# Samuel Schmidgall

# Johns Hopkins University | NSF GRFP Fellow sschmi46@jhu.edu | Google Scholar (click me)

# Research Areas

Biological and artificial intelligence, Brain Organoids, Meta-learning, Online Learning, Neuromorphic Computing

# Education

Johns Hopkins University

Baltimore, MD

PhD in Electrical and Computer Engineering

beginning August 2023

George Mason University

Fairfax, VA

BS in Computer Science

August 2017 - May 2021

# Professional & Research Experience

## Johns Hopkins University

Baltimore, MD

Graduate Research Fellow

beginning August 2023

 Developing neuroscience-inspired learning mechanisms toward applications in artificial intelligence & neuromorphic computing

# Space Robotics Department @ U.S. Naval Research Laboratory

Washington, D.C.

Computer Scientist

since May 2021 (2 years)

- Research toward developing robotic learning systems which can adapt to new challenges during their lifetime. Robotic learning via deep reinforcement learning for quadrupedal (locomotion) and manipulation (articulated) systems using neuromorphic hardware in order to dramatically improve power-efficiency (low SWaP) for space applications. Deployment of trained models on physical robotic hardware (sim2real).

Undergraduate Research Intern

May 2019 - April 2021 (2 years)

- Developed **online reinforcement learning** algorithms for **neuromorphic hardware** (Intel Loihi gen1) on robotic learning applications via meta-learning online fast- and slow-weight learning rules.

## Mason Experimental Geometry Laboratory

Fairfax, VA

Undergraduate Research Assistant

January 2020 – May 2020 (5 months)

- Research in wave propagation dynamics for locked fronts in a discrete time discrete space population model (Matthew Holzer).

Undergraduate Research Assistant

August 2018 - May 2019 (9 months)

- Research in robotic motion planning, finding optimal localized trajectories for the planning of multiple vehicles (Anton Lukyanenko & Damoon Soudbakhsh).

Gartner Arlington, VA

Data Science Intern

May 2018 - March 2019 (10 months)

- Extracting and predicting performance based on resume features & language modelling for chat-bot automation. **Asymmetriq** Marshall, VA

Software Engineering Intern

May 2017 – May 2018 (1 year 1 month)

- Using computer vision learning models (via deep learning) for improving online license plate character recognition (i.e. optical character recognition).



# Publications

## **Under Review/In-Preparation**

- Schmidgall, S., (2023). Backpropagation in networks of biophysical neuron models *In-Preparation*.
- Schmidgall, S., Eshraghian, J., (2023). Surrogate gradient optimization with complex integrate-and-fire neuron models *In-Preparation*.
- Schmidgall, S., Jascha, A., Louis, K., Hajiseyedrazi, P., Lindsey, J., Miconi, T., Andreas, A., (2023). Braininspired learning in artificial neural networks. Nature Machine Intelligence (Under Review).

#### Journal

- Schmidgall, S., Hays, J. (2023). Meta-SpikePropamine: Learning to Learn with Neuromodulated Synaptic Plasticity in Spiking Neural Networks. Frontiers in Neuroscience. (Accepted, in publication process)

- Holzer, M., Richey, Z., Rush, W., Schmidgall, S., (2022). Locked fronts in a discrete time discrete space population model. Journal of Mathematical Biology.
- Schmidgall, S., Ashkanazy, J., Lawson, W., Hays, J. (2021). SpikePropamine: Differentiable Plasticity in Spiking Neural Networks. Frontiers in Neurorobotics.

#### Conference

- Schmidgall, S., Hays, J., (2023). SMA: A three-factor learning rule for synaptic motor adaptation in spiking neural networks. International Conference on Neuromorphic Systems (ICONS).
- Schmidgall, S., Parsa, M., (2023). Biological connectomes as a representation for the architecture of artificial neural networks. Thirty-Seventh AAAI Conference on Artificial Intelligence (AAAI-23) "Systems Neuroscience Approach to General Intelligence" Workshop.
- Schmidgall, S., Hays, J., (2022). Stable Lifelong Learning: Spiking neurons as a solution to instability in plastic neural networks. Neuro-Inspired Computational Elements (NICE).
- Lukyanenko, A., Camphire, H., Austin, A., Schmidgall, S., Soudbakhsh, D., (2021). Optimal Localized Trajectory Planning of Multiple Non-holonomic Vehicles. 5th Conference on Control Technology and Applications (CCTA).
- Schmidgall, S. (2021). Self-constructing Neural Networks through Random Mutation. *International Conference* on Learning Representations (ICLR).
- Schmidgall, S., (2020). Adaptive Reinforcement Learning through Evolving Self-Modifying Neural Networks. The 2020 Genetic and Evolutionary Computation Conference (GECCO).



## Activities and Awards

#### **Awards**

- 2023 National Science Foundation Graduate Research Fellow (NSF GRFP), three year award of \$147,000 to study the application of neuroscience-inspired learning mechanisms in artificial intelligence for neuromorphic.
- 2022 Alan Berman Research Publication Award of \$4,000 for paper SpikePropamine: Differentiable Plasticity in Spiking Neural Networks.
- Best Poster Award MEGL Symposium Poster Presentation Spring 2020
- Outstanding Poster Award Joint Mathematics Meeting Conference Spring 2019

#### Activities

- Invited reviewer at the 2022 NSF "Brain-Inspired Dynamics for Engineering Energy-Efficient Circuits and Artificial Intelligence" Program.
- **Reviewer editor** for *Neural Networks* journal.
- DoD Security Clearance granted security clearance through my work at the US Naval Research Laboratory.

- Invited speaker at the 2023 Neuro-Inspired Computing Elements (NICE).
- Invited speaker at the Intel Labs INRC Spring 2022 Continual Learning Workshop [link].
- Invited speaker for ECE556 Neuromorphic Computing at George Mason University [link].
- Oral Presentation at the 2022 Neuro-Inspired Computational Elements Workshop (NICE) [link].
- Oral Presentation at the 2021 International Conference on Machine Learning "A Roadmap to Never-Ending Reinforcement Learning" (ICLR NERL) Workshop [link].
- **Oral Presentation** at the 2020 Genetic and Evolutionary Computation Conference (GECCO) [link].