



**HACETTEPE UNIVERSITY  
DEPARTMENT OF  
GEOMATICS ENGINEERING**

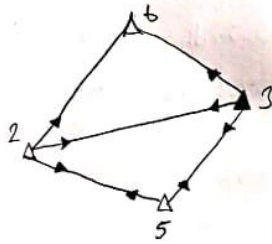


**GMT202  
ADJUSTMENT COMPUTATION & PARAMETER ESTIMATION  
2021-2022 SPRING TERM  
ASSIGNMENT 8**

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D)

Balance the Trigonometric Leveling Network given below using the indirect measures method.



NN	H <sub>i</sub>
Exact Elevation	
3	1016,253
Approximate Heights	
2	1117,001
5	1047,644
6	1101,859

DN	BN	Vertical Angle Z <sub>i-j</sub>	Instrumental height (i)	Reflector height (t)	S <sub>i-j</sub>
2	3	102,92374	1,42	1,75	2194,193
	5	102,28561	1,42	1,81	1924,510
	6	102,51359	1,42	1,76	1875,414
3	2	97,08010	1,61	1,90	2194,200
	5	98,71777	1,61	1,87	1562,956
	6	96,35727	1,61	1,83	1495,632
5	2	97,70589	1,45	1,88	1924,500
	3	101,27326	1,45	1,82	1562,961

Number of measures  
(n) = 8

Unknown Number = 3  
(u)

$f = n - u \Rightarrow 8 - 3 = 5 \checkmark$  There is adjustment.

$$Z_{i,j}^0 = \arccot \left\{ \frac{1}{S_{i,j}} \cdot (H_2^0 - H_1^0 - K \cdot S_{i,j}^2 \cdot i + t) \right\} \quad K = \frac{1-k}{2 \cdot r} = \frac{1-0,13}{2 \cdot (6370000)} = 0,000000683$$

$$a = \frac{\sin^2 Z_{1,2}^0}{S_{1,2} \cdot 100} \cdot \left( \frac{200 \cdot 10000}{\pi} \right) \quad b = -a \quad -l = (Z_{1,2}^0 - Z_{1,2}) \cdot 10000$$

DN	BN	S <sub>i-j</sub>	H <sub>j</sub> <sup>0</sup> - H <sub>i</sub> <sup>0</sup>	K · S <sub>i-j</sub> <sup>2</sup>	i	t	Z <sub>i-j</sub> <sup>0</sup>	Z <sub>i-j</sub>	a (″)	-l (″)
2	3	2194,193	-100,748	0,3288	1,42	1,75	102,92100	102,92374	2,8953	-27,4
	5	1924,510	-69,357	0,2529	1,42	1,81	102,28878	102,28561	3,3037	37,7
	6	1875,414	-15,142	0,2402	1,42	1,76	102,51060	102,51359	3,3943	-29,9
3	2	2194,200	100,748	0,3288	1,61	1,90	97,08010	97,08010	2,8953	0
	5	1562,956	31,391	0,1668	1,61	1,87	98,71777	98,71777	4,0715	0
	6	1495,632	85,606	0,1528	1,61	1,83	96,35728	96,35727	4,2426	0
5	2	1924,500	69,357	0,2529	1,45	1,88	97,70083	97,70589	3,3037	-50,6
	3	1562,961	-31,391	0,1668	1,45	1,82	101,27016	101,27326	4,0715	-31,0

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②  $v_{2,j} = a \cdot dh_1 + b \cdot dh_2 - l$   $dh_3$  is known

$$\begin{aligned} v_{2-3} &= 2,8953 \cdot dh_2 - 2,8953 \cdot dh_3 - 27,4 \\ v_{2-5} &= 3,3037 \cdot dh_2 - 3,3037 \cdot dh_5 + 31,7 \\ v_{2-6} &= 3,3943 \cdot dh_2 - 3,3943 \cdot dh_6 - 29,9 \\ v_{3-2} &= 2,8953 \cdot dh_3 - 2,8953 \cdot dh_2 + 0,0 \\ v_{3-5} &= 4,0715 \cdot dh_3 - 4,0715 \cdot dh_5 + 0,0 \\ v_{3-6} &= 4,2426 \cdot dh_3 - 4,2426 \cdot dh_6 + 0,0 \\ v_{5-2} &= 3,3037 \cdot dh_5 - 3,3037 \cdot dh_2 - 50,6 \\ v_{5-3} &= 4,0715 \cdot dh_5 - 4,0715 \cdot dh_3 - 31,0 \end{aligned}$$

I rewrote it with unknowns for  $v = A \cdot x - l$

$$\begin{aligned} v_{2-3} &= 2,8953 \cdot dh_2 + 0 \cdot dh_5 + 0 \cdot dh_6 - 27,4 \\ v_{2-5} &= 3,3037 \cdot dh_2 - 3,3037 \cdot dh_5 + 0 \cdot dh_6 + 31,7 \\ v_{2-6} &= 3,3943 \cdot dh_2 + 0 \cdot dh_5 - 3,3943 \cdot dh_6 - 29,9 \\ v_{3-2} &= -2,8953 \cdot dh_2 + 0 \cdot dh_5 + 0 \cdot dh_6 + 0,0 \\ v_{3-5} &= 0 \cdot dh_2 - 4,0715 \cdot dh_5 + 0 \cdot dh_6 + 0,0 \\ v_{3-6} &= 0 \cdot dh_2 + 0 \cdot dh_5 - 4,2426 \cdot dh_6 + 0,0 \\ v_{5-2} &= -3,3037 \cdot dh_2 + 3,3037 \cdot dh_5 + 0 \cdot dh_6 - 50,6 \\ v_{5-3} &= 0 \cdot dh_2 + 4,0715 \cdot dh_5 + 0 \cdot dh_6 - 31,0 \end{aligned}$$

$$\underline{N} = \underline{A}^T \underline{A} = \begin{bmatrix} 50,1154 & -21,8287 & -11,5215 \\ -21,8287 & 54,9834 & 0,0000 \\ -11,5215 & 0,0000 & 29,5212 \end{bmatrix}$$

$$\underline{Q} = \underline{N}^{-1} = \begin{bmatrix} 0,0271 & 0,0107 & 0,0106 \\ 0,0107 & 0,0225 & 0,0042 \\ 0,0106 & 0,0042 & 0,0380 \end{bmatrix}$$

$$\begin{aligned} v_{2-3} &= 2,8953 \cdot dh_2 - 27,4 \\ v_{2-5} &= 3,3037 \cdot dh_2 - 3,3037 \cdot dh_5 + 31,7 \\ v_{2-6} &= 3,3943 \cdot dh_2 - 3,3943 \cdot dh_6 - 29,9 \\ v_{3-2} &= -2,8953 \cdot dh_2 + 0,0 \\ v_{3-5} &= -4,0715 \cdot dh_5 + 0,0 \\ v_{3-6} &= -4,2426 \cdot dh_6 + 0,0 \\ v_{5-2} &= 3,3037 \cdot dh_5 - 3,3037 \cdot dh_2 - 50,6 \\ v_{5-3} &= 4,0715 \cdot dh_5 - 31,0 \end{aligned}$$

using  $v = A \cdot x - l$  format;

$$\begin{bmatrix} v_{2-3} \\ v_{2-5} \\ v_{2-6} \\ v_{3-2} \\ v_{3-5} \\ v_{3-6} \\ v_{5-2} \\ v_{5-3} \end{bmatrix} = \begin{bmatrix} 2,8953 & 0 & 0 \\ 3,3037 & -3,3037 & 0 \\ 3,3943 & 0 & -3,3943 \\ -2,8953 & 0 & 0 \\ 0 & -4,0715 & 0 \\ 0 & 0 & -4,2426 \\ -3,3037 & 3,3037 & 0 \\ 0 & 4,0715 & 0 \end{bmatrix} \begin{bmatrix} dh_2 \\ dh_5 \\ dh_6 \end{bmatrix} - \begin{bmatrix} 27,4 \\ -31,7 \\ 29,9 \\ 0 \\ 0 \\ 0 \\ 50,6 \\ 31,0 \end{bmatrix}$$

$$\underline{n} = \underline{A}^T \underline{l} = \begin{bmatrix} -91,32 \\ 398,06 \\ -101,30 \end{bmatrix}$$

$$\underline{x} = \underline{Q} \underline{x} - \underline{n} = \begin{bmatrix} dh_2 \\ dh_5 \\ dh_6 \end{bmatrix} = \begin{bmatrix} 0,74 \\ 7,53 \\ -3,14 \end{bmatrix} \text{ cm}$$

The Exact value of the Unknown;

$$\begin{bmatrix} H_2 \\ H_5 \\ H_6 \end{bmatrix} = \begin{bmatrix} H_2^0 \\ H_5^0 \\ H_6^0 \end{bmatrix} + \begin{bmatrix} dh_2 \\ dh_5 \\ dh_6 \end{bmatrix}$$

$$\begin{bmatrix} H_2 \\ H_5 \\ H_6 \end{bmatrix} = \begin{bmatrix} 1117,001 \\ 1047,644 \\ 1101,859 \end{bmatrix} + \begin{bmatrix} 0,74 \\ 7,53 \\ -3,14 \end{bmatrix} = \begin{bmatrix} 1117,0084 \\ 1047,7193 \\ 1101,8276 \end{bmatrix}$$

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① Corrections  $\underline{y} = \underline{A} \cdot \underline{x} - \underline{1}$  (cc = second)

$$\begin{bmatrix} \sqrt{2}_{2-3} \\ \sqrt{2}_{2-5} \\ \sqrt{2}_{2-6} \\ \sqrt{2}_{3-2} \\ \sqrt{2}_{3-5} \\ \sqrt{2}_{3-6} \\ \sqrt{2}_{5-2} \\ \sqrt{2}_{5-3} \end{bmatrix} = \begin{bmatrix} 2,8953 & 0 & 0 \\ 3,3037 & -3,3037 & 0 \\ 3,3943 & 0 & -3,3943 \\ -2,8953 & 0 & 0 \\ 0 & -4,0715 & 0 \\ 0 & 0 & -4,2426 \\ -3,3037 & 3,3037 & 0 \\ 0 & 4,0715 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0,94 \\ 7,53 \\ -3,14 \end{bmatrix} - \begin{bmatrix} 27,4 \\ -31,7 \\ 29,9 \\ 0 \\ 0 \\ 0 \\ 50,6 \\ 31,10 \end{bmatrix} = \begin{bmatrix} -25,24 \\ 3,28 \\ -16,70 \\ -2,13 \\ -30,66 \\ 13,36 \\ -28,14 \\ -0,30 \end{bmatrix}$$

Adjusted Measures  $\hat{z}_{i-j} = \underline{z}_{i-j} + \underline{vz}_{i-j}$

$$\begin{bmatrix} \hat{z}_{2-3} \\ \hat{z}_{2-5} \\ \hat{z}_{2-6} \\ \hat{z}_{3-2} \\ \hat{z}_{3-5} \\ \hat{z}_{3-6} \\ \hat{z}_{5-2} \\ \hat{z}_{5-3} \end{bmatrix} = \begin{bmatrix} z_{2-3} \\ z_{2-5} \\ z_{2-6} \\ z_{3-2} \\ z_{3-5} \\ z_{3-6} \\ z_{5-2} \\ z_{5-3} \end{bmatrix} + \begin{bmatrix} \sqrt{2}_{2-3} \\ \sqrt{2}_{2-5} \\ \sqrt{2}_{2-6} \\ \sqrt{2}_{3-2} \\ \sqrt{2}_{3-5} \\ \sqrt{2}_{3-6} \\ \sqrt{2}_{5-2} \\ \sqrt{2}_{5-3} \end{bmatrix} = \begin{bmatrix} \hat{z}_{2-3} \\ \hat{z}_{2-5} \\ \hat{z}_{2-6} \\ \hat{z}_{3-2} \\ \hat{z}_{3-5} \\ \hat{z}_{3-6} \\ \hat{z}_{5-2} \\ \hat{z}_{5-3} \end{bmatrix} = \begin{bmatrix} 102,92373 \\ 102,28561 \\ 100,51359 \\ 97,08010 \\ 98,71777 \\ 96,35727 \\ 97,70589 \\ 101,27326 \end{bmatrix} + \begin{bmatrix} -25,24 \\ 3,28 \\ -16,70 \\ -2,13 \\ -30,66 \\ 13,36 \\ -28,14 \\ -0,30 \end{bmatrix} = \begin{bmatrix} 102,92121 \\ 102,28653 \\ 100,51192 \\ 97,07988 \\ 98,71470 \\ 96,35861 \\ 97,70308 \\ 101,27323 \end{bmatrix}$$

Control of Adjusted measures  $\bar{z}$

$$\hat{z}_{i-j} = \underline{z}_{i-j} + \underline{vz}_{i-j} = \hat{z}_{i-j} = \arccot \left\{ \frac{1}{S_{i-j}} \cdot (H_j - H_i - K \cdot S_{i-j}^2 - i + t) \right\}$$

$$\begin{bmatrix} 102,92121 \\ 102,28653 \\ 100,51192 \\ 97,07988 \\ 98,71470 \\ 96,35861 \\ 97,70308 \\ 101,27323 \end{bmatrix} = \begin{bmatrix} 102,92121 \\ 102,28653 \\ 100,51192 \\ 97,07988 \\ 98,71470 \\ 96,35861 \\ 97,70308 \\ 101,27323 \end{bmatrix} \quad \checkmark$$

Square mean Error  $\bar{s}$

$$m_0 = \pm \sqrt{\frac{\underline{v}^T \underline{v}}{n-u}} = \pm \sqrt{\frac{2917,60}{8-3}} = \pm 24,16^{cc}$$

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④ Mean Error of Unknowns is

$$\underline{Q}_{xx} = \underline{N}^{-1} = \begin{bmatrix} 0,0271 & 0,0107 & 0,0106 \\ 0,0107 & 0,0225 & 0,0042 \\ 0,0106 & 0,0042 & 0,0380 \end{bmatrix}$$

$$m_{H_2} = \pm m_0 \sqrt{q_{xx}} = \pm 24,16 \sqrt{0,0271} = \pm 3,97 \text{ cm}$$

$$m_{H_5} = \pm m_0 \sqrt{q_{yy}} = \pm 24,16 \sqrt{0,0225} = \pm 3,62 \text{ cm}$$

$$m_{H_6} = \pm m_0 \sqrt{q_{zz}} = \pm 24,16 \sqrt{0,0380} = \pm 4,71 \text{ cm}$$

Mean Error of Measures ;

$$m_{\hat{p}_i} = \pm \frac{m_0}{\sqrt{P_i}} \text{ cc} \quad \text{Since the weights are taken equal, the mean error of the measures is equal to the mean square error.}$$

Average Error of Adjusted Measures ;

$$\underline{Q}_{\hat{p}\hat{p}} = \underline{A} \cdot \underline{Q}_{xx} \cdot \underline{A}^T = \begin{bmatrix} 0,23 & 0,16 & 0,16 & -0,23 & -0,13 & -0,13 & -0,16 & 0,13 \\ 0,16 & 0,31 & 0,11 & -0,16 & 0,16 & -0,09 & -0,31 & -0,16 \\ 0,16 & 0,11 & 0,51 & -0,16 & -0,09 & 0,40 & -0,11 & 0,09 \\ -0,23 & -0,16 & -0,16 & 0,23 & 0,13 & 0,13 & 0,16 & -0,13 \\ -0,13 & 0,16 & -0,09 & 0,13 & 0,37 & 0,07 & -0,16 & -0,37 \\ -0,13 & -0,09 & 0,40 & 0,13 & 0,07 & 0,68 & 0,09 & -0,07 \\ -0,16 & -0,31 & -0,11 & 0,16 & -0,16 & 0,09 & 0,31 & 0,16 \\ 0,13 & -0,16 & 0,09 & -0,13 & -0,37 & -0,07 & 0,16 & 0,37 \end{bmatrix}$$

$$m_{\hat{z}_i} = \pm m_0 \cdot \sqrt{Q_{\hat{p}\hat{p}_i}} \quad \text{Average of adjusted measures}$$

$$m_{\hat{z}_1} = 11,51^{\text{cc}} \quad m_{\hat{z}_2} = 13,36^{\text{cc}} \quad m_{\hat{z}_3} = 17,19^{\text{cc}} \quad m_{\hat{z}_4} = 11,51^{\text{cc}} \quad m_{\hat{z}_5} = 14,74^{\text{cc}}$$

$$m_{\hat{z}_6} = 19,38^{\text{cc}} \quad m_{\hat{z}_7} = 13,36^{\text{cc}} \quad m_{\hat{z}_8} = 14,74^{\text{cc}}$$

Average Error of Corrections

$$\underline{Q}_{ww} = \underline{Q}_{\hat{p}\hat{p}} - \underline{Q}_{\hat{p}\hat{p}}^T \Rightarrow \text{Covariance matrix of corrections}$$

$$\underline{P}^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\underline{Q}_{ww} = \begin{bmatrix} 0,77 & 0,16 & 0,16 & -0,23 & -0,13 & -0,13 & -0,16 & 0,13 \\ 0,16 & 0,69 & 0,11 & -0,16 & 0,16 & -0,09 & -0,31 & -0,16 \\ 0,16 & 0,11 & 0,51 & -0,16 & -0,09 & 0,40 & -0,11 & 0,09 \\ -0,23 & -0,16 & -0,16 & 0,77 & 0,13 & 0,13 & 0,16 & -0,13 \\ -0,13 & 0,16 & -0,09 & 0,13 & 0,63 & 0,07 & -0,16 & -0,37 \\ -0,13 & -0,09 & 0,40 & 0,13 & 0,07 & 0,72 & 0,09 & -0,07 \\ -0,16 & -0,31 & -0,11 & 0,16 & -0,16 & 0,09 & 0,69 & 0,16 \\ 0,13 & -0,16 & 0,09 & -0,13 & -0,37 & -0,07 & 0,16 & 0,63 \end{bmatrix}$$

$$m_{w_i} = \pm m_0 \cdot \sqrt{Q_{ww_i}} \quad \text{Average error of corrections}$$

\* Calculated with Matlab

$$\begin{aligned} m_{w_1} &= 21,24^{\text{cc}} & m_{w_4} &= 21,24^{\text{cc}} & m_{w_7} &= 20,13^{\text{cc}} \\ m_{w_2} &= 20,13^{\text{cc}} & m_{w_5} &= 19,14^{\text{cc}} & m_{w_8} &= 19,14^{\text{cc}} \\ m_{w_3} &= 16,97^{\text{cc}} & m_{w_6} &= 13,58^{\text{cc}} & & \end{aligned}$$

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