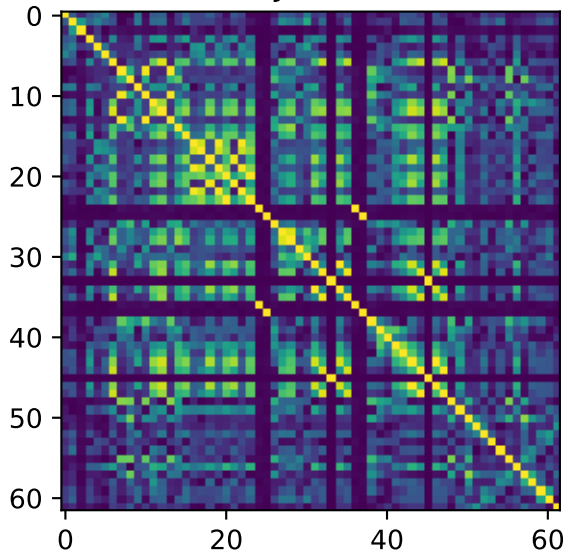


walk

Joint



Parameters

