### **Electric Vehicle Population — Unsupervised Learning Report**

#### **Executive Summary (≤150 words)**

We analysed Washington State's Electric Vehicle (EV) registrations (≈178k rows; Kaggle) using PCA + clustering to surface actionable segments for planning, incentives and infrastructure. PCA (95% variance) followed by a model grid (K-Means, GMM, Agglomerative; k=3–6) on a 5,000-row stratified sample identified K-Means (k=3) as the most effective balance of separation and stability (Silhouette 0.225, CH ≈1,025, bootstrap ARI ≈0.79). Segments split into two large cohorts (≈66% and ≈34%) and a tiny edge group (≈0.2%) likely representing outliers or rare records. Categorical profiling was limited in this run due to missing values; numeric profiles indicate a newer, low-electric-range cohort (likely PHEVs) versus an older, higher-range cohort (BEVs). We recommend k=3 with a follow-up outlier pass (DBSCAN/HDBSCAN) and improved MSRP data quality.

## 1) Objective

- **Primary goal:** derive interpretable **EV segments** to inform infrastructure placement, incentives, and manufacturer insights.
- **Technique focus: Clustering** (with PCA for denoising/acceleration).
- Stakeholder benefits: targeted charger rollout (fast/level-2 mix), refined CAFV/incentive targeting, OEM/regional mix monitoring.
- **Success criteria:** internal separation (Silhouette, CH), **stability** under resampling (bootstrap ARI), and business interpretability.

#### 2) Data Description

- Source: Electric Vehicle Population Data 2024 (Washington State; Kaggle).
- Scope: 177,866 records, 17 columns (vehicle specs + geography + eligibility).
- **Key attributes used (examples):** Model Year, Electric Range, Base MSRP, Electric Vehicle Type, Make/Model, County/City.
- **Limitations noted:** missing or zero **Base MSRP** for many rows; averaging **postal/tract/district codes** is not semantically meaningful; categorical breakdowns were sparse in this sample export.

### 3) Exploration & Preparation

- Cleaning: numeric casting; median imputation; top-K category capping (≤25 per field) to prevent very wide OHE.
- Feature engineering: Vehicle\_Age = current\_year Model Year;
  Range\_per\_1000USD when MSRP available.
- **Scaling & encoding:** StandardScaler for numeric; One-Hot for categorical (capped).
- **Dimensionality reduction: PCA @ 95% variance** (embedding size observed **44** on sample).
- Sample for iteration: 5,000 rows (full run recommended once finalised).

## 4) Models & Variations

**Grid:** K-Means, GMM (full covariance), Agglomerative (Ward), with  $k \in \{3,4,5,6\}$ . **Metrics:** Silhouette ( $\uparrow$ ), Davies–Bouldin ( $\downarrow$ ), Calinski–Harabasz ( $\uparrow$ ), and **bootstrap ARI** stability.

## Top variants (sorted by Silhouette then CH):

Variant	Silhouette	DB	СН
K-Means (k=3)	0.2246	1.5511	1024.67
Agglomerative (k=3)	0.2225	1.5661	994.66
Agglomerative (k=4)	0.2203	1.3313	999.48
K-Means (k=6)	0.1914	1.4885	988.10
Agglomerative (k=6)	0.1754	1.5495	925.33
K-Means (k=5)	0.1702	1.4328	1015.08

Stability: K-Means (k=3) bootstrap ARI ≈ 0.79 (n=5), indicating strong label stability.

## 5) Results & Key Findings

## 5.1 Segment sizes (k=3)

• Cluster 1: 3,286 (≈65.7%)

• Cluster 0: 1,704 (≈34.1%)

• Cluster 2: 10 (≈0.2%) → likely outliers / rare records.

#### 5.2 Numeric profiles (means)

- Cluster 1 (largest): Model Year ≈ 2022.3, Electric Range ≈ 6 mi → newer, low electric-range vehicles (plausibly PHEVs).
- Cluster 0: Model Year ≈ 2017.1, Electric Range ≈ 159 mi → older, higher range vehicles (likely BEVs).
- Cluster 2: tiny group (n=10), Range  $\approx 118$  mi treat as outlier/edge cases rather than a policy segment.
- MSRP caution: Base MSRP shows many zeros/missing → do not rely on MSRP-derived insights until cleaned.

#### 5.3 Visual evidence

- **Silhouette ranking** favours **k=3**, with Agglomerative close behind.
- Elbow lacks a sharp knee → internal metrics + stability trump the elbow in this dataset.
- PCA scatter shows a small, distant cluster consistent with outliers.

#### 6) Recommended Model

- Model: K-Means (k=3) on PCA(95%) features.
- Why: best overall separation + highest stability; interpretable 2-tier structure (BEV-like vs PHEV-like) plus outlier bucket.
- Operationalisation: bake preprocessing → PCA → k=3 assignment; refresh weekly/monthly; monitor drift (silhouette, share per cluster; alert if outlier share >1%).

## 7) Limitations & Risks

- Data quality: MSRP missing/zero; categorical profiling sparse in this export.
- **Geographic codes:** means of codes are not meaningful avoid direct interpretation.
- Outliers: 0.2% micro-cluster suggests noise; clustering can be sensitive to these points.
- **Visual DR caveat:** PCA/t-SNE/UMAP are **visual aids**, not clustering objectives; avoid over-interpreting shapes.

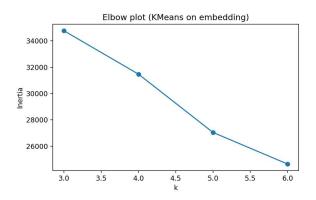
## 8) Next Steps

- Re-run on full dataset (remove --sample), prefer MiniBatchKMeans for speed; validate metrics and stability.
- Outlier-aware pass: try HDBSCAN/DBSCAN; remove noise then refit k-means to improve Silhouette.
- Improve MSRP field (impute from VIN/trim tables or drop MSRP features until reliable).
- **Feature sensitivity:** compare **numeric-only** vs **full** feature set; ablate geography if policy focus is statewide.
- **Actionability:** map cluster shares by county/city; align charger type mix (fast vs L2) to cluster distribution; A/B test incentive targeting by segment.

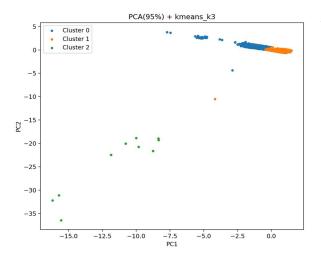
#### References

- Kaggle: Electric Vehicle Population Data 2024 (Washington State).
- scikit-learn documentation (PCA, K-Means, GMM, Agglomerative).

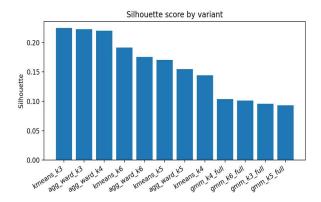
## **Appendix** — Figures



1. Elbow plot (K-Means on embedding)



# 2. Silhouette score by variant



# 3. PCA(95%) + kmeans\_k3 scatter