Assignment 2

Adding a user program to MavOS

hello.c

```
#include "types.h"
#include "stat.h"
#include "user.h"


int main(int argc, char *argv[])
{
  printf("Hello, World\n");
  exit();
}
```

- The **`user`** directory is where all user space code and user applications live.
- Create your new program .c file in the user directory.

Add the user program to the Makefile

```
119  UPROGS=\
120          $U/_cat\
121          $U/_echo\
122          $U/_forktest\
123          $U/_grep\
124          $U/_hello\
125          $U/_init\
126          $U/_kill\
127          $U/_ln\
128          $U/_ls\
129          $U/_mkdir\
130          $U/_rm\
131          $U/_sh\
132          $U/_stressfs\
133          $U/_usertests\
134          $U/_grind\
135          $U/_wc\
136          $U/_zombie\
137
```

- MacOS/Makefile contains the make rules to build our OS.
- In the UPROGS definition add a line for your new program.
  - Note you need to prepend _ to the filename.

Steps to add a system call

- You will modify four files to add a new system call
  1. **`syscall.h`** - Reserve a system call number for your system call.
  2. **`syscall.c`** - Add an entry in the system call vector for your system call.
  3. **`sysproc.c`** - Add the system call function
  4. **`usys.S`** - Add a SYSCALL entry to allow the system to generate an entry point for your system call
  5. **`user.h`** - Add a function signature to the user space header file

Reserving a system call number

```
1   #ifndef __SYSCALL_H_
2   #define __SYSCALL_H_
3
4   // System call numbers
5   #define SYS_fork    1
6   #define SYS_exit    2
7   #define SYS_wait    3
8   #define SYS_pipe    4
9   #define SYS_read    5
10  #define SYS_kill    6
11  #define SYS_exec    7
12  #define SYS_fstat   8
13  #define SYS_chdir   9
14  #define SYS_dup    10
15  #define SYS_getpid 11
16  #define SYS_sbrk   12
17  #define SYS_sleep  13
18  #define SYS_uptime 14
19  #define SYS_open   15
20  #define SYS_write  16
21  #define SYS_mknod  17
22  #define SYS_unlink 18
23  #define SYS_link   19
24  #define SYS_mkdir  20
25  #define SYS_close  21
26  #define SYS_mavup  22
27
28  #endif
29
```

- Claim the next integer for your system call by adding a new **`#define`** in **`syscall.h`**

Add prototype for your system call

```
77   // Prototypes for the functions that handle system calls.
78   extern uint64 sys_fork(void);
79   extern uint64 sys_exit(void);
80   extern uint64 sys_wait(void);
81   extern uint64 sys_pipe(void);
82   extern uint64 sys_read(void);
83   extern uint64 sys_kill(void);
84   extern uint64 sys_exec(void);
85   extern uint64 sys_fstat(void);
86   extern uint64 sys_chdir(void);
87   extern uint64 sys_dup(void);
88   extern uint64 sys_getpid(void);
89   extern uint64 sys_sbrk(void);
90   extern uint64 sys_sleep(void);
91   extern uint64 sys_uptime(void);
92   extern uint64 sys_open(void);
93   extern uint64 sys_write(void);
94   extern uint64 sys_mknod(void);
95   extern uint64 sys_unlink(void);
96   extern uint64 sys_link(void);
97   extern uint64 sys_mkdir(void);
98   extern uint64 sys_close(void);
99   extern uint64 sys_mavup(void);
100
```

- Add a prototype for your system call function in **`syscall.c`**

Add entry for your system call to the syscall vector

```
101    // An array mapping syscall numbers from syscall.h
102    // to the function that handles the system call.
103    static uint64 (*syscalls[])(void) = {
104        [SYS_fork] sys_fork,
105        [SYS_exit] sys_exit,
106        [SYS_wait] sys_wait,
107        [SYS_pipe] sys_pipe,
108        [SYS_read] sys_read,
109        [SYS_kill] sys_kill,
110        [SYS_exec] sys_exec,
111        [SYS_fstat] sys_fstat,
112        [SYS_chdir] sys_chdir,
113        [SYS_dup] sys_dup,
114        [SYS_getpid] sys_getpid,
115        [SYS_sbrk] sys_sbrk,
116        [SYS_sleep] sys_sleep,
117        [SYS_uptime] sys_uptime,
118        [SYS_open] sys_open,
119        [SYS_write] sys_write,
120        [SYS_mknod] sys_mknod,
121        [SYS_unlink] sys_unlink,
122        [SYS_link] sys_link,
123        [SYS_mkdir] sys_mkdir,
124        [SYS_close] sys_close,
125        [SYS_mavup] sys_mavup,
126    };
```

Add an entry for your system call function in the sys call vector

Implement your system call function

```
1   #include "types.h"
2   #include "riscv.h"
3   #include "defs.h"
4   #include "param.h"
5   #include "memlayout.h"
6   #include "spinlock.h"
7   #include "process.h"
8
9   uint64 sys_mavup(void)
10  {
11    // mav up
12    return 0;
13  }
```

- In **`sysproc.c`** add the code for your system call function

Now create the user space hooks

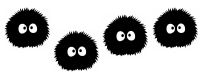
```
18    entry("fork");
19    entry("exit");
20    entry("wait");
21    entry("pipe");
22    entry("read");
23    entry("write");
24    entry("close");
25    entry("kill");
26    entry("exec");
27    entry("open");
28    entry("mknod");
29    entry("unlink");
30    entry("fstat");
31    entry("link");
32    entry("mkdir");
33    entry("chdir");
34    entry("dup");
35    entry("getpid");
36    entry("sbrk");
37    entry("sleep");
38    entry("uptime");
39    entry("mavup");
40
```

- In `user/usys.pl` add an entry for your system call.

Add a function prototype in the user space header

```
3   // system calls
4   int fork(void);
5   int exit(int) __attribute__((noreturn));
6   int wait(int*);
7   int pipe(int*);
8   int write(int, const void*, int);
9   int read(int, void*, int);
10  int close(int);
11  int kill(int);
12  int exec(const char*, char**);
13  int open(const char*, int);
14  int mknod(const char*, short, short);
15  int unlink(const char*);
16  int fstat(int fd, struct stat*);
17  int link(const char*, const char*);
18  int mkdir(const char*);
19  int chdir(const char*);
20  int dup(int);
21  int getpid(void);
22  char* sbrk(int);
23  int sleep(int);
24  int uptime(void);
25  int mavup(void);
```

- Add the function prototype to `user/user.h`



Scheduler

```
451   void scheduler(void)
452   {
453     struct process_control_block *p;
454     struct cpu *c = mycpu();
455
456     c->proc = 0;
457     for(;;){
458       // Avoid deadlock by ensuring that devices can interrupt.
459       intr_on();
460
461       for(p = process_table; p < &process_table[NPROC]; p++)
462       {
463         acquire(&p->lock);
464         if(p->state == RUNNABLE)
465         {
466           // Switch to chosen process.  It is the process's job
467           // to release its lock and then reacquire it
468           // before jumping back to us.
469           p->state = RUNNING;
470           c->proc = p;
471           swtch(&c->context, &p->context);
472
473           // Process is done running for now.
474           // It should have changed its p->state before coming back.
475           c->proc = 0;
476         }
477         release(&p->lock);
478       }
479     }
480   }
```

- **`process.c`** contains the scheduler function **`scheduler()`**.
- The current scheduler implements round robin.
  - Change the for loop to choose based on priority rules

process control block

```
98    // Per-process state
99    struct process_control_block
100   {
101     struct spinlock lock;
102
103     // p->lock must be held when using these:
104     enum procstate state; // Process state
105     void *chan;           // If non-zero, sleeping on chan
106     int killed;           // If non-zero, have been killed
107     int xstate;           // Exit status to be returned to parent's wait
108     int pid;              // Process ID
109
110     // wait_lock must be held when using this:
111     struct process_control_block *parent; // Parent process
112
113     // these are private to the process, so p->lock need not be held.
114     uint64 kstack;               // Virtual address of kernel stack
115     uint64 sz;                   // Size of process memory (bytes)
116     pagetable_t pagetable;       // User page table
117     struct trapframe *trapframe; // data page for trampoline.S
118     struct context context;      // swtch() here to run process
119     struct file *ofile[NOFILE];  // Open files
120     struct inode *cwd;           // Current directory
121     char name[16];               // Process name (debugging)
122   };
```

- The process control block is declared in **`process.h`**
- **`allocproc(void)`** allocates a new process and is a good spot to initialize the new process control block members.

Common git message

```
@trevorbakker-uta ➜ /workspaces/MavOS (main) $ git pull
remote: Enumerating objects: 22, done.
remote: Counting objects: 100% (22/22), done.
remote: Compressing objects: 100% (18/18), done.
remote: Total 20 (delta 10), reused 0 (delta 0), pack-reused 0 (from 0)
Unpacking objects: 100% (20/20), 553.55 KiB | 2.07 MiB/s, done.
From https://github.com/CSE3320-Fall-2024/MavOS
   ed74b27..b392026  main       -> origin/main
hint: You have divergent branches and need to specify how to reconcile them.
hint: You can do so by running one of the following commands sometime before
hint: your next pull:
hint:
hint:   git config pull.rebase false  # merge
hint:   git config pull.rebase true   # rebase
hint:   git config pull.ff only       # fast-forward only
hint:
hint: You can replace "git config" with "git config --global" to set a default
hint: preference for all repositories. You can also pass --rebase, --no-rebase,
hint: or --ff-only on the command line to override the configured default per
hint: invocation.
fatal: Need to specify how to reconcile divergent branches.
@trevorbakker-uta ➜ /workspaces/MavOS (main) $ git config pull.rebase false
```

Type: `git config pull.rebase false`