

Dordis

*Efficient Federated Learning
with Dropout-Resilient Differential Privacy*

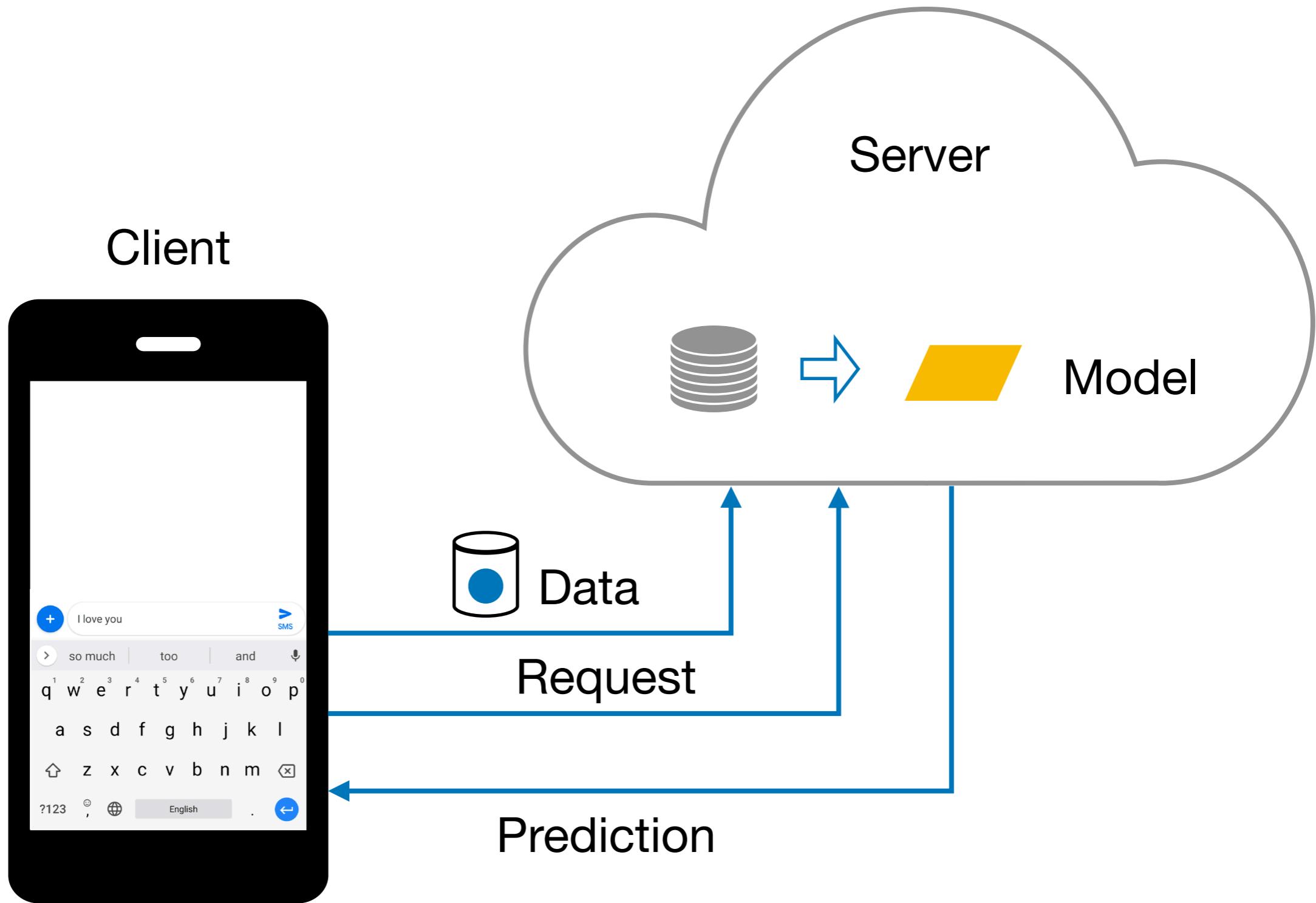
Zhifeng Jiang,
Wei Wang,
Ruichuan Chen



香港科技大學
THE HONG KONG UNIVERSITY OF
SCIENCE AND TECHNOLOGY

NOKIA
BELL
LABS

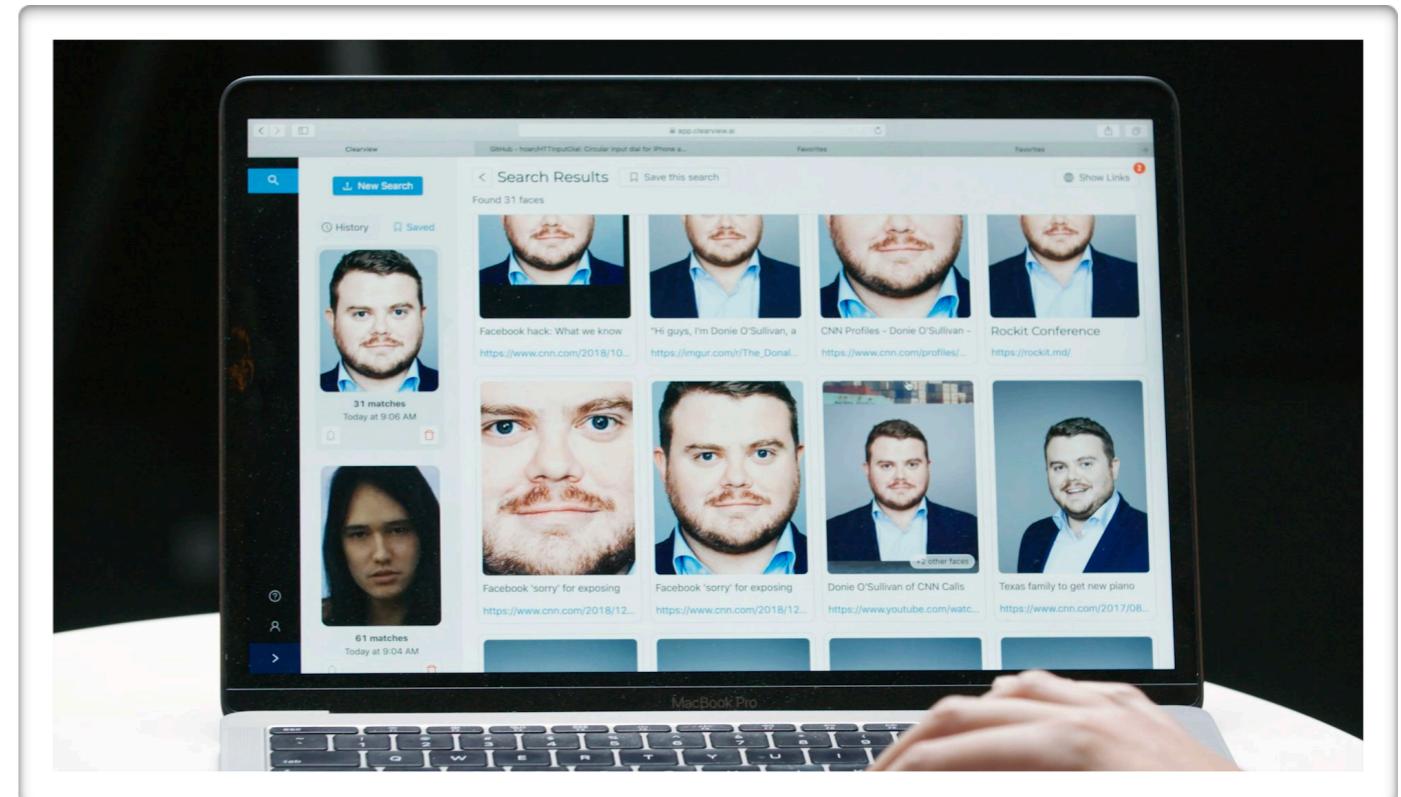
Centralized learning



Centralized learning hurts privacy

Data breaches...

Forbes
Clearview AI, The Company Whose Database Has Amassed 3 Billion Photos, Hacked



Centralized learning hurts privacy

Data breaches...

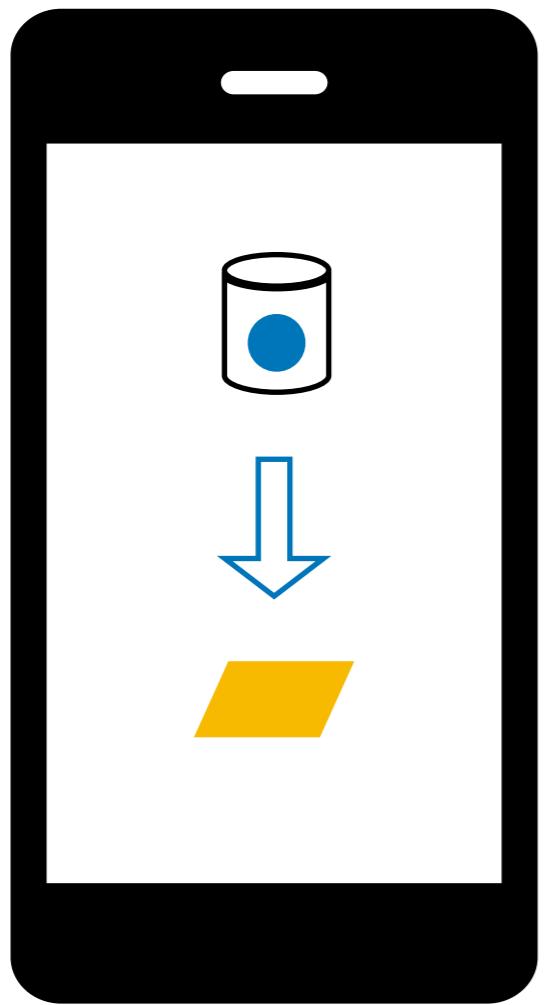
Forbes
Clearview AI, The Company
Whose Database Has Amassed 3
Billion Photos, Hacked

Potential abuse...

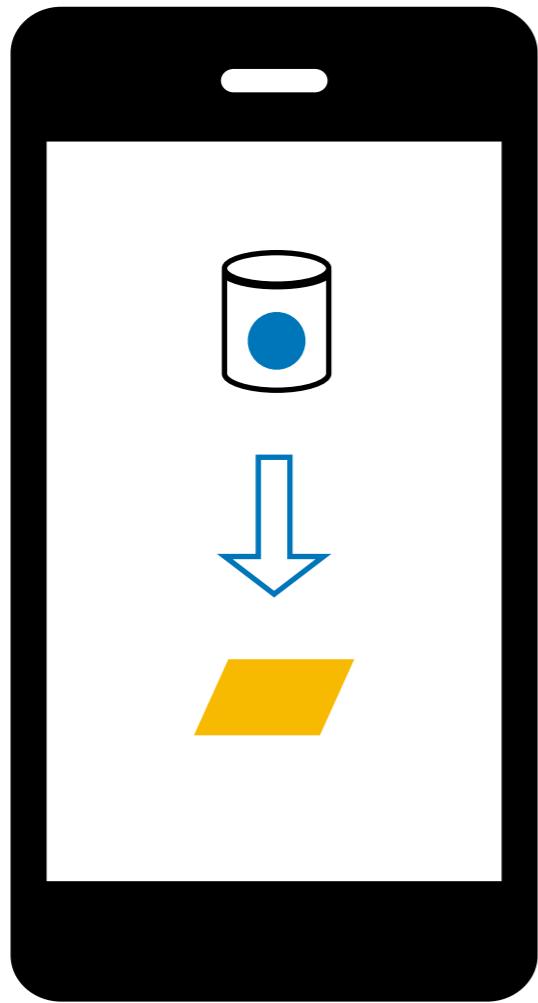
the guardian
Facebook halts use of WhatsApp data
for advertising in Europe

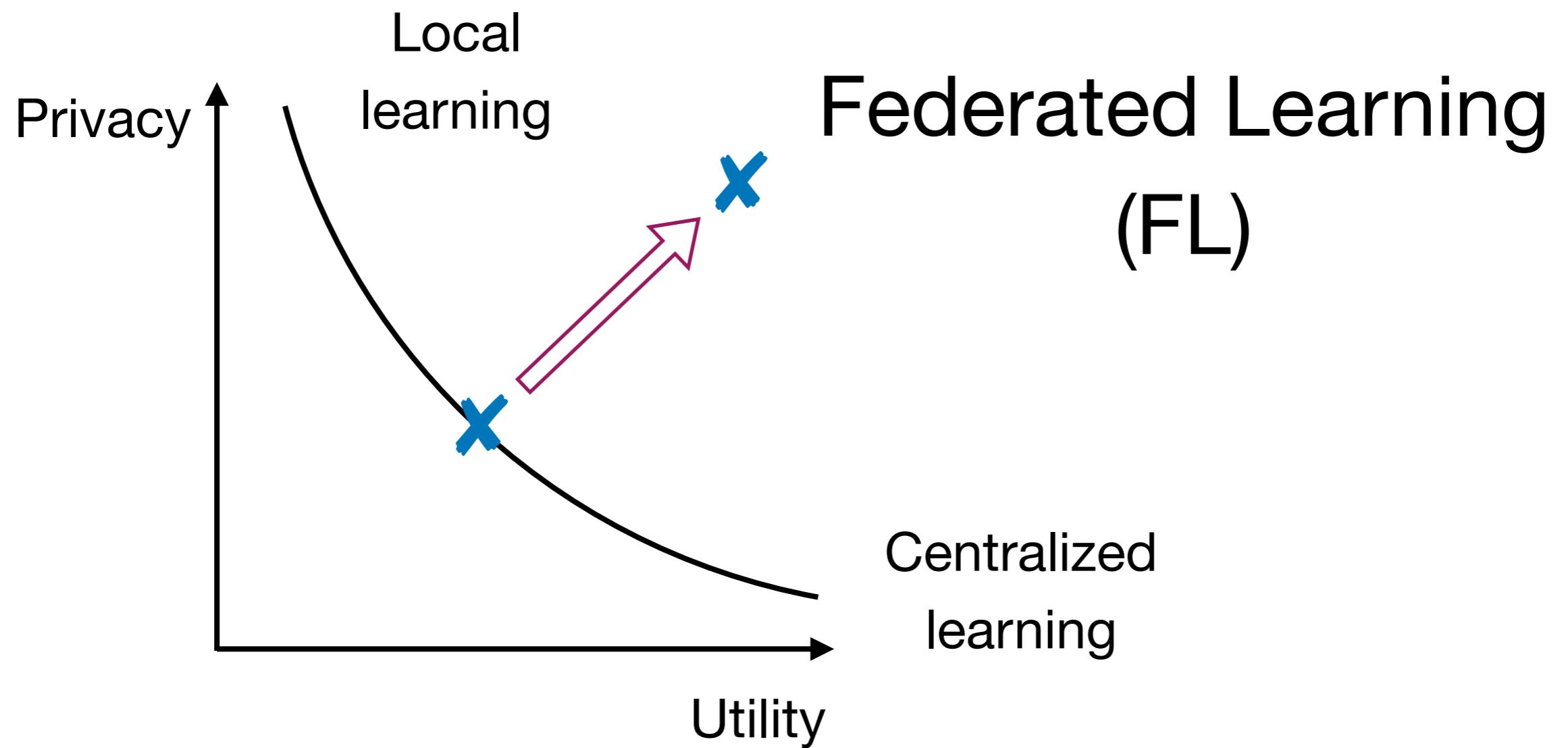


Local learning

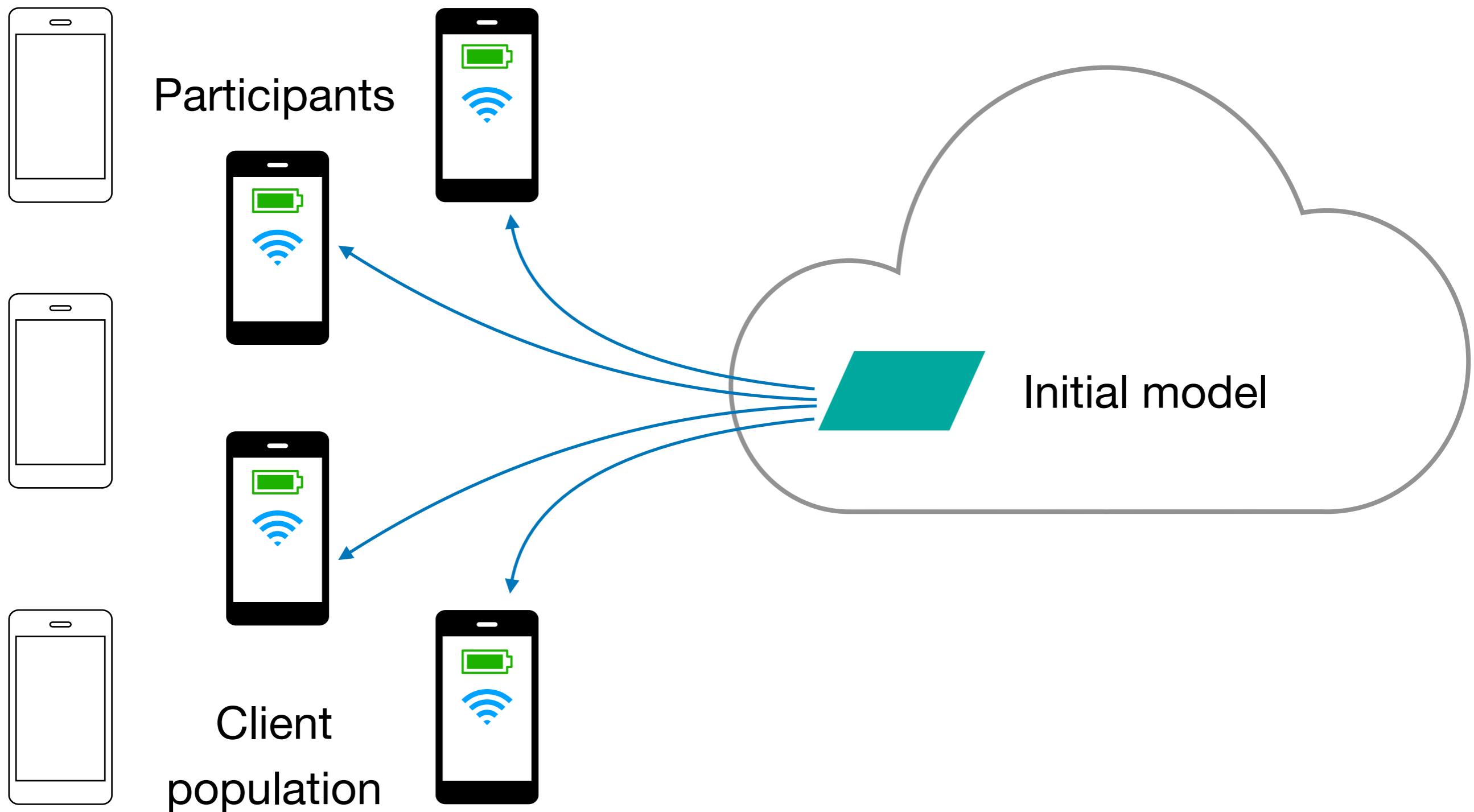


Local learning suffers from **low utility**

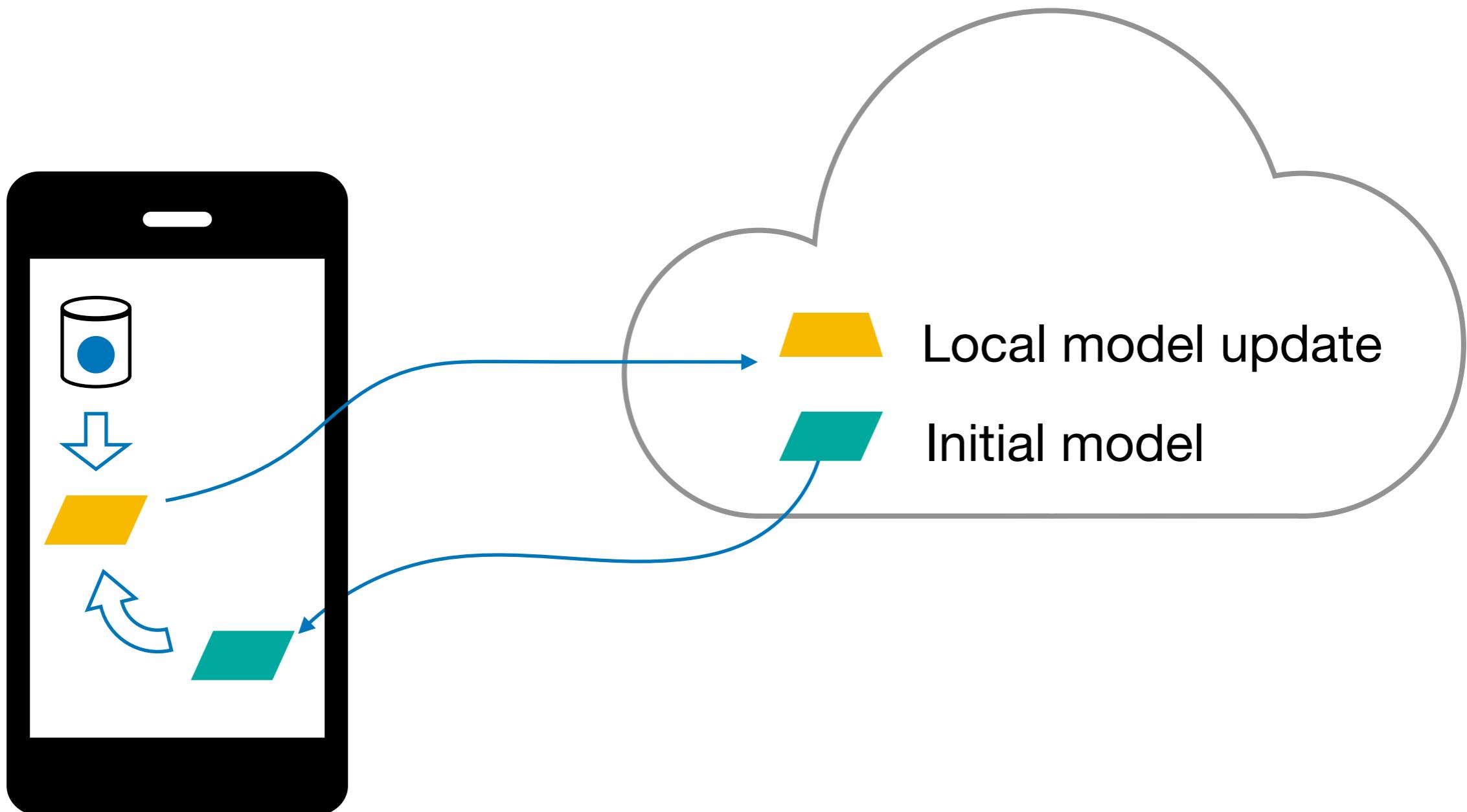




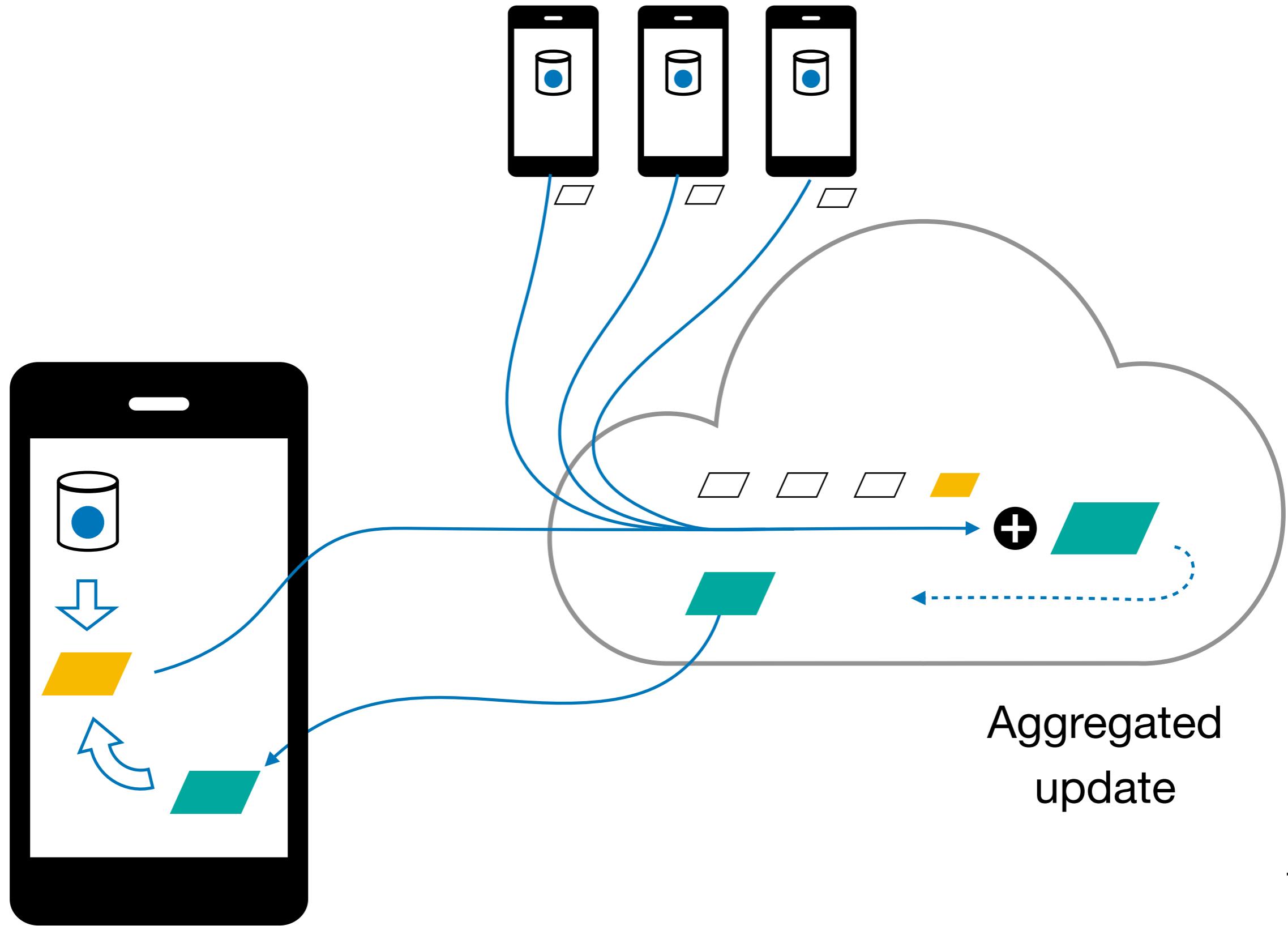
FL Step 1: Participant Selection



FL Step 2: Local Training

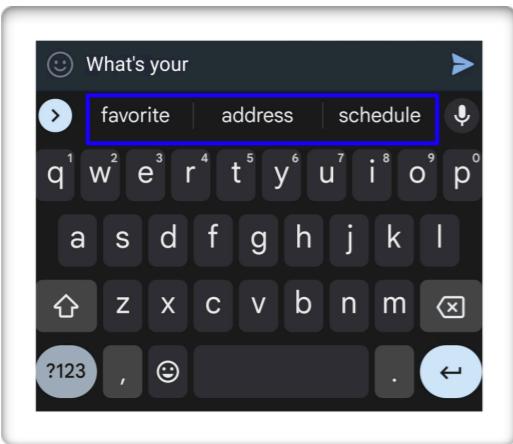


FL Step 3: Model Aggregation



FL Applications

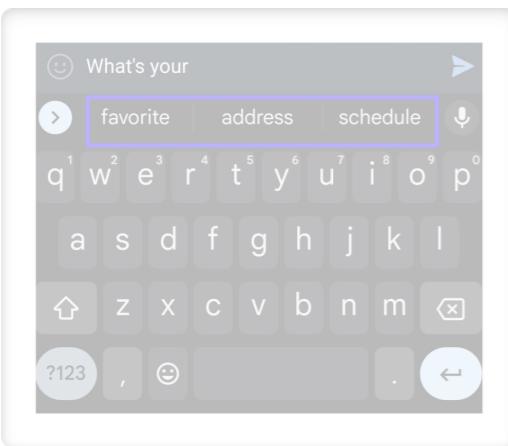
Mobile



Google's Keyboard

FL Applications

Mobile



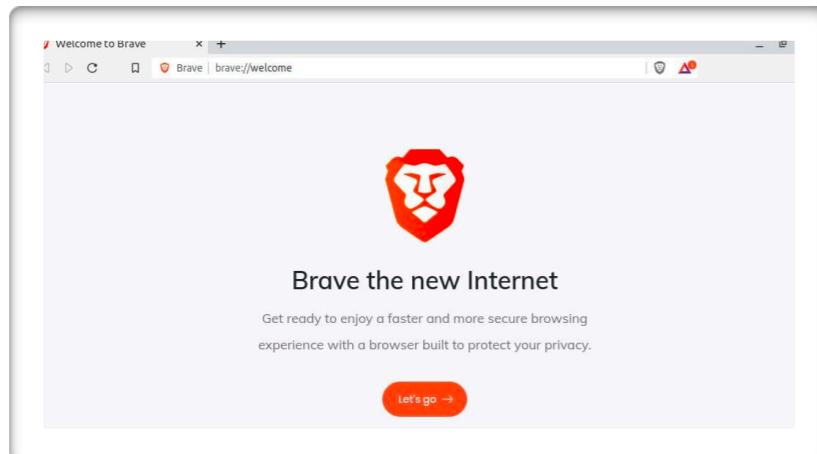
Google's Keyboard



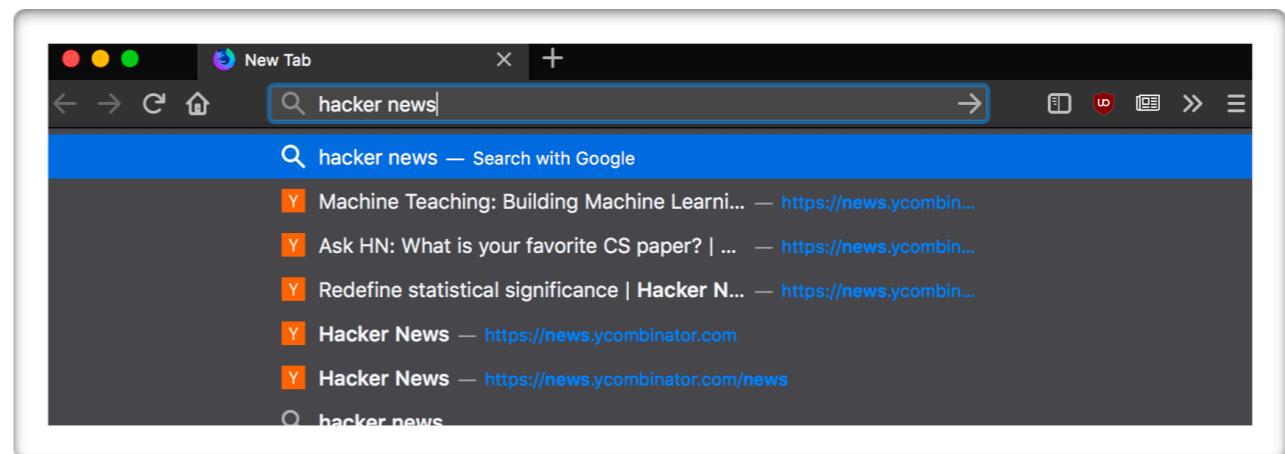
Apple's speaker recognition



Huawei's ads recommendation

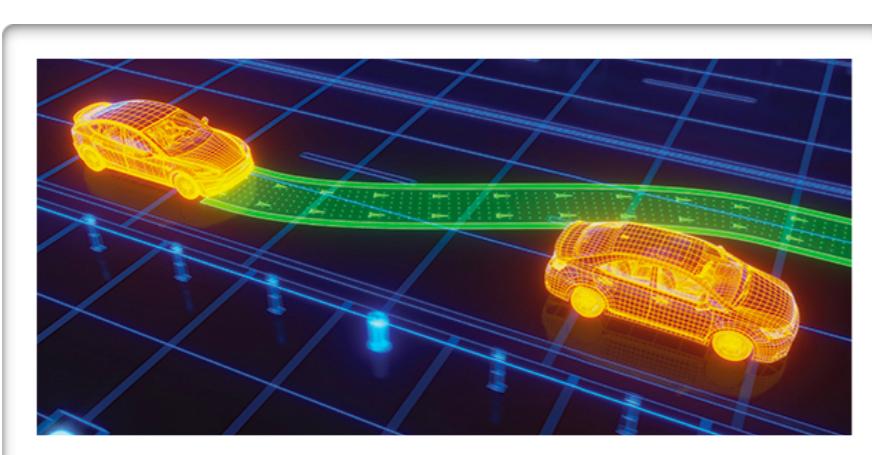


Brave's news recommendation

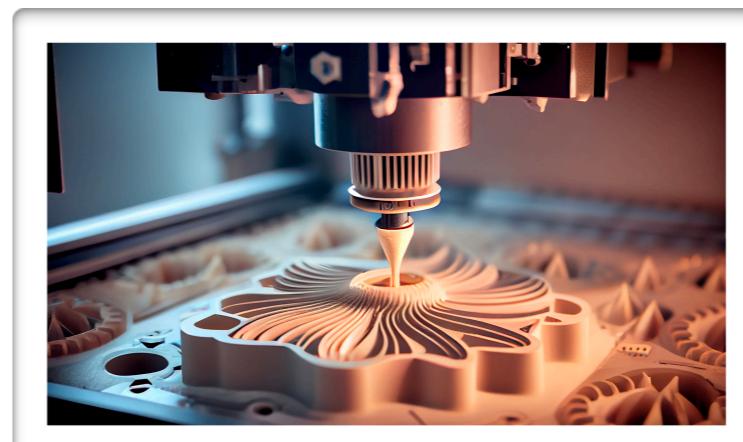


Firefox's URL bar suggestion

IoT



Volvo's trajectory prediction

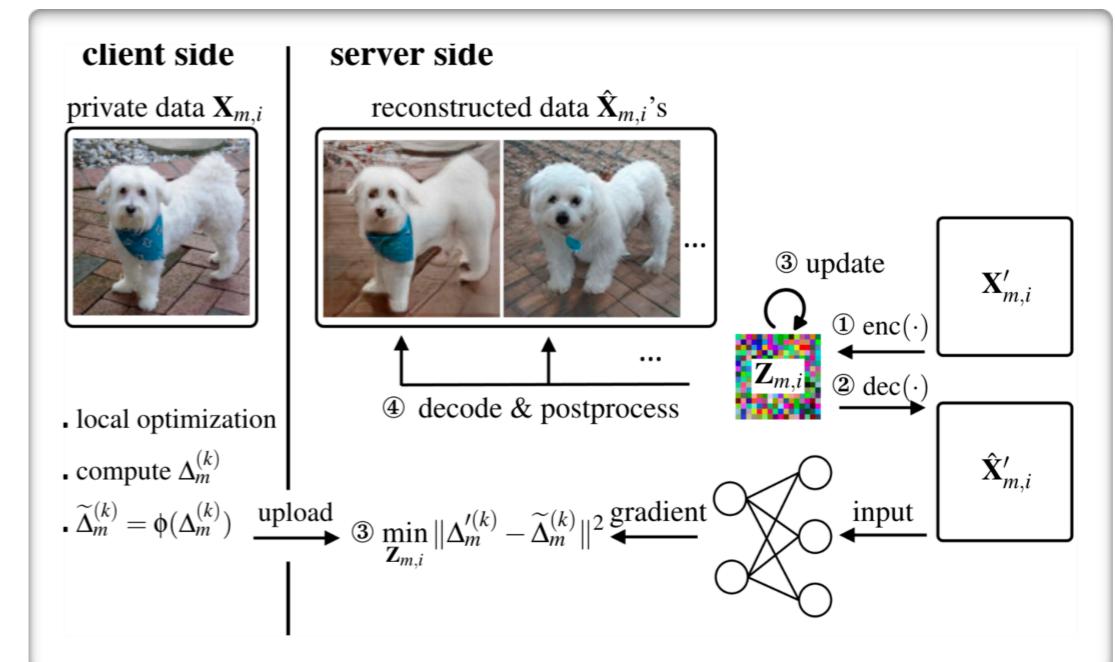
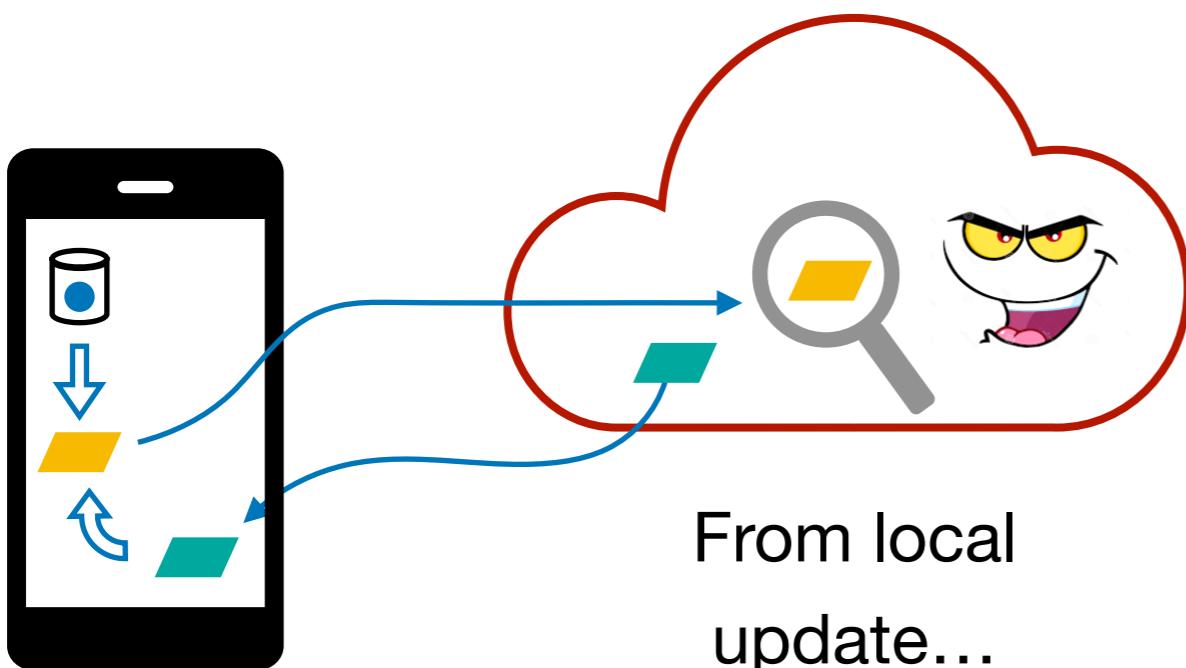


Cisco's 3D printing



Leveno's clogging detection

Data Leakage Remains in FL



e.g., data reconstruction¹ (Security '23)

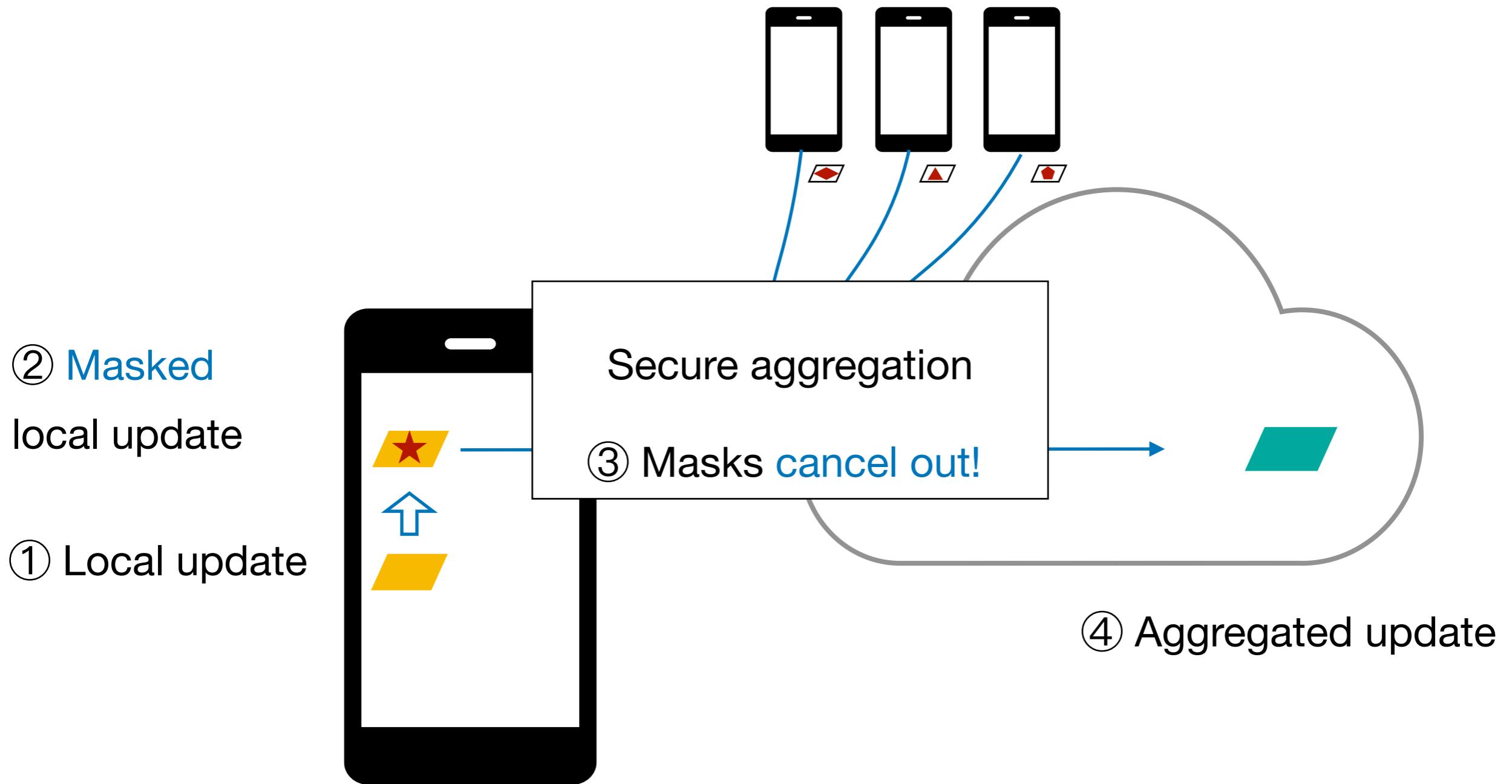
Data Leakage Remains in FL

To conceal local updates?

Secure aggregation¹²
(CCS '17, '20)

Data Leakage Remains in FL

To conceal **local** updates?



Data Leakage Remains in FL

To conceal local updates?

To also perturb the aggregated update?

Sacrifice the
precision

Differential Privacy¹

For enhanced
privacy

Data Leakage Remains in FL

To conceal local updates?

To also perturb the **aggregated update**?

Sacrifice the precision



$$\begin{aligned} \text{aggregation} &= A(\text{local updates}) \\ &= f(\text{local updates}) + \text{random noise} \end{aligned}$$

Differential Privacy¹

For enhanced privacy



DP ensures that  be **insensitive** to the impact of any single local update in 

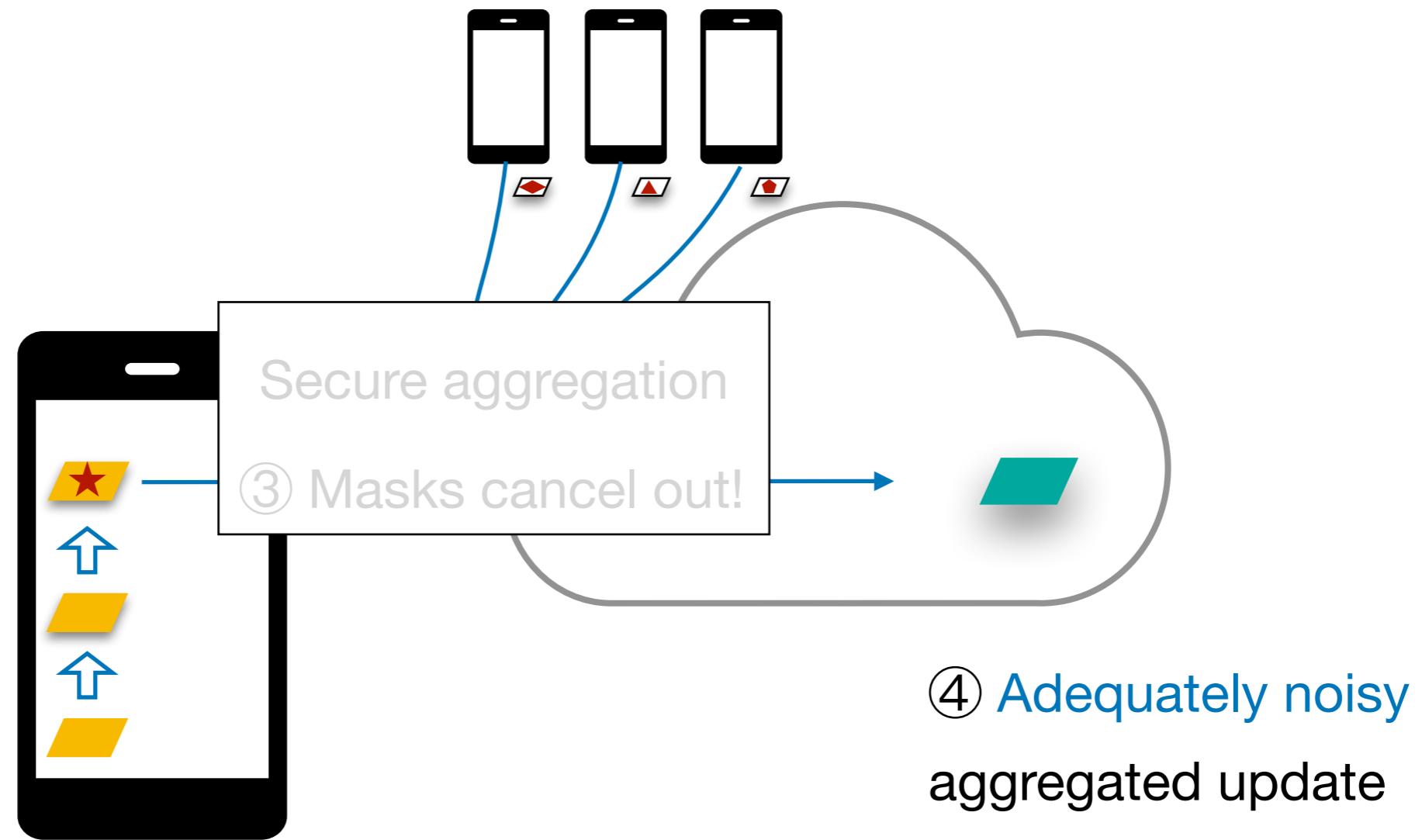
Data Leakage Remains in FL

To conceal local updates?

To also perturb the **aggregated update**?

② Masked
slightly noisy
local update

① Slightly
noisy local
update



⑤ Global privacy budget $\epsilon \rightarrow$ Calculate the **minimum required noise**

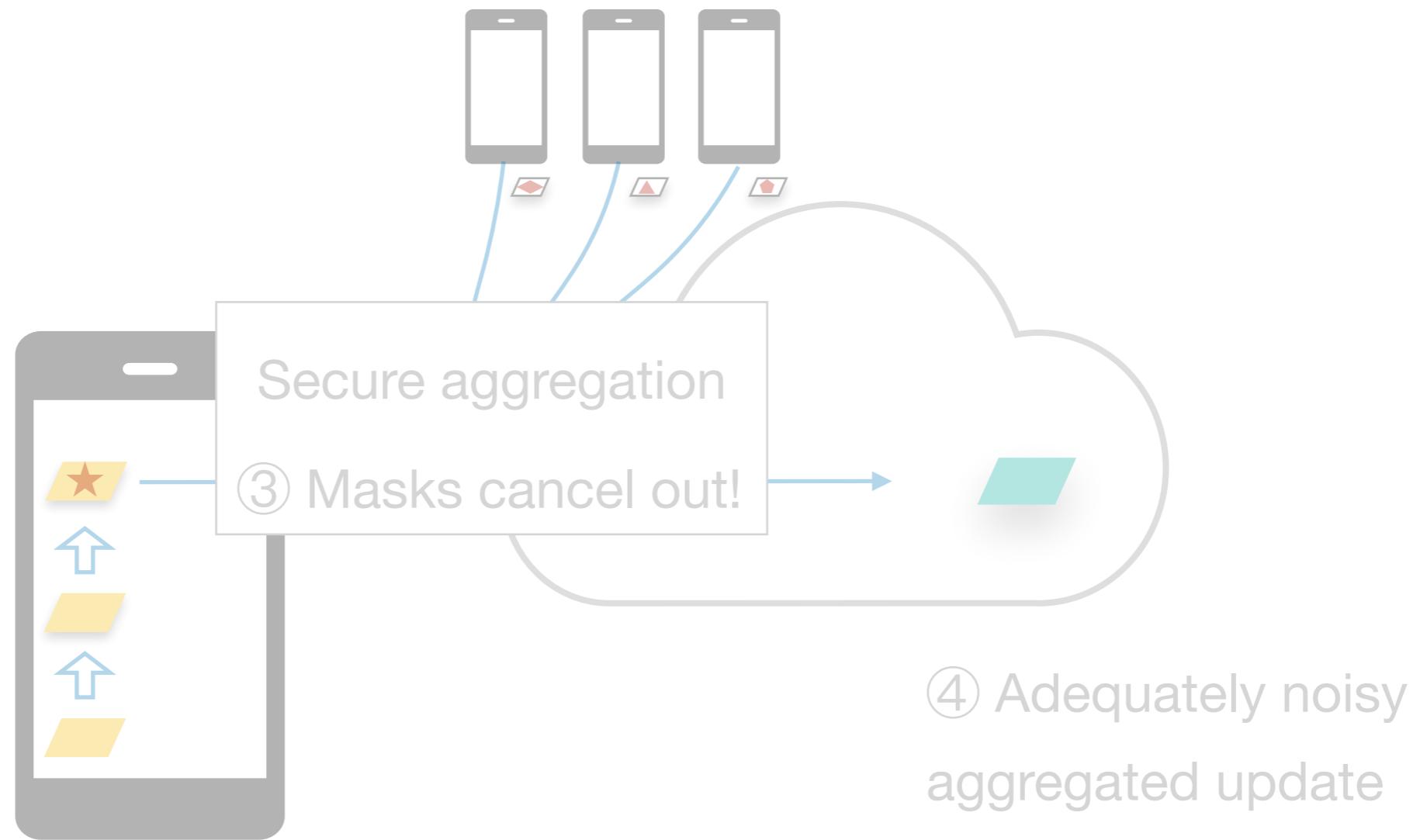
Distributed DP = SecAgg + DP

To conceal local updates?

To also perturb the aggregated update?

② Masked
slightly noisy
local update

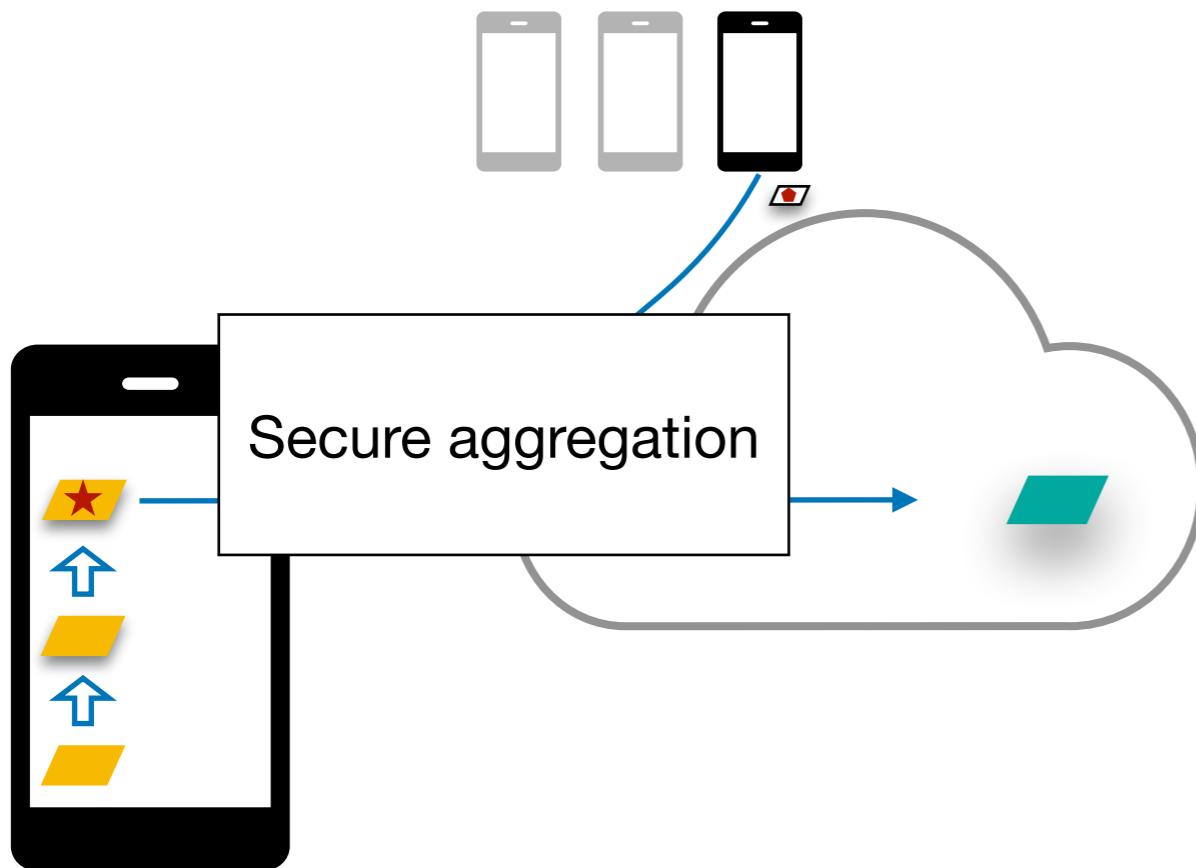
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① Global privacy budget $\epsilon \rightarrow$ Calculate the minimum required noise

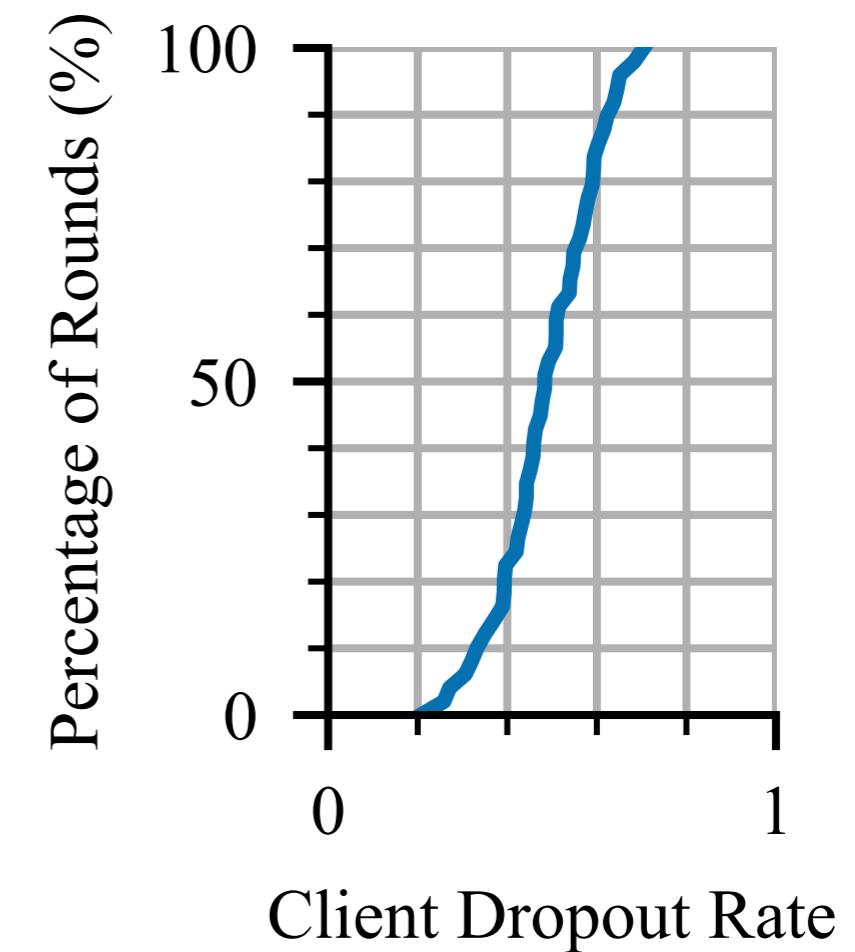
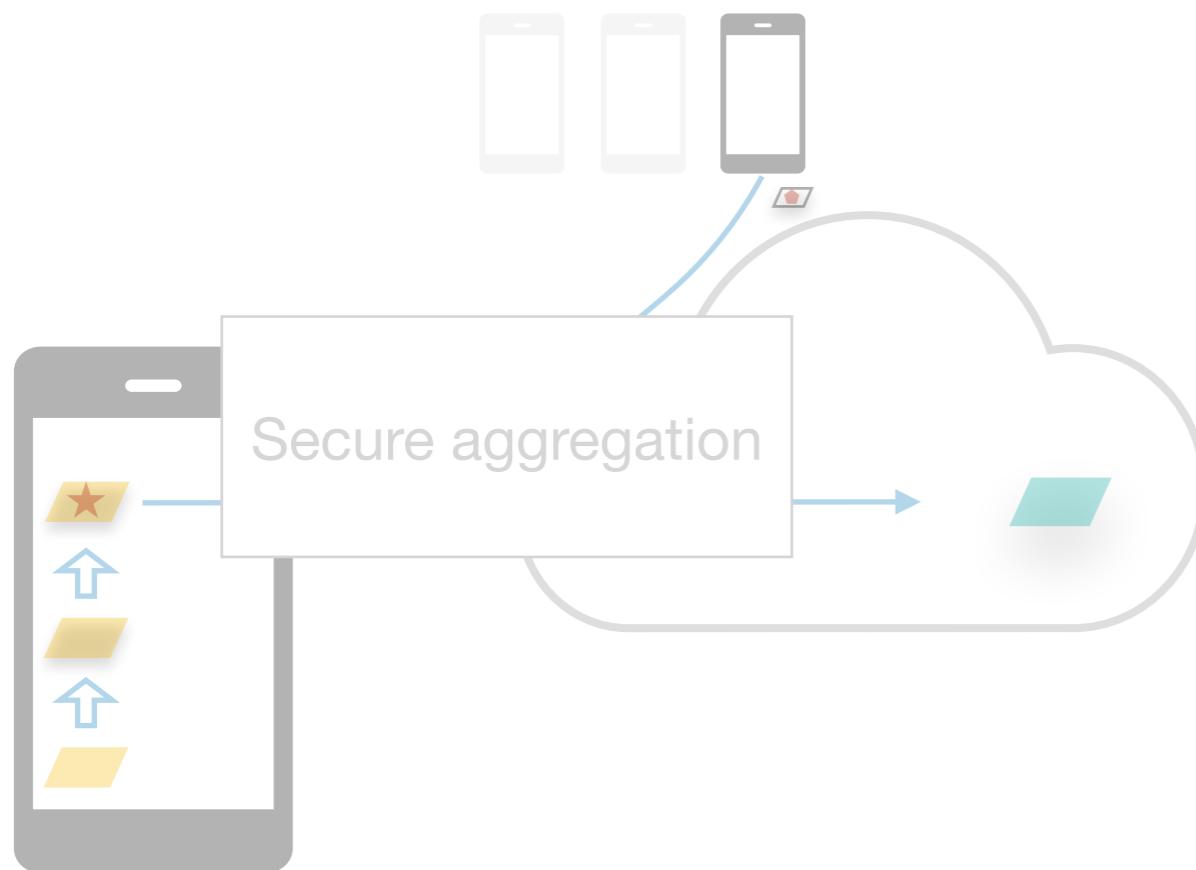
Distributed DP Has Two Practical Issues

1. Privacy Issue: caused by [client dropout](#)



Privacy Issue Caused by Client Dropout

Client dropout can occur anytime



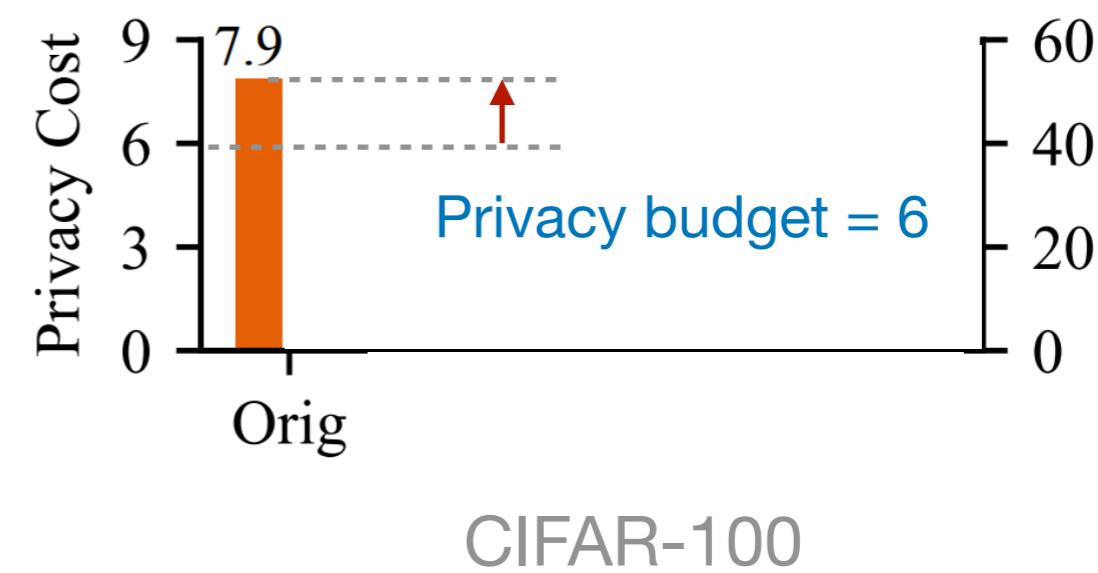
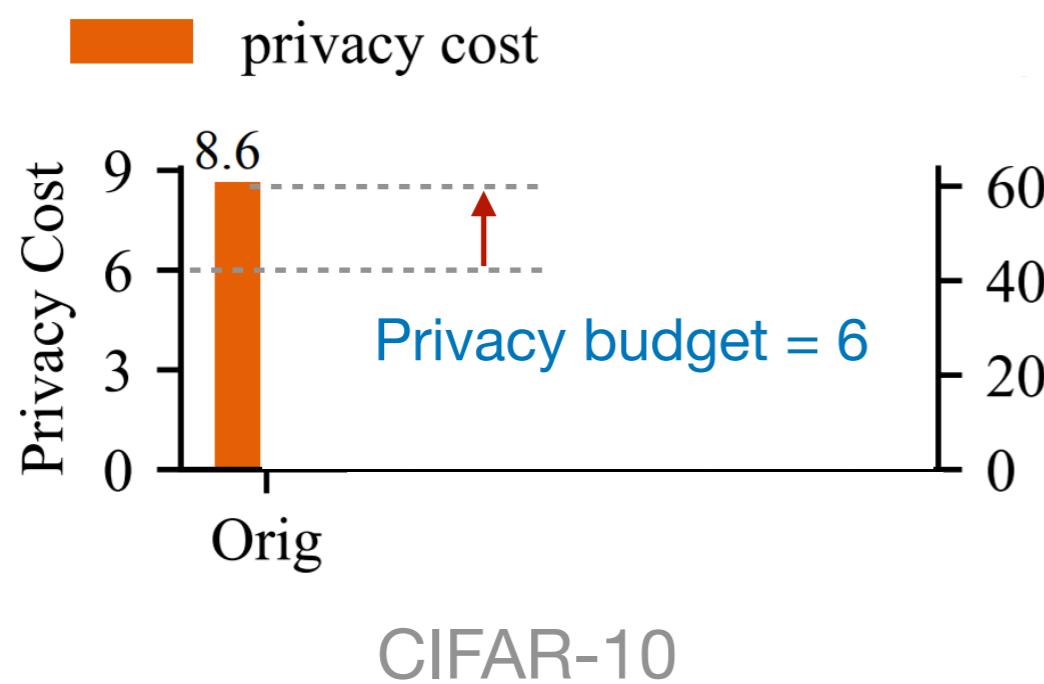
Client behaviors simulated
with 100 volatile users
from the FLASH dataset¹ (WWW '21)

[1] Characterizing impacts of heterogeneity in federated learning upon large-scale smartphone data

Privacy Issue Caused by Client Dropout

Client dropout can occur anytime

Insufficient noise for target privacy



Dropout-Resilient Noise Enforcement

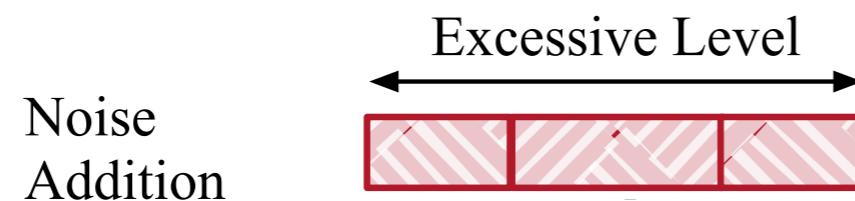
Goal: always enforce the target noise level

Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

Intuition: add-then-remove

- Each client first adds excessive noise as **separate components**

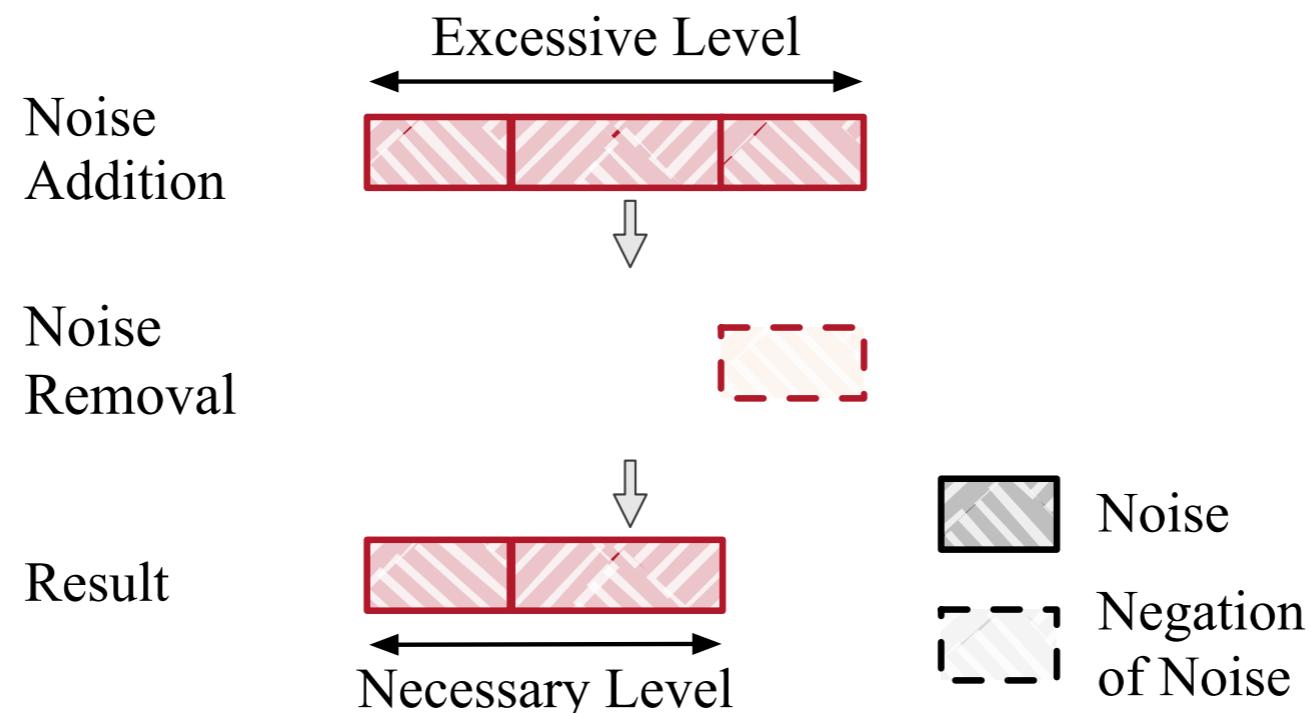


Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

Intuition: add-then-remove

- Each client first adds excessive noise as separate components
- After aggregation, unnecessary ones are removed by the server



Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

Intuition: add-then-remove

Concrete example

Sampled clients $|S| = 4$

Minimum necessary noise level $\sigma_*^2 = 1$

Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

Intuition: add-then-remove

Concrete example

Add

Sampled clients $|S| = 4$

Dropout tolerance $t = 2$,

Minimum necessary noise level $\sigma_*^2 = 1$

Each client adds noise $n_i \sim \chi(1/2)$
to tolerate up to 2 clients to drop

Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

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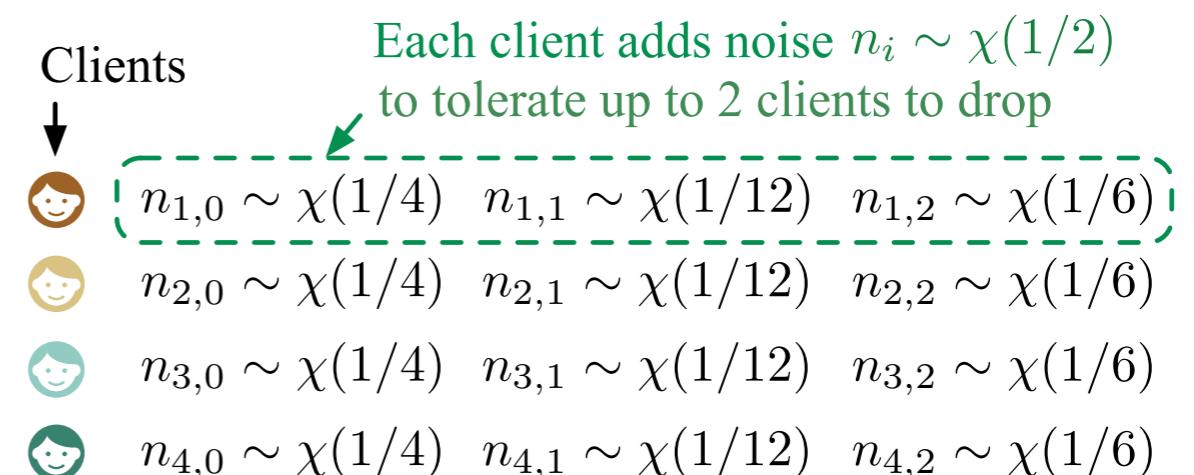
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Dropout-Resilient Noise Enforcement

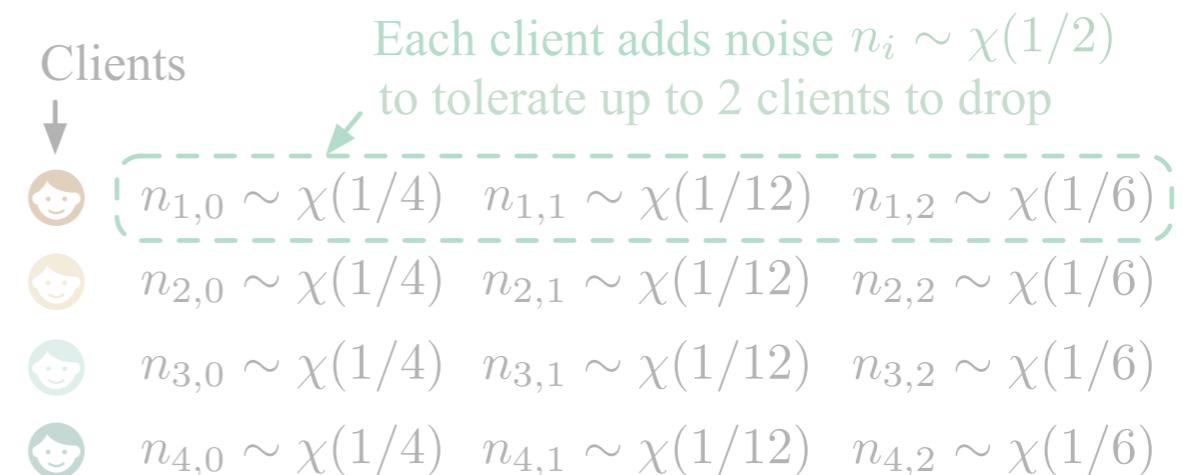
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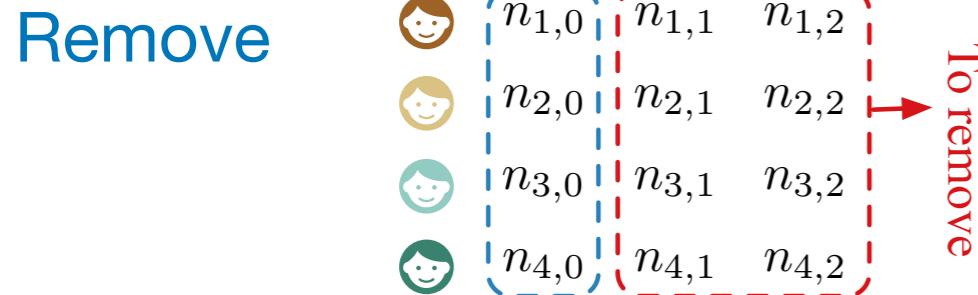
Concrete example

Add
Sampled clients $|S| = 4$
Dropout tolerance $t = 2$,

Minimum necessary noise level $\sigma_*^2 = 1$



If 0 client drops
Achieve target noise $\sigma_*^2 = 1$



Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

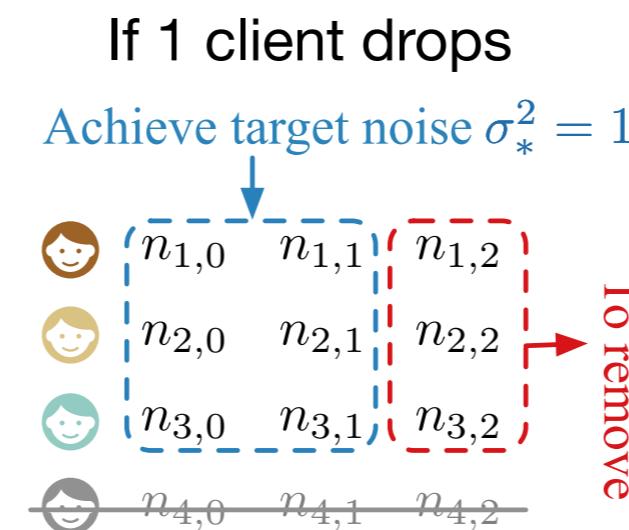
Intuition: add-then-remove

Concrete example

Add
Sampled clients $|S| = 4$
Dropout tolerance $t = 2$,

Minimum necessary noise level $\sigma_*^2 = 1$

Clients	Each client adds noise $n_i \sim \chi(1/2)$ to tolerate up to 2 clients to drop		
	$n_{1,0} \sim \chi(1/4)$	$n_{1,1} \sim \chi(1/12)$	$n_{1,2} \sim \chi(1/6)$
	$n_{2,0} \sim \chi(1/4)$	$n_{2,1} \sim \chi(1/12)$	$n_{2,2} \sim \chi(1/6)$
	$n_{3,0} \sim \chi(1/4)$	$n_{3,1} \sim \chi(1/12)$	$n_{3,2} \sim \chi(1/6)$
	$n_{4,0} \sim \chi(1/4)$	$n_{4,1} \sim \chi(1/12)$	$n_{4,2} \sim \chi(1/6)$



Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

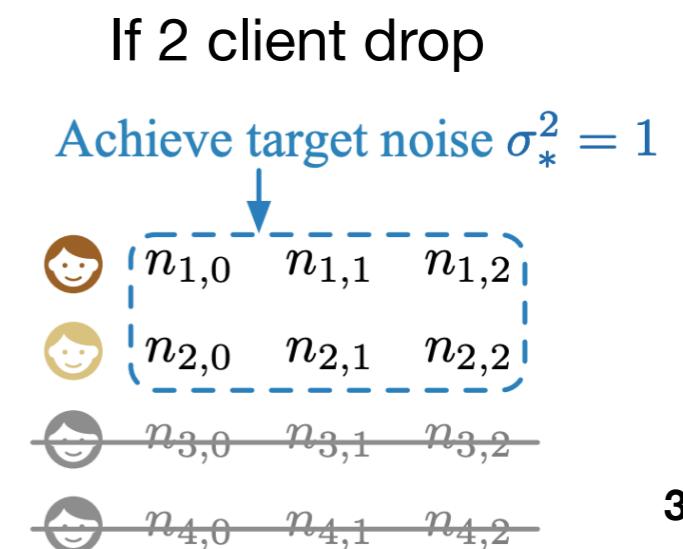
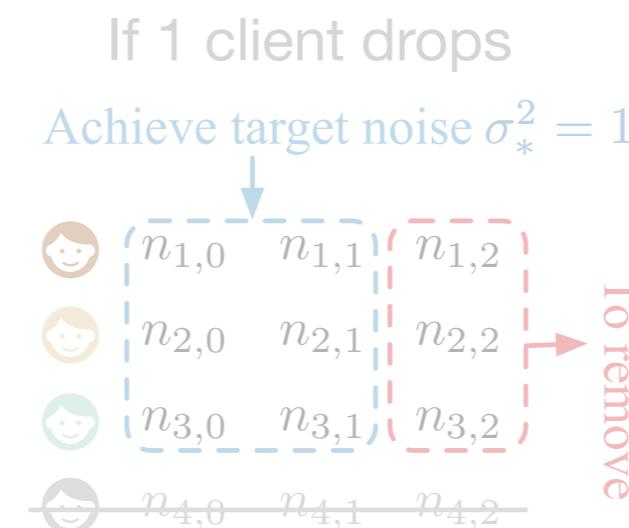
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Concrete example

Add
Sampled clients $|S| = 4$
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	$n_{4,0} \sim \chi(1/4)$	$n_{4,1} \sim \chi(1/12)$	$n_{4,2} \sim \chi(1/6)$



Dropout-Resilient Noise Enforcement

Goal: always enforce the target noise level

Intuition: add-then-remove

Concrete example

Formal definition: **XNoise**

- Add: decompose i 's added noise $n_i \sim \chi\left(\frac{\sigma_*^2}{|S|-t}\right)$ into $t+1$ components:
$$n_i = \sum_{k=0}^t n_{i,k}, n_{i,0} \sim \chi\left(\frac{\sigma_*^2}{|S|}\right), \text{ and } n_{i,k} \sim \chi\left(\frac{\sigma_*^2}{(|S|-k+1)(|S|-k)}\right) (k \in [t])$$
- Remove: when there are $|D|$ clients dropping out, the noise components $n_{i,k}$ contributed by the surviving clients $i \in S \setminus D$ with the index $k > |D|$ becomes excessive and is removed by the server

Practical Design:

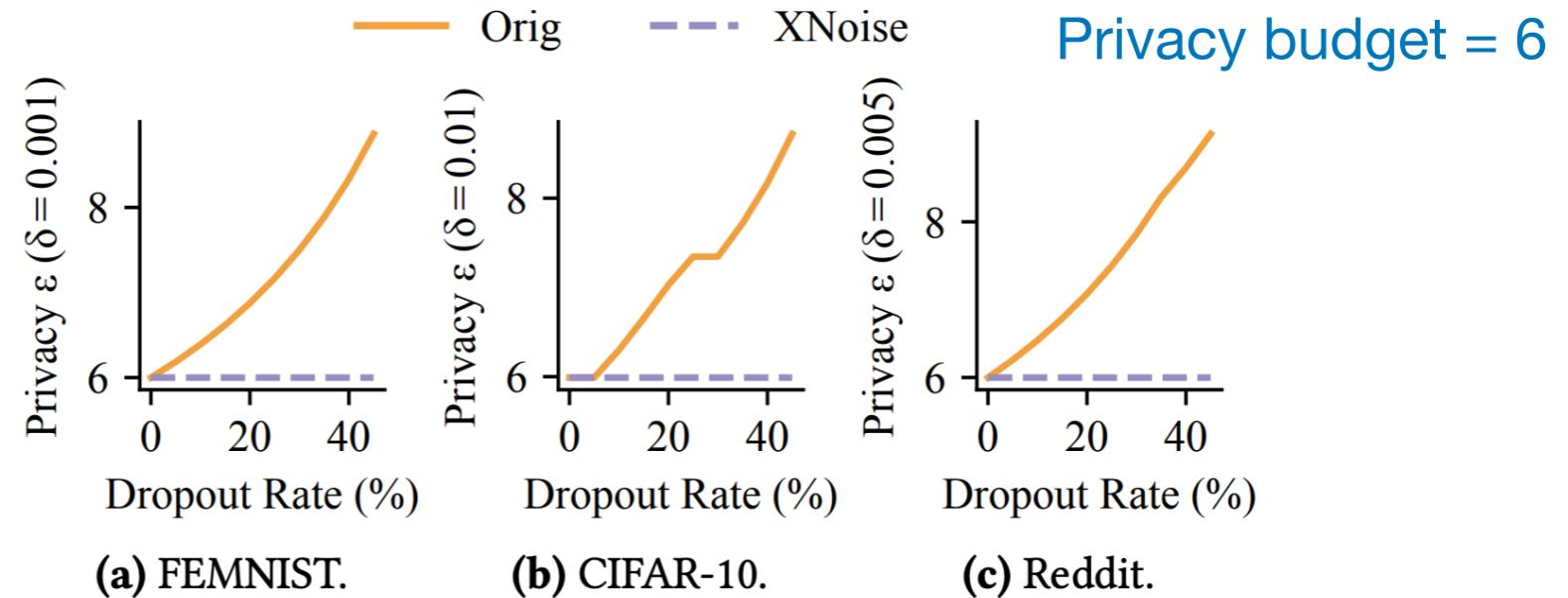
- Avoiding cascading dropout: secret sharing
- Integrity of the dropout outcome: secure signature

Dropout-Resilient Noise Enforcement

XNoise

Improves privacy

without sacrificing
final model utility



Datasets	Dropout rates									
	0		10%		20%		30%		40%	
d	Ori	XNo	Ori	XNo	Ori	XNo	Ori	XNo	Ori	XNo
F	61.3	61.4	61.4	61.4	61.2	61.4	61.2	61.2	61.4	61.5
C	66.5	66.3	66.7	66.9	66.6	65.7	64.3	65.7	63.8	64.2
R	2169	2142	2158	2179	2286	2285	2294	2317	2299	2329

Dropout-Resilient Noise Enforcement

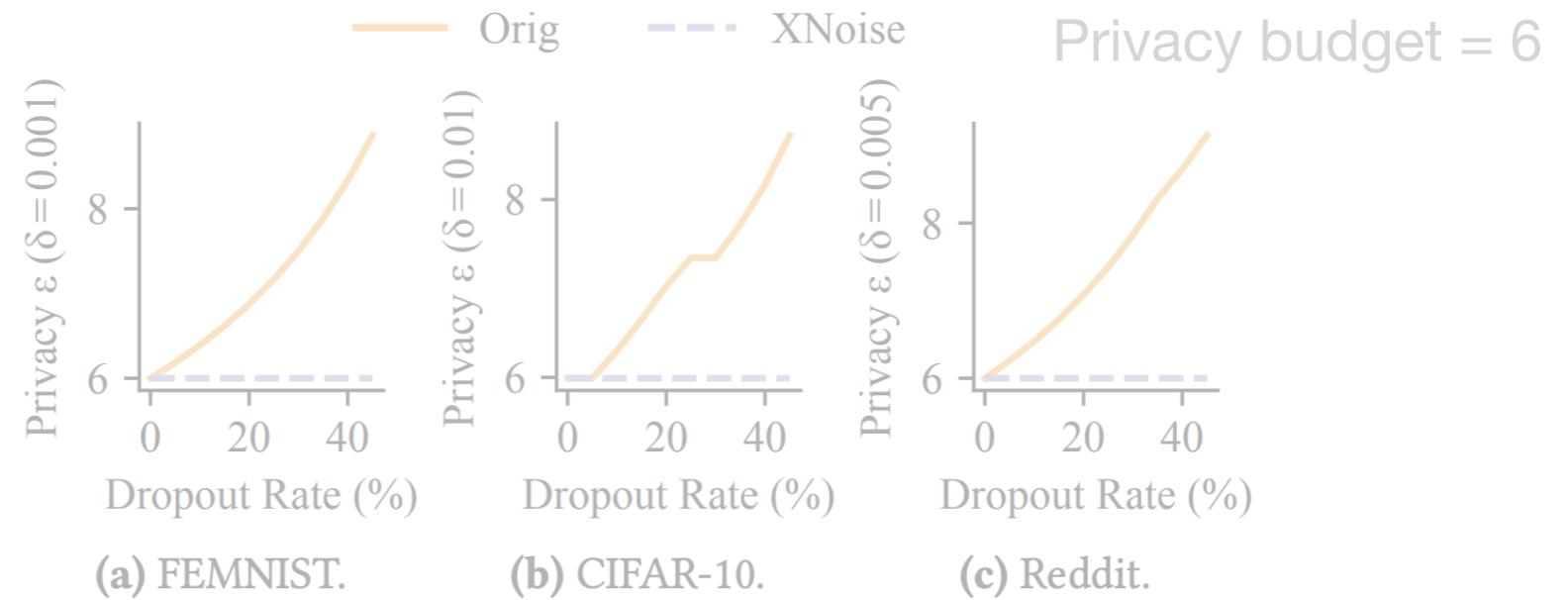
XNoise

Improves privacy

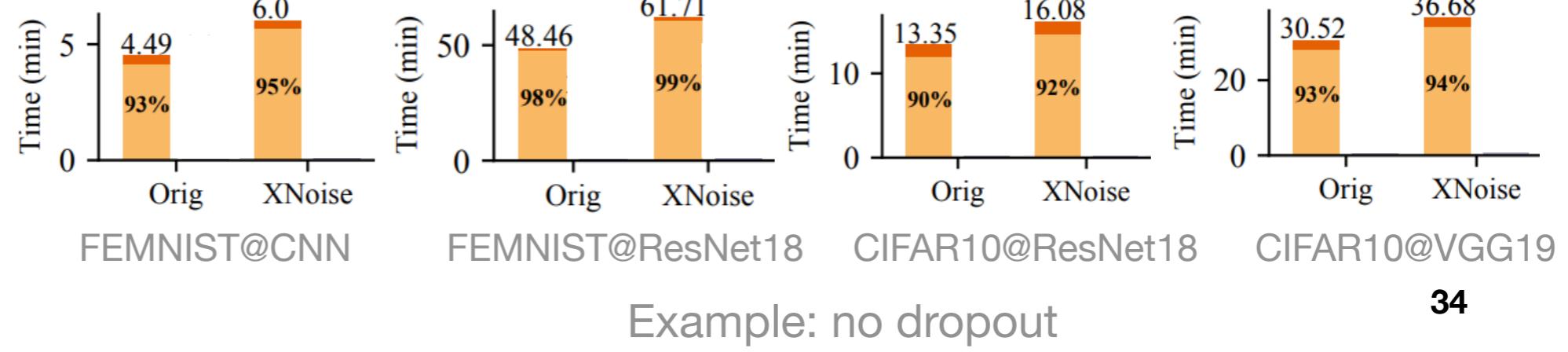
without sacrificing
final model utility

and incurs
acceptable
($\leq 34\%$)

runtime cost



Datasets	Dropout rates										
	d	0		10%		20%		30%		40%	
		Ori	XNo								
F	61.3	61.4	61.4	61.4	61.2	61.4	61.2	61.2	61.2	61.4	61.5
C	66.5	66.3	66.7	66.9	66.6	65.7	64.3	65.7	63.8	63.8	64.2
R	2169	2142	2158	2179	2286	2285	2294	2317	2299	2329	



Distributed DP has Two Issues

1. **Privacy Issue:** caused by client dropout
2. **Performance Issue:** **expensive** use of secure aggregation

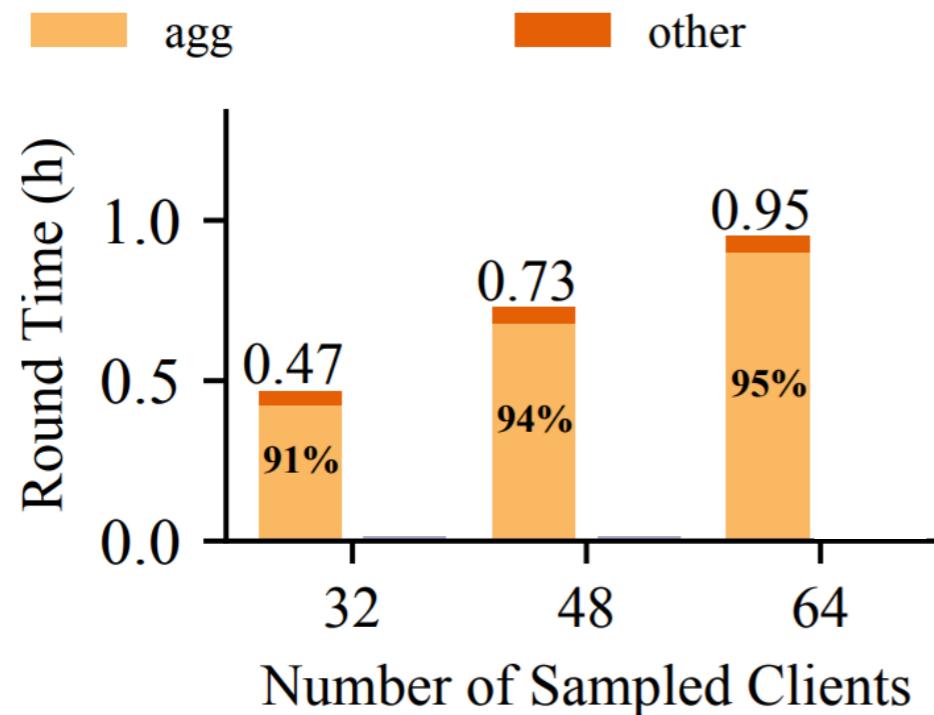
Performance issues with SecAgg

Extensive use of secret sharing and pairwise masking

Performance issues with SecAgg

Extensive use of secret sharing and pairwise masking

Dominates the training time (at least 91%)



original secure aggregation:

SecAgg

Performance issues with SecAgg

Extensive use of secret sharing and pairwise masking

Dominates the training time (at least 91%)

Follow-up solutions

- e.g. **SecAgg+**: improves asymptotically



original secure aggregation:

SecAgg

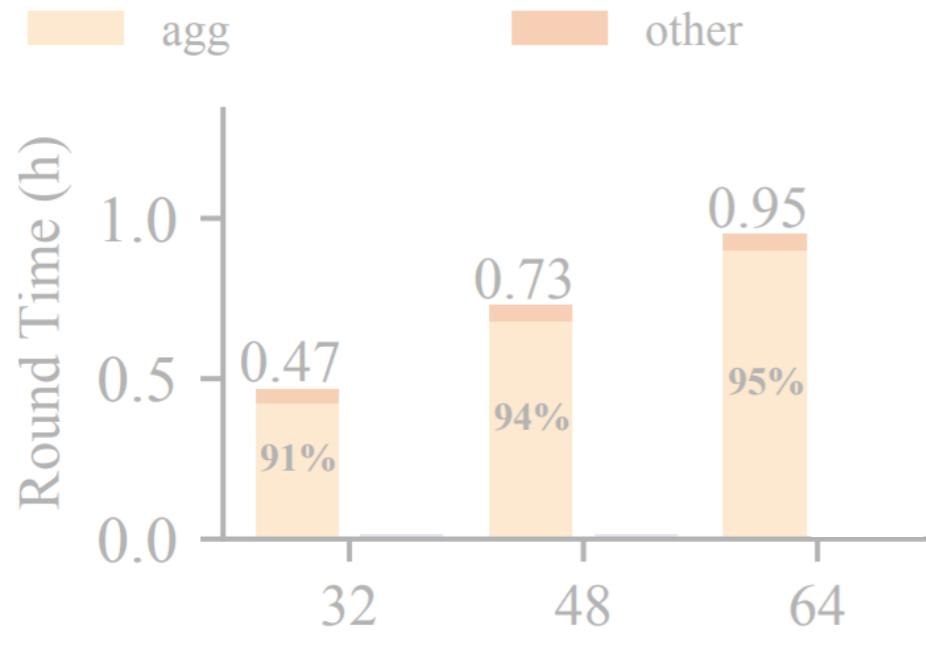
Performance issues with SecAgg

Extensive use of secret sharing and pairwise masking

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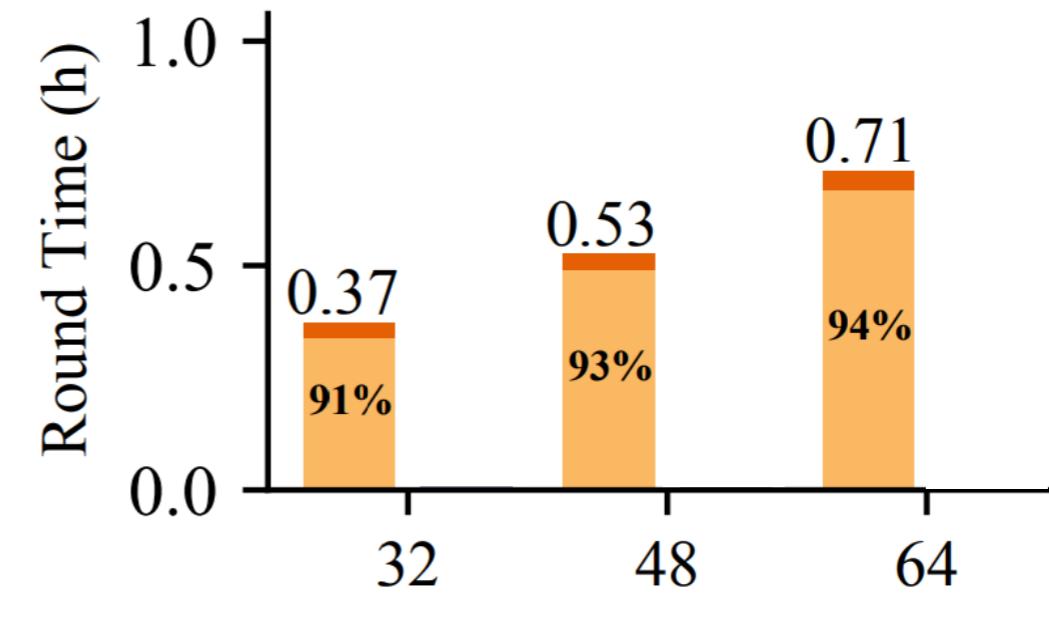
Follow-up solutions have **inefficiencies**

- e.g. SecAgg+: improves asymptotically, but **help little** in small-scale practice¹



original secure aggregation:

SecAgg



SOTA secure aggregation:

SecAgg+

Pipeline-Parallel Acceleration

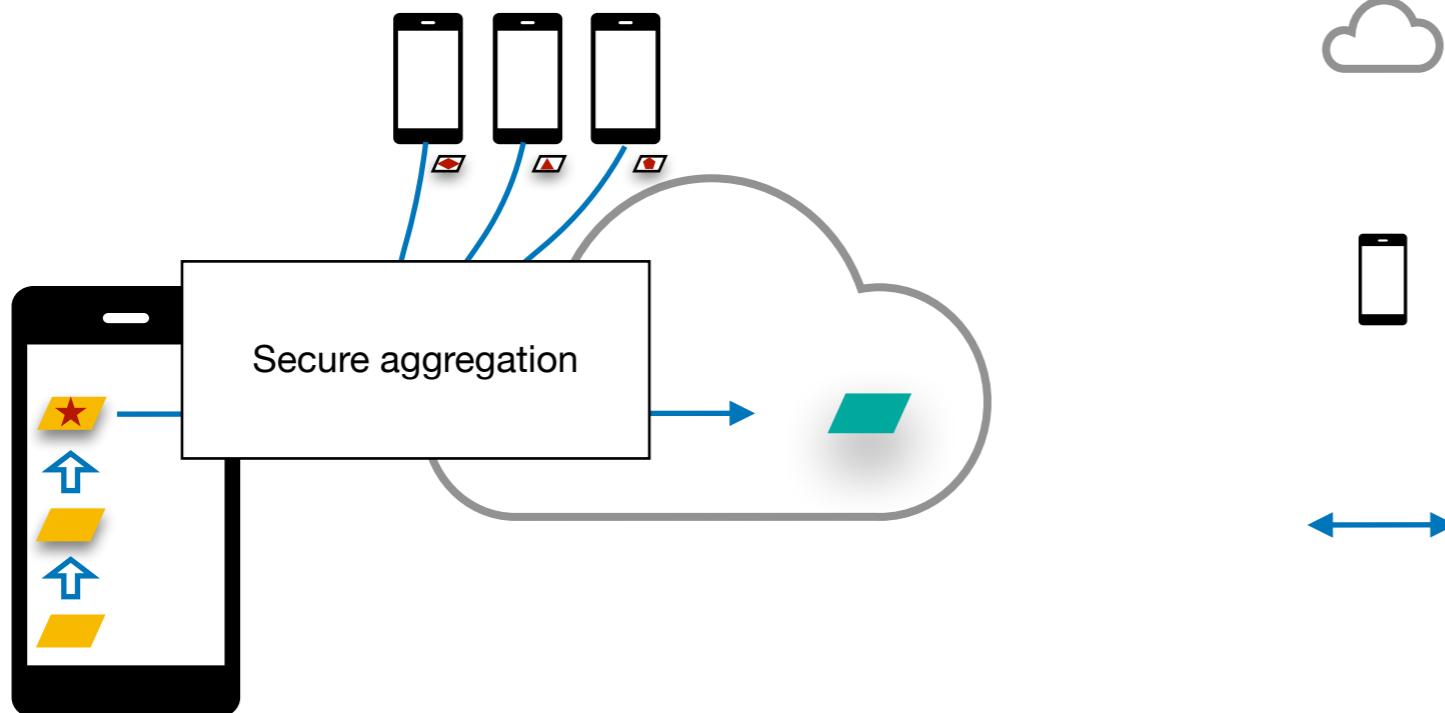
Goal: leverage the **underutilized resources** in the system level

Pipeline-Parallel Acceleration

Goal: leverage the underutilized resources in the system level

Approach:

- Step 1: Identify the **types** of system resources



s-comp: the compute resources (e.g., CPU, GPU, and memory) of the server

c-comp: the compute resources of clients

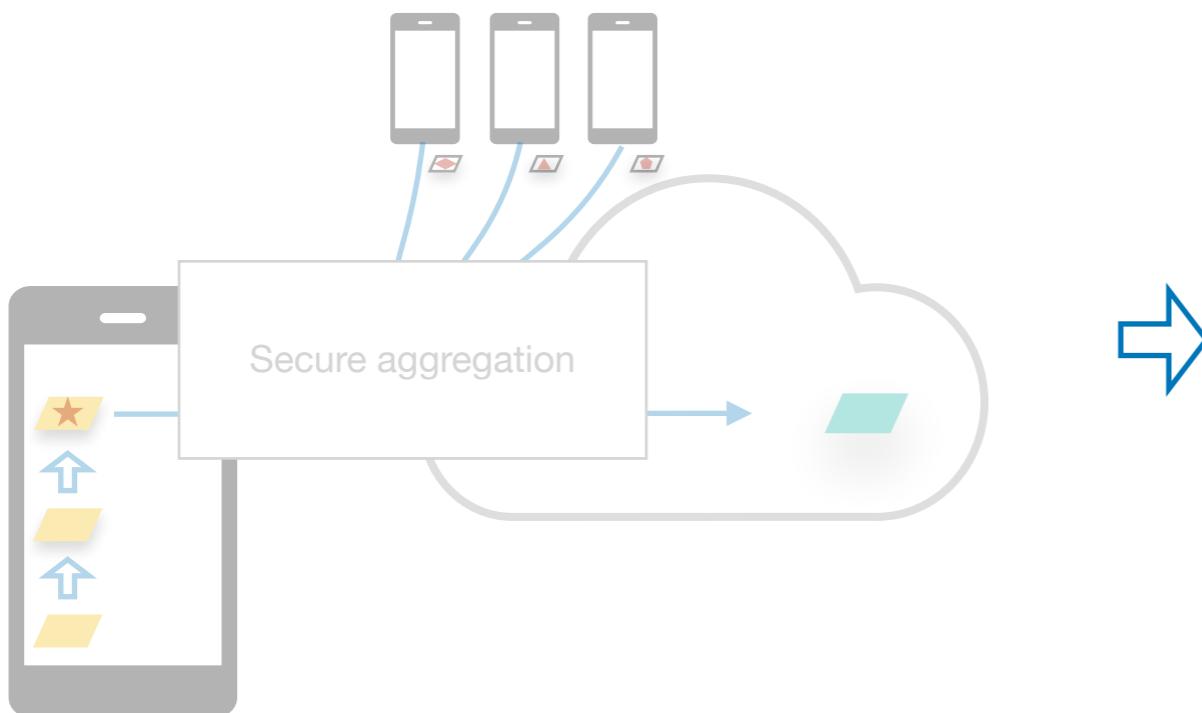
comm: the network resource used for server-client communication

Pipeline-Parallel Acceleration

Goal: leverage the underutilized resources in the system level

Approach:

- Step 1: Identify the types of system resources
- Step 2: **Group consecutive operations that use the same system resources**



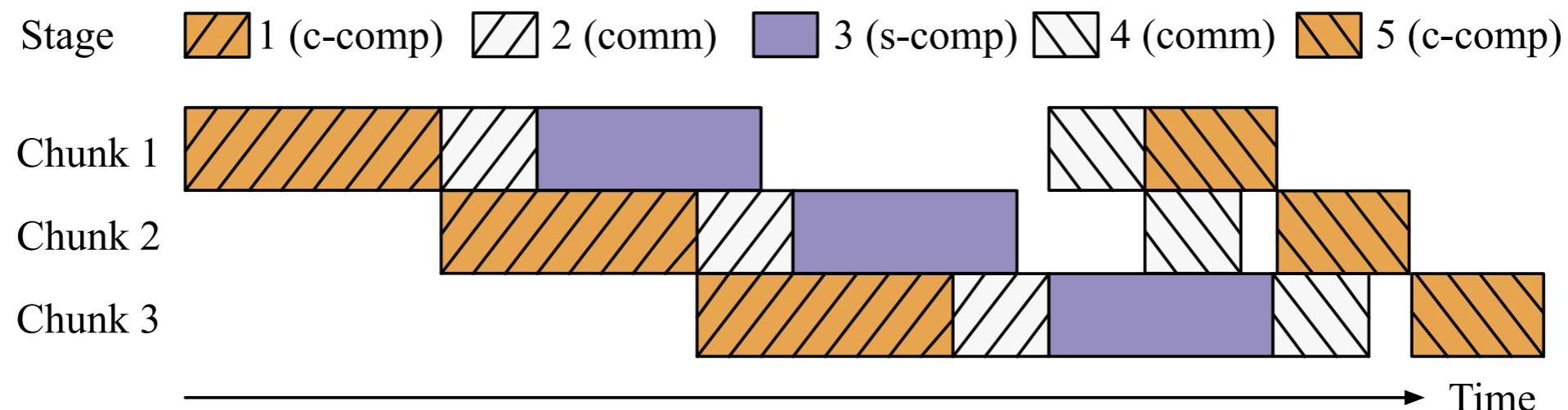
Step	Operation	Stage (Resource)
1	Clients encode updates.	1 (c-comp)
2	Clients generate security keys.	
3	Clients establish shared secrets.	
4	Clients mask encoded updates.	
5	Clients upload masked updates.	2 (comm)
6	Server deals with dropout.	3 (s-comp)
7	Server computes aggregate update.	
8	Server updates the global model.	
9	Server dispatches the aggregate.	4 (comm)
10	Clients decode the aggregate.	5 (c-comp)
11	Clients use the aggregate.	

Pipeline-Parallel Acceleration

Goal: leverage the underutilized resources in the system level

Approach:

- Step 1: Identify the types of system resources
- Step 2: Group consecutive operations that use the same system resources
- Step 3: Evenly **partition** each client's update into chunks and **pipeline** them



Pipeline-Parallel Acceleration

Goal: leverage the underutilized resources in the system level

Approach:

- Step 1: Identify the types of system resources
- Step 2: Group consecutive operations that use the same system resources
- Step 3: Evenly partition each client's update into chunks and pipeline them
 - Optimize to determine the **optimal number of chunk, m^***

$$m^* = \arg \min_{m \in N_+} f_{a,m}$$

$$s.t. \quad f_{s,c} = b_{s,c} + l_s$$

$$b_{s,c} = \max\{o_{s,c}, r_{s,c}\}$$

$$o_{s,c} = \begin{cases} 0, & \text{if } s = 0, \\ f_{s-1,c} & \text{Intra-chunk sequential execution} \end{cases}$$

*Definition of the finish time of
Chunk m at Stage a*

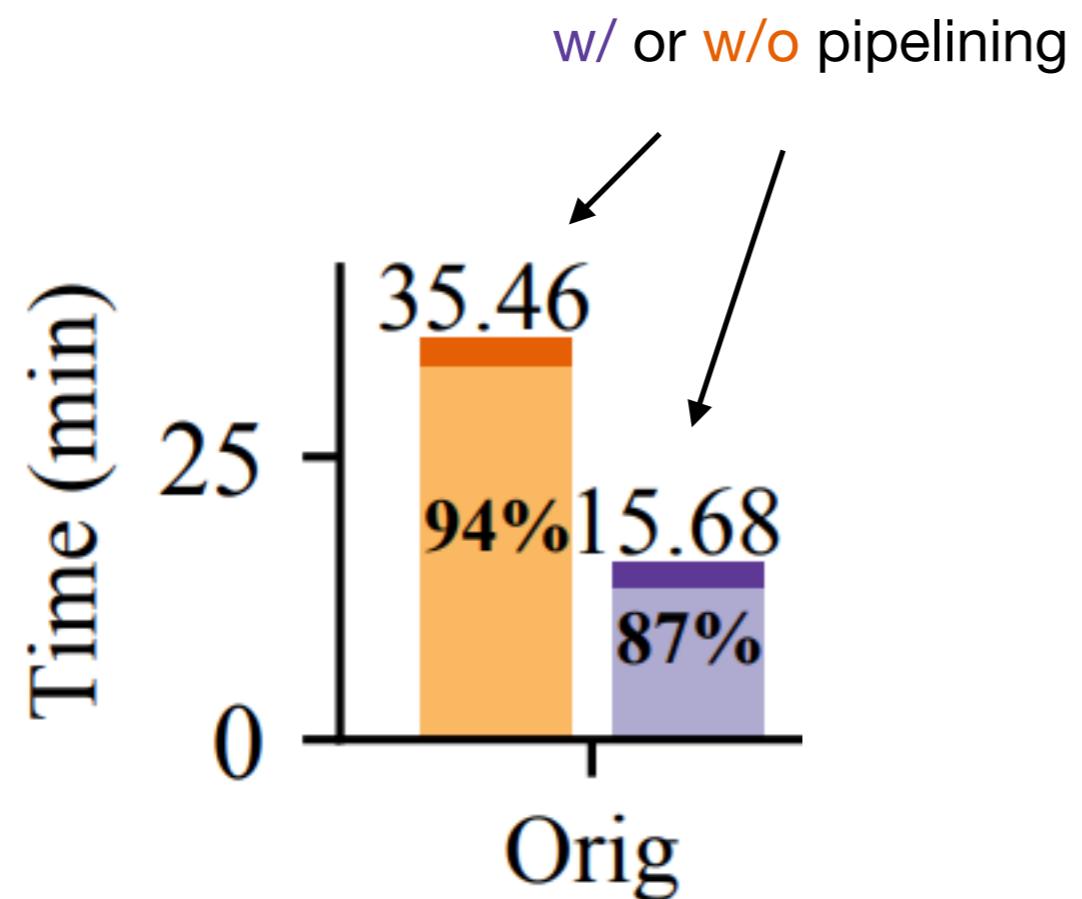
$$r_{s,c} = \begin{cases} 0, & \text{if } s = 0 \text{ and } c = 0, \\ f_{q,m} \text{ or } \perp, & \text{if } s \neq 0 \text{ and } c = 0, \\ f_{s,c-1}, & \text{otherwise} \end{cases}$$

*Exclusive allocation
& Inter-chunk sequential execution*

Pipeline-Parallel Acceleration

Effectiveness:

- ① A maximum speedup of **2.4X**

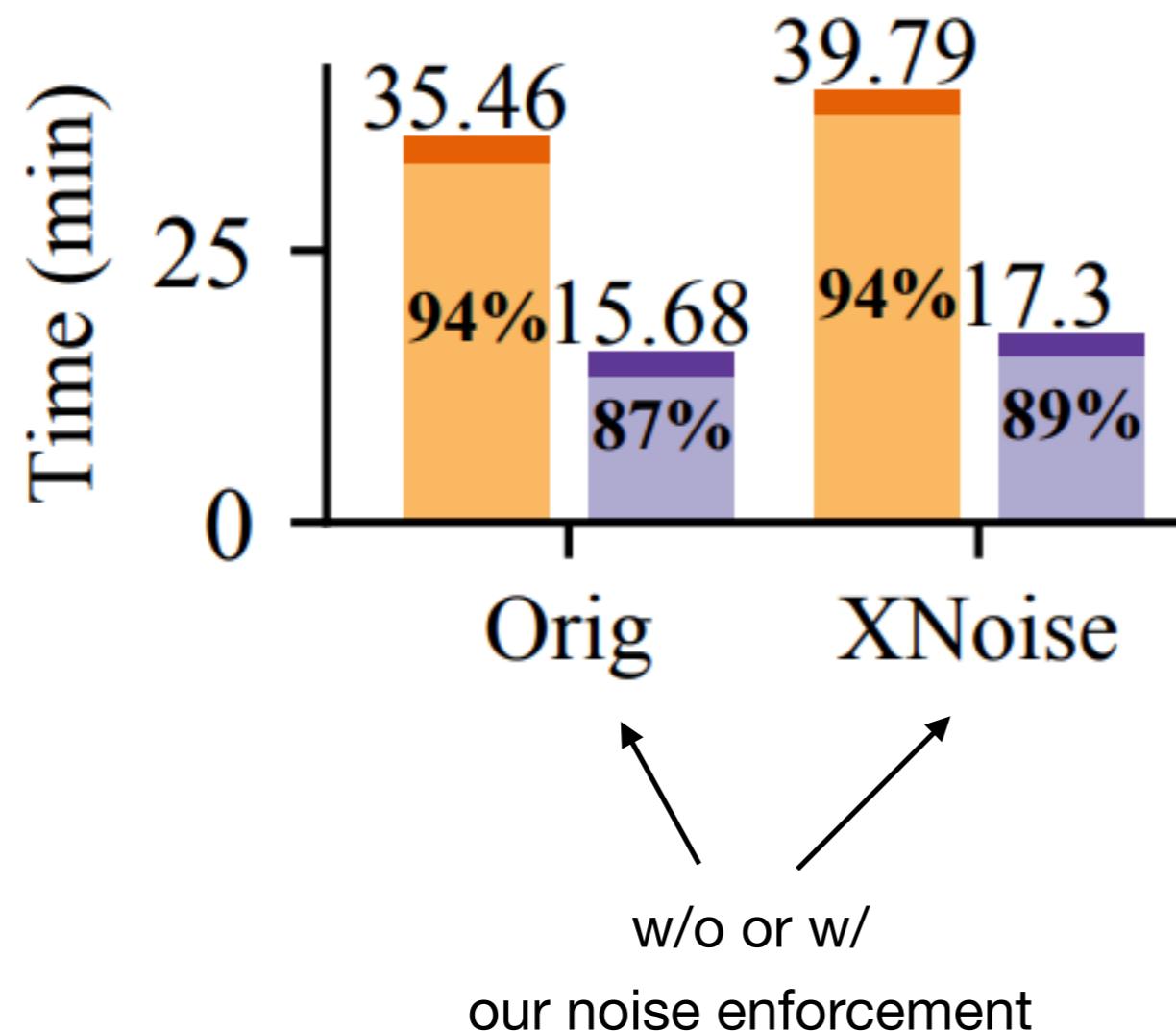


Case study: CIFAR10 @
VGG19, dropout rate = 30%

Pipeline-Parallel Acceleration

Effectiveness:

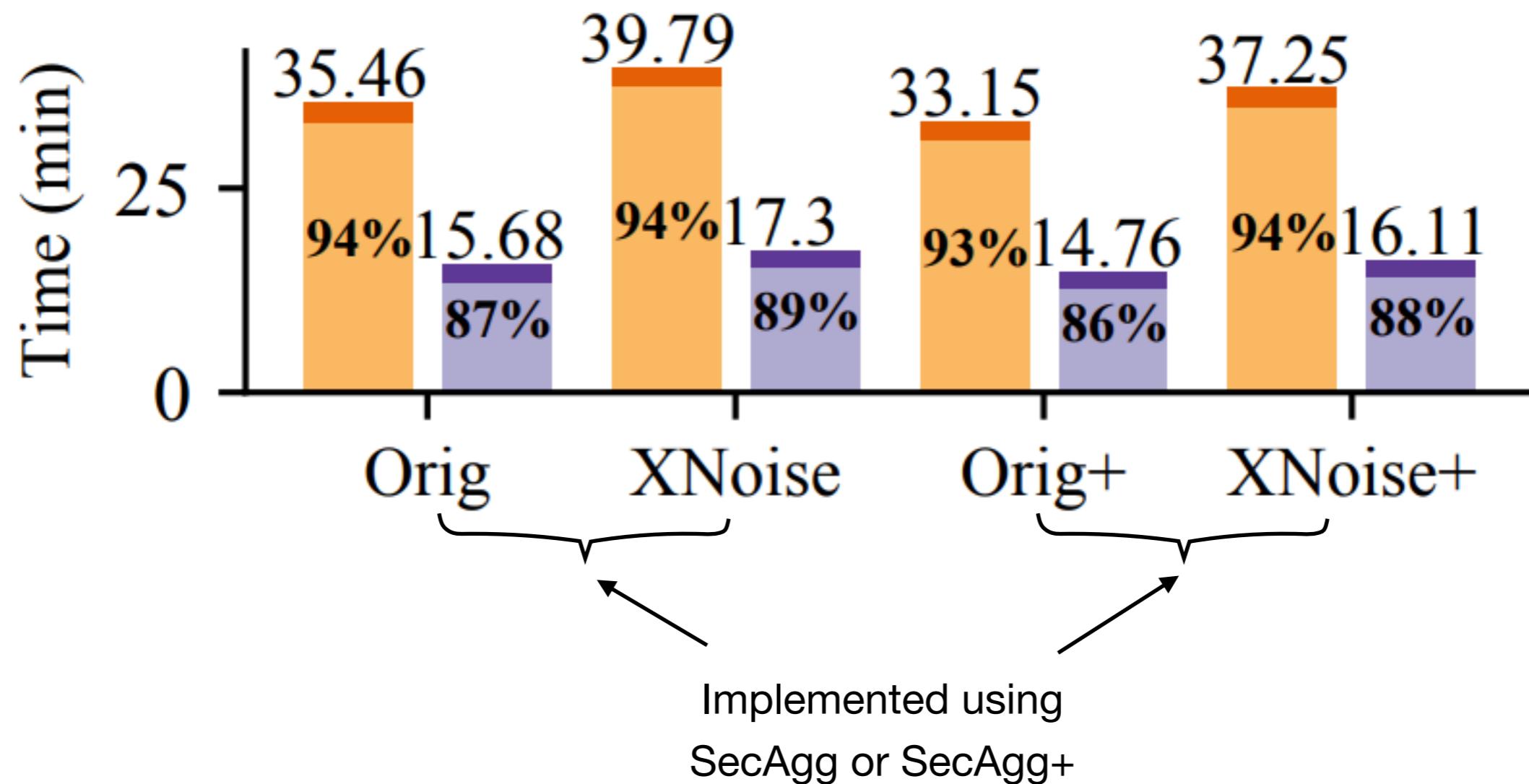
- ① A maximum speedup of **2.4X**



Pipeline-Parallel Acceleration

Effectiveness:

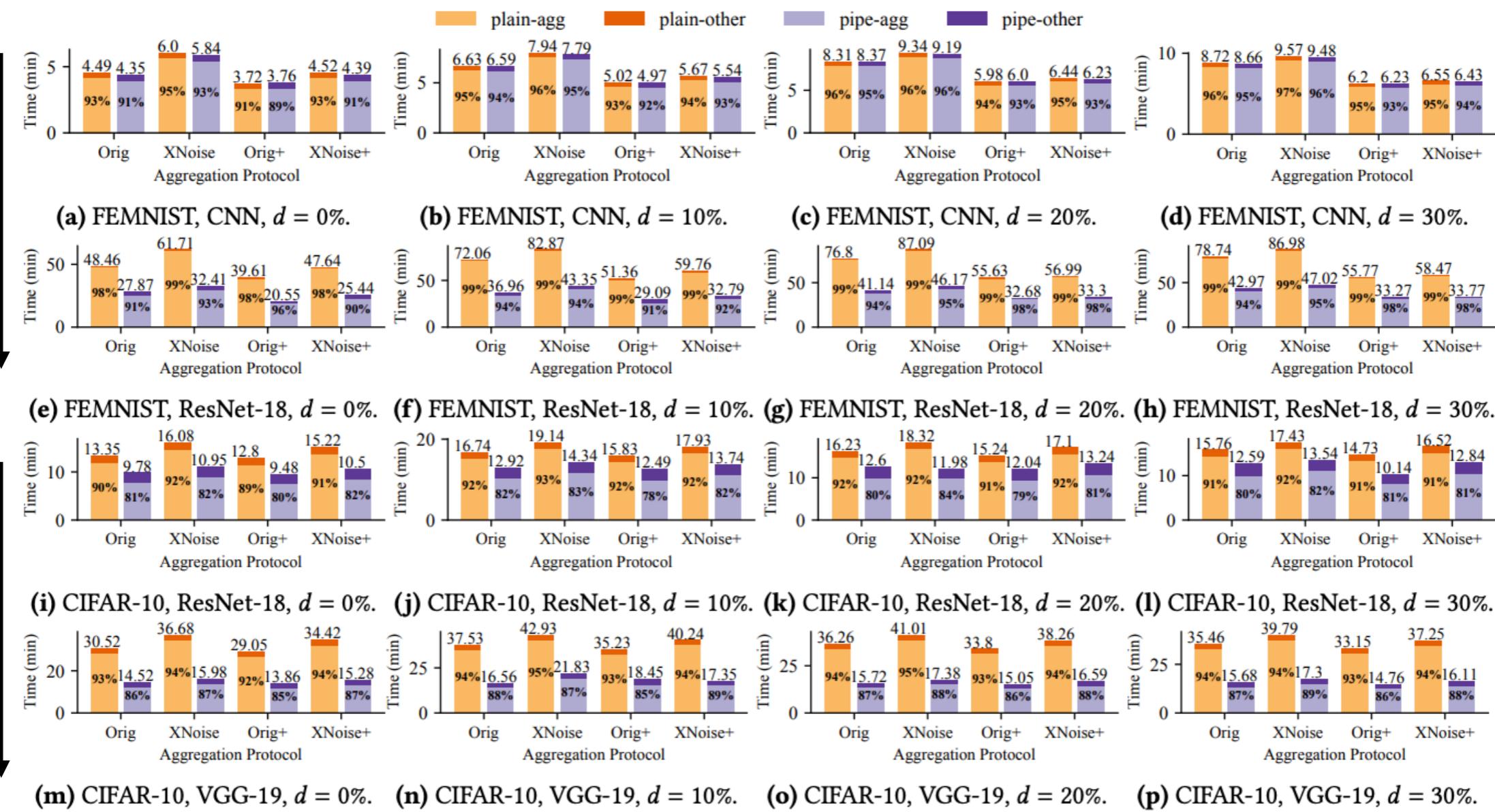
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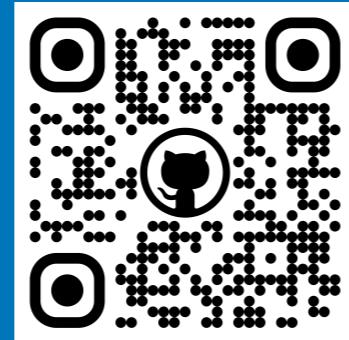
Pipeline-Parallel Acceleration

Effectiveness:

① A maximum speedup of 2.4X



Dordis



A distributed DP framework for
• Privacy
• Efficiency
in FL training

<https://github.com/SamuelGong/Dordis>

Automate

Precise Noise
Enforcement

Optimal Pipelined
Execution

For

Privacy
Preservation

Efficiency
Enhancement

Against

Client
Dropout

SecAgg's
Bottleneck

Thank you!