

Parte 02 - Deslocamento temporal da função de onda

a equação da função de onda completa:

$$i\hbar \frac{\partial \Psi}{\partial t} = \text{op } H \Psi$$

O $\text{op} H$ é um operador de evolução temporal. Pode, ele, também assumir, a seguinte identidade matemática:

$$\text{op } U(\Delta t) = e^{\frac{-i \text{op } H \Delta t}{\hbar}}$$

Resultando, portanto, na solução, descrita abaixo:

$$\Psi(x, t + \Delta t) = e^{\frac{-i \text{op } H \Delta t}{\hbar}} \cdot \Psi(x, t)$$

Podendo tratar o expoente de um operador, por meio de uma série infinita, tem-se:

$$e^{\frac{-i \text{op } H \Delta t}{\hbar}} = \sum_n \frac{\left(\frac{-i \text{op } H \Delta t}{\hbar}\right)^n}{n!}$$

In [12]: `#Bibliotecas`

```
import matplotlib.animation as animation
from IPython.display import HTML
import matplotlib.pyplot as plt
import scipy.fftpack as fft
import scipy.linalg as scl
import numpy as np
import math
%matplotlib widget
%matplotlib inline
```

O Hamiltoniano no espaço:

$$x_n = x_0 + n\Delta x, \text{ com } \Delta x = \frac{(x_N - x_0)}{N}$$

Os valores de entrada:

In [16]: `hbar = 1`
`m = 1`

Processing math: 100%

```

N = 2**11
L = 200.0
step_low = 0.
step_high= 1.
V0 = 10.

```

Definição do espaço:

```

In [18]: n = np.arange(N)
x0 = -L/2.
xN = L/2.
Delta_x = (xN - x0)/N
print("Delta_x = ",Delta_x)

```

Delta_x = 0.09765625

Definição do potencial:

```

In [20]: V = np.zeros(N)
for i in range(N):
    if x[i]>= step_low and x[i]<= step_high:
        V[i]= V0

```

Configuração do Hamiltoniano para a função V , multiplicação com a matriz inversa:

```

In [22]: Mdd = 1./(Delta_x**2)*(np.diag(np.ones(N-1),-1)
        - 2* np.diag(np.ones(N),0)
        + np.diag(np.ones(N-1),1))
H = -(hbar*hbar)/(2.0*m)*Mdd + np.diag(V)

En,psiT = np.linalg.eigh(H)    # autovalores e os autovetores.
psi = np.transpose(psiT)       # Tomamos a transposta de psiT para os vetores de fun
                                # que podem ser acessados como psi[n]

```

Intervalo temporal

```

In [24]: dt_max = 2/np.max(En)    # Critério de estabilidade.
dt = 0.001
if dt > dt_max:
    print("ATENÇÃO: dt está na região instável!")

```

Função de onda inicial

```

In [26]: g_x0=-10.
g_k0=6.
g_sig=2.

```

Definição de um Gaussiano no espaço K, com $p = \hbar k$, um momento k_0 , e o espaço x,

$$\psi(x, 0) = \left(\frac{2L}{\pi}\right)^{1/4} \cdot e^{-Lx^2}:$$

```
In [28]: def psi0(x,g_x0,g_k0,g_sig):
        _Norm_x=np.sqrt(Delta_x/g_sig)/(np.pi**0.25)

        return(_Norm_x*np.exp(-(x-g_x0)**2/(2.*g_sig*g_sig)+1j*g_k0*x))

psi_t0 = psi0(x,g_x0,g_k0,g_sig)
```

```
In [29]: # H é Hermitiano?
print("Verifique se H é realmente Hermitiano : ",np.array_equal(H.conj().T,H))
```

Verifique se H é realmente Hermitiano : True

```
In [30]: Ut_mat = np.diag(np.ones(N,dtype="complex128"),0)

print("Criação de uma matriz U(dt = {})".format(dt))
for n in range(1,3):
    # Realiza a soma. Como se trata de matrizes, o processo irá demorar se N for gr
    Ut_mat += np.linalg.matrix_power((-1j*dt*H/hbar),n)/math.factorial(n)
```

Criação de uma matriz U(dt = 0.001)

```
In [31]: p = Ut_mat.dot(psi_t0)

print("O quanto a normalização muda por etapa? Desde {} até {}".format(np.linalg.no
print("Nº de etapas em que a norma está errada por um fator 2 : ",1/(np.linalg.norm
```

O quanto a normalização muda por etapa? Desde 1.0 até 1.0000000127814086

Nº de etapas em que a norma está errada por um fator 2 : 78238637.96537858

teste do movimento gaussiano:

```
In [33]: psi_t0 = psi0(x,g_x0,g_k0,g_sig)
psi_t1 = psi_t0
psi_tu = []

for t in range(3500):
    psi_t1 = Ut_mat.dot(psi_t1)
    if t>0 and t%500==0:
        psi_tu.append( (t,psi_t1))
psi_tu.append( (t,psi_t1))
```

Teste e verificação de coerência dos resultados:

$\langle E \rangle$ = estado esperado da energia;

$\langle x \rangle$ = estado esperado da posição

```
In [35]: print("Normalização : ",np.linalg.norm(psi_tu[-1][1]))

vev_E0=float(np.real(np.sum(np.conjugate(psi_t0)*H.dot(psi_t0))))
```

```

vev_x0=float(np.real(np.sum(np.conjugate(psi_t0)*x*psi_t0)))

print("<E_(t = 0)> = {:.4f}   <x_(t = 0)> = {:.4f}".format(vev_E0,vev_x0))

for t,p in psi_tu:
    norm = np.linalg.norm(p)
    vev_E1 = float(np.real(np.sum(np.conjugate(p)*H.dot(p))))
    vev_x1 = float(np.real(np.sum(np.conjugate(p)*x*p)))
    print("dt = {:.1f}   norm = {:.5f}   <E> = {:.4f}   <x_(dt)> = {:.4g}".format(

```

Normalização : 1.000044736361259

<E_(t = 0)> = 17.5429 <x_(t = 0)> = -10.0000

dt = 500.0 norm = 1.00001 <E> = 17.5432 <x_(dt)> = -7.164

dt = 1000.0 norm = 1.00001 <E> = 17.5434 <x_(dt)> = -4.335

dt = 1500.0 norm = 1.00002 <E> = 17.5436 <x_(dt)> = -1.55

dt = 2000.0 norm = 1.00003 <E> = 17.5439 <x_(dt)> = 0.8044

dt = 2500.0 norm = 1.00003 <E> = 17.5441 <x_(dt)> = 2.91

dt = 3000.0 norm = 1.00004 <E> = 17.5443 <x_(dt)> = 5.103

dt = 3499.0 norm = 1.00004 <E> = 17.5446 <x_(dt)> = 7.305

Dos dados obtidos, resulta:

```

In [37]: def opt_plot():
    plt.minorticks_on()
    plt.tick_params(axis='both',which='minor', direction = "in",
                    top = True,right = True, length=5,width=1,
                    labelsz=15)
    plt.tick_params(axis='both',which='major', direction = "in",
                    top = True,right = True, length=8,width=1,
                    labelsz=15)

    plt.figure(figsize=(8,5))

    if vev_E0>max(V):
        plt.title('Espalhamento')
    else:
        plt.title('Tunelamento')
    plt.ylabel('$\psi(x,t)$')
    plt.xlabel('$x$')
    # plt.plot(x,np.abs(psi_t0)/np.sqrt(Delta_x),label="$\Psi(x,t=0)$")

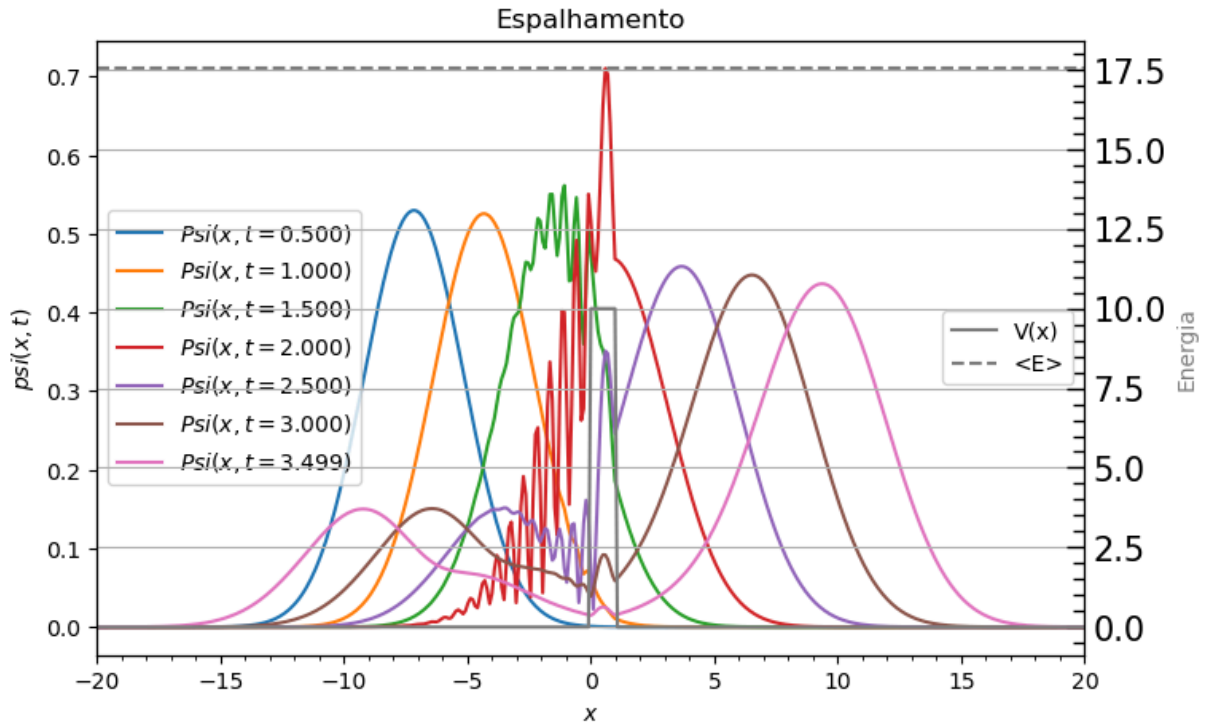
    for t,p in psi_tu:

        plt.plot(x,np.abs(p)/np.sqrt(Delta_x),label="$\Psi(x,t={:.3f})$".format(t*dt))
        plt.legend(loc = 'center left')

    ax1 = plt.twinx()
    plt.plot(x,V,color="grey",label="V(x)")
    plt.plot([x[0],x[N-1]],[vev_E0,vev_E0],color="grey",linestyle="--",label="<E>")
    plt.ylabel("Energia",color="grey")
    plt.xlim(g_x0-5*g_sig,-g_x0+5*g_sig)
    plt.legend(loc='best')
    plt.grid()
    opt_plot()

```

```
plt.savefig('Estado deslocado.png')
```



```
In [38]: %time Ut_05s = np.linalg.matrix_power(Ut_mat,int(0.5/dt) )
```

CPU times: total: 2min

Wall time: 1min 15s

Repetição de tarefa

```
In [40]: psi_t0 = psi0(x,g_x0,g_k0,g_sig)
psi_t1 = psi_t0
psi_tu05 = []

for t in range(7):
    psi_t1 = Ut_05s.dot(psi_t1)
    psi_tu05.append( (t,psi_t1))
    # psi_tu.append( (t,psi_t1))
print("Start")
v1=[]
v2=[]
tm=[]
count=0
for t,p in psi_tu05:
    norm = np.linalg.norm(p)
    vev_E1 = float(np.real(np.sum(np.conjugate(p)*H.dot(p))))
    vev_x1 = float(np.real(np.sum(np.conjugate(p)*x*p)))
    v1.append(vev_E1)

    v2.append(vev_x1)
    tm.append(count)
    count=count+1
print("dt = {:.1f}  norm = {:.5f}  <E> = {:.4f}  <x(dt)> = {:.4g}".format(
```

Processing math: 100%

```

Start
dt =      0.0  norm =  1.00001  <E> =  17.5432  <x_(dt)> =   -7.17
dt =      1.0  norm =  1.00001  <E> =  17.5434  <x_(dt)> =   -4.34
dt =      2.0  norm =  1.00002  <E> =  17.5436  <x_(dt)> =   -1.555
dt =      3.0  norm =  1.00003  <E> =  17.5439  <x_(dt)> =    0.8002
dt =      4.0  norm =  1.00003  <E> =  17.5441  <x_(dt)> =    2.905
dt =      5.0  norm =  1.00004  <E> =  17.5443  <x_(dt)> =    5.099
dt =      6.0  norm =  1.00004  <E> =  17.5446  <x_(dt)> =    7.305

```

```

In [41]: plt.figure(figsize=(8,5))

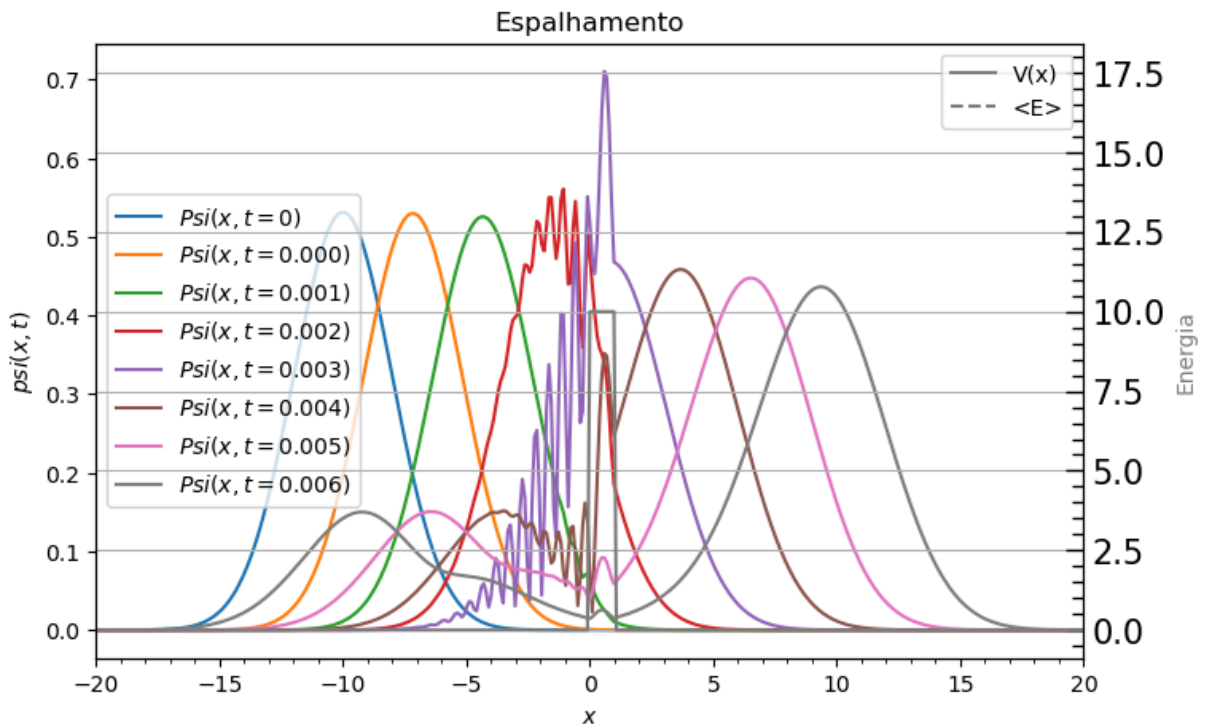
if vev_E0>max(V):
    plt.title('Espalhamento')
else:
    plt.title('Tunelamento')
plt.ylabel('$\psi(x,t)$')
plt.xlabel('$x$')
line, = plt.plot(x,np.abs(psi_t0)/np.sqrt(Delta_x),label="$\Psi(x,t=0)$")

for t,p in psi_tu05:
    plt.plot(x,np.abs(p)/np.sqrt(Delta_x),label="$\Psi(x,t={:6.3f})$".format(t*dt))
    plt.legend(loc='center left')

ax1 = plt.twinx()
plt.plot(x,V,color="grey",label="V(x)")
plt.plot([x[0],x[6]], [vev_E0,vev_E0],color="grey",linestyle="--",label="<E>")
plt.ylabel("Energia",color="grey")
plt.xlim(g_x0-5*g_sig,-g_x0+5*g_sig)
plt.legend(loc='best')
plt.grid()
opt_plot()

plt.savefig('Estado deslocado - Pré-computados.png')

```



Parte 3 - A Regressão Simbólica

```
In [43]: from sklearn.utils import check_random_state, shuffle
from gplearn.genetic import SymbolicRegressor
from sklearn.ensemble import RandomForestRegressor
from sklearn.tree import DecisionTreeRegressor
from sklearn.utils.random import check_random_state
from mpl_toolkits.mplot3d import Axes3D
from IPython.display import Image
import pydot
import graphviz
from sympy import *
import pandas as pd
```

Definição dos Operadores

```
In [45]: converter = {
    'sub': lambda x, y : x - y,
    'div': lambda x, y : x/y,
    'mul': lambda x, y : x*y,
    'add': lambda x, y : x + y,
    'neg': lambda x : -x,
    'pow': lambda x, y : x**y,
    'sin': lambda x : sin(x),
    'cos': lambda x : cos(x),
    'inv': lambda x: 1/x,
    'sqrt': lambda x: x**0.5,
    'pow3': lambda x: x**3
}
```

Interpretação Probabilística Gaussiana da Distribuição Normal

$$N(\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}}$$

:

```
In [47]: m1=[]
md=[]
count=0
tem=0
df=pd.DataFrame()
df2=pd.DataFrame()
xix=[]
df['v1']=v1
df2['v2']=v2

for i in v2:
    m1.append(i)
    tem=i-vev_x0
    md.append(tem**2)
```

Processing math: 100%

```

df['m1']=md
df2['t']=tm

dp=2.83/3
A = [float(i) for i in m1]
for i in A:
    xix=np.linspace(-(3.*dp),(3.*dp),40)
    y=0.39*(2.76**(-0.5*(xix**2)))

```

A amostra acima, resulta:

```

In [49]: def opt_plot():
    plt.minorticks_on()
    plt.tick_params(axis='both',which='minor', direction = "in",
                    top = True,right = True, length=5,width=1,
                    labelsz=15)
    plt.tick_params(axis='both',which='major', direction = "in",
                    top = True,right = True, length=8,width=1,
                    labelsz=15)
    plt.figure(figsize=(8,5))

    textstr = '\n'.join((
        r'$\mu$=%.2f$' % (0, ),
    ))

    textstr02 = '\n'.join((
        r'$\sigma$=%.2f$' % (1, ),
    ))

    textstr03 = '\n'.join((
        r'$\sigma$=%.2f$' % (2, ),
    ))

    textstr04 = '\n'.join((
        r'$\sigma$=%.2f$' % (1, ),
        r'$\mu$=%.2f$' % (0, ),
    ))

    plt.vlines(0, 0, 0.39, linestyle='dashed', color='b', linewidth=1, label=str(textstr)
    plt.vlines(1, 0, 0.23, linestyle='dashed', color='green', linewidth=1.5, label= str
    plt.vlines(-1, 0, 0.23, linestyle='dashed', color='green', linewidth=1.5) # vlines(
    plt.vlines(2, 0, 0.05, linestyle='dashed', color='orange', linewidth=1.5, label= '2
    plt.vlines(-2, 0, 0.05, linestyle='dashed', color='orange', linewidth=1.5) # vlines

    font1 = {'family':'serif','color':'blue','size':20}
    font2 = {'family':'serif','color':'darkred','size':15}

    plt.title("Alternativa ao Modelo Padrão", fontdict = font1)
    plt.xlabel("x", fontdict = font2)
    plt.ylabel("Densidade", fontdict = font2)

    plt.legend(title='Medidas de Dispersão')

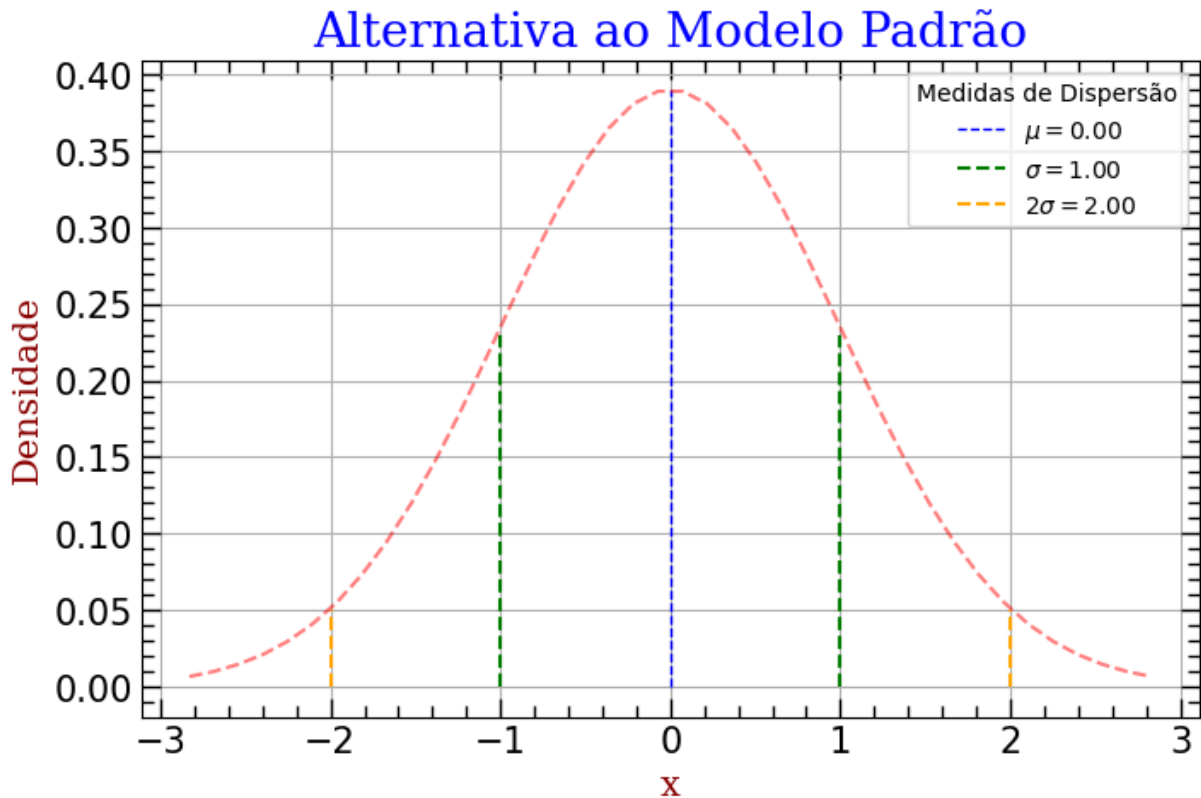
    t.grid()

```



```
opt_plot()
plt.plot(xix,y , 'r--', alpha=0.5, label= textstr04)
```

Out[49]: [<matplotlib.lines.Line2D at 0x21c95f5cda0>]



Criação e Calibração de um modelo Simbólico Regressor:

```
In [51]: function_set = ['add', 'sub', 'mul', 'div', 'cos', 'sin', 'neg', 'inv']
# Instanciação
est_gp = SymbolicRegressor(population_size=5000,
                           generations=20, function_set=function_set,
                           stopping_criteria=0.01,
                           p_crossover=0.7, p_subtree_mutation=0.1,
                           p_hoist_mutation=0.05, p_point_mutation=0.1,
                           max_samples=0.9, verbose=1,
                           parsimony_coefficient=0.01, random_state=0)

# Ajuste
est_gp.fit(xix.reshape(-1, 1), y)
```

Population Average			Best Individual			
Gen	Length	Fitness	Length	Fitness	OOB Fitness	Time Left
0	15.94	8.42754	24	0.101256	0.141842	2.44m
1	8.38	1.41838	10	0.0282817	0.0287366	2.23m
2	4.25	0.913171	10	0.0275074	0.0357058	1.91m
3	2.38	0.458598	10	0.0262319	0.0471853	1.68m
4	2.34	69.5123	10	0.0262295	0.0472067	1.63m
5	4.42	1.11605	11	0.0181481	0.0271488	1.57m
6	6.21	1.40624	11	0.0183373	0.0356987	1.49m
7	6.89	1.00531	11	0.0196629	0.0237683	1.53m
8	7.20	0.86294	11	0.0185499	0.0337846	1.25m
9	7.36	0.927227	12	0.0193277	0.0303689	1.22m
10	7.54	1.14538	12	0.0202671	0.0219142	1.07m
11	7.90	1.22699	8	0.0258667	0.038024	56.28s
12	8.04	1.22625	8	0.0252462	0.0436084	1.06m
13	7.96	1.29076	8	0.0249788	0.0460152	1.05m
14	7.86	1.30819	8	0.0245602	0.04586	55.62s
15	8.06	1.22489	8	0.0247419	0.0481478	38.25s
16	7.99	1.55607	8	0.0246505	0.04897	22.28s
17	7.92	1.26517	11	0.0241093	0.0259531	17.71s
18	7.97	1.25025	8	0.0246505	0.04897	11.49s
19	8.00	1.2177	10	0.023813	0.0384339	0.00s

Out[51]:

SymbolicRegressor

div(0.333, sub(0.812, neg(mul(mul(0.696, X0), X0))))

Escore:

In [53]:

```
print('R2:',est_gp.score(xix.reshape(-1, 1),y))
next_e = sympify(str(est_gp._program), locals=converter)
y1=next_e
```

R2: 0.9502743138806782

Equação Proposta:

In [55]:

y1

Out[55]:

$$\frac{0.333}{0.696X_0^2 + 0.812}$$

Soluções para o Poço de Potencial Infinito

Solução da função de onda da posição

$$\psi_n(x) = \sqrt{\frac{2}{L}} \sin\left(\frac{n\pi x}{L}\right)$$

```

In [58]: import matplotlib.pyplot as plt
import numpy as np
def opt_plot():
    plt.minorticks_on()
    plt.tick_params(axis='both',which='minor', direction = "in",
                    top = True,right = True, length=5,width=1,
                    labelsiz=15)
    plt.tick_params(axis='both',which='major', direction = "in",
                    top = True,right = True, length=8,width=1,
                    labelsiz=15)

a=20
A=np.sqrt(2/a)
# Data for plotting
for i in range(5):
    t = np.arange(0.0, 2.0, 0.01)
    s = A*np.sin(0 * np.pi * t)
    s1 = A*np.sin(0.5 * np.pi * t)
    s2 = A*np.sin(1.0 * np.pi * t)
    s3 = A*np.sin(1.5 * np.pi * t)
    s4 = A*np.sin(2.0 * np.pi * t)

fig, ax = plt.subplots(figsize=(10,6))

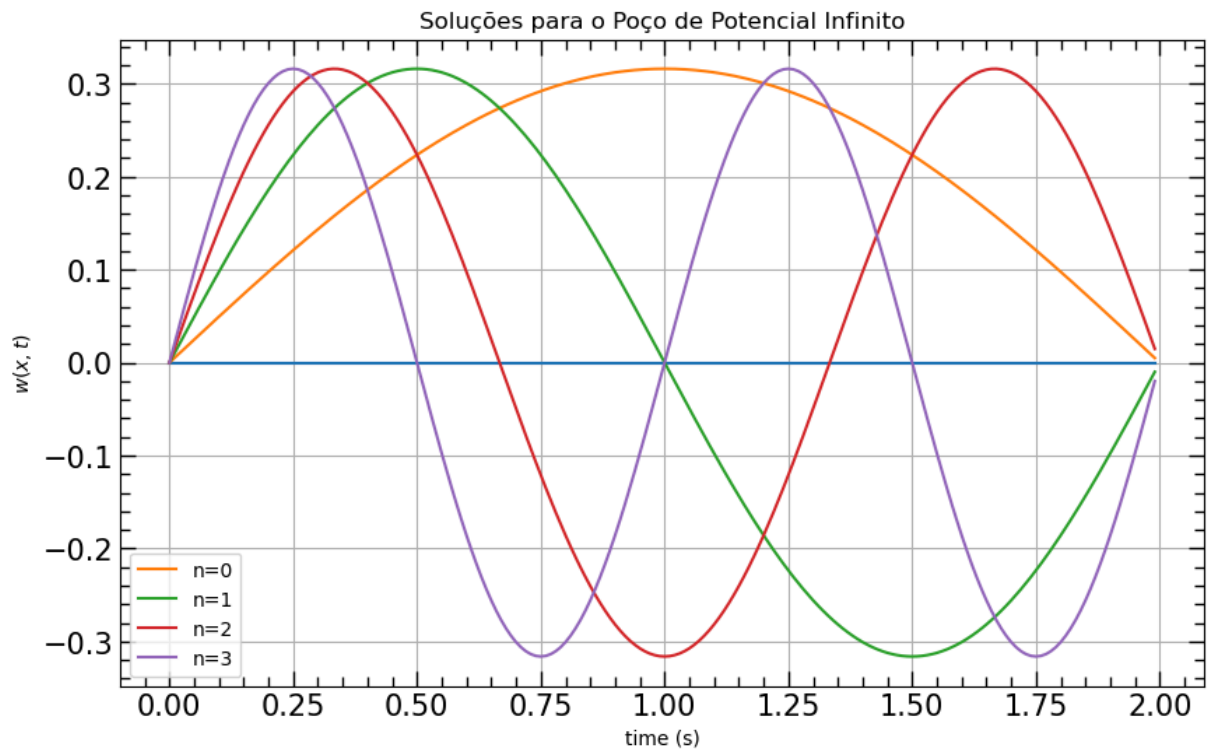
ax.plot(t, s)
ax.plot(t, s1,label='n=0')
ax.plot(t, s2,label='n=1')
ax.plot(t, s3,label='n=2')
ax.plot(t, s4,label='n=3')

ax.set(xlabel='time (s)', ylabel='$w(x,t)$',
       title="Soluções para o Poço de Potencial Infinito")
ax.grid()
opt_plot()

plt.legend()

fig.savefig("test.png")
plt.show()

```



Gera-se e ajusta-se, um modelo Simbólico Regressor para a solução da função de onda da Posição:

```
In [60]: est_gp.fit(t.reshape(-1, 1), s1)
```

Population Average			Best Individual			
Gen	Length	Fitness	Length	Fitness	OOB Fitness	Time Left
0	15.94	10.9162	6	0.0305686	0.0286007	2.70m
1	8.25	1.36407	9	0.0238001	0.0246281	2.65m
2	5.03	0.916274	9	0.0248264	0.0153917	2.21m
3	2.76	0.458664	7	0.0265144	0.031241	2.49m
4	2.38	16.2677	7	0.026512	0.0312625	1.71m
5	5.04	0.628504	6	0.0142702	0.0251	1.70m
6	6.00	1.07399	6	0.0145615	0.0224778	1.70m
7	6.08	0.645816	6	0.0137287	0.0299735	1.32m
8	6.07	0.686379	6	0.013608	0.0310599	1.25m
9	6.19	0.767054	6	0.0124938	0.0410876	1.33m
10	6.10	0.799589	6	0.0129802	0.0367098	1.44m
11	6.08	0.641764	6	0.013121	0.0354423	1.09m
12	6.19	0.677095	6	0.0122761	0.0430471	58.81s
13	6.17	0.895997	6	0.012991	0.0366123	38.97s
14	6.06	0.736398	6	0.0132391	0.03438	32.38s
15	6.18	0.696137	6	0.0133269	0.0335893	26.38s
16	6.17	0.844118	6	0.0132413	0.0343599	20.57s
17	6.09	0.700994	6	0.0128263	0.0380947	13.77s
18	6.16	0.612862	6	0.0130871	0.0357479	6.65s
19	6.17	0.633526	6	0.0125276	0.0407834	0.00s

Out[60]:

```
SymbolicRegressor  
add(mul(-0.517, X0), sin(X0))
```

Escore

```
In [62]: print('R2:',est_gp.score(t.reshape(-1, 1),s1))  
next_e = sympify(str(est_gp._program), locals=converter)  
y2=next_e
```

R2: 0.9048979343134357

Equação Proposta

In [64]: y2

Out[64]: $-0.517X_0 + \sin(X_0)$

Solução para o espectro energético

$$E_n = \frac{n^2 \pi^2 \hbar^2}{2mL^2}$$

Verificando os níveis de energia:

```
In [66]: import numpy as np  
a=1  
h=1  
m=1  
En=0  
Enn=[]  
for i in range(7):  
    En=((i**2)*(h**2)*(np.pi**2))/(2*m*a*a)  
    Enn.append(En)  
  
for i in range(7):  
    n = i+1  
    print("E[{}] = {:.4f}".format(n,Enn[i],n, n*n*np.pi**2*h*h/(2*m*a*a)))
```

```
E[1] = 0.0000  
E[2] = 4.9348  
E[3] = 19.7392  
E[4] = 44.4132  
E[5] = 78.9568  
E[6] = 123.3701  
E[7] = 177.6529
```

Gráfico da Energia Quantizada:

```
In [68]: def opt_plot():  
plt.minorticks_on()
```

```

plt.tick_params(axis='both',which='minor', direction = "in",
               top = True,right = True, length=5,width=1,
               labelsiz=15)
plt.tick_params(axis='both',which='major', direction = "in",
               top = True,right = True, length=8,width=1,
               labelsiz=15)

plt.figure(figsize=(10, 6))
plt.plot(Enn)
plt.text(x=0.0, y=10, s="E0", weight="bold")
plt.text(x=1.0, y=15, s="E1", weight="bold")
plt.text(x=2.0, y=30, s="E2", weight="bold")
plt.text(x=3.0, y=55, s="E3", weight="bold")
plt.text(x=4.0, y=90, s="E4", weight="bold")
plt.text(x=5.0, y=135, s="E5", weight="bold")
plt.text(x=6.0, y=170, s="E6", weight="bold")

for i in range(7):
    En=((i**2)*(h**2)*(np.pi**2))/(2*m*a*a)

    plt.scatter(i,En, marker='o',label="E["+str(i)+"] = "+str(round(Enn[i],2)))

font1 = {'family':'serif','color':'blue','size':20}
font2 = {'family':'serif','color':'darkred','size':15}

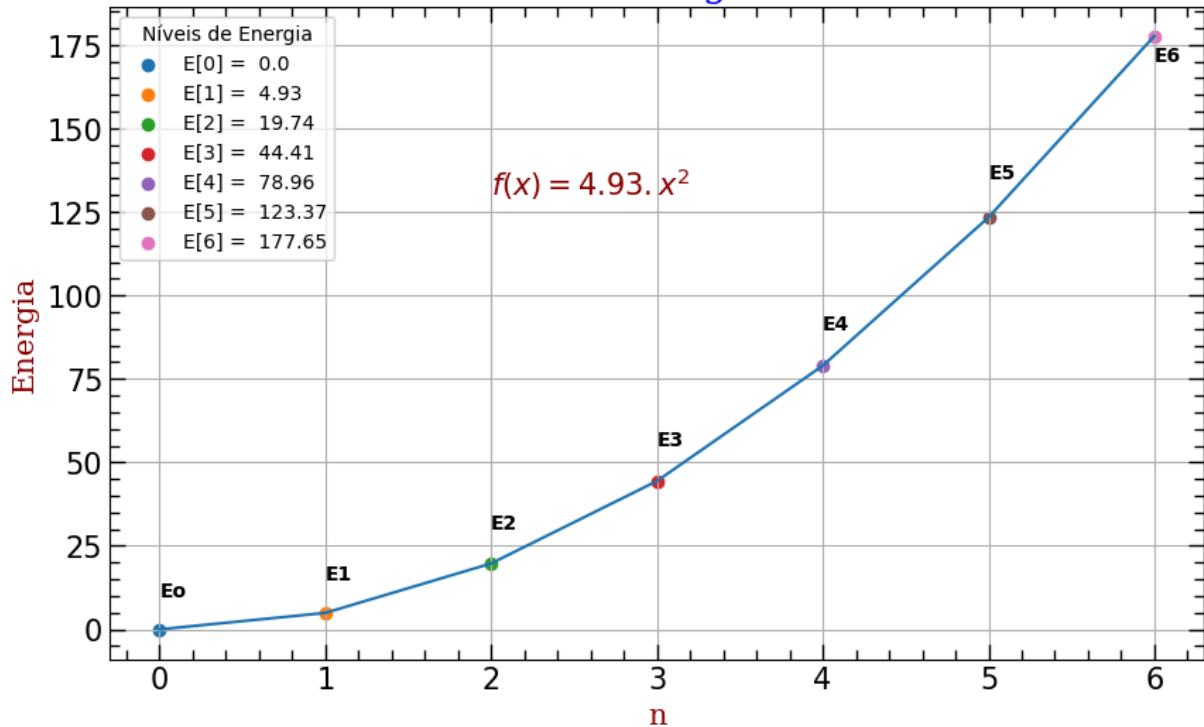
plt.title("Níveis Energéticos", fontdict = font1)
plt.xlabel("n", fontdict = font2)
plt.ylabel("Energia", fontdict = font2)
plt.text(x=2.0, y=130, s=r'$f(x) = 4.93.\{x^2\}$',fontdict = font2)

plt.legend(title='Níveis de Energia')
opt_plot()

plt.grid()

```

Níveis Energéticos



Para:

```
In [70]: l_count=np.linspace(0,6,7)
E_df=np.array([l_count,Enn])
E_df02=E_df.T
E_df02
y_E=4.93*E_df[:,0]**2
```

Obtem-se o seguinte modelo:

```
In [72]: function_set = ['add', 'sub', 'mul', 'div', 'cos', 'sin', 'neg', 'inv']
# Instanciação
est_gp = SymbolicRegressor(population_size=5000,
                           generations=20,function_set=function_set,
                           stopping_criteria=0.01,
                           p_crossover=0.7, p_subtree_mutation=0.1,
                           p_hoist_mutation=0.05, p_point_mutation=0.1,
                           max_samples=0.9, verbose=1,
                           parsimony_coefficient=0.01, random_state=0)

# Ajuste
est_gp.fit(E_df,y_E)
```

Population Average			Best Individual				
Gen	Length	Fitness	Length	Fitness	OOB Fitness	Time Left	
0	10.86	1.23511e+07	14	0	0	2.06m	

Out[72]:

SymbolicRegressor
neg(neg(div(mul(inv(X0), mul(X1, -0.362)), sub(cos(X2), sin(0.200))))))

Cujo Score é:

In [74]: next_e = sympify(str(est_gp._program), locals=converter)
y3=next_e

com a proposta de equação:

In [76]: y3

Out[76]:
$$-\frac{0.362X_1}{X_0(\cos(X_2) - 0.198669330795061)}$$

Densidade de Probabilidade da posição

$$|\psi_n(x)|^2 = \frac{2}{a} \sin^2(n\pi x)$$

In [78]: `import matplotlib.pyplot as plt
import numpy as np

def opt_plot():
 plt.minorticks_on()
 plt.tick_params(axis='both',which='minor', direction = "in",
 top = True,right = True, length=5,width=1,
 labelsz=15)
 plt.tick_params(axis='both',which='major', direction = "in",
 top = True,right = True, length=8,width=1,
 labelsz=15)

val_esp=[-7.17,-4.344,-1.555,0.8002,2.905,5.095 ,7.305]

a=20
A=(2/a)
Data for plotting
t = np.arange(0.0, 2.0, 0.01)
x=np.arange(0.0,2.0,0.01)

s = A*(np.sin((0 * np.pi * x)))**2

s1 = A*(np.sin((0.5 * np.pi * abs(x))))**2
s2 = A*(np.sin((1.0 * np.pi * x)))**2
s3 = A*(np.sin((1.5 * np.pi * x)))**2
s4 = A*(np.sin((2.0 * np.pi * x)))**2`


```

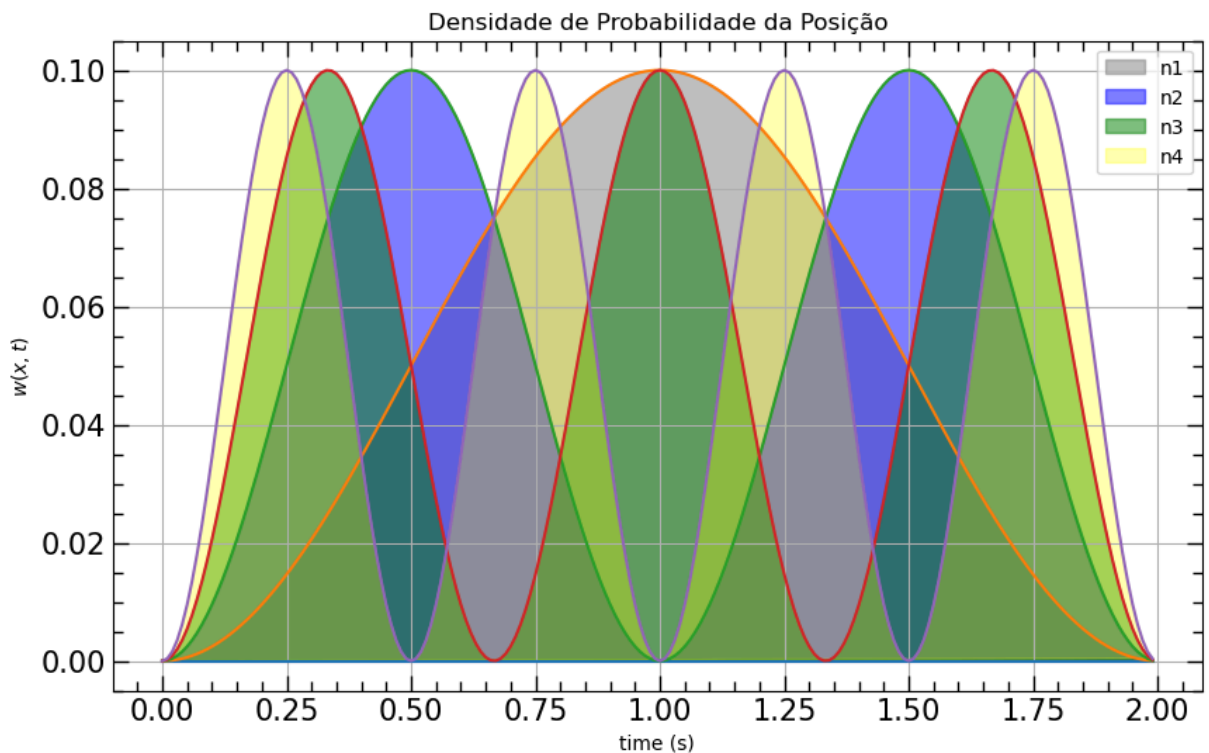
fig, ax = plt.subplots(figsize=(10,6))
ax.plot(x, s)

ax.plot(x, s1)
ax.fill(x,s1,color='grey', alpha=0.5, label='n1')
ax.plot(x, s2)
ax.fill(x,s2,color='blue', alpha=0.5, label='n2')
ax.plot(x, s3)
ax.fill(x,s3,color='green', alpha=0.5, label='n3')
ax.plot(x, s4)
ax.fill(x,s4,color='yellow', alpha=0.3, label='n4')

ax.set(xlabel='time (s)', ylabel='$w(x,t)$',
       title="Densidade de Probabilidade da Posição")
ax.grid()
ax.legend()
opt_plot()

fig.savefig("test.png")
plt.show()

```



Relaciona-se os valores médios esperados, da função de onda, com a função normal gaussiana:

```

In [80]: val_esp=np.array([-7.17, -4.344, -1.555, 0.8002, 2.905, 5.095 , 7.305])
niveis=[0,1,2,3,4,5,6]
arr_value=np.array([[niveis],[val_esp]])
x_arr = val_esp
print(x_arr)
arr=0.399*(2.76**(-0.5*x_arr[:]**2))

```

Processing math: 100%

[-7.17 -4.344 -1.555 0.8002 2.905 5.095 7.305]

para então, modular:

```
In [82]: function_set = ['add', 'sub', 'mul', 'div', 'cos', 'sin', 'neg', 'inv']
# Instanciação
est_gp = SymbolicRegressor(population_size=5000,
                           generations=20, function_set=function_set,
                           stopping_criteria=0.01,
                           p_crossover=0.7, p_subtree_mutation=0.1,
                           p_hoist_mutation=0.05, p_point_mutation=0.1,
                           max_samples=0.9, verbose=1,
                           parsimony_coefficient=0.01, random_state=0)

# Ajuste
est_gp.fit(x_arr.reshape(-1,1), y_arr)
```

Population Average			Best Individual			
Gen	Length	Fitness	Length	Fitness	OOB Fitness	Time Left
0	15.94	24.2581	9	0.0150923	0.125521	2.32m
1	9.25	3.10342	29	0.001741	0.390678	2.51m

```
Out[82]: SymbolicRegressor
sin(mul(cos(sub(sin(add(0.782, 0.138))), sin(sub(0.773, X0)))), div(cos(inv(cos(X0))), sub(sin(add(-0.483, 0.614)), mul(mul(X0, X0), add(X0, X0)))))
```

Escore:

```
In [84]: print('R2:', est_gp.score(x_arr.reshape(-1,1), y_arr))
next_e = sympify(str(est_gp._program), locals=converter)
y2_arr=next_e
```

R2: -1.099778938698206

Equação:

```
In [86]: y2_arr
```

```
Out[86]:
```

$$\sin\left(\frac{\cos\left(\sin\left(X_0 - 0.773\right) + 0.795601620036366\right)\cos\left(\frac{1}{\cos\left(X_0\right)}\right)}{0.130625639531083 - 2X_0^3}\right)$$

O desvio padrão da posição:

$$\Delta x n = \sqrt{\langle x^2 n \rangle - \langle x n \rangle^2} = a \sqrt{\frac{1}{12} - \frac{1}{2\pi^2 n^2}}$$

```
In [88]: import pandas as pd
xx0=-10
val_esp=[-7.17,-4.344,-1.555,0.8002,2.905,5.095,7.305]
a=val_esp[6]-val_esp[0]
x_quadrado=0
dp=[]
n=1
desp=0
j=-10

c=0
dsp=[]
for i in val_esp:
    if (j<0 and i>0):
        c=np.abs(j)+i
    else:
        c=np.abs(j)-np.abs(i)
        c=np.abs(c)
    dsp.append(c)
    j=i
dsp
er_count=0
err=[]
med_ex=2.86
for i in dsp:
    er_count=med_ex-i
    err.append(er_count)
err
dpp=pd.DataFrame()
dpp['DesvioP']=dsp
dpp['ErrDesvioP']=err

dpp
```

```
Out[88]:
```

	DesvioP	ErrDesvioP
0	2.8300	0.0300
1	2.8260	0.0340
2	2.7890	0.0710
3	2.3552	0.5048
4	2.1048	0.7552
5	2.1900	0.6700
6	2.2100	0.6500

Podemos encontrar, também, o desvio padrão do momento

$$e^{\frac{-i \text{ op } H \Delta t}{\hbar}} = \sum_n \frac{\left(\frac{-i \text{ op } H \Delta t}{\hbar}\right)^n}{n!}$$

$$\Delta K n = \langle K^2 n \rangle - \langle K n \rangle^2 = \frac{n \hbar}{a}$$

```
In [90]: import numpy as np
a=20

h=1
dpm=0
dmp=[]
for i in range(7):
    a=np.abs(a)
    dpm=(i*np.pi)/a
    dmp.append(dpm)
```

O Princípio da Incerteza

$$\Delta x. \Delta p > \frac{\hbar}{2}$$

```
In [92]: desvf=pd.DataFrame()
desvf["dp"]=dpp.DesvioP
desvf["dmp"]=dmp
j=0
incerteza=[]
form=[]
f=r'$\Delta x.\Delta p $'
g=r'$\Delta x $'
h=r'$\Delta p $'
c=0
gord=dpp.DesvioP
hord=dmp
for i in dpp.DesvioP:
    j=dmp[c]*i
    incerteza.append(j)
    form.append(f)

    c=c+1
desvf02=pd.DataFrame()
desvf02[g]=gord
desvf02[h]=hord
desvf02["lesquerdo"]=form
desvf02["incerteza"]=incerteza
desvf02
```

Out[92]:

	Δx	Δp	lesquerdo	incerteza
0	2.8300	0.000000	$\Delta x, \Delta p$	0.000000
1	2.8260	0.157080	$\Delta x, \Delta p$	0.443907
2	2.7890	0.314159	$\Delta x, \Delta p$	0.876190
3	2.3552	0.471239	$\Delta x, \Delta p$	1.109862
4	2.1048	0.628319	$\Delta x, \Delta p$	1.322485
5	2.1900	0.785398	$\Delta x, \Delta p$	1.720022
6	2.2100	0.942478	$\Delta x, \Delta p$	2.082876

Regressão Simbólica entre os Δx e Δp , como variáveis independentes.

```
In [94]: from array import array
pr_in=[]
mul=0
co=0
for i in dp:
    mul=dmp[co]*i
    pr_in.append(mul)
    co=co+1
pr_in
l=np.linspace(-20,20,7)
est_gp.fit(desvf,l)
```

Population Average			Best Individual			
Gen	Length	Fitness	Length	Fitness	OOB Fitness	Time Left
0	14.12	17.3358	61	4.58152	2.20469	2.61m
1	13.19	12.2287	63	2.01855	16.5301	2.67m
2	22.91	12.5299	68	1.48236	19.5784	2.70m
3	45.90	11.1265	67	1.35883	16.5595	2.79m
4	57.10	8.42914	74	1.2534	16.1118	2.86m
5	56.64	8.65533	103	0.940835	17.0272	2.81m
6	55.98	8.42966	74	0.897443	18.0636	2.33m
7	55.51	8.75305	89	0.915222	18.4083	2.30m
8	54.16	8.32359	57	0.83206	5.84937	2.04m
9	54.13	8.69014	59	0.601793	5.16499	1.84m
10	51.85	8.2424	59	0.601793	5.16499	1.61m
11	50.01	8.74759	70	0.566704	2.36483	1.44m
12	48.89	8.13448	63	0.433342	38.7046	1.21m
13	51.54	7.87202	75	0.439702	1.6471	1.05m
14	55.80	7.78783	74	0.409549	1.6472	55.09s
15	62.10	7.10821	63	0.414798	1.55232	47.78s
16	65.83	8.2369	79	0.343407	1.43067	45.28s
17	66.11	7.72361	78	0.387547	1.80321	23.63s
18	64.58	7.55171	78	0.274171	1.35523	13.55s
19	63.97	7.15509	77	0.328465	1.395	0.00s

Out[94]:

SymbolicRegressor

```
sub(sub(sub(mul(neg(div(X0, X0)), add(neg(X1), div(X0, X1))), inv(add(neg(-0.046), div(-0.094, X1)))), mul(add(neg(div(add(neg(X1), add(neg(X1), neg(X1))), X0)), sin(X1)), neg(sin(X1))), div(sin(sub(sub(sub(mul(neg(div(X0, X0)), add(neg(sub(X1, -0.041)), div(X0, X1))), inv(add(neg(-0.046), div(-0.094, X1)))), sin(0.355)), div(sin(div(-0.094, X1)), sub(X1, -0.041))), sub(X1, -0.041)))
```

Escore:

```
In [96]: print('R2:',est_gp.score(desvf,1))
next_e = sympify(str(est_gp._program), locals=converter)
y4=next_e
```

R2: 0.9974758366230793

Equação Proposta:

```
In [98]: print(y4)
```

$$-X_0/X_1 + X_1 + (\sin(X_1) + 3 \cdot X_1/X_0) \cdot \sin(X_1) + \sin(X_0/X_1 - X_1 + 0.306590365235784 - \sin(0.094/X_1)/(X_1 + 0.041) + 1/(0.046 - 0.094/X_1))/(X_1 + 0.041) - 1/(0.046 - 0.094/X_1)$$

Regressão Simbólica entre os Δx e Δp , como um produto entre ambas.


```
In [100... deltax=np.linspace(2.1,2.83,100)
deltap=np.linspace(0.15,0.94,100)
delta_dp=pd.DataFrame()
delta_dp['deltax']=deltax
delta_dp['deltap']=deltap
c=0
mult=[]
for i in deltax:
    j=deltap[c]*i
    mult.append(j)

    c=c+1
c_inf=0
mult_inf=[]
mult_sup=[]
for i in mult:
    if i<0.5:
        mult_inf.append(i)
        c_inf=c_inf+1
    else:
        mult_sup.append(i)
```

```
In [101... est_gp.fit(delta_dp,mult)
```

Population Average			Best Individual			
Gen	Length	Fitness	Length	Fitness	OOB Fitness	Time Left
0	14.12	9.75688	5	0	0	2.60m

Out[101...

SymbolicRegressor 
mul(neg(X0), neg(X1))

Escore:

In [103...

```
print('R2:',est_gp.score(delta_dp,mult))
next_e = sympify(str(est_gp._program), locals=converter)
y5=next_e
```

R2: 1.0

Equação

In [105...

```
print(y5)
```

X0*X1

As Equações Sugeridas:

In [107...

```
print('As Equações Sugeridas:')
print('_____')
print('')
print('I - y1(X0) =', y1)
print('-----')
print('II - y2(X0) =', y2)
print('-----')
print('III - y3(X0,X1,X2) =', y3)
print('-----')
print('IV - y2_arr(X0) = ',y2_arr)
print('-----')
print('V - y4(X0,X1) = ', y4)
print('-----')
print('VI - y5(X0,X1) = ', y5)
print('-----')
```

As Equações Sugeridas:

```
I - y1(X0) = 0.333/(0.696*X0**2 + 0.812)
-----
II - y2(X0) = -0.517*X0 + sin(X0)
-----
III - y3(X0,X1,X2) = -0.362*X1/(X0*(cos(X2) - 0.198669330795061))
-----
IV - y2_arr(X0) = sin(cos(sin(X0 - 0.773) + 0.795601620036366)*cos(1/cos(X0)))/(0.130625639531083 - 2*X0**3))
-----
V - y4(X0,X1) = -X0/X1 + X1 + (sin(X1) + 3*X1/X0)*sin(X1) + sin(X0/X1 - X1 + 0.306590365235784 - sin(0.094/X1)/(X1 + 0.041) + 1/(0.046 - 0.094/X1))/(X1 + 0.041) - 1/(0.046 - 0.094/X1)
-----
VI - y5(X0,X1) = X0*X1
-----
```

```
In [108... print('I - y1(X0) =', end=" ")
y1
```

I - $y_1(X_0) = \frac{0.333}{0.696X_0^2 + 0.812}$

```
In [109... y2
```

Out[109... $-0.517X_0 + \sin(X_0)$

```
In [110... y3
```

Out[110...
$$-\frac{0.362X_1}{X_0(\cos(X_2) - 0.198669330795061)}$$

```
In [111... y4
```

Out[111...
$$-\frac{X_0}{X_1} + X_1 + \left(\sin(X_1) + \frac{3X_1}{X_0}\right)\sin(X_1) + \frac{\sin\left(\frac{X_0}{X_1} - X_1 + 0.306590365235784 - \frac{\sin\left(\frac{0.094}{X_1}\right)}{X_1 + 0.041} + \frac{1}{0.046 - \frac{0.094}{X_1}}\right)}{X_1 + 0.041}$$

```
In [112... y5
```

Out[112... X_0X_1

In [113...

`x0=1`
`y2_arr`

Out[113...

$$\sin\left(\frac{\cos\left(\sin\left(X_0 - 0.773\right) + 0.795601620036366\right)\cos\left(\frac{1}{\cos\left(X_0\right)}\right)}{0.130625639531083 - 2X_0^3}\right)$$

In []:

In []:

In []:

In []: