

# API

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## Web client side

### Api call structure

Protocol: WebSocket

Format: JSON

Property **FID**(function ID) - decimal or hexadecimal number of API function

Property **ARG** - payload, json object

Property **SID**(session ID, response only) - auto incrementing request counter for private subscriptions, tick counter for public subscriptions.

### Echo test (1000)

Request `{"FID":1000, "ARG":{"key":"value"}}`

Response `{"FID":"0x000003e8", "SID":"0x000001eb", "ARG":{"key":"value"}}`

### Private subscription or long task test (1001)

Request `{"FID":1001}`

Response `{"FID":"0x000003e9", "SID":"0x00000223", "ARG":{"STA":"0x00000001"}}`

Now user receiving personal data asynchronously

Secondary request `{"FID":1001}`

Response `{"FID":"0x000003e9", "SID":"0x00000223", "ARG":{"STA":"0x00000002"}}`

Task and subscription cancelled

### Public subscription test (1002)

Request `{"FID":1002}`

Response(personal) `{"FID":"0x000003ea", "SID":"0x00000224", "ARG":{"STA":"0x00000001"}}`

Task notifies all subscribers with the same data asynchronously

Response(public) `{"FID":"0x000003ea", "SID":"0x0010e13b", "ARG":{"data":"Async test"}}`

Response(public) `{"FID":"0x000003ea", "SID":"0x0010e525", "ARG":{"data":"Async test"}}`

...

Secondary request `{"FID":1002}`

Response(personal) `{"FID":"0x000003e9", "SID":"0x00000224", "ARG":{"STA":"0x00000002"}}`

User subscription cancelled

### Modbus master (2000)

FN {byte} - function number

ADR {byte} - modbus device address

RA(optional) {word} - register address

RVA(optional) {word} - register value or amount

CV(optional) {byte} - code value

RD(optional) {depends on function} - registers value(s)  
 // RAW(unsupported) {any bytes seq <=255 bytes len} - transfer raw data (see uart api)  
 AWT(optional) {dword} - awaite response timeout ms (0: dotn't awaite, [default] >0: 100ms min)  
 RDL(optional) {dword} - auto repeat delay ms ([default]0: dotn't repeat, >0:(100ms min))  
 TIDC - cancel modbus task with TID. If set, other options ignoreg

### Example:

Request: {"FID":2000,"ARG":{"AWT":500,"RDL":500,"FN":3,"ADR":"0x01","RA":0,"RVC":20}}

Response: {"FID":"0x000007d0","SID":"0x00000006","ARG":{"TID":"0x0000000A","ADR":"0x01","FN":"0x03","CV":"0x00","RA":"0x0000","RC":"0x14","RD":"0x04d2","0x223d","0x0000","0x1165","0x0000","0x0022","0x0002","0x1d0d","0x0059","0x0162","0x18d2","0x0000","0x0022","0x0044","0x0000","0x0381","0x7eb3","0x0000","0x0024","0x0003"]}}

Request: {"FID":2000,"ARG":{"TIDC":10}}

Response: {"FID":"0x000007d0","SID":"0x00000006","ARG":{"STA":"0x00000002"}}

## UART

### (0x1010) Config port1

### (0x1020) Config port2

BR(optional) {dword} - boudrate  
 PAR(optional) {byte} - parity (0 - none; 1 - odd; 2 - even)  
 WL(optional) {byte} - word length (7 - 7bits; 8 - 8bits)  
 SB(optional) {byte} - stop bits (0 - 0.5sb unsupported; 1 - 1sb; 2 - 2sb; 3 - 1,5sb)  
 no arg - subscription on uart notifications (e.g. config change)\

### Example:

Request: {"FID":"1001","ARG":{"BR":115200}} set boudrate and left untouched other options

Response(public): {"FID":"0x00001001","SID":"0x00037053","ARG":{"BR":"0x0001c200","WL":"0x08","PAR":"0x00","SB":"0x01"}}

### (0x1011) Subscribe on port1 data receive

### (0x1021) Subscribe on port2 data receive

No args

### Example:

Request {"FID":"1011"}

Response(personal) {"FID":"0x00001002","SID":"0x00000224","ARG":{"STA":"0x00000001"}}

Response(public) {"FID":"0x00001011","SID":"0x0010e525","ARG":"313233343536373839300d"}

...

Secondary request {"FID":"1011"}

Response(personal) {"FID":"0x000003e9","SID":"0x00000224","ARG":{"STA":"0x00000002"}}

User subscription cancelled

There is port hex encoded raw data string in public responses.

### (0x1012) Transmit data with port1

### (0x1022) Transmit data with port2

Arg is hex encoded raw data string

#### Example:

Request {"FID":"1012", "ARG":"30313233343536373839"}

Response(personal) {"FID":"0x000003e9","SID":"0x00000225","ARG":{"STA":"0x00000001"}}\

## Firmware side

### Api handlers

```
/*
 * Api handler example, user defined. Invoking each time we get websocket
 * request with FID
 * with which this handler was registered.
 * pxApiCall - API call descriptor
 * ppxContext - user context pointer (in/out): can be set by user and will be
 * preserved for next call
 * ulPending - count of pending (uncompleted) API calls
 * pucData - pointer to current API call argument data
 * ulDataLen - size of data buffer pointed by pucData
 * Returns: true if complete
 */
uint8_t bSomeApiHandler(void *pxApiCall, void **ppxContext, uint32_t ulPending,
uint8_t *pucData, uint32_t ulDataLen);

/*
 * Registers API handler function for websocket calls
 * fHandler - API handler function pointer
 * ulFid - websocket function identifier for client-side calls
 * pxContext - initial context passed to handler's ppxContext parameter
 * Returns: true on success, false on failure
 */
uint8_t bApiCallRegister(ApiHandler_t fHandler, uint32_t ulFid, void
*pxContext);

/*
 * Marks one pending API invocation as completed
 * Decrements ulPending by 1. When ulPending becomes 0:
 * - Handler is called final time with ulPending = 0 for cleanup
 */
```

```

*   - System then releases all call resources
*
* Use final handler call (ulPending=0) to free user-allocated resources
*/
void vApiCallComplete(void *pxApiCall);

/*
 * API Call Status Codes:
 * Normal statuses:
 */
#define API_CALL_STATUS_COMPLETE           0x00000000 /**< Operation
completed successfully */
#define API_CALL_STATUS_EXECUTING         0x00000001 /**< Operation
is in progress */
#define API_CALL_STATUS_CANCELED          0x00000002 /**< Operation
was canceled by user */
#define API_CALL_STATUS_BUSY              0x00000003 /**< System is
busy, try again later */

/*
 * Error statuses (bit 31 set):
 */
#define API_CALL_ERROR_STATUS_BAD_REQ      0x80000000 /**< Malformed
request */
#define API_CALL_ERROR_STATUS_FRAGMENTED  0x80000001 /**< Fragmented
request not supported */
#define API_CALL_ERROR_STATUS_NO_FID      0x80000002 /**< Function
ID not found */
#define API_CALL_ERROR_STATUS_BAD_ARG     0x80000003 /**< Invalid
argument provided */
#define API_CALL_ERROR_STATUS_NO_FREE_DESCRIPTOR 0x80000004 /**< No free
API descriptors available */
#define API_CALL_ERROR_STATUS_NO_MEM      0x80000006 /**< Memory
allocation failed */
#define API_CALL_ERROR_STATUS_NO_ACCESS   0x80000007 /**< Access
denied */
#define API_CALL_ERROR_STATUS_NO_HANDLER  0x8000000E /**< No handler
registered for this FID */
#define API_CALL_ERROR_STATUS_INTERNAL    0x8000000F /**< Internal
system error */

/**
 * Sends status update for specific API call
 *
 * Used for individual communication with a single client
 *
 * pxApiCall API call descriptor obtained in handler
 * ulSta Status code (see API_CALL_STATUS_* or API_CALL_ERROR_STATUS_* macros)
 * Returns true on success
 */
uint8_t bApiCallSendStatus(void *pxApiCall, uint32_t ulSta);

/**

```

```

* Sends JSON data for specific API call
*
* Used for individual communication with a single client
*
* pxApiCall API call descriptor obtained in handler
* ucJson Pointer to JSON data buffer
* ulLen Length of JSON data in bytes
* Returns true on success
*/
uint8_t bApiCallSendJson(void *pxApiCall, const uint8_t *ucJson, uint32_t
ulLen);

/**
* Sends JSON data to ALL clients that called specified function ID
*
* Used for broadcast communication to multiple clients
*
* ulFid Function ID to broadcast to
* ucData Pointer to JSON data buffer
* ulLen Length of JSON data in bytes
* Returns true on success
*/
uint8_t bApiCallSendJsonFidGroup(uint32_t ulFid, const uint8_t *ucData,
uint32_t ulLen);

```