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### **Lab 3. Noise Filtering in Images**

#### **1. Adding Salt-and-Pepper Noise**

Salt-and-pepper noise was added to the selected image at three different noise levels: 3%, 5%, and 15%.

This type of noise appears as random black and white pixels and is considered impulsive noise.

#### **2. Applying Noise-Reducing Filters**

Three different filters were applied to reduce the noise:

- Median Filter with window sizes 3×3, 5×5, and 7×7
- Gaussian Filter
- Bilateral Filter

#### **3. Adding Gaussian Noise**

Gaussian noise was added at three levels: 5%, 10%, and 15%.

This noise creates random variations in brightness and is considered smooth, continuous noise.

#### **4. Filtering Gaussian Noise**

The same three filters were used to reduce Gaussian noise.

#### **5. Image Display**

The following were displayed:

- The original image
- The noisy images
- The filtered images
- PSNR values for each filtering result

### **Analysis and Results**

First: Analysis of Salt-and-Pepper Noise Reduction

PSNR Values Obtained:

**3% Noise → Median: 32.25, Gaussian: 30.09, Bilateral: 30.64**

**5% Noise → Median: 31.25, Gaussian: 29.56, Bilateral: 30.54**

**15% Noise → Median: 30.84, Gaussian: 28.44, Bilateral: 29.77**

### **Conclusion**

- The Median Filter consistently performed the best in all salt-and-pepper noise cases. This is because the median filter replaces each pixel with the median of its neighborhood, effectively removing impulsive noise.
- The Gaussian filter was not very effective, as smoothing does not remove extreme pixel values.
- The Bilateral filter performed moderately well, preserving edges but not removing all impulse noise.

### **Important Note**

- Higher noise levels required larger window sizes ( $5 \times 5$  and  $7 \times 7$ ), but larger windows also increased image blurring.

### **Second: Analysis of Gaussian Noise Reduction**

- PSNR Values Obtained:

5% Noise → Median: 31.87, Gaussian: 31.55, Bilateral: 30.74

10% Noise → Median: 30.83, Gaussian: 31.26, Bilateral: 30.72

15% Noise → Median: 30.47, Gaussian: 30.86, Bilateral: 30.66

### **Conclusion**

- The Gaussian filter was generally the most effective for Gaussian noise. It is inherently designed to reduce smooth and dispersed noise.
- The Median filter gives acceptable results but may distort fine details.
- The Bilateral filter preserved edges well but did not achieve the highest PSNR.

### **Qualitative Analysis**

#### **1. Median Filter**

- Best for salt-and-pepper noise
- Completely removes extreme values
- Larger kernels increase blurring

#### **2. Gaussian Filter**

- Best for Gaussian noise
- Smooths random variations effectively
- Can create edge blurring

#### **3. Bilateral Filter**

- Preserves edges very well

- Suitable for low to moderate noise
- Not always the highest PSNR

#### 4.PSNR Interpretation

- Higher PSNR → better image quality
- Median achieved highest PSNR for salt-and-pepper
- Gaussian achieved highest PSNR for Gaussian noise

#### Final Conclusion

1. For salt-and-pepper noise → Median filter is the best choice.
2. For Gaussian noise → Gaussian filter provides the best results.
3. Bilateral filter is useful when we need a balance between noise removal and edge preservation.
4. Higher noise levels require larger kernel sizes → but this increases blurring.

#### Original picture



#### Gray Picture



## All Picture



## Results

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app.py
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt

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Analysis of Salt-and-Pepper Noise Reduction:
3% Noise - Median 3x3 PSNR: 32.25
3% Noise - Gaussian PSNR: 30.09
3% Noise - Bilateral PSNR: 30.64
5% Noise - Median 5x5 PSNR: 31.25
5% Noise - Gaussian PSNR: 29.56
5% Noise - Bilateral PSNR: 30.54
15% Noise - Median 7x7 PSNR: 30.84
15% Noise - Gaussian PSNR: 28.44
15% Noise - Bilateral PSNR: 29.77

Analysis of Gaussian Noise Reduction:
5% Noise - Median 3x3 PSNR: 31.87
5% Noise - Gaussian PSNR: 31.55
5% Noise - Bilateral PSNR: 30.74
10% Noise - Median 5x5 PSNR: 30.83
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Qualitative Analysis:
- Median filter is effective for salt-and-pepper noise as it replaces pixels with median values, reducing impulse noise.
- Gaussian filter smooths the image and is better for Gaussian noise but can blur edges.
- Bilateral filter preserves edges while reducing noise, performing well on both types.
- Higher noise levels require larger kernel sizes for median filter to be effective, but this increases blurring.
- PSNR values indicate that bilateral filter often achieves higher quality for both noise types.
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