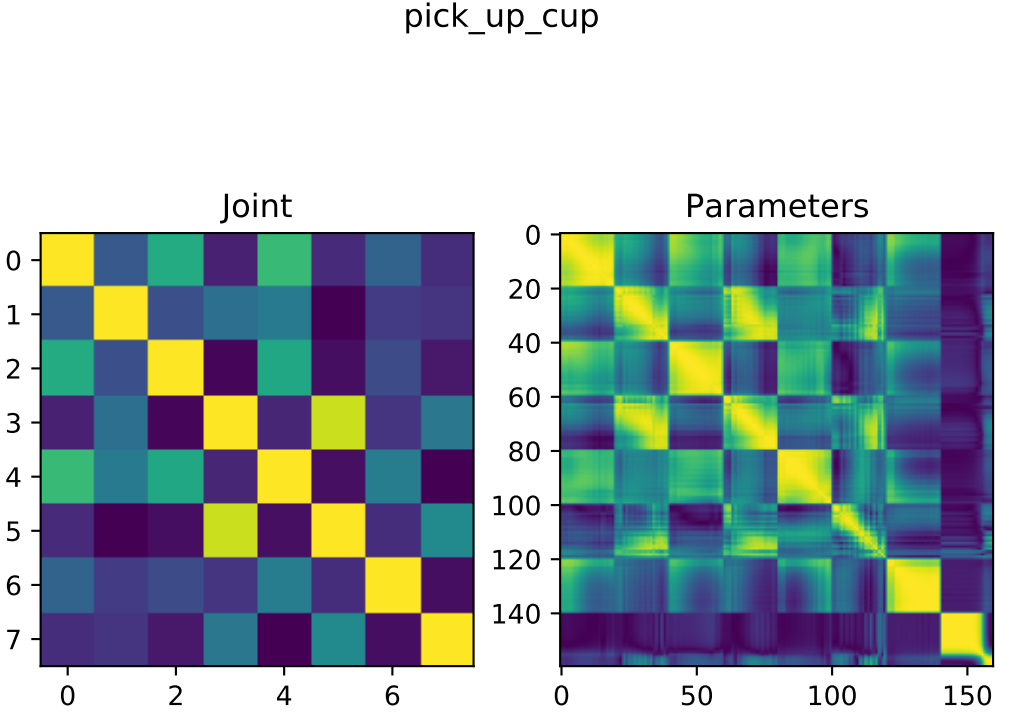
pick_up_cup
Joint
0
1
2
3
4
5
6
7
0
2
4
6
Parameters
0
20
40
60
80
100
120
140
0
50
100
150