

SAMET KARAŞ

Computer Engineer

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SUMMARY

I am a passionate computer engineering candidate specializing in machine learning, artificial intelligence, and image processing. I am committed to improving my skills daily and striving to reach the highest peak in my career.

My love for computers and video games has driven me to pursue a career in technology. I aim to harness this passion as a driving force to enhance my abilities and contribute to innovative projects continuously.

EDUCATION

Recep Tayyip Erdogan University

Computer Engineering
2021-2026

SKILLS

- C#, Python, Java, JavaScript, SQL
- PyTorch
- HTML, CSS, JavaScript, Next.js, Node.js
- Git, GitHub
- Blender

CERTIFICATES

- C# and SQL 101 Training for Beginners
- 25 Practical Projects in 25 Lessons with C#
- Python 2024: 100-Day Programming Bootcamp
- Data Structures and Algorithms: Software Interviews
- Introduction to Digital Game Development with Unity
- Version Control: Git and GitHub

LANGUAGES

- Turkish
- English - B1+

EXPERIENCE

Activities Coordinator

RTEU Computer Engineering Society | 2023 - Present

- I plan and organize the activities of the society. I ensure smooth execution of events by managing communication, logistics, and resource allocation.

PROJECTS

Twitch Clone

Technologies : Next.js, TypeScript, React.js, Tailwind CSS

- The Full Stack Twitch clone includes core Twitch functionalities, such as live streaming features (streamer profiles and viewer interactions). I implemented SSR and SSG with Next.js 14, type safety with TypeScript, and responsive design with Tailwind CSS.

Project Link - [GitHub](#)

Kitchen Chaos

Technologies : C#, Unity, Blender

- The cooking simulation game includes cooking tasks, a user interface, and a task system. I created 3D models with Blender and integrated them into Unity.

Project Link - [GitHub](#)

Teknofest 2024 Robotaksi Binek Otonom Araç

Technologies : ROS1

- As a finalist in the Teknofest 2024 Robotaxi Passenger Autonomous Vehicle Competition, we developed autonomous driving capabilities. In the project, we implemented GPS-based guidance and autonomous navigation algorithms using ROS1 to ensure safe vehicle movement. We focused on solutions to minimize deviations, especially during turns.

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