



**ASSIGNMENT NO: 01**

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## **Lab Manual: Computer Organization and Assembly Language (ARM)**

### **Experiment 1: Understanding ARM Architecture**

#### **Objective:**

To understand the basic components of the ARM architecture.

#### **Task:**

- Research and draw the ARM processor architecture.
- Label the following components:

- **Registers:** General-purpose registers (R0-R15), Program Counter (PC), Link Register (LR), Stack Pointer (SP), Current Program Status Register (CPSR).
- **ALU (Arithmetic Logic Unit):** Handles arithmetic and logical operations.
- **Control Unit:** Manages the execution of instructions.
- **Pipeline Stages:** Fetch, Decode, Execute, Memory Access, and Writeback.
- **Coprocessor Interface:** Used for floating-point operations or specialized instructions.
- **Memory Management Unit (MMU):** Handles memory accesses and translations.

## Experiment 2: Basic Assembly Instructions

### Objective:

To write, execute, and debug basic ARM assembly instructions.

### Tasks:

#### Write a program to load and store data using **LDR** and **STR**:

The **LDR** (Load Register) instruction loads data from memory into a register.

The **STR** (Store Register) instruction stores data from a register into memory.

#### Sample Code for **LDR** and **STR**:

```
AREA Data Section, DATA
num1 DCD 5
num2 DCD 10
```

AREA Code Section, CODE

ENTRY

LDR R0, =num1; Load address of num1 into R0

LDR R1, [R0]; Load value from address in R0 into R1

LDR R0, =num2; Load address of num2 into R0

STR R1, [R0]; Store value of R1 into the address in R0

### **Perform basic arithmetic operations (addition, subtraction) using ADD, SUB:**

The **ADD** instruction performs addition.

The **SUB** instruction performs subtraction.

### **Sample Code for ADD and SUB:**

AREA Code Section, CODE

ENTRY

MOV R0, #5; Load 5 into R0

MOV R1, #10; Load 10 into R1

ADD R2, R0, R1; R2 = R0 + R1 (15)

SUB R3, R1, R0; R3 = R1 - R0 (5)

## **Experiment 3: Conditional Execution**

### **Objective:**

To use conditional execution in ARM assembly.

### **Tasks:**

**Write a program to compare two numbers and output the larger number.**

Use the **CMP** (Compare) and conditional branch instructions **BEQ** (Branch if Equal) and **BNE** (Branch if Not Equal).

### **Sample Code for Conditional Execution:**

```
AREA Code Section, CODE
ENTRY
MOV R0, #15; Load 15 into R0
MOV R1, #10; Load 10 into R1
CMP R0, R1; Compare R0 and R1
BEQ Equal; If R0 == R1, branch to Equal
BGT Greater; If R0 > R1, branch to Greater
BLT Smaller; If R0 < R1, branch to Smaller
```

Equal:

```
MOV R2, R0; Numbers are equal, move R0 to R2
B End
```

Greater:

```
MOV R2, R0; R0 is greater, move R0 to R2
B End
```

Smaller:

```
MOV R2, R1; R1 is greater, move R1 to R2
End:
```

### **Implement a conditional block using CMP, BEQ, BNE:**

Same as the task above with specific conditions being checked using CMP, BEQ, and BNE.

## **Experiment 4: Loops in Assembly**

### **Objective:**

To use loops for repetitive tasks.

### **Tasks:**

**Write a program to calculate the sum of the first N natural numbers:**

Use a loop to sum the numbers from 1 to N.

### **Sample Code for Loop:**

```
AREA Code Section, CODE
ENTRY
MOV R0, #0; Initialize sum to 0
MOV R1, #5; Set N to 5
MOV R2, #1; Initialize counter to 1
Loop:
ADD R0, R0, R2; sum = sum + counter
ADD R2, R2, #1; increment counter
CMP R2, R1; Compare counter to N
BLT Loop; Branch if counter < N
```

**Implement a multiplication operation using iterative addition:**

Use a loop to simulate multiplication by repeated addition.

### **Sample Code for Multiplication:**

```
AREA Code Section, CODE
ENTRY
MOV R0, #0; Initialize result to 0
MOV R1, #4; Set first number
MOV R2, #3; Set second number (multiplier)
MOV R3, #0; Counter for second number
Loop:
```

```
ADD R0, R0, R1; result += first number
ADD R3, R3, #1; increment counter
CMP R3, R2; Compare counter to second number
BLT Loop; Loop until counter equals second number
```

## **Experiment 5: Arrays in Assembly**

### **Objective:**

To work with arrays in ARM assembly language.

### **Tasks:**

#### **Write a program to find the maximum value in an array:**

Iterate through the array and track the maximum value.

#### **Sample Code for Finding Maximum Value:**

```
AREA Data Section, DATA
nums DCD 5, 12, 8, 2, 19
AREA Code Section, CODE
ENTRY
LDR R0, =nums ; Load address of nums into R0
LDR R1, [R0]; Load first number into R1 (max)
MOV R2, #1; Set index to 1
MOV R3, #5; Set array size

Loop:
CMP R2, R3; Compare index to array size
BEQ End; If index == size, end loop
LDR R4, [R0, R2, LSL #2]; Load next element from
array
CMP R4, R1; Compare with current max
```

BGT DataMax; If greater, update max  
B Next Iteration

Update:

MOV R1, R4; Update max with new value

Next Iteration:

ADD R2, R2, #1; Increment index

B Loop

End:

### **Sort an array using the bubble sort algorithm:**

Implement the bubble sort algorithm to reorder elements.

### **Sample Code for Bubble Sort:**

AREA Data Section, DATA

nums DCD 5, 12, 8, 2, 19

AREA Code Section, CODE

ENTRY

LDR R0, =nums ; Load address of nums into R0

MOV R1, #5; Array size

Outer Loop:

MOV R2, #0; Reset inner loop counter

MOV R3, R1; Reset iteration counter

Inner Loop:

CMP R2, R3; Compare index to iteration count

BEQ Outer End; If end of array, exit inner loop

LDR R4, [R0, R2, LSL #2]; Load current element

LDR R5, [R0, R2, LSL #2 + 4]; Load next element

```
CMP R4, R5; Compare current and next elements
BLE Skip Swap; If current <= next, no swap
STR R5, [R0, R2, LSL #2]; Swap values
STR R4, [R0, R2, LSL #2 + 4]
Skip Swap:
ADD R2, R2, #1; Increment inner loop counter
B Inner Loop
```

```
Outer End:
SUB R1, R1, #1; Decrement outer loop counter
CMP R1, #1; Check if sorted
BGT Outer Loop; If not, continue
```

## **Assessment Questions**

### **Describe the difference between RISC and CISC architectures:**

RISC (Reduced Instruction Set Computing) focuses on a small set of simple instructions, while CISC (Complex Instruction Set Computing) uses a large set of complex instructions.

### **Explain the role of the program counter (PC) in ARM architecture:**

The **PC** holds the address of the next instruction to be executed.

### **What is the significance of condition codes in ARM assembly?**

Condition codes (N, Z, C, V) store the status of the result of the last operation (negative, zero, carry, overflow) and affect conditional execution.



## **How does the ARM pipeline improve performance?**

The pipeline allows multiple instructions to be processed simultaneously at different stages, improving execution speed.

## **Compare direct and indirect addressing modes in ARM assembly:**

Direct addressing directly uses a memory address, while indirect addressing uses a register that contains a memory address.

## **What is the difference between LDR and LDM instructions?**

**LDR** loads a single value from memory into a register, while **LDM** (Load Multiple) loads multiple values into a set of registers.

## **Explain the use of the stack pointer (SP) in subroutine calls:**

The **SP** points to the top of the stack, which stores return addresses, local variables, and saved registers during function calls.

## **How are interrupts handled in ARM architecture?**

ARM uses a vector table to handle interrupts and jumps to a specific address based on the interrupt type.

## **What are the advantages of using thumb instructions in ARM?**

Thumb instructions are more compact, reducing memory usage and improving performance on memory-constrained systems.

## **Write a code snippet for swapping two numbers without using a third variable:**

```
MOV R0, #5; First number  
MOV R1, #10; Second number
```

EOR R0, R1; XOR R0 and R1

EOR R1, R0; XOR R1 and R0 (now R1 = original R0)

EOR R0, R1; XOR R0 and R1 (now R0 = original R1)

### **Define the term "endianness" and its impact on memory storage in ARM:**

- Endianness refers to the order in which bytes are stored. ARM can be configured as big-endian or little-endian, affecting how multi-byte data is stored and read.

### **How does the barrel shifter in ARM instructions work?**

- The **barrel shifter** allows shifting or rotating of a value by a specified number of positions without needing multiple instructions.

### **Why is pipelining important in ARM processors?**

- Pipelining increases the throughput of instructions by allowing multiple instructions to be processed simultaneously in different stages.

### **Explain how floating-point operations differ from integer operations:**

- Floating-point operations handle real numbers (fractions), while integer operations deal with whole numbers.

### **What are the advantages of inline assembly in ARM-based C programming?**

- Inline assembly allows developers to write highly optimized code for specific tasks, improving performance where C might be less efficient.