo apt-get install dpdk dpdk-dev libdpdk-dev dpdk-igb-uio-dkms

\$ sudo apt install -y python3-pip

\$ pip3 install ipython

\$ pip3 install kiwi

\$ wget https://www.nsnam.org/release/ns-allinone-3.33.tar.bz2

\$ tar xjf ns-allinone-3.33.tar.bz2

\$ cd ns-allinone-3.33

\$./build.py --enable-examples --enable-tests

```
$ cd ns-3.33
$ ./test.py or ./test.py -c core
$ ./waf -d debug --enable-examples --enable-tests configure
(recommended not required)
```

• Run first script:

- Open a new terminal window.
- Go to the tutorial folder \rightarrow \$ cd Desktop/ns-allinone-3.33/ns-3.33/examples/tutorial
- Copy the code file in scratch folder \rightarrow \$ cp first.cc ../../scratch/
- o \$ cd ../..
- o ./waf --run scratch/first
- The output should look like this:

```
samar@ubuntu:~/Desktop/ns-allinone-3.33/ns-3.33$ ./waf --run scratch/first
Waf: Entering directory `/home/samar/Desktop/ns-allinone-3.33/ns-3.33/build'
[2863/2938] Compiling scratch/first.cc
[2864/2938] Compiling scratch/subdir/scratch-simulator-subdir.cc
[2895/2938] Linking scratch/scratch-simulator.cc
[2896/2938] Linking build/scratch/scratch-simulator
[2898/2938] Linking build/scratch/scratch-simulator
[2898/2938] Linking build/scratch/first
Waf: Leaving directory `/home/samar/Desktop/ns-allinone-3.33/ns-3.33/build'
Build commands will be stored in build/compile_commands.json
'build' finished successfully (10.174s)
At time +2s client sent 1024 bytes to 10.1.1.2 port 9
At time +2.00369s server received 1024 bytes from 10.1.1.1 port 49153
At time +2.00737s client received 1024 bytes from 10.1.1.2 port 9
samar@ubuntu:~/Desktop/ns-allinone-3.33/ns-3.33$
```

• <u>netanim Installation</u>

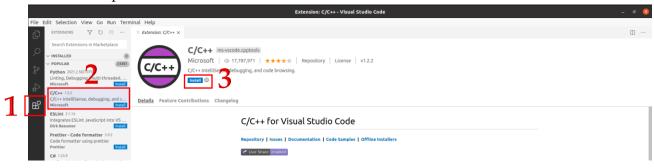
- Open a new terminal window.
- o \$ sudo apt-get install qt5-default mercurial
- o \$ cd Desktop/ns-allinone-3.33/netanim-3.108
- \$ make clean (make: *** No rule to make target 'clean'. Stop. → this output is not an error it means that the make is already clean)
- o \$ qmake NetAnim.pro
- o \$ make
- Open the NetAnim application \rightarrow \$./NetAnim

• <u>VS Code Installation</u>

○ Open Ubuntu Software \rightarrow Development \rightarrow Visual Studio Code \rightarrow Install.



o Open VS code and install C/C++ Microsoft Extension.



- o Open a new terminal window.
- o \$ cd Desktop/ns-allinone-3.33/ns-3.33
- o \$ code.
- o Ctrl+Shift+P → Edit C/C++: Edit Configuration (UI)
- o Include the following paths:

Include path

An include path is a folder that contains header files (such as #include "myHeaderFile.h") that are included in a source file. Specify a list of paths for the IntelliSense engine to use while searching for included header files. Searching on these paths is not recursive. Specify ** to indicate recursive search. For example, \${workspaceFolder}/** will search through all subdirectories while \${workspaceFolder} will not. If on Windows with Visual Studio installed, or if a compiler is specified in the compilerPath setting, it is not necessary to list the system include paths in this list.

One include path per line.

\${workspaceFolder}/build/ns3/**
/home/samar/Desktop/ns-allinone-3.33/ns-3.33/build