# dog\_app

November 11, 2019

# 1 Convolutional Neural Networks

# 1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

**Note**: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

**Note:** Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

## Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog\_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human\_files and dog\_files.

## Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [20]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face\_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

#### 1.1.1 Write a Human Face Detector

dogs as human: 0.17

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face\_detector, takes a string-valued file path to an image as input and appears in the code block below.

#### 1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

**Question 1:** Use the code cell below to test the performance of the face\_detector function.

- What percentage of the first 100 images in human\_files have a detected human face?
- What percentage of the first 100 images in dog\_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human\_files\_short and dog\_files\_short.

**Answer:** (You can print out your results and/or write your percentages in this cell)

```
In [4]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        missed_humans = 0
        missed_dogs = 0
        for himg, dimg in tqdm(zip(human_files_short, dog_files_short)):
            missed_humans += not (face_detector(himg))
            missed_dogs += face_detector(dimg)
        human_acc = (len(human_files_short) - missed_humans )/ len(human_files_short)
        dog_acc = (len(dog_files_short) - missed_dogs) / len(dog_files_short)
        total_h_acc = (human_acc*len(human_files_short) + dog_acc*len(dog_files_short))/(len(dog
        print('human_accuracy: %.2f' % human_acc)
        print('dogs as human: %.2f' % (1-dog_acc))
        print('Accuracy in human detection: %.3f' % total_h_acc)
100it [00:32, 3.03it/s]
human_accuracy: 0.98
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

```
In [5]: ### (Optional)
        ### TODO: Test performance of anotherface detection algorithm.
        ### Feel free to use as many code cells as needed.
        def check_detection_acc(face_cascade):
            human_files_short = human_files[:100]
            dog_files_short = dog_files[:100]
            missed_humans = 0
            missed_dogs = 0
            for himg, dimg in tqdm(zip(human_files_short, dog_files_short)):
                missed_humans += not (face_detection(himg,face_cascade))
                missed_dogs += face_detection(dimg,face_cascade)
            human_acc = (len(human_files_short) - missed_humans )/ len(human_files_short)
            dog_acc = (len(dog_files_short) - missed_dogs) / len(dog_files_short)
            total_h_acc = (human_acc*len(human_files_short) + dog_acc*len(dog_files_short))/(len
            return human_acc, dog_acc, total_h_acc
        def face_detection(img_path, face_cascade):
            img = cv2.imread(img_path)
            gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
            faces = face_cascade.detectMultiScale(gray)
            return len(faces) > 0
In [6]: ### (Optional)
        ### TODO: Test performance of anotherface detection algorithm.
        ### Feel free to use as many code cells as needed.
        face_cascade_ = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')
        h_a, d_a, th_a = check_detection_acc(face_cascade_)
        print('human_accuracy: %.2f' % h_a)
        print('dogs as human: %.2f' % (1-d_a))
        print('Accuracy in human detection: %.3f' % th_a)
100it [01:28, 3.05it/s]
human_accuracy: 0.98
dogs as human: 0.17
Accuracy in human detection: 0.905
```

```
In []: ### (Optional)
        ### TODO: Test performance of anotherface detection algorithm.
        ### Feel free to use as many code cells as needed.
        face_cascade_ = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_default.xml'
        h_a, d_a, th_a = check_detection_acc(face_cascade_)
        print('human_accuracy: %.2f' % h_a)
        print('dogs as human: %.2f' % (1-d_a))
        print('Accuracy in human detection: %.3f' % th_a)
In []: ### (Optional)
        ### TODO: Test performance of anotherface detection algorithm.
        ### Feel free to use as many code cells as needed.
        face_cascade_ = cv2.CascadeClassifier('haarcascades/haarcascade_smile.xml')
        h_a, d_a, th_a = check_detection_acc(face_cascade_)
        \verb|print('human_accuracy: \%.2f' \% h_a)|\\
        print('dogs as human: %.2f' % (1-d_a))
        print('Accuracy in human detection: %.3f' % th_a)
```

In this section, we use a pre-trained model to detect dogs in images.

1.1.3 Obtain Pre-trained VGG-16 Model

## Step 2: Detect Dogs

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [1]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:05<00:00, 103950416.25it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

### 1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher\_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
In [16]: from PIL import Image
         import torchvision.transforms as transforms
         def VGG16_predict(img_path, img_size, model):
             Use pre-trained VGG-16 model to obtain index corresponding to
             predicted ImageNet class for image at specified path
             Args:
                 img_path: path to an image
             Returns:
                 Index corresponding to VGG-16 model's prediction
             ## TODO: Complete the function.
             ## Load and pre-process an image from the given img_path
             img = Image.open(img_path)
             in_transform = transforms.Compose([
                 transforms . CenterCrop(img_size),
                 transforms.ToTensor(),
                  transforms.Normalize()
            #
             image = in_transform(img).unsqueeze(0)
             print(image.shape)
             ## Return the *index* of the predicted class for that image
             model.eval()
             _, pred_idx = torch.max(model(image),1)
             return pred_idx # predicted class index
```

# 1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog\_detector function below, which returns True if a dog is detected in an image (and False if not).

```
In [2]: ### returns "True" if a dog is detected in the image stored at img_path
```

```
def dog_detector(img_path, img_size, model = VGG16):
    ## TODO: Complete the function.
    output = VGG16_predict(img_path,img_size, model)
    return output in range(151,268)
```

# 1.1.6 (IMPLEMENTATION) Assess the Dog Detector

**Question 2:** Use the code cell below to test the performance of your dog\_detector function.

- What percentage of the images in human\_files\_short have a detected dog?
- What percentage of the images in dog\_files\_short have a detected dog?

#### Answer:

```
In [18]: ### TODO: Test the performance of the dog_detector function
         ### on the images in human_files_short and dog_files_short.
         human_files_short = human_files[:100]
         dog_files_short = dog_files[:100]
         human_as_dog = 0
         dog_wclassified = 0
         for img_path in tqdm(human_files_short):
             human_as_dog += dog_detector(img_path, 224)
         for img_path in tqdm(dog_files_short):
             dog_wclassified += dog_detector(img_path, 224)
         h_accuracy = (len(human_files_short)-human_as_dog)/len(human_files_short)
         d_accuracy = dog_wclassified / len(dog_files_short)
         print("human misclassified as dogs: %.2f %%" %(1-h_accuracy))
         print("dogs well-classified as dogs: %.2f %%" %d_accuracy)
  0%1
              | 0/100 [00:00<?, ?it/s]
  1% I
              | 1/100 [00:01<01:45, 1.06s/it]
  2%1
             | 2/100 [00:01<01:38, 1.00s/it]
             | 3/100 [00:02<01:33, 1.04it/s]
  3% l
              | 4/100 [00:03<01:29, 1.07it/s]
  4% l
             | 5/100 [00:04<01:27, 1.09it/s]
  5% l
100%|| 100/100 [01:27<00:00, 1.15it/s]
100%|| 100/100 [01:28<00:00, 1.11it/s]
human misclassified as dogs: 0.00 %
dogs well-classified as dogs: 0.59 %
```

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use

the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

```
In [6]: ### (Optional)
        ### TODO: Report the performance of another pre-trained network.
        ### Feel free to use as many code cells as needed.
        # define Inception V3 model
        IncV3 = models.inception_v3(pretrained=True)
        # check if CUDA is available
        use_cuda = torch.cuda.is_available()
        # move model to GPU if CUDA is available
        if use_cuda:
            IncV3 = VGG16.cuda()
Downloading: "https://download.pytorch.org/models/inception_v3_google-1a9a5a14.pth" to /root/.to
100%|| 108857766/108857766 [00:01<00:00, 99235441.35it/s]
In [7]: # ResNet-50
        # define Resnet50 model
        RNET = models.resnet50(pretrained=True)
        # check if CUDA is available
        use_cuda = torch.cuda.is_available()
        # move model to GPU if CUDA is available
        if use_cuda:
            RNET = VGG16.cuda()
Downloading: "https://download.pytorch.org/models/resnet50-19c8e357.pth" to /root/.torch/models/
100%|| 102502400/102502400 [00:01<00:00, 87675184.45it/s]
In [9]: def check_detector_performance(input_img_size = 224, model = VGG16, detector = dog_detector)
            human_files_short = human_files[:100]
            dog_files_short = dog_files[:100]
            human_as_dog = 0
            dog_wclassified = 0
            for img_path in tqdm(human_files_short):
                human_as_dog += detector(img_path, input_img_size, model)
            for img_path in tqdm(dog_files_short):
                dog_wclassified += detector(img_path, input_img_size, model)
```

```
h_accuracy = (len(human_files_short)-human_as_dog)/len(human_files_short)
            d_accuracy = dog_wclassified / len(dog_files_short)
            return h_accuracy, d_accuracy
In [23]: h_acc, d_acc = check_detector_performance(224, VGG16, dog_detector)
        print("human misclassified as dogs: %.2f" %h_acc)
        print("dogs well-classified as dogs: %.2f" %d_acc)
100%|| 100/100 [01:31<00:00, 1.10it/s]
100%|| 100/100 [01:21<00:00, 1.19it/s]
human misclassified as dogs: 1.00
dogs well-classified as dogs: 0.59
In [24]: h_acc, d_acc = check_detector_performance(448, IncV3, dog_detector)
        print("human misclassified as dogs: %.2f" %h_acc)
        print("dogs well-classified as dogs: %.2f" %d_acc)
100%|| 100/100 [01:41<00:00, 1.07it/s]
100%|| 100/100 [01:33<00:00, 1.14it/s]
human misclassified as dogs: 1.00
dogs well-classified as dogs: 0.96
In [16]: h_acc, d_acc = check_detector_performance(224, RNET, dog_detector)
        print("human misclassified as dogs: %.2f" %h_acc)
        print("dogs well-classified as dogs: %.2f" %d_acc)
100%|| 100/100 [00:29<00:00, 3.41it/s]
100%|| 100/100 [00:30<00:00, 3.39it/s]
human misclassified as dogs: 1.00
dogs well-classified as dogs: 0.75
```

## Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

Curly-Coated Retriever American Water Spaniel

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

Yellow Labrador Chocolate Labrador

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

#### 1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog\_images/train, dog\_images/valid, and dog\_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
## Specify appropriate transforms, and batch_sizes
def load_data_in_DataLoaders(data_dir, tr_data_transform = transforms.ToTensor(), vt_da
    # Assemble dir paths
  # train_dir = os.path.join(data_dir, 'train')
  # valid_dir = os.path.join(data_dir, 'valid')
  # test_dir = os.path.join(data_dir, 'test')
    net_stage = ['train', 'valid', 'test']
    # Load Images dataset using ImageFolder
    data_scratch = { item: datasets.ImageFolder(os.path.join(data_dir, item), transform
                    for item in net_stage}
  # train_data = datasets.ImageFolder(train_dir, transform=ut_data_transform)
  # valid_data = datasets.ImageFolder(valid_dir, transform=vt_data_transform)
  # test_data = datasets.ImageFolder(test_dir, transform=vt_data_transform)
    # Print out info
    for stage in net_stage:
        print('Num images in',stage, ':', len(data_scratch[stage]) )
   print('Num training images: ', len(train_data))
   print('Num validation images: ', len(valid_data))
 # print('Num test images: ', len(test_data))
    # Set data Loaders
    # define dataloader parameters
    batch_size = 20
    num_workers=0
    # prepare data loaders
  # train_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size,
   valid_loader = torch.utils.data.DataLoader(valid_data, batch_size=batch_size,
    loaders_scratch = {item : torch.utils.data.DataLoader(data_scratch[item], batch_siz
                                              num_workers=num_workers, shuffle=True) fo
    return loaders scratch
# Define transforms on the data
tr_data_transform = transforms.Compose([
    transforms.Resize((224,224)),
    transforms.RandomHorizontalFlip(0.05),
    transforms.RandomRotation(30),
    transforms.RandomAffine(10),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                     std=[0.229, 0.224, 0.225])
1)
tr_crop_data_transform = transforms.Compose([
    transforms.CenterCrop(224),
    transforms.RandomHorizontalFlip(0.05),
    transforms.RandomRotation(30),
    transforms.RandomAffine(10),
    transforms.ToTensor(),
```

```
transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                                                                               std=[0.229, 0.224, 0.225])
                     1)
                     vt_data_transform = transforms.Compose([
                               transforms.Resize((224,224)),
                               transforms.ToTensor(),
                               transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                                                                               std=[0.229, 0.224, 0.225])
                     ])
                     vt_crop_data_transform = transforms.Compose([
                               transforms.CenterCrop(224),
                               transforms.ToTensor(),
                               transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                                                                               std=[0.229, 0.224, 0.225])
                     1)
                     res_loaders = load_data_in_DataLoaders('/data/dog_images', vt_data_transform, vt_data_t
                     cr_loaders = load_data_in_DataLoaders('/data/dog_images', vt_crop_data_transform, vt_cr
                     resaug_loaders = load_data_in_DataLoaders('/data/dog_images', tr_data_transform, vt_data_transform, vt_data_
                     craug_loaders = load_data_in_DataLoaders('/data/dog_images', tr_crop_data_transform, vt
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
In [9]: max_label = 0
                   labels_num = np.zeros(133)
                   for images, labels in res_loaders['train']:
                             for label in labels:
                                      labels_num[label] += 1
                                      if max_label < label:</pre>
                                                max_label = label
In [10]: print(max_label)
                     print(labels_num)
                     len(labels_num)
tensor(132)
[ 64. 58. 52. 63. 77. 64. 50. 66. 34. 50. 66. 66. 46. 69. 73.
```

```
59.
            50.
                               64.
      62.
                  48.
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                                                                            30.1
```

Out[10]: 133

**Question 3:** Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

### Answer:

After looking into the "dog\_images" folder we can make the following statements: - There are ~8k images. Which should be initially enough to traing and test a pre-trained network - Most breed are represented by 5-8 images in the test dataset; whereas there are 50 images for training each breed - Images have different zoom but most of them contain the dog in the center of the picture without rotation (dog feet are normally at the bottom) - Full-body pictures are centered too but the head of the dog lies on one side. A crop could erase relevant information related to head shape.

The following preprocessing has been applied to enhance detection results: - Image has to be resized to 224 px to feed into VGG16 (Inception uses 448). This resizing can be done either by cropping (Which can result in erasing head or other part of the dog relevant for detection) or by resizing (Which applies perspective perturbations to the picture). As both solutions can hamper proper detection, I encourage testing both. The cell above contains loaders for both transformations. Note that crop in training is randomly performed in an attempt to reduce centerCrop effect during test and validation. - Considering a real-world future application, rotation and perspective invariance should be provided by data augmentation. In such a manner rotation, horizontal flip and affine transformation is applied on training data. To monitor the benefit of this fact, loaders without augmentation are also kept. For the test data provided, results should be really similar between augmentation and without as most test images have similar orientation and perspective than training images. - Normalization can help convergence by reducing pixel-value-variance range between images. Normalization mean and std values taken from:

https://github.com/pytorch/examples/blob/97304e232807082c2e7b54c597615dc0ad8f6173/imagenet/main.pyL198

## 1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
In [5]: import torch.nn as nn
    import torch.nn.functional as F
    from collections import OrderedDict
    from tqdm import tqdm
```

```
# define the CNN architecture
class Net(nn.Module):
    ### TODO: choose an architecture, and complete the class
    def __init__(self, dog_breeds):
        super(Net, self).__init__()
        ## Define layers of a CNN as Ordered Dicts
        self.features = nn.Sequential(OrderedDict([
            # convolutional layer (gets 224x224x3 image tensor)
            ('conv1', nn.Conv2d(3, 16, 3, padding=1)),
            ('ReLu1', nn.ReLU(True)),
            ('maxpool1', nn.MaxPool2d(2,2)),
            # convolutional layer (gets 128x128x16 tensor)
            ('conv2', nn.Conv2d(16, 32, 3, padding=1)),
            ('ReLu2', nn.ReLU(True)),
            ('maxpool2', nn.MaxPool2d(2,2)),
            # convolutional layer (gets 64x64x32 tensor)
            ('conv3', nn.Conv2d(32, 64, 3, padding=1)),
            ('ReLu3', nn.ReLU(True)),
            ('maxpool3', nn.MaxPool2d(2,2)),
            # convolutional layer (gets 32x32x64 tensor)
            ('conv4', nn.Conv2d(64, 128, 3, padding=1)),
            ('ReLu4', nn.ReLU(True)),
            ('maxpool4', nn.MaxPool2d(2,2)),
            # convolutional layer (gets 16x16x128 tensor)
            ('conv5', nn.Conv2d(128, 256, 3, padding=1)),
            ('ReLu5', nn.ReLU(True)),
            ('maxpool5', nn.MaxPool2d(2,2)),
            # convolutional layer (gets 8 x 8 x 256)
            ('conv6', nn.Conv2d(256, 512, 3, padding=1)),
            ('ReLu6', nn.ReLU(True)),
            ('maxpool6', nn.MaxPool2d(2,2))
        1))
        #outputs 256*8*8
        self.classifier = nn.Sequential(OrderedDict([
            # linear layer (512*4*4=8192)
            ('dropout1', nn.Dropout(0.5)),
            ('fc1', nn.Linear(512*3*3, 1000)),
            ('ReLu1', nn.ReLU(True)),
            ('dropout2', nn.Dropout(0.5)),
            # linear layer (6000 -> 1000)
            ('fc2', nn.Linear(1000, dog_breeds))
        1))
    def forward(self, x):
        ## Define forward behavior
        x = self.features(x)
```

```
#print(x.shape)
    x = x.view(x.shape[0],-1)
    x = self.classifier(x)
    return x

#-#-# You so NOT have to modify the code below this line. #-#-#

# instantiate the CNN
dog_breeds = 133
model_scratch = Net(dog_breeds)

# move tensors to GPU if CUDA is available
if use_cuda:
    model scratch.cuda()
```

**Question 4:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

#### **Answer:**

I've chosen a kernel 3x3 as it one of the most encouraged in state of the art when working with limited resolution. Following previous examples, the first layer uses 16 filters (depth). Then, by using a maxpool layer the (X,Y) is reduced by half while the depth is doubled, promoting feature detection. I've decided to using 6 conv layer to reduce the image resolution down to 4x4 in the last layer. The networks works with  $224 \times 224$  px so as to have similar resolution than vgg16, the network against our scrath-net competes with.

Then, we have the classifier part using fully-connected layers with ReLU activation. There are also 2 dropout layers to reduce overfitting. I have decided to apply three fully-connected layers to improve interpolation and classification as the classifier outputs 4608 features to the classifier.

### 1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_scratch, and the optimizer as optimizer\_scratch below.

```
In [30]: import torch.optim as optim
    ### TODO: select loss function
    criterion_scratch = nn.CrossEntropyLoss()

### TODO: select optimizer
    optimizer_scratch = optim.SGD(model_scratch.parameters(), lr=0.03)
```

#### 1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_scratch.pt'.

```
valid_loss_min = np.Inf
for epoch in range(1, n_epochs+1):
    # initialize variables to monitor training and validation loss
    train_loss = 0.0
    valid_loss = 0.0
    ###################
    # train the model #
    ###################
    model.train()
    for batch_idx, (data, target) in enumerate(loaders['train']):
        # move to GPU
        if use cuda:
            data, target = data.cuda(), target.cuda()
        ## find the loss and update the model parameters accordingly
        # clear the gradients of all optimized variables
        #print(target)
        #print(target.shape)
        optimizer.zero_grad()
        # forward pass: compute predicted outputs by passing inputs to the model
        output = model(data)
        # calculate the batch loss
        loss = criterion(output, target)
        # backward pass: compute gradient of the loss with respect to model parameter
        loss.backward()
        # perform a single optimization step (parameter update)
        optimizer.step()
        # update training loss
        #train_loss += loss.item()*data.size(0)
        ## record the average training loss, using something like
        train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss))
    #####################
    # validate the model #
    #####################
    model.eval()
    for batch_idx, (data, target) in enumerate(loaders['valid']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
        ## update the average validation loss
        output = model(data)
        loss = criterion(output, target)
        valid_loss = valid_loss + ((1 / (batch_idx + 1)) * (loss.data - valid_loss))
    # print training/validation statistics
    print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
```

```
epoch,
                    train_loss,
                    valid_loss
                    ))
                ## TODO: save the model if validation loss has decreased
                if valid_loss < valid_loss_min:</pre>
                    print('Validation loss decreased. Saving model ...')
                    torch.save(model.state_dict(), save_path)
                    torch.save
                    valid_loss_min = valid_loss
            # return trained model
            return model
In [8]: # set loaders to use
        loaders_scratch = res_loaders
        # train the model
        model_scratch = train(10, loaders_scratch, model_scratch, optimizer_scratch,
                              criterion_scratch, use_cuda, 'model_scratch.pt')
        # load the model that got the best validation accuracy
        model_scratch.load_state_dict(torch.load('model_scratch.pt'))
 0%|
               | 0/10 [00:00<?, ?it/s]
                                                 Validation Loss: 4.888226
Epoch: 1
                 Training Loss: 4.889492
Validation loss decreased. Saving model ...
20%|
             | 2/10 [03:20<13:51, 103.99s/it]
Epoch: 2
                 Training Loss: 4.887559
                                                 Validation Loss: 4.886303
Validation loss decreased. Saving model ...
30%1
            | 3/10 [04:51<11:40, 100.07s/it]
                 Training Loss: 4.885317
                                                 Validation Loss: 4.883965
Epoch: 3
Validation loss decreased. Saving model ...
40%|
           | 4/10 [06:22<09:43, 97.30s/it]
Epoch: 4
                 Training Loss: 4.882019
                                                 Validation Loss: 4.879751
Validation loss decreased. Saving model ...
 50%|
          | 5/10 [07:52<07:56, 95.21s/it]
```

```
Epoch: 5
                Training Loss: 4.873405
                                                Validation Loss: 4.865295
Validation loss decreased. Saving model ...
60% l
        | 6/10 [09:22<06:14, 93.75s/it]
Epoch: 6
                Training Loss: 4.865494
                                               Validation Loss: 4.858145
Validation loss decreased. Saving model ...
       | 7/10 [10:53<04:38, 92.71s/it]
70%|
                                                Validation Loss: 4.848002
Epoch: 7
                Training Loss: 4.857098
Validation loss decreased. Saving model ...
80% | 8/10 [12:23<03:03, 91.89s/it]
                Training Loss: 4.841722
                                                Validation Loss: 4.821765
Validation loss decreased. Saving model ...
90% | 9/10 [13:53<01:31, 91.33s/it]
Epoch: 9
                Training Loss: 4.790226
                                                Validation Loss: 4.748716
Validation loss decreased. Saving model ...
100%|| 10/10 [15:23<00:00, 90.99s/it]
                 Training Loss: 4.734379
Epoch: 10
                                                 Validation Loss: 4.696525
Validation loss decreased. Saving model ...
```

### 1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [9]: def test(loaders, model, criterion, use_cuda):
    # monitor test loss and accuracy
    test_loss = 0.
    correct = 0.
    total = 0.
    model.eval()
```

```
# move to GPU
                if use cuda:
                    data, target = data.cuda(), target.cuda()
                # forward pass: compute predicted outputs by passing inputs to the model
                output = model(data)
                # calculate the loss
                loss = criterion(output, target)
                # update average test loss
                test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                # convert output probabilities to predicted class
                pred = output.data.max(1, keepdim=True)[1]
                # compare predictions to true label
                correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                total += data.size(0)
            print('Test Loss: {:.6f}\n'.format(test_loss))
            print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                100. * correct / total, correct, total))
        # call test function
        test(loaders_scratch, model_scratch, criterion_scratch, use_cuda)
Test Loss: 4.687901
Test Accuracy: 2% (19/836)
In [10]: def evaluate_model(loaders_scratch, model_scratch, optimizer_scratch, criterion_scratch
                            use_cuda, epochs = 10, save_path = 'model_scratch.pt'):
             # train the model
             model_scratch = train(epochs, loaders_scratch, model_scratch, optimizer_scratch,
                               criterion_scratch, use_cuda, save_path)
             # load the model that got the best validation accuracy
             model_scratch.load_state_dict(torch.load(save_path))
             # call test function
             test(loaders_scratch, model_scratch, criterion_scratch, use_cuda)
In [12]: evaluate_model(res_loaders, model_scratch, optimizer_scratch, criterion_scratch, use_cu
              | 1/10 [01:30<13:34, 90.50s/it]
10%|
Epoch: 1
                 Training Loss: 4.684037
                                                 Validation Loss: 4.612476
Validation loss decreased. Saving model ...
```

for batch\_idx, (data, target) in enumerate(loaders['test']):

20%| | 2/10 [03:01<12:04, 90.62s/it] Validation Loss: 4.552939 Epoch: 2 Training Loss: 4.573919 Validation loss decreased. Saving model ... 30%| | 3/10 [04:32<10:34, 90.65s/it] Epoch: 3 Training Loss: 4.505886 Validation Loss: 4.504832 Validation loss decreased. Saving model ... 40%| | 4/10 [06:03<09:04, 90.73s/it] Epoch: 4 Training Loss: 4.442260 Validation Loss: 4.523919 | 5/10 [07:33<07:33, 90.77s/it] 50% l Epoch: 5 Training Loss: 4.374512 Validation Loss: 4.457346 Validation loss decreased. Saving model ... 60% | 6/10 [09:05<06:03, 90.87s/it] Validation Loss: 4.370283 Epoch: 6 Training Loss: 4.303151 Validation loss decreased. Saving model ... 70% | 7/10 [10:35<04:32, 90.82s/it] Epoch: 7 Training Loss: 4.209877 Validation Loss: 4.290996 Validation loss decreased. Saving model ... 80% | 8/10 [12:05<03:01, 90.62s/it] Epoch: 8 Training Loss: 4.106763 Validation Loss: 4.259809 Validation loss decreased. Saving model ... 90% | | 9/10 [13:35<01:30, 90.43s/it] Epoch: 9 Training Loss: 4.003677 Validation Loss: 4.200664 Validation loss decreased. Saving model ... 100%|| 10/10 [15:06<00:00, 90.44s/it] Epoch: 10 Training Loss: 3.894820 Validation Loss: 4.167188

Validation loss decreased. Saving model ...

Test Loss: 4.157565

Test Accuracy: 8% (68/836)

In [13]: evaluate\_model(cr\_loaders, model\_scratch, optimizer\_scratch, criterion\_scratch, use\_cuc

10% | 1/10 [01:09<10:22, 69.17s/it]

Epoch: 1 Training Loss: 4.358610 Validation Loss: 4.307395

Validation loss decreased. Saving model ...

20% | 2/10 [02:18<09:13, 69.22s/it]

Epoch: 2 Training Loss: 4.197330 Validation Loss: 4.268797

Validation loss decreased. Saving model ...

30% | 3/10 [03:27<08:04, 69.20s/it]

Epoch: 3 Training Loss: 4.069749 Validation Loss: 4.222246

Validation loss decreased. Saving model ...

40% | 4/10 [04:36<06:54, 69.11s/it]

Epoch: 4 Training Loss: 3.958261 Validation Loss: 4.156859

Validation loss decreased. Saving model ...

50% | | 5/10 [05:45<05:44, 68.93s/it]

Epoch: 5 Training Loss: 3.822164 Validation Loss: 4.238466

60% | 6/10 [06:54<04:35, 68.97s/it]

Epoch: 6 Training Loss: 3.682541 Validation Loss: 4.232671

70% | 7/10 [08:02<03:26, 68.87s/it]

Epoch: 7 Training Loss: 3.535999 Validation Loss: 4.186358

80%| | 8/10 [09:11<02:17, 68.85s/it]

Epoch: 8 Training Loss: 3.339648 Validation Loss: 4.222634

90% | 9/10 [10:19<01:08, 68.71s/it]

Epoch: 9 Training Loss: 3.161209 Validation Loss: 4.240358

100%|| 10/10 [11:28<00:00, 68.65s/it]

Epoch: 10 Training Loss: 2.970675 Validation Loss: 4.220605

Test Loss: 4.089101

Test Accuracy: 8% (74/836)

In [14]: evaluate\_model(resaug\_loaders, model\_scratch, optimizer\_scratch, criterion\_scratch, use

10% | 1/10 [01:32<13:56, 92.92s/it]

Epoch: 1 Training Loss: 3.991425 Validation Loss: 4.126298

Validation loss decreased. Saving model ...

20% | 2/10 [03:05<12:21, 92.68s/it]

Epoch: 2 Training Loss: 3.851191 Validation Loss: 3.978856

Validation loss decreased. Saving model ...

30% | 3/10 [04:37<10:48, 92.59s/it]

Epoch: 3 Training Loss: 3.747243 Validation Loss: 3.893922

 ${\tt Validation\ loss\ decreased.} \quad {\tt Saving\ model\ } \ldots$ 

40% | 4/10 [06:09<09:14, 92.44s/it]

Epoch: 4 Training Loss: 3.656609 Validation Loss: 3.948472

50% | 5/10 [07:42<07:43, 92.64s/it]

Epoch: 5 Training Loss: 3.579864 Validation Loss: 3.859303

Validation loss decreased. Saving model ...

60% | 6/10 [09:15<06:11, 92.82s/it]

Epoch: 6 Training Loss: 3.501025 Validation Loss: 3.808497

Validation loss decreased. Saving model ...

70% | 7/10 [10:48<04:38, 92.91s/it]

Epoch: 7 Training Loss: 3.428164 Validation Loss: 3.761371

Validation loss decreased. Saving model ...

80% | 8/10 [12:22<03:05, 92.94s/it]

Epoch: 8 Training Loss: 3.323892 Validation Loss: 3.744287

Validation loss decreased. Saving model ...

90% | 9/10 [13:55<01:33, 93.09s/it]

Epoch: 9 Training Loss: 3.254543 Validation Loss: 3.752984

100%|| 10/10 [15:29<00:00, 93.30s/it]

Epoch: 10 Training Loss: 3.149271 Validation Loss: 3.715734

Validation loss decreased. Saving model ...

Test Loss: 3.743450

Test Accuracy: 13% (113/836)

In [34]: evaluate\_model(craug\_loaders, model\_scratch, optimizer\_scratch, criterion\_scratch, use\_

Epoch: 1 Training Loss: 3.981338 Validation Loss: 4.000509

Validation loss decreased. Saving model ...

Epoch: 2 Training Loss: 3.779310 Validation Loss: 3.965888

Validation loss decreased. Saving model ...

Epoch: 3 Training Loss: 3.660987 Validation Loss: 3.906343

Validation loss decreased. Saving model ...

Epoch: 4 Training Loss: 3.547598 Validation Loss: 3.859987

Validation loss decreased. Saving model ...

Epoch: 5 Training Loss: 3.476992 Validation Loss: 3.784964

Validation loss decreased. Saving model ...

```
Epoch: 6
                 Training Loss: 3.411273
                                                 Validation Loss: 3.839303
Epoch: 7
                 Training Loss: 3.321054
                                                 Validation Loss: 4.000874
Epoch: 8
                 Training Loss: 3.236289
                                                 Validation Loss: 3.849416
                 Training Loss: 3.131379
                                                 Validation Loss: 3.766074
Epoch: 9
Validation loss decreased. Saving model ...
                  Training Loss: 3.050062
Epoch: 10
                                                  Validation Loss: 3.773075
Test Loss: 3.715546
Test Accuracy: 15% (131/836)
```

## Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

# 1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

```
In [2]: ## TODO: Specify data loaders
        import numpy as np
        import torch
        import torchvision.models as models
        import os
        from torchvision import datasets, transforms
        from PIL import ImageFile
        ImageFile.LOAD_TRUNCATED_IMAGES = True
        ### TODO: Write data loaders for training, validation, and test sets
        ## Specify appropriate transforms, and batch_sizes
        def load_transfer_data_in_DataLoaders(data_dir, tr_data_transform = transforms.ToTensor()
            # Assemble dir paths
            net_stage = ['train', 'valid', 'test']
            # Load Images dataset using ImageFolder
            data_transfer = { item: datasets.ImageFolder(os.path.join(data_dir, item), transform
                            for item in net_stage}
            # Print out info
            for stage in net_stage:
                print('Num images in',stage, ':', len(data_transfer[stage]) )
            # prepare data loaders
```

```
loaders_transfer = {item : torch.utils.data.DataLoader(data_transfer[item], batch_si
                                                       num_workers=num_workers, shuffle = True) f
            return loaders_transfer
In [3]: def create_transfer_transforms(img_size):
        # Define transforms on the data
            tr_data_transform = transforms.Compose([
                transforms Resize((img_size,img_size)),
                transforms.RandomHorizontalFlip(0.05),
                transforms.RandomRotation(30),
                transforms.RandomAffine(10),
                transforms.ToTensor(),
                transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                  std=[0.229, 0.224, 0.225])
            ])
            tr_crop_data_transform = transforms.Compose([
                transforms.RandomCrop(img_size),
                transforms.RandomHorizontalFlip(0.05),
                transforms.RandomRotation(30),
                transforms.RandomAffine(10),
                transforms.ToTensor(),
                transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                  std=[0.229, 0.224, 0.225])
            1)
            vt_data_transform = transforms.Compose([
                transforms.Resize((img_size,img_size)),
                transforms.ToTensor(),
                transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                  std=[0.229, 0.224, 0.225])
            1)
            vt_crop_data_transform = transforms.Compose([
                transforms.CenterCrop(img_size),
                transforms.ToTensor(),
                transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                  std=[0.229, 0.224, 0.225])
            ])
            return tr_data_transform, tr_crop_data_transform, vt_data_transform, vt_crop_data_tr
In [4]: img_size = 224
        tr_transfer_data_transform, tr_crop_transfer_data_transform, vt_transfer_data_transform,
        transfer_res_loaders = load_transfer_data_in_DataLoaders('/data/dog_images', vt_transfer
        transfer_cr_loaders = load_transfer_data_in_DataLoaders('/data/dog_images', vt_crop_transfer_cr_loaders)
        transfer_resaug_loaders = load_transfer_data_in_DataLoaders('/data/dog_images', tr_trans
        transfer_craug_loaders = load_transfer_data_in_DataLoaders('/data/dog_images', tr_crop_t
Num images in train: 6680
```

Num images in valid: 835

```
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
In [5]: img_size = 448
       tr_transfer_data_transform_448, tr_crop_transfer_data_transform_448, vt_transfer_data_tr
       res_loaders_448 = load_transfer_data_in_DataLoaders('/data/dog_images', vt_transfer_data
        cr_loaders_448 = load_transfer_data_in_DataLoaders('/data/dog_images', vt_crop_transfer_
       resaug_loaders_448 = load_transfer_data_in_DataLoaders('/data/dog_images', tr_transfer_
       craug_loaders_448 = load_transfer_data_in_DataLoaders('/data/dog_images', tr_crop_transf
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
Num images in train: 6680
Num images in valid: 835
Num images in test: 836
```

#### 1.1.13 (IMPLEMENTATION) Model Architecture

Num images in test: 836

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model\_transfer.

```
In [6]: import torchvision.models as models
    import torch.nn as nn

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

## TODO: Specify model architecture
    VGG16 = models.vgg16(pretrained=True)
    IncV3 = models.inception_v3(pretrained=True)
```

```
RNET50 = models.resnet50(pretrained=True)
    models = {'VGG16': VGG16, 'IncV3': IncV3, 'RNET50': RNET50}

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:07<00:00, 73288210.20it/s]

Downloading: "https://download.pytorch.org/models/inception_v3_google-1a9a5a14.pth" to /root/.torch/models/100%|| 108857766/108857766 [00:01<00:00, 72424541.94it/s]

Downloading: "https://download.pytorch.org/models/resnet50-19c8e357.pth" to /root/.torch/models/100%|| 102502400/102502400 [00:01<00:00, 86107776.63it/s]
```

```
In [6]: model_transfer = VGG16
    if use_cuda:
        model_transfer = model_transfer.cuda()
```

**Question 5:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

**Answer:** Three architectures are evaluated: vgg16, inception v3 and resnet. Vgg16 tradesoff accuracy with ease of computation. The 3x3 kernel allows increasing the depth of the CNN convs providing better detection that previous network. Thus, it is a good choice starting with it and moving into other architectures when higher accuracy is required. Resnet is computionally complexer models but not too demanding to train. The architecture has delivered better results when assessed in dog/human detector at step 2. I have used the nets freezing the feature / conv layers, and changed only the linear output to adapt the fully connected layer to fit the classes at hand.

# 1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_transfer, and the optimizer as optimizer\_transfer below.

#### 1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_transfer.pt'.

```
model_transfer.classifier[-1] = nn.Linear(model_transfer.classifier[-1].in_features
             # move to gpu is available
             if use_cuda:
                 model_transfer = model_transfer.cuda()
             return model_transfer
In [12]: # train the model
        dog\_breeds = 133
        model_transfer = VGG16
         if use_cuda:
             model_transfer = model_transfer.cuda()
        model_transfer = freeze_feature_layers(model_transfer, dog_breeds, use_cuda)
        model_transfer = train(10, transfer_resaug_loaders, model_transfer, optimizer_transfer
                                 use_cuda, 'model_transfer.pt')
         # load the model that got the best validation accuracy (uncomment the line below)
         model_transfer.load_state_dict(torch.load('model_transfer.pt'))
                                                 Validation Loss: 2.379578
Epoch: 1
                 Training Loss: 3.992542
Validation loss decreased. Saving model ...
Epoch: 2
                 Training Loss: 2.157105
                                                 Validation Loss: 1.429146
Validation loss decreased. Saving model ...
                 Training Loss: 1.570267
                                                 Validation Loss: 1.162556
Epoch: 3
Validation loss decreased. Saving model ...
                 Training Loss: 1.301861
                                                 Validation Loss: 1.085887
Epoch: 4
Validation loss decreased. Saving model ...
                Training Loss: 1.109071
Epoch: 5
                                                 Validation Loss: 0.924187
Validation loss decreased. Saving model ...
Epoch: 6
                Training Loss: 0.998924
                                                 Validation Loss: 0.883514
Validation loss decreased. Saving model ...
Epoch: 7
                 Training Loss: 0.898183
                                                 Validation Loss: 0.905753
                 Training Loss: 0.821752
                                                 Validation Loss: 0.868860
Epoch: 8
Validation loss decreased. Saving model ...
                                                 Validation Loss: 0.848797
Epoch: 9
                 Training Loss: 0.739293
Validation loss decreased. Saving model ...
Epoch: 10
                  Training Loss: 0.696382
                                                  Validation Loss: 0.824698
Validation loss decreased. Saving model ...
In [10]: import torch.optim as optim
        model_transfer_RNET = RNET50
         ### TODO: select loss function
        criterion_transfer = nn.CrossEntropyLoss()
         ### TODO: select optimizer
```

```
optimizer_transfer = optim.SGD(model_transfer_RNET.parameters(), lr=0.01)
         # train the model
         def freeze_RNET_layers(model_transfer, output_classes, use_cuda):
             for param in model_transfer.parameters():
                 param.requires_grad = True
             # modify last classifier layer to fit our output
             model_transfer.classifier = nn.Linear(2048, output_classes)
             # move to qpu is available
             if use_cuda:
                 model_transfer = model_transfer.cuda()
             return model transfer
         dog_breeds = 133
         if use_cuda:
             model_transfer_RNET = model_transfer_RNET.cuda()
        model_transfer_RNET = freeze_RNET_layers(model_transfer_RNET, dog_breeds, use_cuda)
        model_transfer_RNET = train(10, transfer_resaug_loaders, model_transfer_RNET, optimize
                                 use_cuda, 'model_transfer_RNET.pt')
         # load the model that got the best validation accuracy (uncomment the line below)
        model_transfer_RNET.load_state_dict(torch.load('model_transfer_RNET.pt'))
Epoch: 1
                 Training Loss: 3.320516
                                                 Validation Loss: 1.316821
Validation loss decreased. Saving model ...
Epoch: 2
                 Training Loss: 1.074966
                                                 Validation Loss: 0.979682
Validation loss decreased. Saving model ...
                                                 Validation Loss: 0.751343
Epoch: 3
                 Training Loss: 0.676241
Validation loss decreased. Saving model ...
Epoch: 4
                 Training Loss: 0.463238
                                                 Validation Loss: 0.714227
Validation loss decreased. Saving model ...
Epoch: 5
                 Training Loss: 0.345936
                                                 Validation Loss: 0.705079
Validation loss decreased. Saving model ...
Epoch: 6
                 Training Loss: 0.256075
                                                 Validation Loss: 0.718243
                                                 Validation Loss: 0.686255
                 Training Loss: 0.198520
Epoch: 7
Validation loss decreased. Saving model ...
Epoch: 8
                 Training Loss: 0.176412
                                                 Validation Loss: 0.678906
Validation loss decreased. Saving model ...
Epoch: 9
                 Training Loss: 0.129701
                                                 Validation Loss: 0.678232
Validation loss decreased. Saving model ...
                  Training Loss: 0.109922
Epoch: 10
                                                  Validation Loss: 0.687057
```

#### 1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [12]: def test(loaders, model, criterion, use_cuda):
             # monitor test loss and accuracy
             test_loss = 0.
             correct = 0.
             total = 0.
             model.eval()
             for batch_idx, (data, target) in enumerate(loaders['test']):
                 # move to GPU
                 if use_cuda:
                     data, target = data.cuda(), target.cuda()
                 # forward pass: compute predicted outputs by passing inputs to the model
                 output = model(data)
                 # calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                 # convert output probabilities to predicted class
                 pred = output.data.max(1, keepdim=True)[1]
                 # compare predictions to true label
                 correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                 total += data.size(0)
             print('Test Loss: {:.6f}\n'.format(test_loss))
             print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                 100. * correct / total, correct, total))
In [17]: test(transfer_resaug_loaders, model_transfer, criterion_transfer, use_cuda)
Test Loss: 0.866053
Test Accuracy: 74% (620/836)
In [14]: test(transfer_resaug_loaders, model_transfer_RNET, criterion_transfer, use_cuda)
Test Loss: 0.645941
Test Accuracy: 82% (693/836)
```



Sample Human Output

#### 1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [7]: ### TODO: Write a function that takes a path to an image as input
        ### and returns the dog breed that is predicted by the model.
        data_transfer = transfer_res_loaders
        # list of class names by index, i.e. a name can be accessed like class_names[0]
        class_names = [item[4:].replace("_", " ") for item in data_transfer['train'].dataset.cla
        def predict_breed_transfer(img_path, transforms, model_transfer, class_names, use_cuda):
            # load the image and return the predicted breed
            image = Image.open(img_path).convert('RGB')
            img = transforms(image)
            img = img.unsqueeze(0)
            if use_cuda:
                img = img.cuda()
            model_transfer.eval()
            output = model_transfer(img)
            _ , pred = torch.max(output, 1)
            return class_names[pred]
```

## Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face\_detector and human\_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

### 1.1.18 (IMPLEMENTATION) Write your Algorithm

```
In [8]: def dog_detector(img_path, img_size, model = VGG16):
            ## TODO: Complete the function.
            output = VGG16_predict(img_path,img_size, model)
            return output in range(151,268)
In [22]: ### TODO: Write your algorithm.
         ### Feel free to use as many code cells as needed.
         def run_app(img_path):
             ## handle cases for a human face, dog, and neither
             img_size = 224
             img = Image.open(img_path)
             plt.figure()
             plt.title(img_path)
             plt.imshow(img)
             plt.show()
             vt_data_transform = transforms.Compose([
                 transforms.Resize((img_size,img_size)),
                 transforms.ToTensor(),
                 transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                   std=[0.229, 0.224, 0.225])
             ])
             if dog_detector(img_path, img_size, VGG16):
                 print ('Dog detected. Breed', predict_breed_transfer(img_path,vt_data_transform
                                                                                  class_names, use
             elif face_detector(img_path):
                 print ('Human detected, looks like a : ', predict_breed_transfer(img_path, vt_da
                                                                                  class_names, use
             else:
                 print ('Bad detection. What is that?')
```

## Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

# 1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

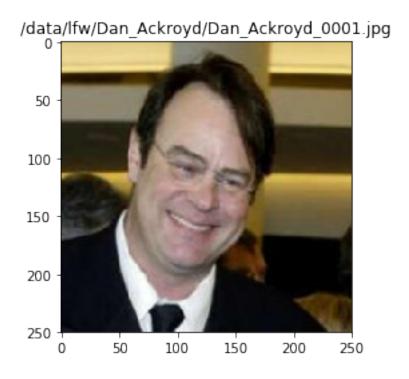
**Question 6:** Is the output better than you expected:) ? Or worse:(? Provide at least three possible points of improvement for your algorithm.

**Answer:** (Three possible points for improvement):

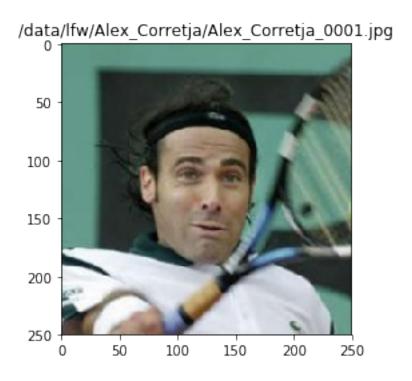
Three points for improvement are: - Use face detector to mask and isolate faces so bakeground has less impact - Determine or improve face detectors to determine whether there are more faces

in the images. Same for dogs - Get more images to improve training dataset, especially of dogs in sideview or not centered - Train for more epochs, use adaptive learning rates - Use batchnormalization layers - Try different networks that admit higher resolution - Define functions to mask the siluette of the dog / human face so the network always focus of face + body features

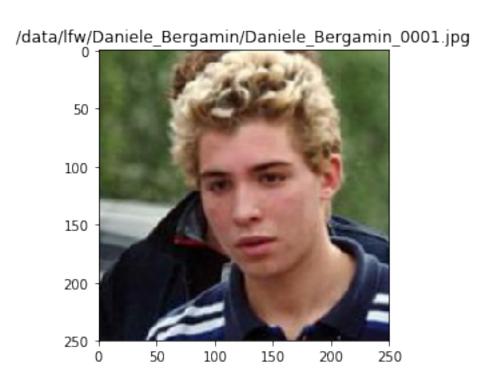
```
In [10]: import numpy as np
         from glob import glob
         # load filenames for human and dog images
         human_files = np.array(glob("/data/lfw/*/*"))
         dog_files = np.array(glob("/data/dog_images/*/*/*"))
         # print number of images in each dataset
         print('There are %d total human images.' % len(human_files))
         print('There are %d total dog images.' % len(dog_files))
There are 13233 total human images.
There are 8351 total dog images.
In [12]: import torch.optim as optim
         model_transfer_RNET = RNET50
         ### TODO: select loss function
         criterion_transfer = nn.CrossEntropyLoss()
         ### TODO: select optimizer
         optimizer_transfer = optim.SGD(model_transfer_RNET.parameters(), lr=0.01)
         # train the model
         def freeze_RNET_layers(model_transfer, output_classes, use_cuda):
             for param in model_transfer.parameters():
                 param.requires_grad = True
             # modify last classifier layer to fit our output
             model_transfer.classifier = nn.Linear(2048, output_classes)
             # move to gpu is available
             if use_cuda:
                 model_transfer = model_transfer.cuda()
             return model_transfer
         dog_breeds = 133
         if use_cuda:
             model_transfer_RNET = model_transfer_RNET.cuda()
         model_transfer_RNET = freeze_RNET_layers(model_transfer_RNET, dog_breeds, use_cuda)
```



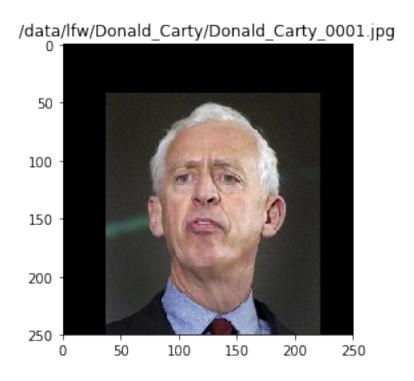
Human detected, looks like a : Dogue de bordeaux



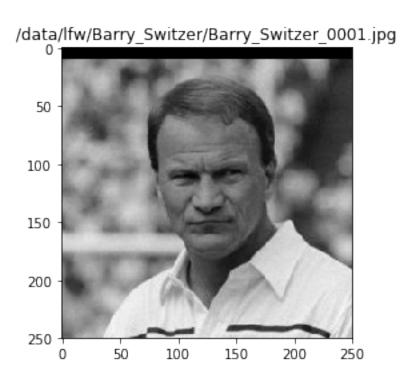
Human detected, looks like a : Lakeland terrier



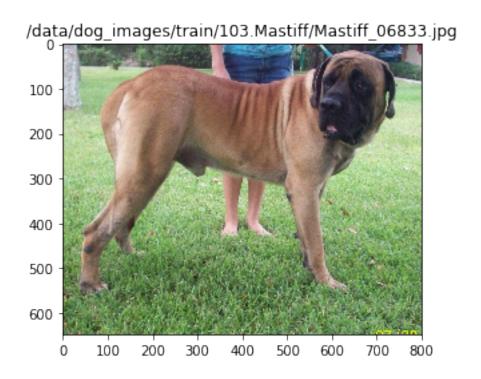
Human detected, looks like a : American water spaniel



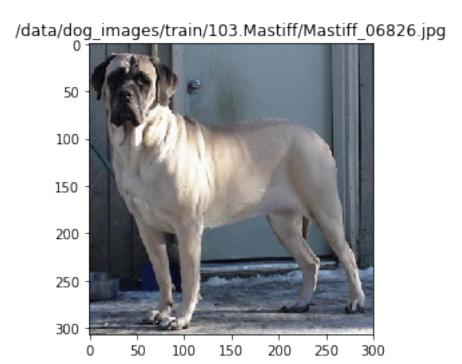
Human detected, looks like a : Dogue de bordeaux



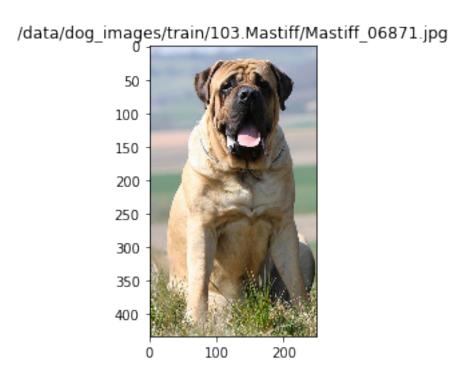
Human detected, looks like a : Dogue de bordeaux



Bad detection. What is that?

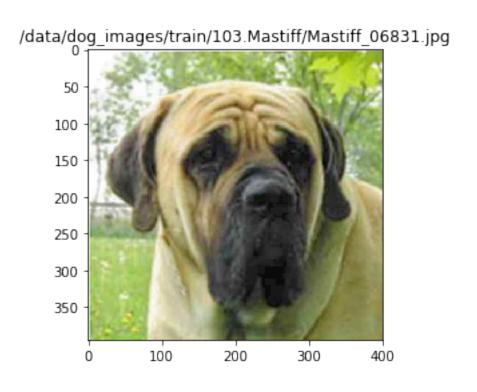


Dog detected. Breed Mastiff





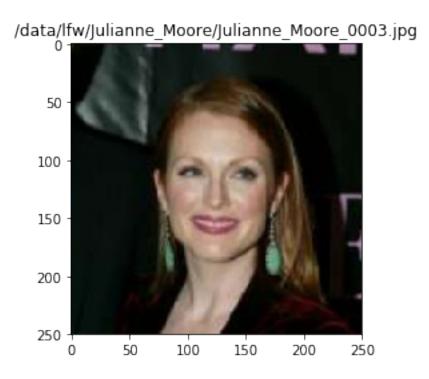
Bad detection. What is that?



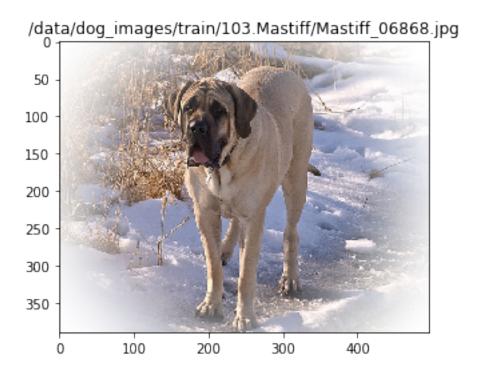
# Dog detected. Breed Mastiff

```
In [25]: ## TODO: Execute your algorithm from Step 6 on
    ## at least 6 images on your computer.
    ## Feel free to use as many code cells as needed.
    from PIL import Image
    import matplotlib.pyplot as plt
    %matplotlib inline

## suggested code, below
    for file in np.hstack((human_files[50], dog_files[50])):
        run_app(file)
```

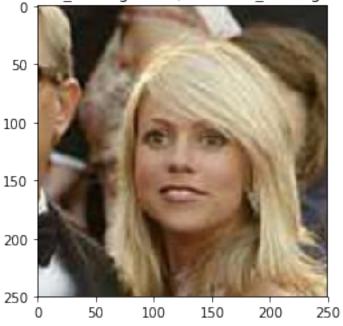


Human detected, looks like a : Dogue de bordeaux



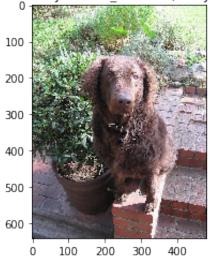
# Dog detected. Breed Mastiff

/data/lfw/Christine\_Baumgartner/Christine\_Baumgartner\_0002.jpg

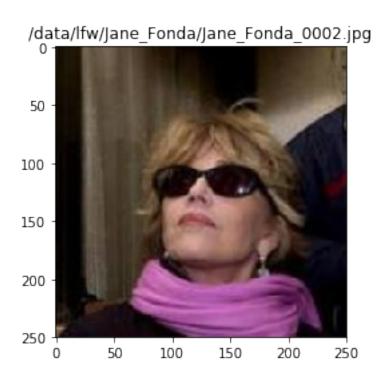


Human detected, looks like a : American water spaniel

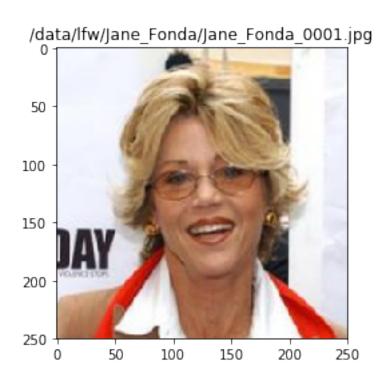
/data/dog\_images/train/055.Curly-coated\_retriever/Curly-coated\_retriever\_03873.jpg



Dog detected. Breed Curly-coated retriever

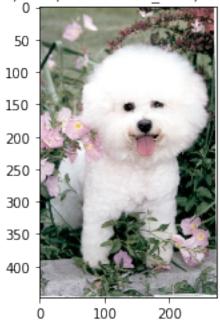


Bad detection. What is that?

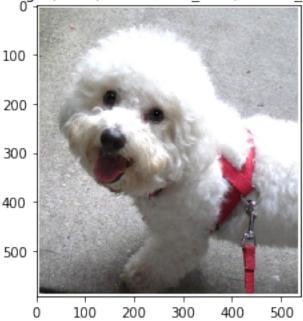


Human detected, looks like a : Afghan hound









Dog detected. Breed Bichon frise

In []: