Samuel Leong Chee Weng

ELECTRICAL AND COMPUTER ENGINEER · INTEREST IN ROBOTICS, COMPUTER VISION AND EMBEDDED SYSTEMS

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Education ___

Carnegie Mellon University (CMU)

Pittsburgh, PA, USA

Bachelors of Science, Major in Electrical and Computer Engineering, Minor in Robotics Key Classes Taken/Taking:

Class of 2022

- 16-833: Localization and Mapping A
- 16-761: Mobile Robots A
- 16-385: Computer Vision A
- 18-349: Embedded Systems A
- 18-370: Fund. of Controls A
- 16-384: Robot Kinematics and Dynamics A
- 16-311: Intro. to Robotics A
- 18-213: Intro. to Computer Systems A

- 21-241: Matrices and Linear Transformations A
- 21-259: Calculus in 3D A
- 21-260: Differential Equations A
- 36-225: Intro. to Probability Theory A
- 18-240: Struct. and Design of Digital Systems A
- 18-220: Analog Circuits and Devices A
- 18-290: Signals and Systems A
- 16-385: Human-Robot Interaction A

Skills_

Programming C/C++, Python, MATLAB, Bash, HTML5/CSS, JavaScript, NodeJS, Java, PHP/MySQL

Hardware Breadboarding/Soldering, TI-MSP430, Arduino

Languages English, Chinese, ASL

Experience

DSO National Laboratories

Singapore

RESEARCH INTERN: REAL-TIME RADAR ODOMETRY FOR ADVERSE WEATHER CONDITIONS USING PHASE CORRELATION AND LOCAL POSE-GRAPH ESTIMATION

Jun. 2019 - Aug. 2020

- Successfully implemented phase correlation and partially implemented local pose-graph estimation components of the PhaRaO radar odometry paper by Park et. al. in C++, using the OpenCV and Ceres Solver libraries.
- Algorithm to be adapted and actively used for organisation's unmanned ground vehicles. It will be part of a radar odometry pipeline, to supplement LiDAR for navigation in adverse conditions such as rain and dust.

CMU Human And Robotic Partners (HARP) Lab

Singapore

RESEARCH INTERN: EVALUATING MULTI-VIEW HUMAN POSE ESTIMATION ALGORITHM ON CMU

Feb. 2019 - Apr. 2019

Panoptic Studio and other datasets 1 🖸 🗖 Learnable-triangulation-pytorch

- Briefly evaluated various state-of-the-art methods for multi-view 3D human pose estimation, and sought to adapt the most suitable one for use on a dataset which the lab had collected prior.
- Successfully developed an open source toolkit in Python for evaluating the CMU Panoptic Dataset using Iskakov et. al.'s learnable triangulation algorithm.
- Also worked on generalising the toolkit for use with general datasets, including that of the lab.
- Been approached by PhD students to help integrate my work into their active research.

DSO National Laboratories Singapore

RESEARCH INTERN: INTEGRATED DATA ANNOTATION AND AUGMENTATION TOOL FOR OBJECT

RECOGNITION AND TRACKING

Feb. 2019 - Apr. 2019

- Successfully developed a data annotation and augmentation tool in C#. The tool was integrated with a proprietary algorithm provided by our mentor (adapted from YOLOv2 and another proprietary tracking algorithm).
- Used the tool we developed to generate bounding box data, correct it manually, and augment it automatically. We then used the data for retraining the said algorithm.
- Also explored ways to improve the algorithm by adapting it for use with YOLOv3 and other trackers.

DSO National Laboratories

Singapore

RESEARCH INTERN: LOW-POWERED WIRELESS SOUND PROCESSING

Jan. 2017 - Feb. 2017

- Successfully implemented and tested algorithm for communication between a TI-MSP430 microcontroller and an ASIC Chip (Application Specific Integrated Circuit), via the Serial Peripheral Interface (SPI) Protocol.
- Implemented data transmission from said microcontroller to another via Wi-Fi, to allow for wireless data processing.
- Algorithm further modified by organisation for their internal applications.

DSO National Laboratories

Singapore

RESEARCH INTERN: OPTICALLY-ILLUMINATED DIRECTIONAL SENSING FOR GUIDANCE SYSTEMS

Apr. 2015 - Mar. 2016

- Successfully prototyped an analog circuit capable of demodulating and amplifying a frequency-modulated laser signal.
- Programmed algorithm on TI-MSP430 Launchpad microcontroller to digitise analog input from circuit. Digitised signal then used to sense direction of laser-point, and actuate a novel omni-directional land robot.
- Represented Singapore at Intel International Science and Engineering Fair (ISEF).

DSO National Laboratories

Singapore

RESEARCH (TEAM): ANALYSIS OF MULTIMODAL INTERACTION METHODS FOR MULTI-TASKING
Apr. 2014 - Jan. 2015

- Tested intuitiveness and efficiency of multiple interaction methods (eye-tracking, gestures, touch, speech and keyboard) in completing load-intensive tasks, via a custom-designed Flash game.
- Helped team design said Flash game, and a custom website to highlight advantages of eye-tracking.
- Presented to then Minister of State for Defence, Mr Maliki Osman, at the Young Defence Scientists Congress

Honors & Awards ____

UNIVERSITY

2022	University Honors , Bachelors of Science in ECE, University Honors, May 2022	Pittsburgh, PA, USA
2022	Dean's List, Spring 2022, 4.0 GPA	Pittsburgh, PA, USA
2021	Dean's List, Fall 2021, 3.95 GPA	Pittsburgh, PA, USA
2021	Dean's List, Spring 2021, 4.0 GPA	Pittsburgh, PA, USA
2020	Dean's List, Fall 2020, 4.0 GPA	Pittsburgh, PA, USA
2020	Dean's List , Spring 2020, 4.0 GPA	Pittsburgh, PA, USA
2019	Dean's List, Fall 2019, 4.0 GPA	Pittsburgh, PA, USA

INTERNATIONAL

2016 **Finalist**, Intel International Science and Engineering Fair (ISEF)

Phoenix, AZ, USA

NATIONAL

2017	Awardee, DSTA Undergraduate Scholarship (Overseas)	Singapore
2016	Gold, ISEF Delegate, Singapore Science and Engineering Fair (SSEF)	Singapore
2014	Bronze, National Informatics Olympiad (NOI)	Singapore
2014	2nd (Team), Bronze (Indv.), Singapore Physics Engineering Challenge	Singapore
2014	Bronze, Singapore Junior Physics Olympiad (SJPO)	Singapore
2014	Outstanding Student Award, Hwa Chong Institution (High School)	Singapore
2013	Bronze, Singapore Junior Physics Olympiad (SJPO)	Singapore

Extracurricular Activities

InterVarsity Christian Fellowship (IVCF)

Singapore

CHAIRPERSON, BIBLE STUDY LEADER

2021 - Present

- Chairperson of IVCF. Involved in leading the chapter and organizing events.
- Small Group Bible Study Leader. Involved in leading a study session of the Bible and mentoring students under my care both spiritually and emotionally.

CMU Foosball Club Singapore

CHAIRPERSON 2020 - Present

• Chairperson of the CMU Foosball Club. Revived the club after 6 years of inactivity.

Hwa Chong Computer and Robotics Club CHAIRPERSON

Singapore

2011 - 2016

- Chairperson of the Junior College (2016) and High School (2014) section of the club. Facilitated the merger and co-operation of the computer and robotics club.
- Gained expertise in web and game programming through self-motivated learning. Also trained for the National Informatics Olympiad, and attained bronze in 2013.
- Challenged my programming skills by participating in several team competitions:
 - 2015 **3rd**, NYAA Canada-Singapore Website Design Competition
 - 2015 **Consolation Award (4th)**, Singapore Games Creation Competition (SGCC) **1**
 - 2014 **Finalist (Top 5)**, Splash Awards (app prototyping competition)
 - 2014 Commendation Award (Top 10), SGCC 1