

MODULE-4  
DYNAMIC  
PROGRAMMING

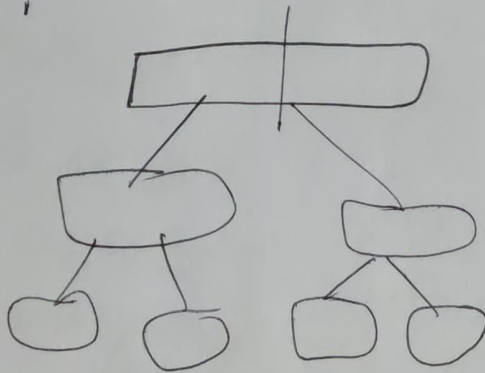
①

// Dynamic programming :- It divides the problem into series of overlapping sub-problems.

Two 2 features 1) Optimal substructure  
2) Overlapping subproblems

Minimum cost.

\* Dynamic programming is an algorithm design method that can be used when the solution to a problem can be viewed as the result of a sequence of decisions.



In DGC, there is no repeat.

But in DP, the sub-problems repeat.

store and retrieve later.

Eg:- Fibonacci series  $f(n) = f(n-1) + f(n-2)$

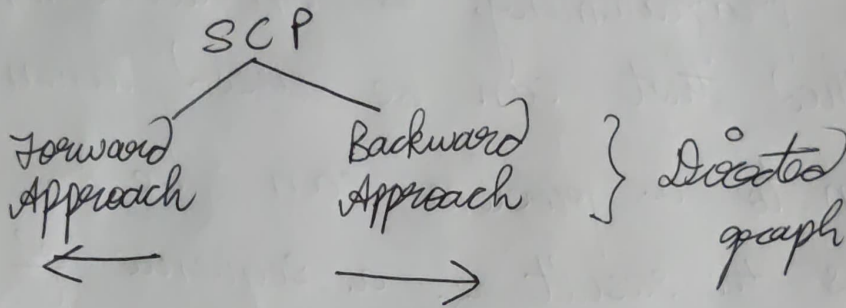
## MULTISTAGE GRAPH

(2)

Definition  $\rightarrow$  sg is defined as

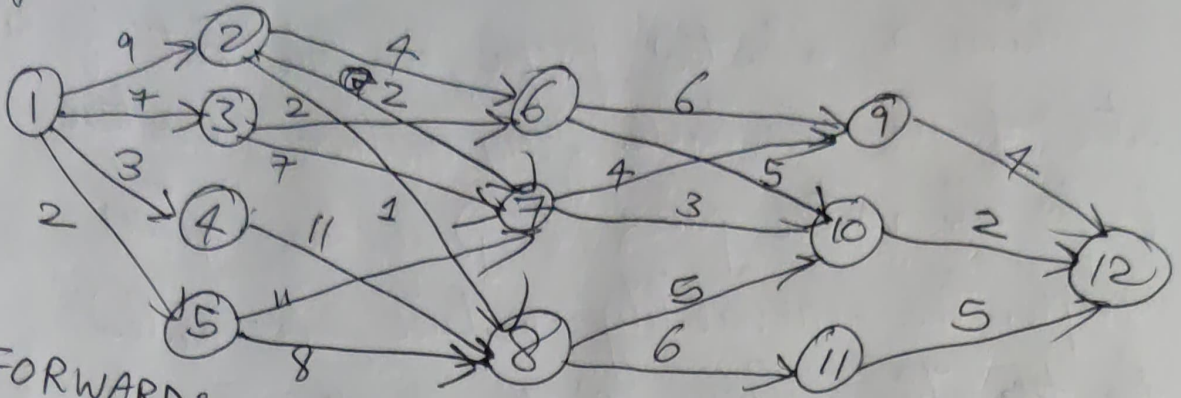
\* Directed graph  $G=(V,E)$  in which vertices are partitioned into ' $k$ ' stages, where  $k \geq 2$ .

\* Each stage contains disjoint sets  $V_i$  where  $1 \leq i \leq k$ , i.e., any stage the number of vertices should not exceed



Ex:-

(3)



FORWARD:-  $1 \leftarrow 12$

BACKWARD:-  $1 \rightarrow 12$

Solution:- A is a 2-D array of weights  
 $n=12, s=1$  (source)  
 $d=12$  (destination)

FORWARD

BACKWARD

$$C[12] = 0, p[12] = 12$$

$$C[11] = \min \{a[11,12] + C[12]\} = 5$$

$$C[10] = 2$$

$$C[9] = 4$$

$$C[8] = \min \{5+2, 6+5\} = 7$$

$$C[7] = \min \{3+2, 4+9\} = 5$$

$$C[6] = \min \{6+4, 5+2\} = 7$$

$$C[5] = \min \{8+6+5, 11+3+2\} = 16$$

$$C[4] = \min \{11+6+5\} = 22$$

$$C[3] = \min \{2+6+4, 7+3+2\} = 12$$

$$C[2] = \min \{4+6+4, 2+3+2, 2+6+5\} = 7$$

$$C[1] = \min \{9+4+6+4, 12, 9+7, 12+7, 3+22, 2+16\} = 16$$

$$C[1] = 0, p[1] = 0$$

$$C[2] = \min \{9, 7, 2\} = 2$$

$$C[3] = 7$$

$$C[4] = 3$$

$$C[5] = 2$$

$$C[6] = \min \{9+4, 7+2\} = 7$$

$$C[7] = \min \{9+2, 7+7, 2+11\} = 5$$

$$C[8] = \min \{2+8, 3+11\} = 10$$

$$C[9] = \min \{6+4, 7+4\} = 10$$

$$C[10] = \min \{6+5, 7+3, 8+5\} = 11$$

$$C[11] = \min \{8+6, 9+4\} = 14$$

$$C[12] = \min \{9+4, 10+2, 11+5\} = 14$$

$$C[12] = 16$$



## TRANSITIVE CLOSURE

Given a directed graph, we find out if a vertex  $j$  is reachable from another vertex  $i$  for all vertex pairs  $(i, j)$  in the given graph. The reachability matrix is called the transitive closure of the graph.

### WARSHALL'S ALGORITHM

$$R^{(0)} = A$$

for  $k=1$  to  $n$  do

for  $i=1$  to  $n$  do

for  $j=1$  to  $n$

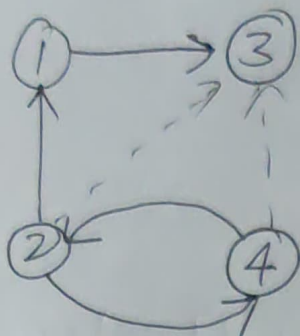
$$R^{(k)}[i, j] \leftarrow R^{(k-1)}[i, j] \text{ or } (R^{(k-1)}[i, k] \text{ and } R^{(k-1)}[k, j])$$

return  $R^{(n)}$



Eg:-

5



$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

If 1 is present, leave it as it is.  
 If 0, change to 1 in  $R^{(k)}$  if and only if  
 the element in its row  $i$  and column  $k$  and  
 the element in column  $j$  and row  $k$  are  
 both 1s in  $R^{(k-1)}$

$$R^{(k-1)} \begin{bmatrix} & j & k \\ k & & \\ i & & \end{bmatrix} \rightarrow$$

$$R^{(k)} = \begin{bmatrix} & j & k \\ k & 1 & \\ i & 1 & 1 \end{bmatrix}$$

If both are 1,  
 change to 1

$$R^{(0)} = \begin{matrix} & a & b & c & d \\ a & 0 & 1 & 0 & 0 \\ b & 0 & 0 & 0 & 1 \\ c & 0 & 0 & 0 & 0 \\ d & 1 & 0 & 1 & 0 \end{matrix}$$

$$R^{(3)} = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$R^{(1)} = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$R^{(4)} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix}$$

$$R^{(2)} = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$O(n^3)$

⑥

# FLOYD'S ALGORITHM

Floyd( $W[1 \dots n, 1 \dots n]$ )  
 for ( $k=1$  to  $n$ )  
 {

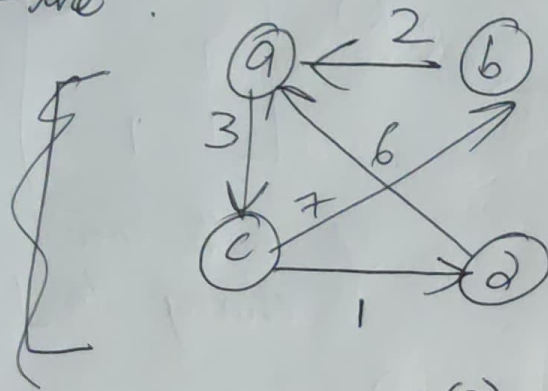
  for ( $i=1$  to  $n$ )  
 {

    for ( $j=1$  to  $n$ )  
 {

$D[i,j] \leftarrow \min \{ D[i,j], D[i,k] + D[k,j] \}$   
 }

  }  
 }  
 return D

All pair shortest path ~~it is used to~~  
 find the



$D(0)$

	a	b	c	d
a	0	$\infty$	3	$\infty$
b	2	0	$\infty$	$\infty$
c	$\infty$	7	0	1
d	6	$\infty$	$\infty$	0

$D(1)$

0	$\infty$	3	$\infty$
2	0	5	$\infty$
$\infty$	7	0	1
6	$\infty$	9	0

$D(2)$

0	$\infty$	3	$\infty$
2	0	5	$\infty$
9	7	0	1
6	$\infty$	9	0

$D(3)$

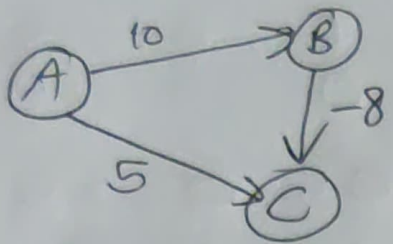
0	10	3	4
2	0	5	6
9	7	0	1
6	16	9	0

$D(4)$

0	10	3	4
2	0	5	6
7	7	0	1
6	16	9	0

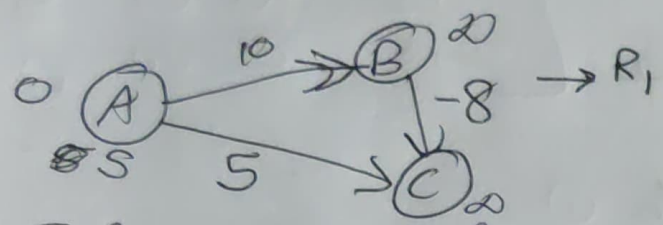


# BELLMAN FORD ALGORITHM



A	B	C
0	$\infty$	$\infty$
	10	5

Dijkstra's  
X

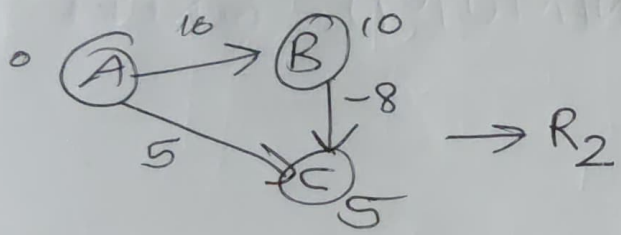


$0 + 10 = 10$   
 $0 + 5 = 5$

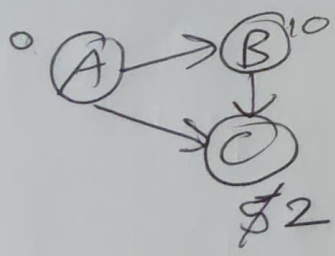
Relax every edge

$V-1$  number of times

$3-1 = 2$  times relax

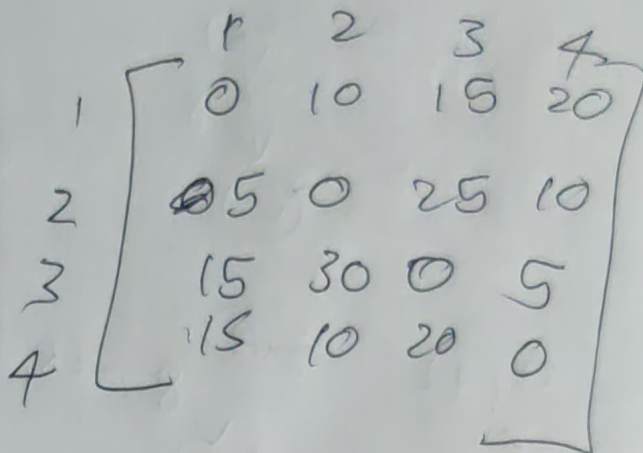


$m=8$   
 $n=4$



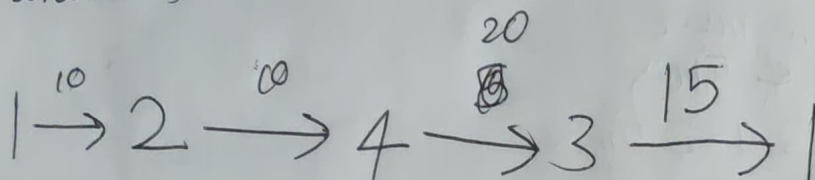
	0	1	2	3	4	5	6	7	8
0	0	0	0	0	0	0	0	0	0
1	0	0	1	1	1	1	1	1	1
2	0	0	1	2	2	3	3	3	3
3	0	0	1	2	5	5	6	7	7
4	0	0	1	2	5	6	6	7	8

## PROBLEM



travel all and come back to ①.

Minimum cost



$= 55$  (NOT MINIMUM) = GREEDY

