Samarth Jain

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Education

R V College of Engineering

Karnataka, India

B.E in Telecommunication Engineering; CGPA: 8.2

2014 - 2018

- Key Courses: Embedded Systems programming, MIMO and Wireless systems, HDL implementation on FPGA, Networking, Microprocessors And Microcontroller, Network Analysis and Control Theory, Signal Processing

Experience

Hyperloop India

Auto Pilot using MATLAB

Jan. 2016 - 2017

- Design and Simulation of high speed levitating train auto pilot using Simulink and MATLAB
- Implemented the auto pilot on actual levitating train at Hyperloop competition held by SpaceX and represented India as Hyperloop India student team.
- Development of electronic eddy braking system using actuators like stepper motors

Cloud based education system

Networking Jan. 2017

- Implemention of smart beam focusing antenna system establishing Wlan using 802.11 n to communicate information. The system establishes a network with 175 clients and autofocus beamwidth according to user position in surrounding.
- A complete server-client web interface working on above network with learning open source platforms like coursera, nptel and wikispace hosted on Google Cloud

Project Garuda

Electrical Subsystem

Jan. 2015 - 2016

- Design of a 3 phase inverter for BLDC motor control and implementation of design using Atmega controller. The controller was manufactured and tested on self made electric vehicle.
- The embed project required development of logic, hardware and software design from scratch
- The embed code is written to maximize Torque and speed response using interrupt routines in Atmega controller.

Skills

Languages: C/C++, Assembly language programming, VERILOG, HTML, PHP

Manufacturing Skills: Multilayer PCB

Tools: Proteus for Embed design, NI Labview for algorithm development

Academic Projects

Academic Project

3 Phase Motor Controller For Commercial Electric Vehicle

- Developed a **Brushless DC Motor controller** for electric vehicles

Jan. 2015 - Sep. 2016

- Implemented a novel design for above using Power MOSFET, logic gates and ATMEGA32 to increase efficiency
- Achieved simpler, efficient and lower cost design of a 3 Phase Trapezoidal controller
- Design verified by rigorously testing on an self designed vehicle

Achievements

- Initiated and designed STAND ALONE SOLAR POWER PLANT for Project Garuda
- Member of Hyperloop India, a multicampus student team comprising of students from RV college, BITS Pilani **THE TEAM** is currently making Indias first Hyperloop.
- Member of Project Garuda, Student electric vehicle team. The team now makes urban concept vehical motorcontroller and has completed endurance at an international event, SHELL ECO MARATHON held at Singapore March 2017
- Secured 1st position in the state of Delhi and 27th Position nationally at the National Math Olympiad 2013

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