## Plan of the Presentation

- Introduction
- Origin of the model
  - Stochastic Gradient Descent (SGD)
  - Stochastic Weight Averaging (SWA)
  - Assumptions
- Presentation of SWAG
  - Theoretical presentation of SWAG
  - SWAG Diagonal
  - SWAG Low Rank + Diagonal Structure
- Experimental Results
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## A Simple Baseline for Bayesian Uncertainty

## Algorithm 1 Continuous learning of SWAG model

```
\theta_{\text{pre}}: pretrained weights; \eta: learning rate; T: number of steps; c: moment
update frequency; K: required rank; S: number of samples
    \overline{\theta} \leftarrow \theta_0, \quad \overline{\theta^2} \leftarrow \theta_0^2
                                                                                          {Initialize moments}
     for i \leftarrow 1, 2, ..., T do
          \theta_i \leftarrow \text{SGD}(\theta_{i-1})
                                                                                     {Perform SGD update}
          if update time = True then
               n \leftarrow i/c
                                                                                          {Number of models}
              \overline{\theta} \leftarrow \frac{n\overline{\theta} + \theta_i}{n+1}, \ \overline{\theta^2} \leftarrow \frac{n\overline{\theta^2} + \theta_i^2}{n+1}
                                                                                            {Update moments}
               if nbr stored param = K then
                    forget first param
                    store new param(\theta_i - \overline{\theta})
                                                                                                {Store deviation}
          if estimate time = True then
               for i \leftarrow 1, 2, ..., S do
                     Draw \widetilde{\theta}_i \sim \mathcal{N}\left(\theta_{\text{SWA}}, \frac{1}{2}\Sigma_{\text{diag}} + \frac{\widehat{D}\widehat{D}^{\top}}{2(K-1)}\right)
                     p(y^*|\text{Data}) += \frac{1}{S}p(y^*|\widetilde{\theta}_i)
     return p(y^*|Data)
```