Samuel's Imajinary Theorym

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Teknik Elektro

Prodi Teknik Robotika dan Kecerdasan buatan

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$$Omega = (\{6 \times (4 - \pi)\} - \pi)$$

$$Omega = \left(\left\{6 \times \left(\frac{(28 - 22)}{7}\right)\right\} - \pi\right)$$

$$Omega = \left(\left\{6 \times \left(\frac{6}{7}\right)\right\} - \pi\right)$$

$$Omega = (-2)$$

$$2 = (-Omega)$$

$$\sqrt{(-1)} = \left(\left\{-\left(\frac{2}{2}\right)\right\}^{\left(\frac{1}{2}\right)}\right)$$

$$\sqrt{(-1)} = \left(\left(\frac{Omega}{(-Omega)}\right)^{\left(\frac{1}{(-Omeg)}\right)}\right)$$

$$\sqrt{(-1)} = \left( \begin{matrix} (-1) \\ \square \end{matrix} \left( \frac{f(Omega)}{f(-Omega)} \right)^{(f(-Omega))} \right)$$

$$f(-Omega) = \left\{ \left( \left( (-Omega) \right) + \pi \right) - \pi \right\}$$

$$f(Omega) = \left\{ \left( \pi - \left( (-Omega) - \pi \right) \right) \right\}$$

$$\sqrt{(-1)} = e$$

$$e = \left( \begin{matrix} (-1) \\ \square \end{matrix} \left( \frac{f(Omega)}{f(-Omega)} \right)^{(f(-Om \quad ))} \right)$$

$$\sqrt{(-1)} = \left( \begin{matrix} (-1) \\ \square \end{matrix} \left( \frac{f(Omega)}{f(-Omega)} \right)^{(f(-Omega))} \right)$$

$$e = 0{,}34740416688982559338631922050232$$

Conclution :

“ Imaginary’s Variable values $0{,}34740416688982559338631922050232$ ”

~ Samuel Hasiholan Omega Purba, S. Tr. T. ~

Bachelor of Robotic’s Technology and Artificial’s Intelligent

[“ Politeknik Negeri Batam for International Future ”]