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Question 1: Program Newton's Method and apply it to the function $f(x)=x^3+4x^2-10$. This function has a rootiin [1,2][1,2][1,2]

```
import numpy as np
In [ ...
         import pandas as pd
         def fixed_point (p0,e, max_it,g):
            p = np.zeros(max_it)
            p[0] = p0
            i = 1
            while i < max_it:</pre>
              try:
                p[i] = g(p[i-1])
              except:
                print('Arithmetic error')
                return(p)
              if abs(p[i] - p[i-1]) <= e:
                return(p)
                i += 1
              print('max number of iteration exceeded')
              return(p)
         def newton_bisection(a, b, e, max_it, f):
            FA = f(a)
            i = 0
            p = np.zeros(max_it)
            while i< max_it:</pre>
              p[i] = (a + b) / 2
              FP = f(p[i])
              if (abs(b - a) \le e/2):
                return p
              if FA * FP < 0:
                b = p[i]
              else:
                  a = p[i]
                  FA = FP
              i += 1
            return(p)
            print('Warning. Max Iter Reached!')
         def f(x):
            y = x**3 + 4 * x**2 - 10
            return y
         def g1(x):
            y = x - (x**3 + 4 * x**2 - 10)
            return y
```

```
def g2(x):
    y = np.sqrt(10/x - 4 * x)
    return y

def g3(x):
    y = (1/2) * np.sqrt(10 - x**3)
    return y

def g4(x):
    y = np.sqrt(10/(4+x))
    return y

def g5(x):
    y = x - (x**3 + 4 * x**2 - 10)/(3 * x**2 + 8 * x)
    return y
```

```
p0 = 1.35
In [ ...
         max it = 30
         e = 1e-8
         a = 1
         b = 2
         p1 = fixed_point(p0, e, max_it, g1)
         p2 = fixed_point(p0, e, max_it, g2)
         p3 = fixed_point(p0, e, max_it, g3)
         p4 = fixed_point(p0, e, max_it, g4)
         p5 = fixed_point(p0, e, max_it, g5)
         pn = newton_bisection(a, b, e, max_it, f)
        max number of iteration exceeded
         np.array([p1, p2, p3, p4, p5, pn]).reshape(6,max_it).transpose()
```

```
],
              [1.599625 , 1.41683006, 1.37291888, 1.36717185, 1.36534501,
              1.25
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                                , 0.
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              1.34375
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              1.359375 ],
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              1.3671875 ],
              [0. , 0.
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              1.36328125],
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              1.36523438],
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              1.36499023],
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              1.36517334],
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              [0. , 0.
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              [0. , 0.
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                                                    , 0.
              1.36522961],
              [0. , 0.
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              1.36523008],
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              1.36522985],
              [0. , 0.
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                                          , 0.
              1.36522996],
              [0. , 0.
                                 , 0.
                                          , 0.
                                                    , 0.
              1.36523002],
              [0. , 0.
                                 , 0.
                                           , 0.
                                                    , 0.
              1.36522999],
              [0. , 0.
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                                                    , 0.
              1.36523001],
              [0. , 0.
                                 , 0.
                                          , 0.
                                                    , 0.
              1.36523002],
                                , 0.
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              1.36523001],
```

```
[0. , 0. , 0. , 0. , 0. , 0. , 0. , 1.36523001],
[0. , 0. , 0. , 0. , 0. , 0. , 0. , 0. ]])
```

pd.DataFrame(np.array([p1,p2,p3,p4,p5,pn]).reshape(6,max_it).transpose(), co

Out[... g1 g2 g3

			_
1.3500000000000000	1.3500000000000000	1.3500000000000000	1.350
1.599624999999998	1.416830055937340	1.372918879613796	1.367
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.000
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
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0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
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0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
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g1 g2 g3

```
## Using a Pandas data frame, we can look at the convergence.
all_ps = {'p1' :p1, 'p2':p2, 'p3':p3, 'p4':p4, 'p5':p5, 'pn':pn}
#print(all_ps)

pd.DataFrame (dict([(k, pd.Series(v)) for k, v in all_ps.items()]))
```

Out[... p1 p2 p3

			_
1.3500000000000000	1.3500000000000000	1.3500000000000000	1.350
1.599624999999998	1.416830055937340	1.372918879613796	1.367
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
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0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.000
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.006
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	1.599624999999998 0.000000000000000000000000000	1.599624999999998 1.416830055937340 0.00000000000000000 0.0000000000000000 0.00000000000000000 0.0000000000000000 0.0000000000000000 0.0000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.000000000000000 0.0000000000000000 0.000000000000000 0.0000000000000000 0.000000000000000 0.0000000000000000 0.0000000000000000 0.000000000000000 0.0000000000000000 0.0000000000000000 0.000000000000000 0.00000000000000000 0.0000000000000000 0.00000000000000000 0.0000000000000000000 0.000000000000000000 0.00000000000000000 0.00000000000000000000 0.000000000000000000 0.000000000000000000 0.00000000000000000000000000000000000	1.59962499999998 1.416830055937340 1.372918879613796 8.0000000000000000 0.00000000000000 0.000000000000000 8.000000000000000 0.00000000000000 0.00000000000000 8.00000000000000 0.00000000000000 0.0000000000000 8.000000000000000 0.0000000000000 0.000000000000000 8.00000000000000 0.0000000000000 0.00000000000000 8.00000000000000 0.0000000000000 0.00000000000000 8.000000000000000 0.00000000000000 0.00000000000000 8.000000000000000 0.000000000000000 0.00000000000000 8.0000000000000000 0.000000000000000 0.000000000000000 8.000000000000000 0.000000000000000 0.000000000000000 8.000000000000000 0.000000000000000 0.000000000000000 8.000000000000000 0.000000000000000 0.000000000000000 8.000000000000000 0.000000000000000000000 0.0000000000000000 8.000000000000000 0.00000000000000000000000000 0.00000000000000000000000000000000000

p1 p2 p3

```
## Testing Newton's Method
In [ ...
         def q1(x):
           y = np.cos(x)
           return y
         def q2(x):
           y = x + (np.cos(x) - x)/(np.sin(x) + 1)
           return y
         p0 = np.pi / 4
         max it = 10
         e = 1e - 8
         p1 = fixed_point(p0, e, max_it, g1)
         p2 = fixed_point(p0, e, max_it, g1)
         all_ps = {'p1':p1, 'p2':p2}
         D = pd.DataFrame(dict([(k,pd.Series(v)) for k, v in all_ps.items()]))
         pd.options.display.float format = '{:,.15f}'.format
         print(D)
        max number of iteration exceeded
        max number of iteration exceeded
                          p1
        0 0.785398163397448 0.785398163397448
        1 0.707106781186548 0.707106781186548
        2 0.000000000000000 0.000000000000000
        3 0.000000000000000 0.000000000000000
        4 0.000000000000000 0.000000000000000
        5 0.000000000000000 0.000000000000000
        6 0.000000000000000 0.000000000000000
        7 0.000000000000000 0.000000000000000
        8 0.000000000000000 0.0000000000000000
        9 0.000000000000000 0.000000000000000
```

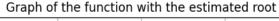
Multiple Roots
def fixed_point(p0, e, max_it, g):
 p = []
 p.append(p0)
 i = 1
 while i <= max_it:
 try:
 p.append(g(p0))
 except:
 print('Arithmetic error')
 return(p)</pre>

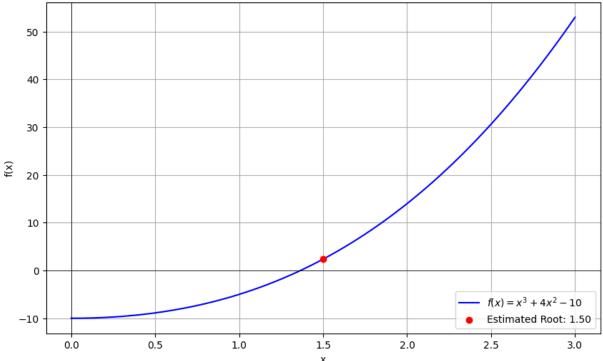
```
if abs(p[i] - p0) <= e:
    return(p)
p0 = p[i]
i += 1

print('max number of iteration exceeded')
return(p)</pre>
```

Question 2: Use the `matplotlib library to plot the function. Place a red dot on the figure where the estimated root is. Make sure that the xxx and yyy axes are visible.

```
import matplotlib.pyplot as plt
In [ ...
         # Get the estimated root using the newton bisection method
         pn = newton_bisection(a, b, e, max_it, f)
         estimated_root = pn[0]
         x_values = np.linspace(0, 3, 400)
In [ ...
         y_values = f(x_values)
         # Plotting the function and the estimated root on the same graph
         plt.figure(figsize=(10, 6))
         plt.plot(x_values, y_values, label=r'f(x) = x^3 + 4x^2 - 10, color='blue'
         plt.scatter(estimated_root, f(estimated_root), color='red', zorder=5, label=
         plt.axhline(0, color='black', linewidth=0.5)
         plt.axvline(0, color='black', linewidth=0.5)
         plt.title("Graph of the function with the estimated root")
         plt.xlabel("x")
         plt.ylabel("f(x)")
         plt.grid(True)
         plt.legend()
         plt.show()
```





Question 3: Show that for a fixed point iteration procedure pn+1=g(pn)pn+1=g(pn)p_{n+1}=g(p_n) with $|g'(x)| \le K < 1, |pn-p| \le K n 1 - K |p 1 - p 0|g$ $'(x)| \le K < 1, |pn-p| \le K n 1 - K |p 1 - p 0|g'(x)| \setminus leq K < 1, |p_n-p| \setminus leq \setminus cfrac\{K^n\}\{1-K\} |p_1-p_0|g'(x)|$

Proof:

Given a fixed point iteration procedure defined by $pn+1=g(pn)pn+1=g(pn)\ p_-\{n+1\}\ =\ g(p_-n)\ \text{we aim to}$ $demonstrate\ that\ if\ |g'(x)|\le K<1|g'(x)|\le K<1\ |g'(x)|\ \setminus \{K<1\}\ |g'(x)|\ \setminus \{K>1\}\ |g'(x)|\ \setminus \{K$

We will employ Mathematical Induction.

Consider the error iteration formula for fixed point iteration: en+1=|pn+1-p|en+1=|pn+1-p| e_{n+1} = $|p_{n+1}-p|$ en= $|p_{n-1}-p|$ en= $|p_{n-1}-p|$ en= $|p_{n-1}-p|$ en= $|p_{n-1}-p|$

By invoking the Mean Value Theorem, which states:

```
If a function (f) is continuous on the closed interval
([a, b]) and differentiable on the open interval ((a,
b)), then there exists at least one number ( c ) in the
open interval ((a, b)) such that: f'(c)=f(b)-f(a)b-af
 '(c)=f(b)-f(a)b-a f'(c) = \frac{f(b)-f(a)}{b-a}
there exists a number (c) between (p) and (p_n)
such that: g'(c)=g(pn)-g(p)pn-pg'(c)=g(pn)-g(p)pn-p
g'(c) = \frac{g(p_n)-g(p)}{p_n-p}
Rearranging, we obtain: g(pn)-g(p)=g
'(c)(pn-p)g(pn)-g(p)=g'(c)(pn-p) g(p_n)-g(p) =
g'(c)(p_n-p)
Given (p_{n+1} = g(p_n)) and (p = g(p)) (since (p)
is a fixed point), substituting into the above equation
yields: pn+1-p=g'(c)(pn-p)pn+1-p=g'(c)(pn-p) p_{n+1}-p=
g'(c)(p_n-p)
Taking the absolute value, we get: |pn+1-p|=|g|
'(c)|\times|pn-p||pn+1-p|=|g'(c)|\times|pn-p||p_{n+1}-p|=
 |g'(c)| \times |p_n-p| or equivalently, en+1=|g|
 '(c) | \times enen+1 = | g'(c) | \times en e_{n+1} = | g'(c) | \times enen
Given the condition (|g'(x)| \setminus leq K), it follows that:
en+1≤K×enen+1≤K×en e_{n+1} \leg K \times e_n
Base Case: For (n = 1): e2 \le K \times e1 = 2 
\times e_1
This is validated by the previous equation.
Inductive Step:
Assuming the inequality holds for (n = k):
ek+1 \le Kk1-K \times e1ek+1 \le Kk1-K \times e1 e_{k+1} \setminus e_{Kk1-K \times e1}
\times e_1
From our derived inequality, we infer:
ek+2 \le K \times ek+1 e_{k+2} \le K \times ek+1 e_{k+1}
```

Substituting our inductive assumption into this gives: $ek+2 \leq K \times Kk1-K \times e1ek+2 \leq K \times Kk1-K \times e1 \ e_{k+2} \ \text{leq } K \ \text{times} \\ \text{frac}\{K^k\}\{1-K\} \ \text{times} \ e_1 \ \text{or} \\ ek+2 \leq Kk+11-K \times e1ek+2 \leq Kk+11-K \times e1 \ e_{k+2} \ \text{leq} \\ \text{frac}\{K^k\{k+1\}\}\{1-K\} \ \text{times} \ e_1$

By induction, this inequality stands for all (n).

Lastly, given ($e_1 = |p_1 - p_0|$), we deduce: $e_1 = |p_1 - p_0|$), we deduce: $e_1 = |p_1 - p_0|$ ($e_1 = |p_1 - p_0|$), we deduce: $e_1 = |p_1 - p_0|$ ($e_1 = |p_1 - p_0|$)

This completes the proof of the given inequality.