## Web client side

```
Api call structure
Protocol: WebSocket
Format: JSON
Property FID(function ID) - decimal or hexadecimal number of API function
Property ARG - payload, ison object
Property SID(session ID, responce only) - auto incrementing request counter for private subscriptions, tick
counter for public subscriptions.
Echo test (1000)
Request {"FID":1000, "ARG":{"key":"value"}}
Response {"FID": "0x0000003e8", "SID": "0x0000001eb", "ARG": {"key": "value"}}
Private subscription or long task test (1001)
Request {"FID":1001}
Response {"FID":"0x000003e9", "SID":"0x00000223", "ARG": {"STA":"0x00000001"}}
Now user receiving personal data asinchroniusly
Secondary request {"FID":1001}
Response {"FID":"0x0000003e9", "SID":"0x000000223", "ARG":{"STA":"0x00000002"}}
Task and subscription cancelled
Public subscription test (1002)
Request {"FID":1002}
Response(personal) {"FID":"0x0000003ea", "SID":"0x000000224", "ARG": {"STA":"0x000000001"}}
Task notifies all subscribers with the same data asinchroniusly
Response(public) {"FID": "0x0000003ea", "SID": "0x0010e13b", "ARG": {"data": "Async test"}}
Response(public) {"FID": "0x0000003ea", "SID": "0x0010e525", "ARG": {"data": "Async test"}}
Secondary request {"FID":1002}
Response(personal) {"FID":"0x0000003e9", "SID":"0x000000224", "ARG": {"STA":"0x000000002"}}
User subscription cancelled
Modbus master (2000)
FN {byte} - function number
ADR {byte} - modbus device address
RA(optional) {word} - register address
RVA(optional) {word} - register value or amount
CV(optional) {byte} - code value
```

```
RD(optoanal) {depends on function} - registers value(s)

// RAW(unsupported) {any bytes seq <=255 bytes len} - transfer raw data (see uart api)

AWT(optional) {dword} - awaite responce timeout ms (0: dotn't awaite, [default] >0: 100ms min)

RDL(optional) {dword} - auto repeat delay ms ([default]0: dotn't repeat, >0:(100ms min))

TIDC - cancel modbus task with TID. If set, other options ignoreg
```

#### **Example:**

```
Request: {"FID": 2000, "ARG": {"AWT": 500, "RDL": 500, "FN": 3, "ADR": "0x01", "RA": 0, "RVC": 20}}
Response: {"FID": "0x000007d0", "SID": "0x00000006", "ARG":
{"TID": "0x00000000A", "ADR": "0x01", "FN": "0x03", "CV": "0x00", "RA": "0x00000", "RC": "0x14", "RD":
["0x04d2", "0x223d", "0x0000", "0x1165", "0x00000", "0x0022", "0x00002", "0x1d0d", "0x0059", "0x00162", "0x18d2", "0x00000", "0x0022", "0x00044", "0x0000", "0x0381", "0x7eb3", "0x00000", "0x0024", "0x00003"]}}
Request: {"FID": 2000, "ARG": {"TIDC": 10}}
Response: {"FID": "0x0000007d0", "SID": "0x000000006", "ARG": {"STA": "0x0000000002"}}

UART (3000)

BR(optional) {dword} - boudrate

PAR(optional) {byte} - parity (0 - none; 1 - odd; 2 - even)

WL(optional) {byte} - word length (0 - 7bits; 1 - 8bits)

SB(optional) {byte} - stop bits (0 - 1sb; 1 - 2sb; 2 - unsupported; 3 - 1,5sb)

no arg - subscription on uart notifications (e.g. config change)\
```

### **Example:**

```
Request: {"FID":3000, "ARG": {"BR":115200}} set boudrate and left untouched other options Response(public): {"FID":"0x000000bb8", "SID":"0x00037053", "ARG": {"BR":"0x0001c200", "WL":"0x01", "PAR":"0x00", "SB":"0x000"}}
```

## Firmware side

# Api handlers

```
/*
 * Api handler example, user defined. Invoking each time we get websocket
request with FID
 * with which this handler was registered.
 * pxApiCall - API call descriptor
 * ppxContext - user context pointer (in/out): can be set by user and will be
preserved for next call
 * ulPending - count of pending (uncompleted) API calls
 * pucData - pointer to current API call argument data
 * ulDataLen - size of data buffer pointed by pucData
 * Returns: true if complete
 */
```

```
uint8_t bSomeApiHandler(void *pxApiCall, void **ppxContext, uint32_t ulPending,
uint8 t *pucData, uint32 t ulDataLen);
/*
* Registers API handler function for websocket calls
* fHandler - API handler function pointer
* ulFid - websocket function identifier for client-side calls
 * pxContext - initial context passed to handler's ppxContext parameter
 * Returns: true on success, false on failure
uint8_t bApiCallRegister(ApiHandler_t fHandler, uint32_t ulFid, void
*pxContext);
 * Marks one pending API invocation as completed
 * Decrements ulPending by 1. When ulPending becomes 0:

    Handler is called final time with ulPending = 0 for cleanup

 * - System then releases all call resources
 * Use final handler call (ulPending=0) to free user-allocated resources
 */
void vApiCallComplete(void *pxApiCall);
/*
 * API Call Status Codes:
* Normal statuses:
*/
#define API_CALL_STATUS_COMPLETE
                                                  0x00000000 /**< Operation
completed successfully */
                                                  0x00000001 /**< Operation
#define API_CALL_STATUS_EXECUTING
is in progress */
                                                  0x00000002 /**< Operation
#define API CALL STATUS CANCELED
was canceled by user */
#define API_CALL_STATUS_BUSY
                                                  0x00000003 /**< System is
busy, try again later */
 * Error statuses (bit 31 set):
#define API_CALL_ERROR_STATUS_BAD_REQ
                                                 0x80000000 /**< Malformed
request */
#define API CALL ERROR STATUS FRAGMENTED
                                                 0x80000001 /**< Fragmented
request not supported */
#define API_CALL_ERROR_STATUS_NO_FID
                                                 0x80000002 /**< Function
ID not found */
#define API_CALL_ERROR_STATUS_BAD_ARG
                                                 0x80000003 /**< Invalid
argument provided */
#define API_CALL_ERROR_STATUS_NO_FREE_DESCRIPTORS  0x80000004  /**< No free
API descriptors available */
#define API_CALL_ERROR_STATUS_NO_MEM
                                        0x80000006 /**< Memory
allocation failed */
#define API_CALL_ERROR_STATUS_NO_ACCESS
                                                 0x80000007 /**< Access
denied */
```

```
0x8000000E /**< No handler
#define API_CALL_ERROR_STATUS_NO_HANDLER
registered for this FID */
#define API CALL ERROR STATUS INTERNAL
                                                   0x8000000F /**< Internal
system error */
/**
 * Sends status update for specific API call
 * Used for individual communication with a single client
 * pxApiCall API call descriptor obtained in handler
 * ulSta Status code (see API CALL STATUS * or API CALL ERROR STATUS * macros)
 * Returns true on success
uint8_t bApiCallSendStatus(void *pxApiCall, uint32_t ulSta);
/**
 * Sends JSON data for specific API call
 * Used for individual communication with a single client
 * pxApiCall API call descriptor obtained in handler
 * ucJson Pointer to JSON data buffer
 * ullen Length of JSON data in bytes
 * Returns true on success
uint8_t bApiCallSendJson(void *pxApiCall, const uint8_t *ucJson, uint32_t
ullen);
 * Sends JSON data to ALL clients that called specified function ID
 * Used for broadcast communication to multiple clients
* ulFid Function ID to broadcast to
 * ucData Pointer to JSON data buffer
 * ullen Length of JSON data in bytes
 * Returns true on success
uint8_t bApiCallSendJsonFidGroup(uint32_t ulFid, const uint8_t *ucData,
uint32_t ullen);
```