Samuel **Leong** Chee Weng

ELECTRICAL AND COMPUTER ENGINEER · INTEREST IN ROBOTICS, COMPUTER VISION AND EMBEDDED SYSTEMS

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Education

Carnegie Mellon University (CMU)	*Pittsburgh, PA, USA*
MASTERS OF SCIENCE, MAJOR IN ELECTRICAL AND COMPUTER ENGINEERING (QPA 4.0)	*Class of 2023*

- 16-833: Localization and Mapping A
- 16-761: Mobile Robots A
- 16-883: Provably Safe Robotics A
- 18-661: Intro. to Machine Learning A

- 16-824: Visual Learning and Recognition A
- 18-848: Embedded Deep Learning (TinyML) A
- 18-642: Embedded Software Engineering A
- 18-660: Optimization A

NOTE: CMU does not issue A+ for 18-xxx courses. A+ grades are sometimes given in 16-xxx courses.

Carnegie Mellon University (CMU)	*Pittsburgh, PA, USA*
BACHELORS OF SCIENCE, MAJOR IN ELECTRICAL AND COMPUTER ENGINEERING, MINOR IN ROBOTICS UNIVERSITY HONORS (QPA 3.96)	*Class of 2022*

- 16-385: Computer Vision A
- 18-349: Embedded Systems A
- 18-370: Fund. of Controls A
- 21-241: Matrices and Linear Transformations A
- 36-225: Intro. to Probability Theory A
- 21-259: Calculus in 3D A
- 21-260: Differential Equations A

- 16-384: Robot Kinematics and Dynamics A
- 16-311: Intro. to Robotics A
- 18-213: Intro. to Computer Systems A
- 18-240: Struct. and Design of Digital Systems A
- 18-220: Analog Circuits and Devices A
- 18-290: Signals and Systems A
- 16-467: Human-Robot Interaction A

NOTE: CMU does not issue +/− grades for undergraduate courses.

Skills

Programming	C/C++, Python, MATLAB, Bash, HTML5/CSS, JavaScript, NodeJS, Java, PHP/MySQL
Hardware	Breadboarding/Soldering, TI-MSP430, Arduino
Languages	English, Chinese, Cantonese, ASL

Experience

DSO National Laboratories	*Singapore*
RESEARCH INTERN: 3D RADAR ODOMETRY FOR ADVERSE WEATHER CONDITIONS ▢ CFEAR	*Jun. 2022 - Aug. 2022*

- Successfully implemented 2D version of CFEAR radar odometry paper by Adolfsson et. al. in C++, using the OpenCV and Ceres Solver libraries.
- Ported 2D code to 3D, for use with a new 3D radar. Algorithm to be adapted and used for novel 3D radar odometry research.

DSO National Laboratories

Research Intern: Real-time radar odometry for adverse weather conditions using phase correlation and local pose-graph estimation

Singapore

Jun. 2019 - Aug. 2020

- Successfully implemented phase correlation and partially implemented local pose-graph estimation components of the PhaRaO radar odometry paper by Park et. al. in C++, using the OpenCV and Ceres Solver libraries.
- Algorithm to be adapted and actively used for organisation's unmanned ground vehicles. It will be part of a radar odometry pipeline, to supplement LiDAR for navigation in adverse conditions such as rain and dust.

CMU Human And Robotic Partners (HARP) Lab

Research Intern: Evaluating multi-view human pose estimation algorithm on CMU Panoptic Studio and other datasets ❶ ⬚ learnable-triangulation-pytorch

Singapore

Feb. 2019 - Apr. 2019

- Briefly evaluated various state-of-the-art methods for multi-view 3D human pose estimation, and sought to adapt the most suitable one for use on a dataset which the lab had collected prior.
- Successfully developed an open source toolkit in Python for evaluating the CMU Panoptic Dataset using Iskakov et. al.'s learnable triangulation algorithm.
- Also worked on generalising the toolkit for use with general datasets, including that of the lab.
- Been approached by PhD students to help integrate my work into their active research.

DSO National Laboratories

Research Intern: Integrated Data Annotation and Augmentation Tool for Object Recognition and Tracking

Singapore

Feb. 2019 - Apr. 2019

- Successfully developed a data annotation and augmentation tool in C#. The tool was integrated with a proprietary algorithm provided by our mentor (adapted from YOLOv2 and another proprietary tracking algorithm).
- Used the tool we developed to generate bounding box data, correct it manually, and augment it automatically. We then used the data for retraining the said algorithm.
- Also explored ways to improve the algorithm by adapting it for use with YOLOv3 and other trackers.

DSO National Laboratories

Research Intern: Low-powered Wireless Sound Processing

Singapore

Jan. 2017 - Feb. 2017

- Successfully implemented and tested algorithm for communication between a TI-MSP430 microcontroller and an ASIC Chip *(Application Specific Integrated Circuit)*, via the Serial Peripheral Interface *(SPI)* Protocol.
- Implemented data transmission from said microcontroller to another via Wi-Fi, to allow for wireless data processing.
- Algorithm further modified by organisation for their internal applications.

DSO National Laboratories

Research Intern: Optically-Illuminated Directional Sensing for Guidance Systems ❶

Singapore

Apr. 2015 - Mar. 2016

- Successfully prototyped an analog circuit capable of demodulating and amplifying a frequency-modulated laser signal.
- Programmed algorithm on TI-MSP430 Launchpad microcontroller to digitise analog input from circuit. Digitised signal then used to sense direction of laser-point, and actuate a novel omni-directional land robot.
- Represented Singapore at Intel International Science and Engineering Fair (ISEF).

DSO National Laboratories

Research (Team): Analysis of Multimodal Interaction methods for Multi-Tasking ❶

Singapore

Apr. 2014 - Jan. 2015

- Tested intuitiveness and efficiency of multiple interaction methods (eye-tracking, gestures, touch, speech and keyboard) in completing load-intensive tasks, via a custom-designed Flash game.
- Helped team design said Flash game, and a custom website to highlight advantages of eye-tracking.
- Presented to then Minister of State for Defence, Mr Maliki Osman, at the Young Defence Scientists Congress

Honors & Awards

2022	**University Honors**, Bachelors of Science in ECE, University Honors, May 2022	*Pittsburgh, PA, USA*
2022	**Dean's List**, Spring 2022, 4.0 GPA	*Pittsburgh, PA, USA*
2021	**Dean's List**, Fall 2021, 3.95 GPA	*Pittsburgh, PA, USA*
2021	**Dean's List**, Spring 2021, 4.0 GPA	*Pittsburgh, PA, USA*
2020	**Dean's List**, Fall 2020, 4.0 GPA	*Pittsburgh, PA, USA*
2020	*Dean's List*, Spring 2020, 4.0 GPA	*Pittsburgh, PA, USA*
2019	**Dean's List**, Fall 2019, 4.0 GPA	*Pittsburgh, PA, USA*

INTERNATIONAL

| 2016 | **Finalist**, Intel International Science and Engineering Fair (ISEF) | *Phoenix, AZ, USA* |

NATIONAL

2017	**Awardee**, DSTA Undergraduate Scholarship (Overseas)	*Singapore*
2016	**Gold, ISEF Delegate**, Singapore Science and Engineering Fair (SSEF)	*Singapore*
2014	**Bronze**, National Informatics Olympiad (NOI)	*Singapore*
2014	**2nd (Team), Bronze (Indv.)**, Singapore Physics Engineering Challenge	*Singapore*
2014	**Bronze**, Singapore Junior Physics Olympiad (SJPO)	*Singapore*
2014	**Outstanding Student Award**, Hwa Chong Institution (High School)	*Singapore*
2013	**Bronze**, Singapore Junior Physics Olympiad (SJPO)	*Singapore*

Extracurricular Activities

InterVarsity Christian Fellowship (IVCF) *Singapore*
CHAIRPERSON, BIBLE STUDY LEADER *2021 - 2023*

- Chairperson of IVCF. Involved in leading the chapter, supervising executive team, and organizing events.
- Small Group Bible Study Leader. Involved in leading a study session of the Bible and mentoring students under my care both spiritually and emotionally.

CMU Foosball Club *Singapore*
CHAIRPERSON *2020 - 2023*

- Chairperson of the CMU Foosball Club. Revived the club after 6 years of inactivity.

Hwa Chong Computer and Robotics Club *Singapore*
CHAIRPERSON *2011 - 2016*

- Chairperson of the Junior College (2016) and High School (2014) section of the club. Facilitated the merger and co-operation of the computer and robotics club.
- Gained expertise in web and game programming through self-motivated learning. Also trained for the National Informatics Olympiad, and attained bronze in 2013.
- Challenged my programming skills by participating in several team competitions:

2015	**3rd**, NYAA Canada-Singapore Website Design Competition
2015	**Consolation Award (4th)**, Singapore Games Creation Competition *(SGCC)* 🛈
2014	**Finalist (Top 5)**, Splash Awards *(app prototyping competition)*
2014	**Commendation Award (Top 10)**, SGCC 🛈