## Results assignment 2

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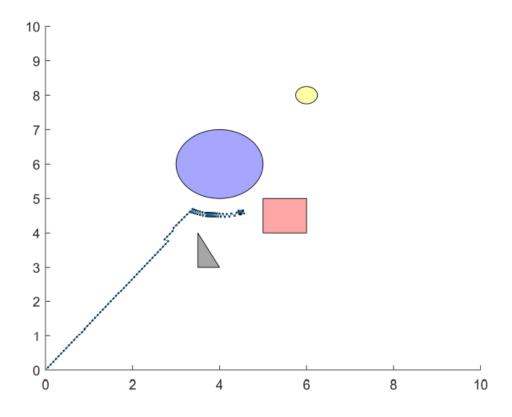
To obtain the following configuration change the following variable values

Goal point - (6,8) (variable name - gpoint)

zeta = 10 (attractive constant)

eta = 5000 (repulsive constant)

Trapped configuration



To obtain the below 3 paths change the following constant with these values

Goal point - (4,8) (variable name - gpoint)

zeta = 100 (for inner most curve)

eta = 500

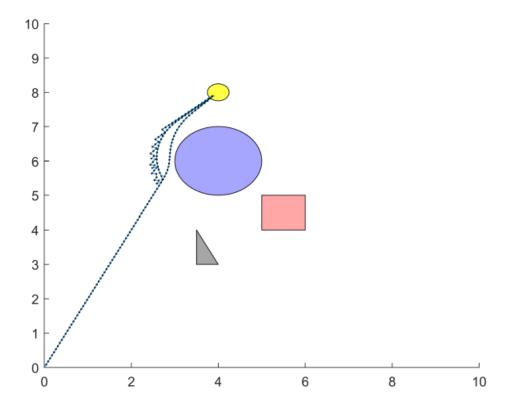
zeta = 100 (for middle curve)

eta = 5000

zeta = 10 (for the outer most curve)

eta = 10000

## All three paths are shown at once



Code for both results is attached below