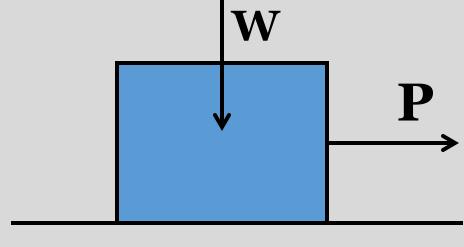


- Friction or retards slipping of the body relative to a second body or surface which it is in contact.
- Acts tangents to the surfaces at point of contact with other body
- Dopposing possible or existing motion of the body relatives of points of contact.
- Two types of friction Fluid and Coulomb friction.

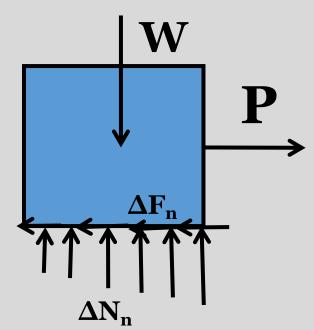
- Fluid friction exist when the contacting surface are separated by a film of fluid(gas or liquid)
- Depends on velocity of the fluids and its ability to resist shear force.
- Coulomb friction, is also known as dry friction, occurs between contacting surfaces of bodies in the absence of a lubricating fluid.

#### Theory of dry friction:-

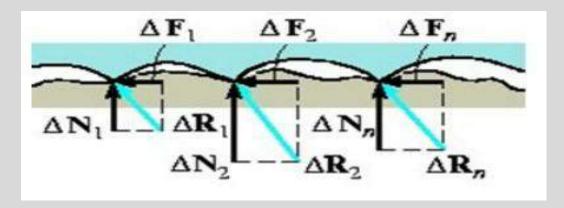
- Consider the effects caused by pulling horizontally on a block of uniform weight W which is resting on the rough horizontal surface.
- Consider the surface of contact to be nonrigid or deformable and other parts of the block to be rigid.
- >FBD of the block :-



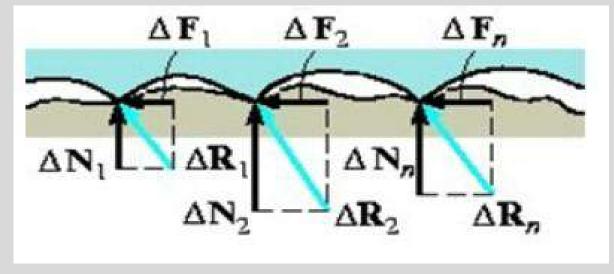
- The floor experts a distribution of the normal force  $\Delta N_n$  and frictional force  $\Delta F_n$  along the contact surface.
- For equilibrium, the normal forces act upward to balance the block's weight **W**, and the frictional forces act to the left to prevent force **P** from moving the block to the right.



- Examining the contacting surfaces between the floor and the block, it can see that many microsropic irregularities exist between the two surfaces.
- $\triangleright$  Reactive forces  $\Delta R_n$  developed at each of the protuberances.

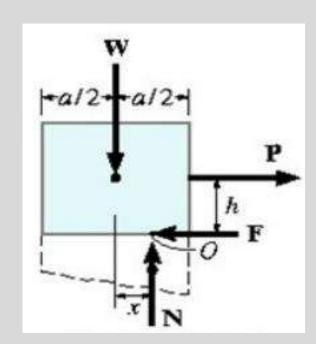


These forces act at all points of contact and each reactive force consist of both a frictional component  $\Delta F_n$  and a normal componenet  $\Delta N_n$ .



#### ☐ Equilibrium :-

- Effect of normal and frictional loadings are indicating by their resultant N and F.
- ightharpoonup Dristribution of  $\Delta F_n$  indicates that F is tangent to the contacting surface , opposite to the direction of P.

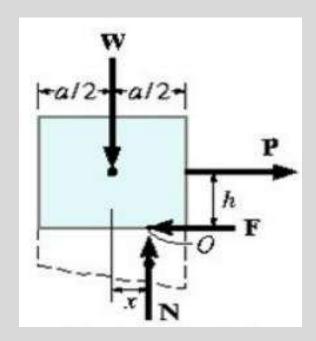


Resultant force and normal forces

ightharpoonup Normal force N is determined from the distribution of  $\Delta N_n$ 

### □Example:-

- P is applied at a height h from the surface
- Moment equilibrium about point O is satisfied if X = Ph/W
- The block is on the verge on tipping if N acts at the right corner of the block X = a/2

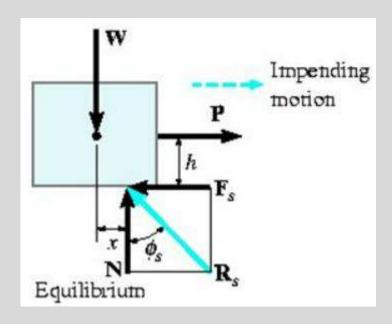


Resultant force and normal forces

- ☐ Impending motion:-
- In cases h is small or surfaces of contact are rather "slippery", the frictional force F may not be great enough to balance P and consequently, the block will tend to slip before it can tip.
- As P is slowly increased, F correspondingly increase untill it attains a certain maximum value F, called the limiting static force.

- When the value is reached, any further increase in P will cause deformation and fractures at the points of surface contact and consequently, the block will begin to move.
- $\blacktriangleright$  Limiting static frictional force  $F_s$  is directly proportional to resultant normal force N

$$F_s = \mu_s N$$



- $\triangleright$  Constant of proportionlity  $\mu_s$  is known as the coefficient of static friction .
- When the block is on the verge of sliding, the normal force N and the frictional force  $F_s$  combine to form a resultant  $R_s$ .
- $\blacktriangleright$  Angel  $\emptyset_s$  that  $R_s$  makes with N is called the angle of static friction.

$$\emptyset_S = \tan^{-1}\left(\frac{F_S}{N}\right) = \tan^{-1}\left(\frac{\mu_S N}{N}\right) = \tan^{-1}\mu_S$$

 $\triangleright$  Typical values of  $\mu_S$ 

#### Contact metarials

Metal on ice

Wood on wood

Leather on wood

Leather on metal

Aluminium on aluminium

### Coefficient of static friction

0.03 - 0.05

0.3 - 0.7

0.2 - 0.5

0.3 - 0.6

1.1 - 1`.7

- $\Box$  Tabular values of  $\mu_S$ : —
- Coefficient usually < 1 but for aluminium on aluminium, coefficient > 1.
- For coefficient > 1, frictional force > normal force
- $\blacktriangleright \mu_{S}$  is dimensionless and depends on the characteristics of the contacting surfaces .
- When a more accurate calculation of  $F_{\rm s}$  is needed , coefficient of friction is determined by experiments of the two metarials involved.

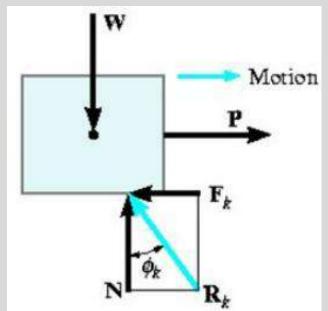
#### ☐Motion:-

If the magnitude of P acting on the block is increased so that it is greater than  $F_s$ , the frictional force at the contacting surfaces

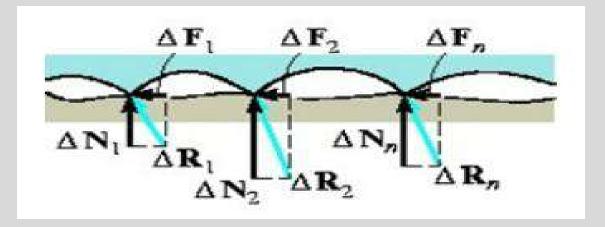
drops slightly to a smaller value  $\boldsymbol{F}_{s}$ , called kinetic

frictional force.

The block will not be held in equilibrium  $(P > F_s)$  but slide with increasing speed.



- The drop made in the frictional force magnitude from  $F_s$  (static) to  $F_k$  (kinetic), can explained by examining the contacting surfaces.
- When  $P > F_s$ , P has the capacity to shear off the peaks at the contact surfaces, causing the blocks to lift and ride on top of these peaks.



- Once the block begins to slide, high local temparatures at these points of contact cause momentary adhesion (welding) of these points.
- Continued shearing of these welds is the dominate mechanism causing friction.
- Since resultant forces  $\Delta R_n$  are aligned more in the vertical direction than before, they contribute smaller frictional components  $\Delta F_n$  than when the irregularities are meshed.

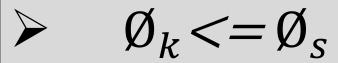
Resultant frictional force  $F_k$  is directly proportional to the magnitude of the resultant normal force N.

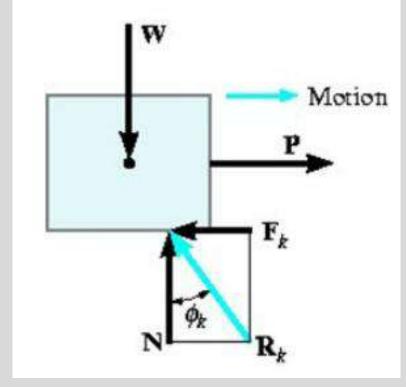
$$F_k = \mu_k N$$

- ightharpoonup Constant of proportionality  $\mu_k$  is called the coefficient of kinetic friction .
- $\succ \mu_k$  are typically 25% smaller than  $\mu_S$  .

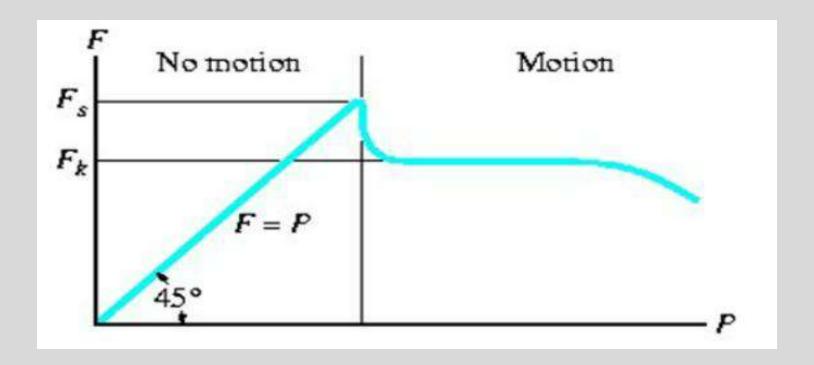
 $ightharpoonup \operatorname{Resultant} R_k$  has a line of action defined by  $\emptyset_k$  , angle of kinetic friction

$$\emptyset_k = \tan^{-1}\left(\frac{F_k}{N}\right) = \tan^{-1}\left(\mu_k\right)$$





The graph summarizes the effects regarding friction and shows the variation of frictional force F versus applied load P



- Frictional force is categorized into three ways
- 1. F is a static frictional force if equilibrium is maintained.
- 11. F is a limiting static frictional force  $F_s$  when it reaches the maximum value needed to maintain equilibrium
- III. F is a kinetic-frictional force  $F_k$  when when sliding occurs at the contact surface

- The frictional force acts tangent to the contacting surfaces in a direction opposite to the relative motion or tendency for motion of one surface against another.
- The maximum frictional force  $F_{\scriptscriptstyle S}$  that can be developed is independent of the area of contact, provided the normal pressures is not very low or great enough to severely deform of crush the contacting surfaces of the bodies .

- The maximum static frictional force is generally greater than the kinetic frictional force.
- $\blacktriangleright$  However, if one of the bodies is moving with a very slow velocity over the surface of another  $\digamma_k$  becomes approximately equal to  $\digamma_s$ .
- When slipping at the surface of contact is about to occur, the maximum static frictional force is proportional to the normal force.

# THANK YOU SIR

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