Image class classification of garbage to identify the correct bin in Manningham

Planning

Aim:

The aim is to create a neural network that can use an image of some piece of garbage and identify which bin it should be placed into based on manninghams local garbage policies.

Manningham's Bins:

Manningham has three bin types:

- Red General Garbage Bin
- Yellow Recycling Bin
- Green FOGO Bin

In the future I will just be referring to these bins by color.

Model design

I intend on creating a **convnet** which takes an input of an image and an output of the type of rubbish, which will then be used to assign the rubbish to a bin via non-machine learning systems. This implementation allows for more specific training with teaching the type of trashing, making it more flexible if recycling guidelines change in the future.

- The input is an image.
- The target class is the type of garbage.
- The final output is the type of bin the garbage should be placed into

Dataset

The dataset I plan on using is the "Garbage Classification" dataset from Kaggle https://www.kaggle.com/datasets/asdasdasasdas/garbage-classification

Except from the page: "The Garbage Classification **Dataset contains 6 classifications**: cardboard (393), glass (491), metal (400), paper(584), plastic (472) and trash(127)."

Of these classes (the target classes) I will outline which bin contains which piece of trash from the dataset.

Red Bin Contains

- General Trash
- Plastic

Yellow Bin Contains

- Cardboard
- Glass
- Metal
- Paper

Green Bin Contains

- Nothing from this dataset and this bin will be not included in the future of this task
- Is intended to contain food scraps and plant matter

Due to the nature of the dataset, splitting it into types of trash will also help me avoid unbalanced training data, as it will be easier to even out the number of samples for the individual trash types as opposed to samples from each bin.

Labels

The data is already pre-labeled for my use.

Number of samples per class

I plan on using NUM_SAMPLES samples per class with a 60/20/20% test/train/validation split. I selected this value as it will involve me using data augmentation, but not to an excessive degree, with 3 variations of each image being required for general trash (only 127 unique samples).

I believe that, as this is a fairly simple classification task, using smaller amounts of samples (mid-hundreds) will be sufficient for the convnet.

Implimentation

Data preparation

In this code block I import all images, augmenting all of them, if I can not get to 480 images I begin picking random images out and augmenting them till I have the 480 samples per class.

Data Augmentation

I only read after I'd implimented it that a augmentation pipeline is the C task, I have included the comparison without augmentation later on.

```
In [3]:
```

```
%%time
import os
import random
import tensorflow as tf
random.seed(42)
NUM SAMPLES = 480
data folder = 'Garbage classification'
classes = os.listdir(data folder)
output folder = 'processed data augmented'
if not os.path.exists(output folder):
   os.makedirs(output folder)
# Rotation model
rotate = tf.keras.Sequential([
   tf.keras.layers.RandomRotation(factor=(1/12, 1/12)),
   tf.keras.layers.RandomZoom(0.2)
])
def augmentation pipeline(image):
   image = tf.cast(image, tf.float32) / 255.0
   image = tf.image.random flip left right(image)
   image = tf.image.random flip up down(image)
```

```
image = rotate(image)
    image = tf.cast(image * 255.0, tf.uint8)
    return image
for class name in classes:
    class path = os.path.join(data folder, class name)
    images = [os.path.join(class path, image) for image in os.listdir(class path) if ima
ge.endswith('.jpg')]
    output class folder = os.path.join(output folder, class name)
    if not os.path.exists(output class folder):
        os.makedirs(output class folder)
    augmented data count = 0
    while augmented data count < NUM SAMPLES:
        image path = random.choice(images)
        original_image = tf.io.read file(image path)
        original image = tf.image.decode jpeg(original image, channels=3)
        # Apply augmentation
        augmented image = augmentation pipeline(original image)
        # Save the augmented image
        augmented image path = os.path.join(output class folder, f'{augmented data count
}.jpg')
        tf.io.write file(augmented image path, tf.image.encode jpeg(augmented image))
        augmented data count += 1
print("done")
done
CPU times: total: 3min 18s
```

Wall time: 1min 47s

Profiler - Could not get it working properly - wasn't quite sure how to apply it

```
In [20]:
rotate = tf.keras.Sequential([
   tf.keras.layers.RandomRotation(factor=(1/12, 1/12)),
    tf.keras.layers.RandomZoom(0.2)
])
def augmentation pipeline(image):
    with tf.profiler.experimental.Trace('cast to float'):
        image = tf.cast(image, tf.float32) / 255.0
    with tf.profiler.experimental.Trace('random flip left right'):
        image = tf.image.random flip left right(image)
    with tf.profiler.experimental.Trace('random flip up down'):
        image = tf.image.random flip up down(image)
    with tf.profiler.experimental.Trace('rotate'):
        image = rotate(image) # Assuming rotate is defined elsewhere
    with tf.profiler.experimental.Trace('cast to uint8'):
        image = tf.cast(image * 255.0, tf.uint8)
    return image
# Assuming the use of TensorFlow 2.x and its profiler API
logdir = './logs'
tf.profiler.experimental.start(logdir, tf.profiler.experimental.ProfilerOptions())
# Example usage with a dummy image
dummy image = tf.random.uniform(shape=[256, 256, 3], minval=0, maxval=256, dtype=tf.int3
augmented image = augmentation pipeline(tf.cast(dummy image, tf.uint8))
```

```
# Running the function to profile
for _ in range(1000): # Adjusted range to start from 0 for better practice
    augmented_image = augmentation_pipeline(tf.cast(dummy_image, tf.uint8))
# Stopping the profiler
tf.profiler.experimental.stop()
```

```
In [36]:
```

```
%reset -f
```

Test Train Validation Split

```
In [37]:
```

```
%%time
import tensorflow as tf
dataset path = 'processed data'
train dataset = tf.keras.preprocessing.image dataset from directory(
    dataset path,
    validation split=0.2,
   subset="training",
    seed=123,
   image_size=(256, 256),
   batch size=32)
validation dataset = tf.keras.preprocessing.image dataset from directory(
    dataset path,
    validation_split=0.2,
    subset="validation",
   seed=123,
   image size=(256, 256),
   batch size=32)
# Configure the dataset for performance
AUTOTUNE = tf.data.AUTOTUNE
train dataset = train dataset.cache().shuffle(1000).prefetch(buffer size=AUTOTUNE)
validation dataset = validation dataset.cache().prefetch(buffer size=AUTOTUNE)
```

```
CPU times: total: 0 ns
Wall time: 0 ns
Found 2880 files belonging to 6 classes.
Using 2304 files for training.
Found 2880 files belonging to 6 classes.
Using 576 files for validation.
```

In [42]:

```
import tensorflow as tf
from tensorflow.keras.regularizers import 12
model = tf.keras.models.Sequential([
   tf.keras.layers.Rescaling(1./255),
   tf.keras.layers.Conv2D(32, 3, activation='relu'),
   tf.keras.layers.MaxPooling2D(),
   tf.keras.layers.Conv2D(64, 3, activation='relu'),
    tf.keras.layers.MaxPooling2D(),
    tf.keras.layers.Dropout(0.15),
    tf.keras.layers.Conv2D(128, 3, activation='relu', kernel regularizer=12(0.25)),
    tf.keras.layers.MaxPooling2D(),
    tf.keras.layers.Flatten(),
    tf.keras.layers.Dense(128, activation='relu'),
    tf.keras.layers.Dropout(0.15),
    tf.keras.layers.Dense(6)
])
```

In [43]:

```
%%time
with tf.device('/GPU:0'):
   history = model.fit(
       train dataset,
       validation data=validation dataset,
       epochs=10
CPU times: total: 0 ns
Wall time: 0 ns
Epoch 1/10
                  47s 613ms/step - accuracy: 0.1977 - loss: 15.2438 - val accura
72/72 -
cy: 0.3785 - val loss: 3.1527
Epoch 2/10
                      - 47s 650ms/step - accuracy: 0.4508 - loss: 2.5776 - val accurac
72/72
y: 0.4705 - val loss: 1.7987
Epoch 3/10
                     72/72 •
y: 0.5174 - val loss: 1.3836
Epoch 4/10
                       - 45s 624ms/step - accuracy: 0.5365 - loss: 1.3273 - val accurac
72/72
y: 0.5278 - val loss: 1.2658
Epoch 5/10
72/72
                       – 43s 593ms/step – accuracy: 0.6031 – loss: 1.1628 – val accurac
y: 0.5660 - val loss: 1.2416
Epoch 6/10
                      - 46s 633ms/step - accuracy: 0.6067 - loss: 1.1395 - val_accurac
72/72
y: 0.6007 - val loss: 1.1769
Epoch 7/10
72/72 •
                       - 46s 628ms/step - accuracy: 0.6597 - loss: 1.0169 - val accurac
y: 0.5885 - val loss: 1.1420
Epoch 8/10
                      - 43s 588ms/step - accuracy: 0.6914 - loss: 0.9088 - val accurac
y: 0.5851 - val loss: 1.2516
Epoch 9/10
                       - 47s 640ms/step - accuracy: 0.6944 - loss: 0.9338 - val accurac
72/72 •
y: 0.6389 - val loss: 1.1048
Epoch 10/10
                     72/72 -
y: 0.6146 - val loss: 1.1525
```

In [44]:

```
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.metrics import classification_report, confusion_matrix

class_names = ["CardBoard", "Glass", "Metal", "Paper", "Plastic", "Trash"]

# Predicting on validation dataset
predictions = model.predict(validation_dataset)

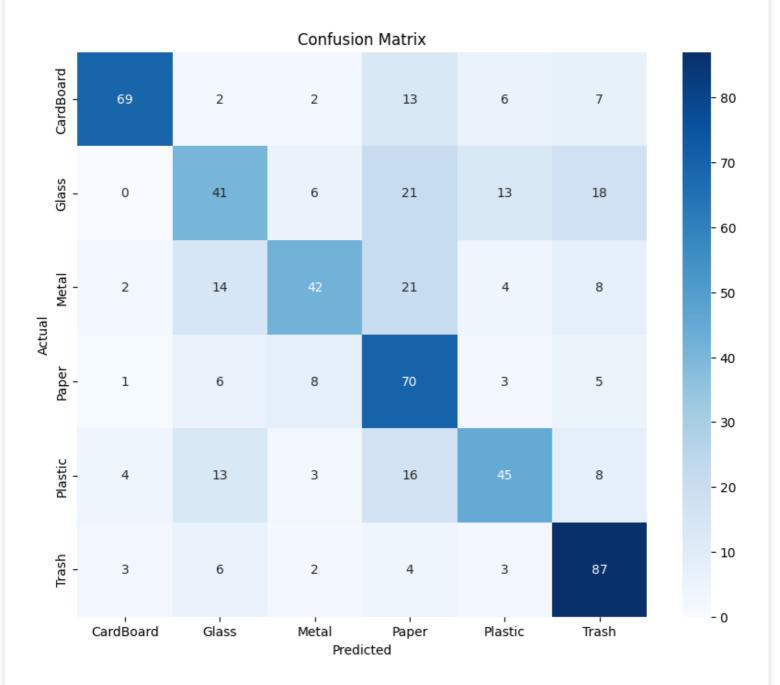
# Getting true labels
true_labels = np.concatenate([y for x, y in validation_dataset], axis=0)

# Converting predictions to class labels
predicted_labels = np.argmax(predictions, axis=1)
```

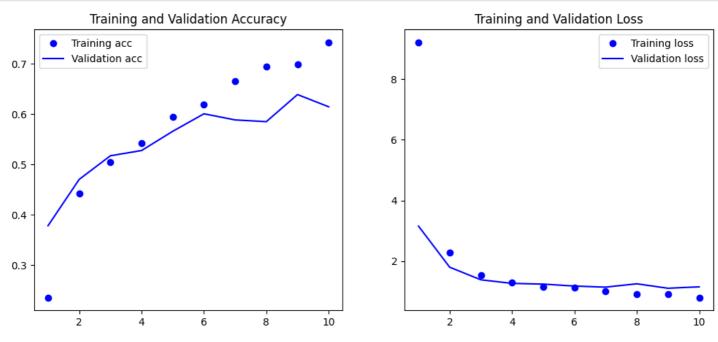
```
# Printing classification report
print(classification_report(true_labels, predicted_labels))

# Plotting confusion matrix
cm = confusion_matrix(true_labels, predicted_labels)
plt.figure(figsize=(10, 8))
sns.heatmap(cm, annot=True, fmt="d", cmap="Blues", xticklabels=class_names, yticklabels=
class_names)
plt.xlabel('Predicted')
plt.ylabel('Actual')
plt.title('Confusion Matrix')
plt.show()
```

18/18	3s 118ms/step				
	precision	recall	f1-score	support	
0	0.87	0.70	0.78	99	
1	0.50	0.41	0.45	99	
2	0.67	0.46	0.55	91	
3	0.48	0.75	0.59	93	
4	0.61	0.51	0.55	89	
5	0.65	0.83	0.73	105	
accuracy			0.61	576	
macro avg	0.63	0.61	0.61	576	
weighted avg	0.63	0.61	0.61	576	



```
acc = history.history['accuracy']
val acc = history.history['val accuracy']
loss = history.history['loss']
val loss = history.history['val loss']
epochs = range(1, len(acc) + 1)
plt.figure(figsize=(12, 5))
plt.subplot(1, 2, 1)
plt.plot(epochs, acc, 'bo', label='Training acc')
plt.plot(epochs, val acc, 'b', label='Validation acc')
plt.title('Training and Validation Accuracy')
plt.legend()
plt.subplot(1, 2, 2)
plt.plot(epochs, loss, 'bo', label='Training loss')
plt.plot(epochs, val_loss, 'b', label='Validation loss')
plt.title('Training and Validation Loss')
plt.legend()
plt.show()
```



Most metrics are around 61%, which isn't great, although it is with 6 target classes, which makes it slightly less bad sounding than if it was binary. Lets convert it to bins to identify if I succeeded with my goal.

Converting trash training data to bin training data.

```
In [48]:
```

```
class_names = ["CardBoard", "Glass", "Metal", "Paper", "Plastic", "Trash"]
bin_names = ["Yellow Bin", "Red Bin"]

# Mapping class labels to bin labels
class_to_bin = {
    "CardBoard": "Yellow Bin",
    "Metal": "Yellow Bin",
    "Paper": "Yellow Bin",
    "Plastic": "Red Bin",
    "Trash": "Red Bin"
}

# Function to convert class labels to bin labels
def convert_to_bins(labels, class_to_bin, class_names):
    bin_labels = [class_to_bin[class_names[label]]] for label in labels]
    return np.array([bin_names.index(bin_label)] for bin_label in bin_labels])
```

```
# Predicting on validation dataset
predictions = model.predict(validation dataset)
# Getting true labels
true labels = np.concatenate([y for x, y in validation dataset], axis=0)
# Converting predictions to class labels
predicted labels = np.argmax(predictions, axis=1)
# Converting true and predicted class labels to bin labels
true bin labels = convert to bins(true labels, class to bin, class names)
predicted bin labels = convert to bins(predicted labels, class to bin, class names)
# Printing classification report for bin labels
print("Classification Report for Bin Labels:")
print(classification report(true bin labels, predicted bin labels, target names=bin names
# Plotting confusion matrix for bin labels
cm bin = confusion matrix(true bin labels, predicted bin labels)
plt.figure(figsize=(8, 6))
sns.heatmap(cm bin, annot=True, fmt="d", cmap="Blues", xticklabels=bin names, yticklabel
s=bin names)
plt.xlabel('Predicted Bin')
plt.ylabel('Actual Bin')
plt.title('Confusion Matrix for Bins')
plt.show()
```

18/18 -- 3s 141ms/step Classification Report for Bin Labels: precision recall f1-score support Yellow Bin 0.86 0.83 0.85 382 Red Bin 0.69 0.74 0.71 194 0.80 576 accuracy 0.78 0.78 0.78 macro avq 576

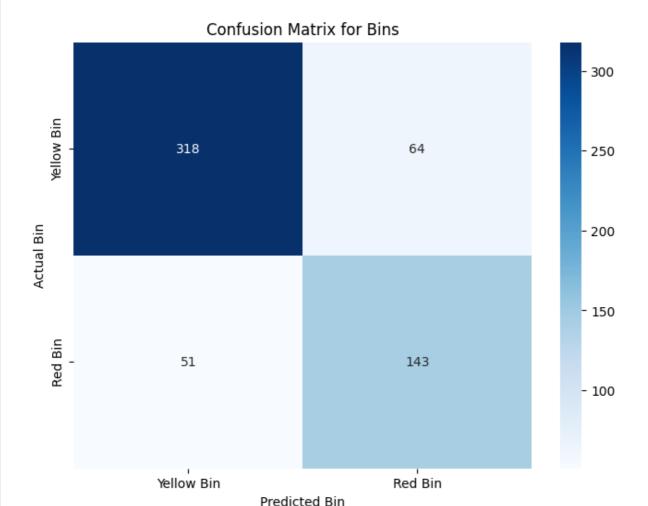
0.80

0.80

576

0.80

weighted avg



Model performance analysis

import tensorflow as tf

dataset path = 'processed data'

The Model selects the correct bin on average ~80% of the time, with similar precision and recall. The bin data is biased towards the yellow bin due to having more samples overall, but it's hard to tell if the statistics are being skewed or the model it's self is being biased by this.

Model without augmentation

I repeat the exact same process but I remove the augmentations entirely.

```
In [50]:
%reset -f
In [52]:
%%time
import os
import random
import tensorflow as tf
random.seed(42)
NUM SAMPLES = 480
data folder = 'Garbage classification'
classes = os.listdir(data folder)
output folder = 'processed data'
if not os.path.exists(output folder):
   os.makedirs(output folder)
for class name in classes:
    class path = os.path.join(data folder, class name)
   images = [os.path.join(class path, image) for image in os.listdir(class path) if ima
ge.endswith('.jpg')]
    output_class_folder = os.path.join(output_folder, class_name)
    if not os.path.exists(output class folder):
        os.makedirs(output class folder)
    data count = 0
    while data count < NUM SAMPLES:
        image path = random.choice(images)
        original image = tf.io.read file(image path)
        original image = tf.image.decode jpeg(original image, channels=3)
        data image path = os.path.join(output class folder, f'{data count}.jpg')
        tf.io.write file(data image path, tf.image.encode jpeg(original image))
        data count += 1
print("done")
CPU times: total: 0 ns
Wall time: 0 ns
done
In [53]:
%reset -f
In [56]:
%%time
```

```
train dataset = tf.keras.preprocessing.image dataset from directory(
   dataset path,
   validation split=0.2,
    subset="training",
    seed=123,
    image size=(256, 256),
   batch size=32)
validation dataset = tf.keras.preprocessing.image dataset from directory(
    dataset path,
   validation split=0.2,
    subset="validation",
    seed=123,
    image size=(256, 256),
    batch size=32)
# Configure the dataset for performance
AUTOTUNE = tf.data.AUTOTUNE
train dataset = train dataset.cache().shuffle(1000).prefetch(buffer size=AUTOTUNE)
validation dataset = validation dataset.cache().prefetch(buffer size=AUTOTUNE)
Found 2880 files belonging to 6 classes.
Using 2304 files for training.
Found 2880 files belonging to 6 classes.
Using 576 files for validation.
CPU times: total: 2.3 s
Wall time: 999 ms
In [57]:
import tensorflow as tf
from tensorflow.keras.regularizers import 12
model = tf.keras.models.Sequential([
   tf.keras.layers.Rescaling(1./255),
    tf.keras.layers.Conv2D(32, 3, activation='relu'),
   tf.keras.layers.MaxPooling2D(),
   tf.keras.layers.Conv2D(64, 3, activation='relu'),
   tf.keras.layers.MaxPooling2D(),
   tf.keras.layers.Dropout(0.15),
   tf.keras.layers.Conv2D(128, 3, activation='relu', kernel regularizer=12(0.25)),
   tf.keras.layers.MaxPooling2D(),
   tf.keras.layers.Flatten(),
    tf.keras.layers.Dense(128, activation='relu'),
   tf.keras.layers.Dropout(0.15),
   tf.keras.layers.Dense(6)
1)
model.compile(optimizer='adam',
              loss=tf.keras.losses.SparseCategoricalCrossentropy(from logits=True),
              metrics=['accuracy'])
early stopping callback = tf.keras.callbacks.EarlyStopping(
   monitor='val loss',
    patience=3,
```

In [58]:

)

restore best weights=True

```
import tensorflow as tf
from tensorflow.keras.regularizers import 12

model = tf.keras.models.Sequential([
    tf.keras.layers.Rescaling(1./255),
    tf.keras.layers.Conv2D(32, 3, activation='relu'),
    tf.keras.layers.MaxPooling2D(),
    tf.keras.layers.Conv2D(64, 3, activation='relu'),
    tf.keras.layers.MaxPooling2D(),
```

In [59]:

import numpy as np

import seaborn as sns

import matplotlib.pyplot as plt

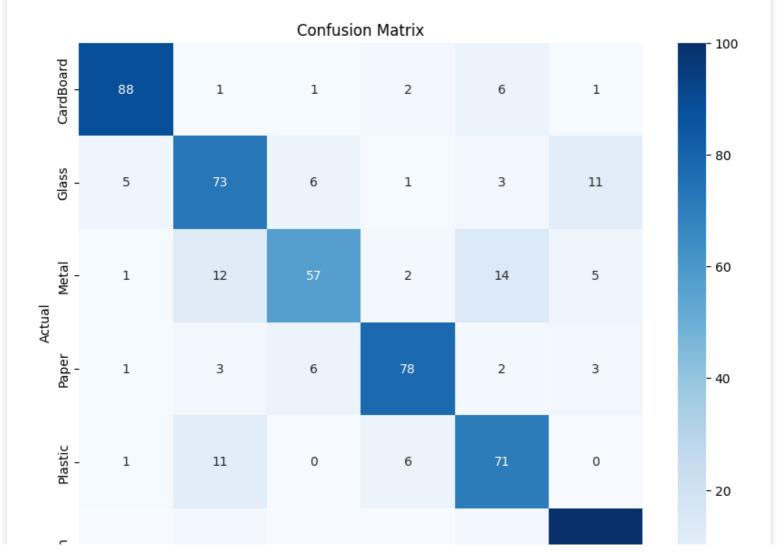
from sklearn.metrics import classification report, confusion matrix

class names = ["CardBoard", "Glass", "Metal", "Paper", "Plastic", "Trash"]

```
with tf.device('/GPU:0'):
   history = model.fit(
       train dataset,
       validation data=validation dataset,
       epochs=10
   )
Epoch 1/10
                        - 52s 648ms/step - accuracy: 0.2579 - loss: 14.1893 - val accura
72/72 -
cy: 0.3490 - val loss: 2.4995
Epoch 2/10
                        - 45s 627ms/step - accuracy: 0.4636 - loss: 1.9932 - val accurac
72/72
y: 0.5538 - val loss: 1.3716
Epoch 3/10
72/72
                        - 46s 637ms/step - accuracy: 0.5723 - loss: 1.2962 - val accurac
y: 0.6042 - val loss: 1.1917
Epoch 4/10
                        - 52s 719ms/step - accuracy: 0.6641 - loss: 1.0250 - val accurac
72/72 -
y: 0.6632 - val loss: 1.0068
Epoch 5/10
                         - 53s 734ms/step - accuracy: 0.6951 - loss: 0.8979 - val_accurac
72/72
y: 0.6910 - val loss: 0.9467
Epoch 6/10
                       — 47s 651ms/step - accuracy: 0.7520 - loss: 0.7507 - val accurac
72/72 -
y: 0.7188 - val loss: 0.9069
Epoch 7/10
72/72
                        - 51s 703ms/step - accuracy: 0.8004 - loss: 0.6449 - val accurac
y: 0.7951 - val loss: 0.7279
Epoch 8/10
                       — 48s 667ms/step - accuracy: 0.8551 - loss: 0.5046 - val accurac
72/72
y: 0.7934 - val loss: 0.7557
Epoch 9/10
                        - 48s 665ms/step - accuracy: 0.8629 - loss: 0.4717 - val accurac
72/72
y: 0.8038 - val_loss: 0.6854
Epoch 10/10
72/72 -
                      y: 0.8108 - val loss: 0.7047
CPU times: total: 1h 3min 7s
Wall time: 8min 8s
In [61]:
```

```
# Predicting on validation dataset
predictions = model.predict(validation dataset)
# Getting true labels
true labels = np.concatenate([y for x, y in validation dataset], axis=0)
# Converting predictions to class labels
predicted labels = np.argmax(predictions, axis=1)
# Printing classification report
print(classification report(true labels, predicted labels))
# Plotting confusion matrix
cm = confusion matrix(true labels, predicted labels)
plt.figure(figsize=(10, 8))
sns.heatmap(cm, annot=True, fmt="d", cmap="Blues", xticklabels=class names, yticklabels=
class names)
plt.xlabel('Predicted')
plt.ylabel('Actual')
plt.title('Confusion Matrix')
plt.show()
```

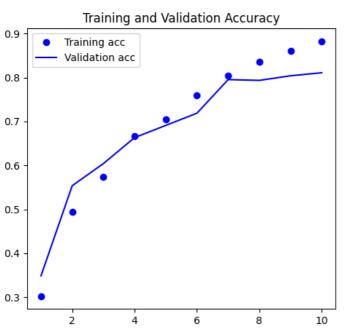
18/18 ———	2s 103ms/step			
	precision	recall	f1-score	support
0	0.92	0.89	0.90	99
1	0.72	0.74	0.73	99
2	0.81	0.63	0.71	91
3	0.88	0.84	0.86	93
4	0.72	0.80	0.76	89
5	0.83	0.95	0.89	105
accuracy			0.81	576
macro avg	0.81	0.81	0.81	576
weighted avg	0.81	0.81	0.81	576

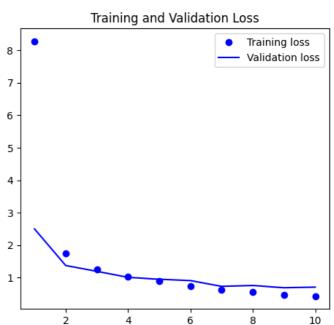




In [62]:

```
acc = history.history['accuracy']
val acc = history.history['val accuracy']
loss = history.history['loss']
val loss = history.history['val loss']
epochs = range(1, len(acc) + 1)
plt.figure(figsize=(12, 5))
plt.subplot(1, 2, 1)
plt.plot(epochs, acc, 'bo', label='Training acc')
plt.plot(epochs, val acc, 'b', label='Validation acc')
plt.title('Training and Validation Accuracy')
plt.legend()
plt.subplot(1, 2, 2)
plt.plot(epochs, loss, 'bo', label='Training loss')
plt.plot(epochs, val loss, 'b', label='Validation loss')
plt.title('Training and Validation Loss')
plt.legend()
plt.show()
```





Comparison and design flaws for experiment

The result of this where time spent was 7:30 and 8:08 for augmented and non-augmented respectively was that the non-augmented performed significantly better, notably in the trash data comparison where it was ~95% accurate which was when I realised the methodology for creating the data set can place the same data image in both test and train. I didn't think this was an issue when designing it, as I assumed that augmentations would be applied to mitigate this effect of damaging the test results. However, upon reviewing the Augmented confusion matrix, I found that the trash also had a high number of True positives, which leads me to believe that in the future, I would need to separate the datasets better to avoid the algorithm 'cheating'.

Bin data conversion

```
class_names = ["CardBoard", "Glass", "Metal", "Paper", "Plastic", "Trash"]
bin_names = ["Yellow Bin", "Red Bin"]
# Mapping class labels to bin labels
class to bin = {
   "CardBoard": "Yellow Bin",
   "Glass": "Yellow Bin",
    "Metal": "Yellow Bin",
    "Paper": "Yellow Bin",
    "Plastic": "Red Bin",
    "Trash": "Red Bin"
# Function to convert class labels to bin labels
def convert to bins(labels, class to bin, class names):
    bin_labels = [class_to_bin[class names[label]] for label in labels]
    return np.array([bin names.index(bin label) for bin label in bin labels])
# Predicting on validation dataset
predictions = model.predict(validation dataset)
# Getting true labels
true_labels = np.concatenate([y for x, y in validation dataset], axis=0)
# Converting predictions to class labels
predicted labels = np.argmax(predictions, axis=1)
# Converting true and predicted class labels to bin labels
true bin labels = convert to bins(true labels, class to bin, class names)
predicted bin labels = convert to bins(predicted labels, class to bin, class names)
# Printing classification report for bin labels
print("Classification Report for Bin Labels:")
print(classification report(true bin labels, predicted bin labels, target names=bin names
# Plotting confusion matrix for bin labels
cm bin = confusion matrix(true bin labels, predicted bin labels)
plt.figure(figsize=(8, 6))
sns.heatmap(cm bin, annot=True, fmt="d", cmap="Blues", xticklabels=bin names, yticklabel
s=bin names)
plt.xlabel('Predicted Bin')
plt.ylabel('Actual Bin')
plt.title('Confusion Matrix for Bins')
plt.show()
18/18 -
                         - 2s 114ms/step
Classification Report for Bin Labels:
             precision recall f1-score
                                              support
                   0.94
                            0.88
                                      0.91
 Yellow Bin
                                                   382
    Red Bin
                   0.79
                             0.90
                                       0.84
                                                   194
```

Confusion Matrix for Bins

0.89

0.89

accuracy

macro avq

weighted avg

0.87

0.89



0.89

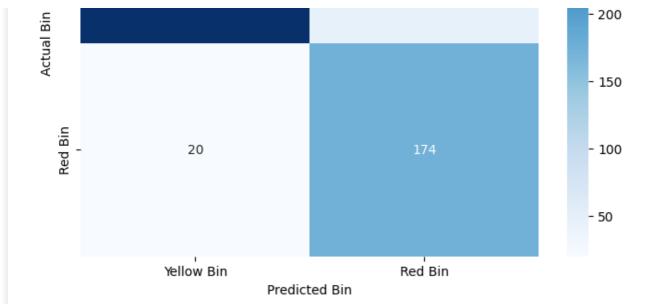
0.88

0.89

576

576

576



Once again the unaugmented data performs better due to poorly split dataset.

I did not attempt to identify what was in common for most incorrect guesses