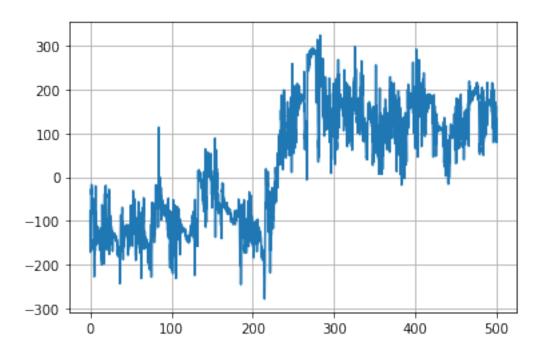
## accelerometre\_gyroscope

## July 1, 2020

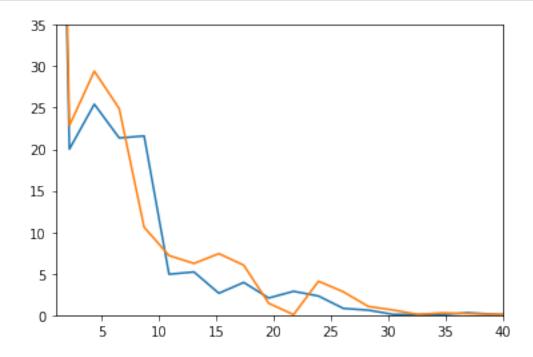
```
[42]: import pandas as pd
      data = pd.read_csv("log_event.csv", delimiter=";")
      data.head()
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      [5 rows x 194 columns]
 [44]: data = data[['event', 'TAx', 'TAy', 'TAz', 'TGx', 'TGy', 'TGz', 'Iuser_int']]
      data=(data-data.mean())/data.std()
 [35]: data.head()
      taille = len(data)
[189]: import numpy as np
      t = np.linspace(0,500, taille)
      plt.grid()
      plt.plot(t, data.iloc[:,2])
[189]: [<matplotlib.lines.Line2D at 0x7f8ed350a198>]
```



```
[219]: from scipy.fft import fft
      from scipy.signal.windows import hann
      from scipy.signal import convolve
      from scipy.fftpack import fftfreq
      window = hann(7)
      def tracerFFT(i):
          y = np.abs(data.iloc[:,i].dropna())
          y = convolve(window, y)
          y = fft(y)
          N = taille
          fs = 10
          T = 1/fs
          xf = np.linspace(0.0, 10000, N//2)
          plt.xlim([1,1000])
          plt.ylim([0,10000])
          plt.plot(xf,np.abs(y[0:N//2]))
          return None
      def tracerFFTData(data, taille):
          signal = convolve(window, np.abs(data))
          N = taille
          fs=100
          Ts = 1.0/fs # sampling interval in time
          t = np.arange(0, taille, Ts) # time vector as scipy arange field / numpy.
       \rightarrowndarray
```

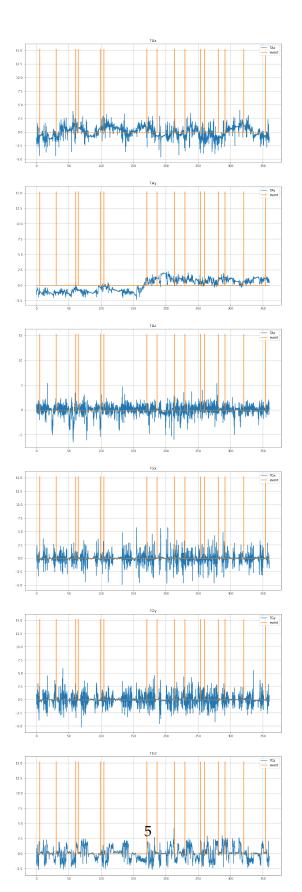
```
FFT = abs(scipy.fft.fft(signal))
FFT_side = FFT[range(int(N/2))] # one side FFT range
freqs = fftfreq(signal.size, t[1]-t[0]) #t[1] - t[0], sample spacing
freqs_side = freqs[range(int(N/2))] # one side frequency range
#fig, ax = plt.subplots()
plt.xlim([1,40])
plt.ylim([0,35])
plt.plot(freqs_side, FFT_side)
return None
```

[221]: tracerFFTData(data.iloc[:,1][0:40], 40) tracerFFTData(data.iloc[:,1][120:160], 40)



```
ax[i].grid()
ax[i].title.set_text((data.columns)[i+1])
ax[i].plot(np.linspace(0,360,3721), data.iloc[:,i+1], label=data.

columns[i+1])
ax[i].plot(np.linspace(0,360,3721), data.iloc[:,0], label=data.columns[0])
ax[i].legend(loc='upper right')
```



L'accélération selon l'axe *x* semble la plus pertinente. Celle selon *y* est compliquée à analyser d'autant plus que comme les essais ont été réalisés dans un terrain en pente, ca fausse les courbes.

## 0.1 Plot de l'accélération selon x et du courant consommé en fonction du temps

```
[51]: fig, ax = plt.subplots(1, figsize=(15,10))
    ax.plot(np.linspace(0,360,3721), data.iloc[:,0], label=data.columns[0])
    ax.plot(np.linspace(0,360,3721), data.iloc[:,1],label=data.columns[1])
    ax.plot(np.linspace(0,360,3721), data.iloc[:,-1], label=data.columns[-1])
    ax.legend(loc='upper right')
```

[51]: <matplotlib.legend.Legend at 0x7fc207446518>

