Lab 8

January 14, 2022

Machine Learning Lab

Lab 08

0.0.1 Exercise 1: Optical Character Recognition via Neural Networks

Importing Packages

```
#Importing Pandas
[1]: import pandas as pd
     import numpy as np
                                                                      #Importing Numpy
     from sklearn.datasets import load_digits
                                                                      #Importing MNIST
      \hookrightarrow Dataset from Sklearn
     import matplotlib.pyplot as plt
                                                                      #Importing Matplotlib
     from sklearn.model_selection import train_test_split
                                                                      #Importing Train test
     from sklearn.neural_network import MLPClassifier
                                                                      #Importing MLP
      \hookrightarrow Classifier
     from sklearn.model_selection import RandomizedSearchCV
                                                                      #Importing Randomized
      \hookrightarrow Search
     from sklearn.metrics import accuracy_score
                                                                      #Importing Accuracy
      \rightarrowScore
```

Initializing Random Seed

```
[2]: random_seed = 3116
```

Loading the MNIST digits dataset via sklearn provided built-in utility function(s).

```
[3]: mnist_digits = load_digits()
```

Plotting the Initial 10 Handwritten Digits from the Dataset

```
[4]: #Creating a Figure
fig = plt.figure(figsize=(15, 10))

#Iterating through the first 10 handwritten digits from the dataset
for i in range(1, 11):
    #Adding a subplot
    plt.subplot(1, 10, i)

#Plotting the Image in Grayscale
```

```
plt.imshow(mnist_digits.images[i - 1], cmap = 'gray')

#Adjusting Spacing and Showing the plots
plt.tight_layout()
plt.show()
```

K-cross Fold Validation and Train Test Split

```
Initializing the value of k for K-cross fold validation
```

```
[5]: k = 5
```

```
Splitting the Dataset into Train and Test with 20% Testing set
```

```
[6]: X_train, X_test, y_train, y_test = train_test_split(mnist_digits.data, __ 

→mnist_digits.target, test_size = 0.2, random_state = random_seed)
```

Defining a hyperparameter grid for the MLP Classifier

```
[7]: hyperparameter_grid = {
         'hidden_layer_sizes': [(10,), (10,20), (10,20,10)],
                                                                           #The number
      →of neurons in each hidden layer
         'activation': ['identity', 'logistic', 'tanh', 'relu'],
                                                                           #Activation
      → function for the hidden layer
         'solver': ['lbfgs', 'sgd', 'adam'],
                                                                            #Weight
      \hookrightarrow Optimization techniques
         'alpha': [0.5, 0.01, 0.001, 0.0001,],
                                                                            #L2
      \rightarrowRegularization term
         'learning_rate': ['constant', 'invscaling', 'adaptive']
                                                                          #Learning_
      →rate schedule for weight updates
     }
```

Defining a Random Search procedure over the ranges of Hyperparameters above

```
[8]: #Creating the object of MLP(Multi Layer Perceptron) Classifier with maximum_
iteration of 100

mlp = MLPClassifier(max_iter = 100, random_state = random_seed)

#Creating and Initializing the object for Randomized Search with the MLP_
Classifier and the hyperparameter grid

rand_mlp = RandomizedSearchCV(mlp, hyperparameter_grid, random_state = □
random_seed, n_jobs = -1,n_iter = 20, cv = k, scoring = 'accuracy')
```

```
#Fitting the training dataset on the MLP Classifier using Randomized Search for⊔
→finding the best hyperparameters
rand_mlp.fit(X_train, y_train)
```

[8]: RandomizedSearchCV(cv=5,

Reporting the test accuracy and the best hyperparameters found

```
Best Hyperparameters Found
```

```
[9]: print('The Best Hyperparameter Combination is:')
rand_mlp.best_params_
```

The Best Hyperparameter Combination is:

Test Accuracy

```
[10]: print('The Test Accuracy of MLP Classifier with best Hyperparameters is: {:.

→2f}'.format(accuracy_score(y_test, rand_mlp.predict(X_test))))
```

The Test Accuracy of MLP Classifier with best Hyperparameters is: 0.96

0.0.2 Exercise 2: End-to-End Self-Driving via Convolutional Neural Networks

Importing Packages

```
[11]: import torch
from torch.utils.data import DataLoader , Dataset

→ and Dataset from pytorch
import torchvision
from torch.utils.data import random_split

→ Split from pytorch

#Importing torch
#Importing Torchvision
#Importing Random_
#Importing Random_
```

C:\Users\dell\anaconda3\envs\ml_lab\lib\site-

packages\torchvision\io\image.py:11: UserWarning: Failed to load image Python extension: Could not find module 'C:\Users\dell\anaconda3\envs\ml_lab\Lib\site-packages\torchvision\image.pyd' (or one of its dependencies). Try using the full path with constructor syntax.

warn(f"Failed to load image Python extension: {e}")

Class to load Dataset containing data and its labels

```
[12]: class Dataset(Dataset): #Inherits from torch.utils.data.Dataset
          #Constructor Function which read image names and its label from the
       \rightarrow directory
          def __init__(self):
              #default directory where data is loaded
              self.filepath = 'archive/driving_dataset/'
              #default directory where labels for each image is saved
              self.filepath_angles = 'archive/driving_dataset/angles.txt'
              #Creating lists for storing filenames and its label(steering angle)
              self.filenames = []
              self.steering_angle = []
              #Opening the angles file and saving the filenames and angles in the
       \rightarrow created lists
              with open(self.filepath_angles) as angles:
                  line = angles.readline()
                  while line:
                      tokens = line.split()
                      self.filenames.append(tokens[0])
                      self.steering_angle.append(tokens[1])
                      line = angles.readline()
          #Function to return the total datapoints in the dataset
          def len (self):
              return len(self.filenames)
          #Function to get the image and its label at specified index
          def __getitem__(self, index):
```

```
#Extracting filename and angle from the list
filename = self.filenames[index]
angle = self.steering_angle[index]

#Reading the image using opencu
img = cv2.imread(self.filepath + filename)

#Resizing images to(32,32)
resized = cv2.resize(img, (200, 66),interpolation = cv2.INTER_AREA)

#return the image converted to a numpy array its corresponding steering
→angle
return torch.from_numpy(resized.transpose()).float(), torch.tensor(np.
→float32(angle))
```

Class which Implements the Convolutional Neural Network Architecture proposed in the paper

```
[13]: class ConvNet(torch.nn.Module):
          #Constructor function which list all the layers in CNN model
          def __init__(self):
              super().__init__()
              self.norm1 = nn.LayerNorm([200,66])
              self.conv1 = nn.Conv2d(in_channels = 3, out_channels = 24, kernel_size_
       \Rightarrow= 5, stride = 2)
              self.conv2 = nn.Conv2d(in_channels = 24, out_channels = 36, kernel_size_
       \rightarrow= 5, stride = 2)
              self.conv3 = nn.Conv2d(in_channels = 36, out_channels = 48, kernel_size_
       \Rightarrow= 5, stride = 2)
              self.conv4 = nn.Conv2d(in_channels = 48, out_channels = 64, kernel_size_
       \Rightarrow= 3, stride = 1)
              self.conv5 = nn.Conv2d(in_channels = 64, out_channels = 64, kernel_size_
       \Rightarrow= 3, stride = 1)
              self.fc1 = nn.Linear(in_features = 64 * 1 * 18, out_features = 100)
              self.fc2 = nn.Linear(in features = 100, out features = 50)
              self.fc3 = nn.Linear(in_features = 50, out_features = 10)
              self.fc4 = nn.Linear(in_features = 10, out_features = 1)
          #Function to link all the layers in the sequence
          def forward(self, x):
              x = self.norm1(x)
              x = F.relu(self.conv1(x))
              x = F.relu(self.conv2(x))
              x = F.relu(self.conv3(x))
              x = F.relu(self.conv4(x))
              x = F.relu(self.conv5(x))
```

```
x = x.view(x.shape[0], -1)
x = F.relu(self.fc1(x))
x = F.relu(self.fc2(x))
x = F.relu(self.fc3(x))
x = self.fc4(x)
return x
```

Dividing the dataset into corresponding train/validation/test splits. Leaving the last 10k images for testing.

Converting the Datasets into Dataloaders for Iterations

```
[15]: #Train Dataloader
train_dataloader = DataLoader(train_dataset, batch_size = 64, shuffle = True)

#Validation Dataloader
val_dataloader = DataLoader(val_dataset, batch_size = 64, shuffle = True)

#Test Dataloader
test_dataloader = DataLoader(test_dataset, batch_size = 64, shuffle = True)
```

Training and Evaluating the CNN on the dataset Sets

```
Checking for GPU, if present then changing device to Cuda
```

```
[16]: device = 'cpu'
if torch.cuda.is_available():
    device = 'cuda'
torch.device(device)
```

```
[16]: device(type='cuda')
     Creating the Object of our CNN model and transferring it to the Device
[17]: model = ConvNet().to(device)
      model
[17]: ConvNet(
        (norm1): LayerNorm((200, 66), eps=1e-05, elementwise_affine=True)
        (conv1): Conv2d(3, 24, kernel_size=(5, 5), stride=(2, 2))
        (conv2): Conv2d(24, 36, kernel_size=(5, 5), stride=(2, 2))
        (conv3): Conv2d(36, 48, kernel_size=(5, 5), stride=(2, 2))
        (conv4): Conv2d(48, 64, kernel_size=(3, 3), stride=(1, 1))
        (conv5): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1))
        (fc1): Linear(in_features=1152, out_features=100, bias=True)
        (fc2): Linear(in features=100, out features=50, bias=True)
        (fc3): Linear(in_features=50, out_features=10, bias=True)
        (fc4): Linear(in features=10, out features=1, bias=True)
      )
     Initiating the RMSE Loss function and the ADAM optimizer
[18]: #Creating the RMSE loss function object provided in Pytorch
      criterion = nn.MSELoss()
      #Creating the Adam Optimizer object with model parameters and learning rate
      optimizer = torch.optim.Adam(model.parameters(), lr = 0.001)
[19]: #Initializing the number of Epochs
      epochs = 30
      #Creating list to store the RMSE of Training and Validation dataset in each
      \rightarrow Epochs
      training_rmse = []
      validation rmse = []
     Training the model and Evaluating it on the Validation dataset
[20]: #Iterating over all Epochs
      for e in range(epochs):
          #Initiating the training and validation loss to 0
          running_loss = 0.0
          val_running_loss = 0.0
          #Iterating over all Training datapoints
          for inputs, labels in train_dataloader:
```

```
#Extracting Input image and label and doing a forward pass on our 	extstyle 	extstyl
\rightarrowmodel
                  inputs = inputs.to(device)
                  labels = labels.to(device)
                  outputs = model(inputs)
                   #Calculating the RMSE loss
                  loss = criterion(outputs, labels)
                   #Setting the gradient to Zero for next Iteration
                  optimizer.zero_grad()
                   #Computing the Back propogation on CNN
                  loss.backward()
                  optimizer.step()
                   #Adding the RMSE loss to the total loss
                  running_loss += loss.item()
        #Evaluating the model on the Validation set
       with torch.no_grad():
                   #Iterating over the validation dataset
                  for val_inputs, val_labels in val_dataloader:
                             #Extracting Input image and label and doing a forward pass on our
\hookrightarrow CNN model
                             val_inputs = val_inputs.to(device)
                             val_labels = val_labels.to(device)
                             val_outputs = model(val_inputs)
                             #Calculating the RMSE loss
                             val_loss = criterion(val_outputs, val_labels)
                             #Adding the RMSE loss to the total validation loss
                             val_running_loss += val_loss.item()
        #Calculating the current Epoch average RMSE loss on training and Validation
\rightarrow dataset
        epoch_loss = np.sqrt(running_loss/len(train_dataloader))
       val_epoch_loss = np.sqrt(val_running_loss/len(val_dataloader))
       #Apending the loss in the final list
       training_rmse.append(epoch_loss)
       validation_rmse.append(val_epoch_loss)
        #Printing the Results
```

```
print('epoch :', (e+1))
    print('training loss: {:.4f}'.format(epoch_loss))
    print('validation loss: {:.4f}'.format(val_epoch_loss))
C:\Users\dell\anaconda3\envs\ml_lab\lib\site-
packages\torch\nn\modules\loss.py:520: UserWarning: Using a target size
(torch.Size([64])) that is different to the input size (torch.Size([64, 1])).
This will likely lead to incorrect results due to broadcasting. Please ensure
they have the same size.
  return F.mse_loss(input, target, reduction=self.reduction)
C:\Users\dell\anaconda3\envs\ml_lab\lib\site-
packages\torch\nn\modules\loss.py:520: UserWarning: Using a target size
(torch.Size([37])) that is different to the input size (torch.Size([37, 1])).
This will likely lead to incorrect results due to broadcasting. Please ensure
they have the same size.
  return F.mse_loss(input, target, reduction=self.reduction)
C:\Users\dell\anaconda3\envs\ml lab\lib\site-
packages\torch\nn\modules\loss.py:520: UserWarning: Using a target size
(torch.Size([41])) that is different to the input size (torch.Size([41, 1])).
This will likely lead to incorrect results due to broadcasting. Please ensure
they have the same size.
 return F.mse_loss(input, target, reduction=self.reduction)
epoch: 1
training loss: 30.7713
validation loss: 30.6681
epoch: 2
training loss: 30.8140
validation loss: 30.6546
epoch: 3
training loss: 30.7403
validation loss: 30.7443
epoch: 4
training loss: 30.7487
validation loss: 30.6669
epoch: 5
training loss: 30.7302
validation loss: 30.6170
epoch: 6
training loss: 30.7283
validation loss: 30.6350
epoch: 7
training loss: 30.7212
validation loss: 30.6243
epoch: 8
training loss: 30.7345
validation loss: 30.6251
```

epoch: 9

training loss: 30.7226 validation loss: 30.6772

epoch: 10

training loss: 30.7315 validation loss: 30.6287

epoch: 11

training loss: 30.7257 validation loss: 30.6631

epoch: 12

training loss: 30.7104 validation loss: 30.6013

epoch: 13

training loss: 30.7099 validation loss: 30.5996

epoch: 14

training loss: 30.7055 validation loss: 30.6503

epoch: 15

training loss: 30.7067 validation loss: 30.6314

epoch: 16

training loss: 30.7075 validation loss: 30.6021

epoch: 17

training loss: 30.7182 validation loss: 30.6359

epoch: 18

training loss: 30.7094 validation loss: 30.5985

epoch: 19

training loss: 30.7059 validation loss: 30.6455

epoch: 20

training loss: 30.7141 validation loss: 30.6004

epoch: 21

training loss: 30.7196 validation loss: 30.6249

epoch: 22

training loss: 30.7305 validation loss: 30.6666

epoch: 23

training loss: 30.7101 validation loss: 30.6908

epoch: 24

training loss: 30.7082 validation loss: 30.6702

epoch: 25

training loss: 30.7077 validation loss: 30.6096

epoch: 26

training loss: 30.7337 validation loss: 30.5962

epoch: 27

training loss: 30.7234 validation loss: 30.6321

epoch: 28

training loss: 30.7240 validation loss: 30.5973

epoch: 29

training loss: 30.7038 validation loss: 30.5974

epoch: 30

training loss: 30.7068 validation loss: 30.6074

Plotting Training RMSE vs Validation RMSE in each Epoch

```
[21]: fig = plt.figure(figsize=(18,8))
    plt.plot(training_rmse, label = 'Training RMSE')
    plt.plot(validation_rmse, label = 'Validation RMSE')
    plt.title('Training RMSE vs Validation RMSE')
    plt.xlabel('Epochs')
    plt.ylabel('RMSE')
    plt.legend()
    plt.show()
```



From the above graph we can see that both Train RMSE and Test RMSE are decreasing but fluctuation very abruptly, to smooth this curve we can basically use the regularization term to add some weight on negative examples.

Evaluating the Trained CNN Model with the Test Dataset

```
[22]: #Initializing the loss to 0
      running_loss = 0.0
      #Evaluating the model on the Test set
      with torch.no_grad():
          #Iterating over the Test dataset
          for inputs, labels in test_dataloader:
               \#Extracting\ Input\ image\ and\ label\ and\ doing\ a\ forward\ pass\ on\ our\ CNN_{\sqcup}
       \hookrightarrow model
               inputs = inputs.to(device)
               labels = labels.to(device)
               outputs = model(inputs)
               #Calculating the RMSE loss
               loss = criterion(outputs, labels)
               #Adding the RMSE loss to the total Test loss
              running_loss += loss.item()
      #Calculating the current Epoch average RMSE loss on Test dataset
      epoch_loss = np.sqrt(running_loss/len(test_dataloader))
```

C:\Users\dell\anaconda3\envs\ml_lab\lib\sitepackages\torch\nn\modules\loss.py:520: UserWarning: Using a target size
(torch.Size([16])) that is different to the input size (torch.Size([16, 1])).
This will likely lead to incorrect results due to broadcasting. Please ensure they have the same size.

return F.mse_loss(input, target, reduction=self.reduction)

```
[23]: print('Test RMSE: {:.4f}'.format(epoch_loss))
```

Test RMSE: 31.6328