



Deep Learning 1

2025-2026 – Pascal Mettes

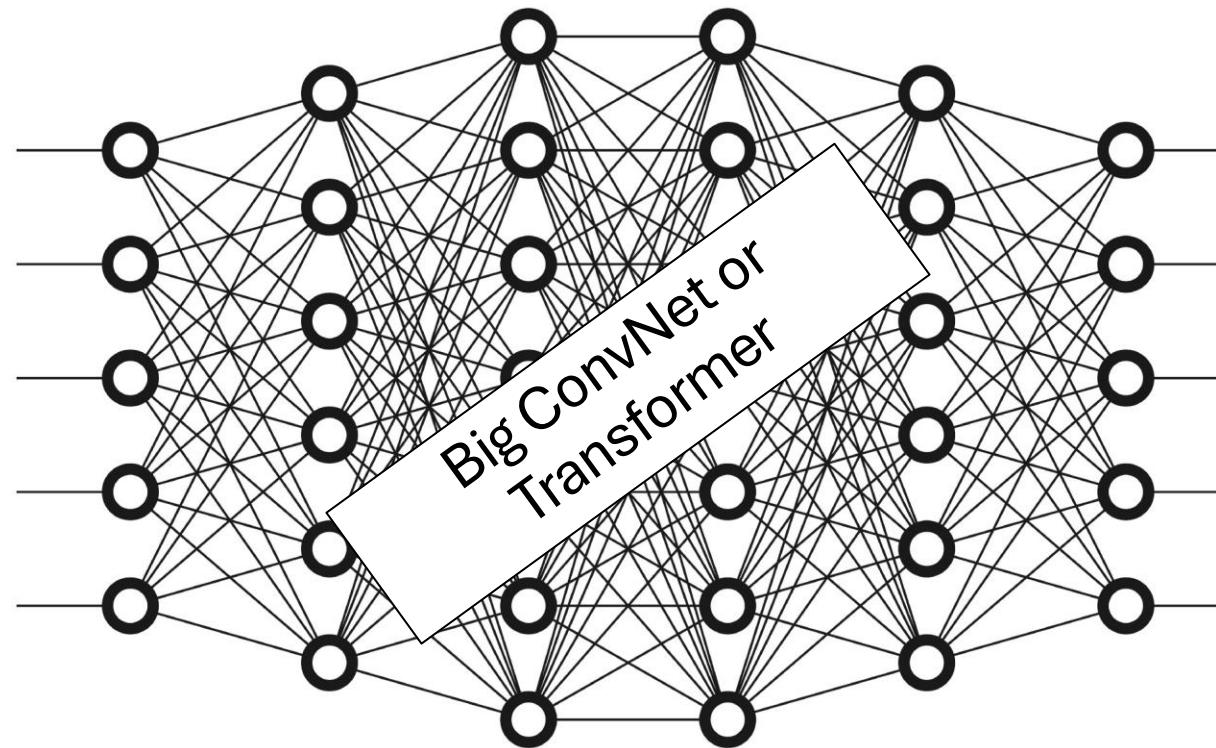
Lecture 12

Non-Euclidean deep learning

Previous lecture

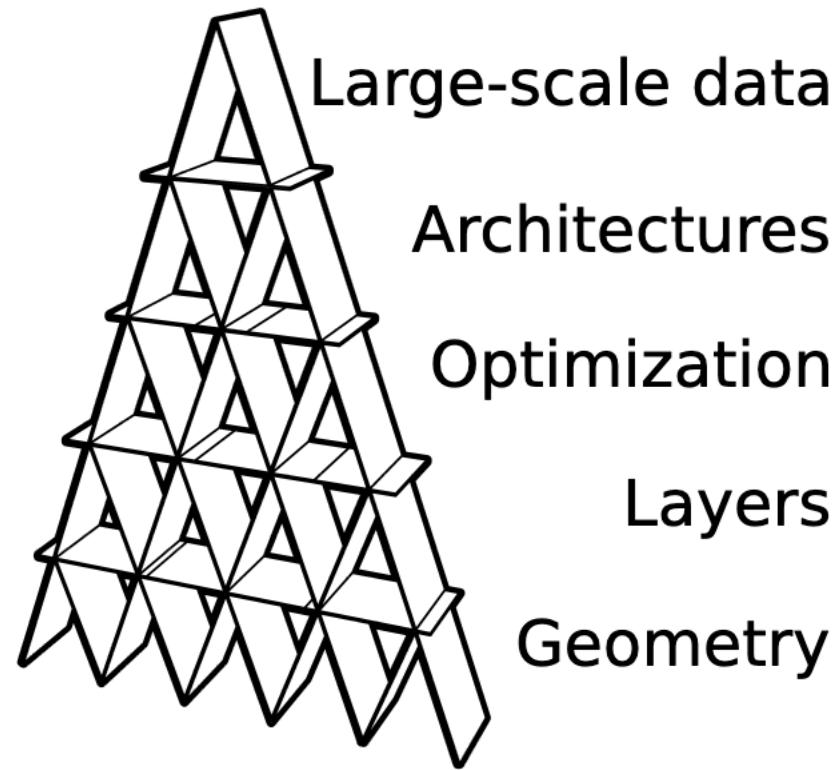
Lecture	Title	Lecture	Title
1	Intro and history of deep learning	2	AutoDiff
3	Deep learning optimization I	4	Deep learning optimization II
5	Convolutional deep learning	6	Attention-based deep learning
7	Graph deep learning	8	From supervised to unsupervised deep learning
9	Multi-modal deep learning	10	Generative deep learning
11	What doesn't work in deep learning	12	Non-Euclidean deep learning
13	Q&A	14	Deep learning for videos

Canonical deep learning



Person with dog

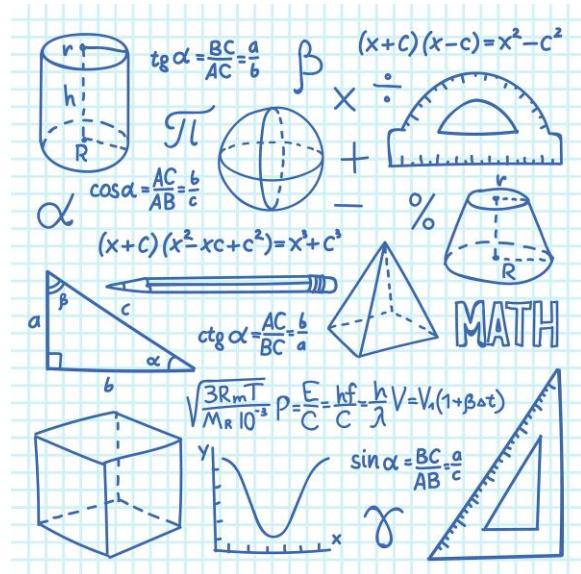
House of cards in deep learning



Our default choice of geometry in deep learning is Euclidean, but should it be?

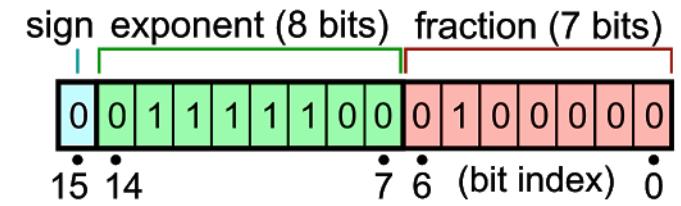
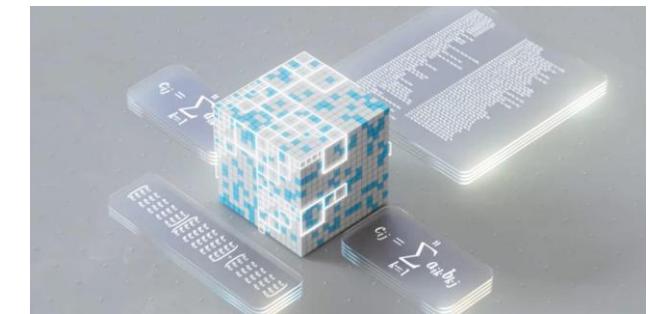
Non-Euclidean geometry

We have a Euclidean bias in deep learning



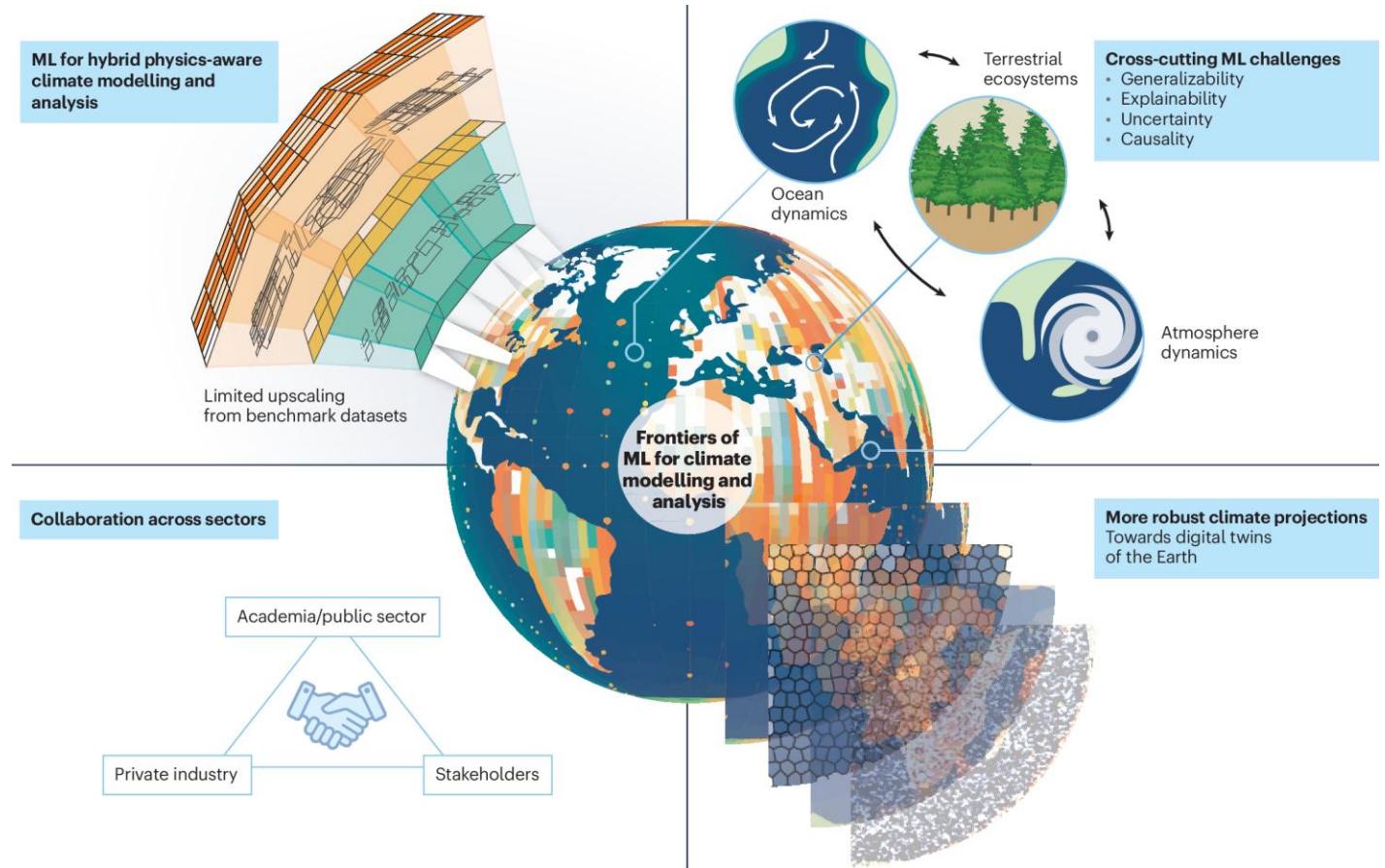
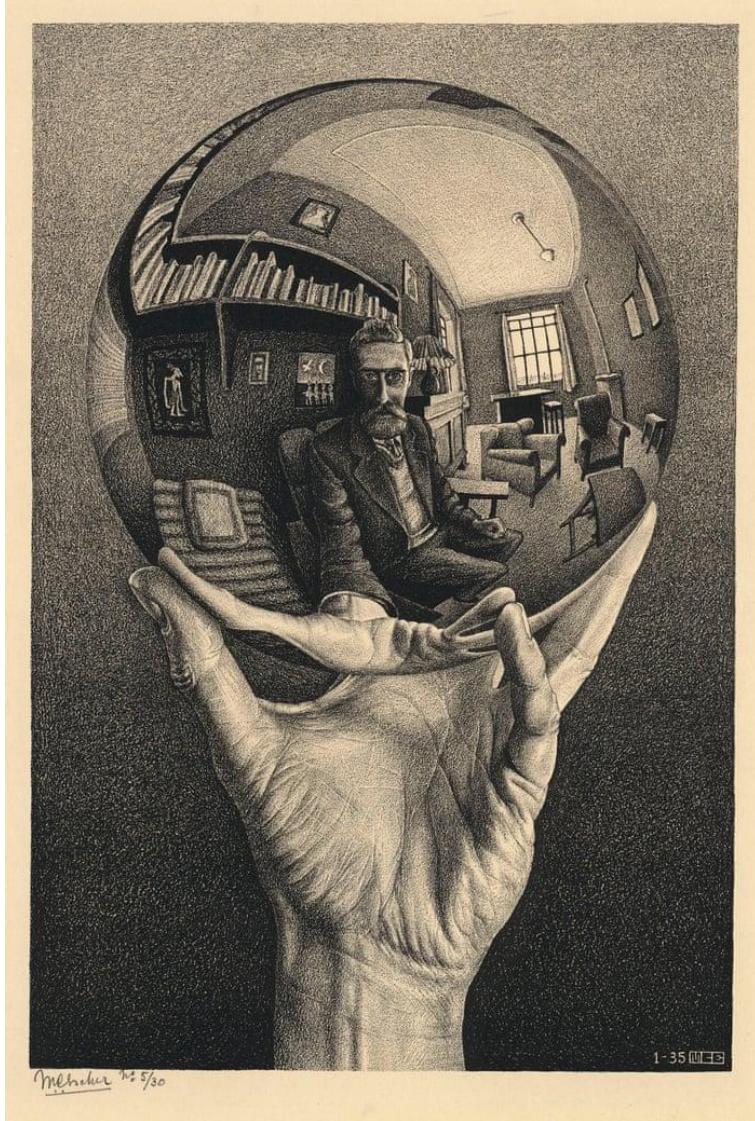
Our school curricula
are Euclidean

Our deep learning tools
are Euclidean

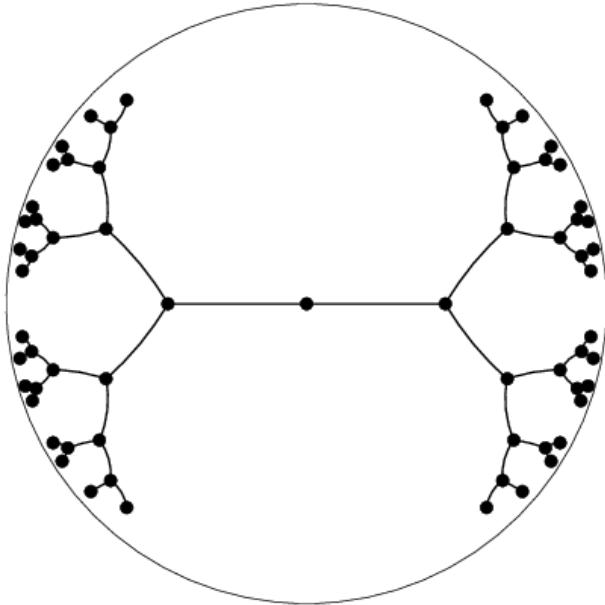


Our computers are built
for Euclidean space

But is Euclidean always the answer?



But is Euclidean always the answer?

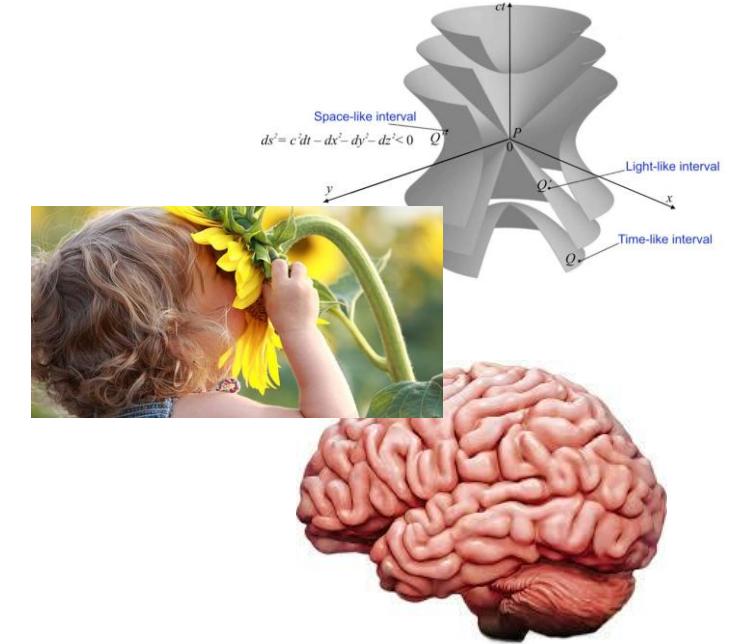


Euclidean is not hierarchical



Euclidean is not compact

usually a compact representation is better



The world is not always Euclidean

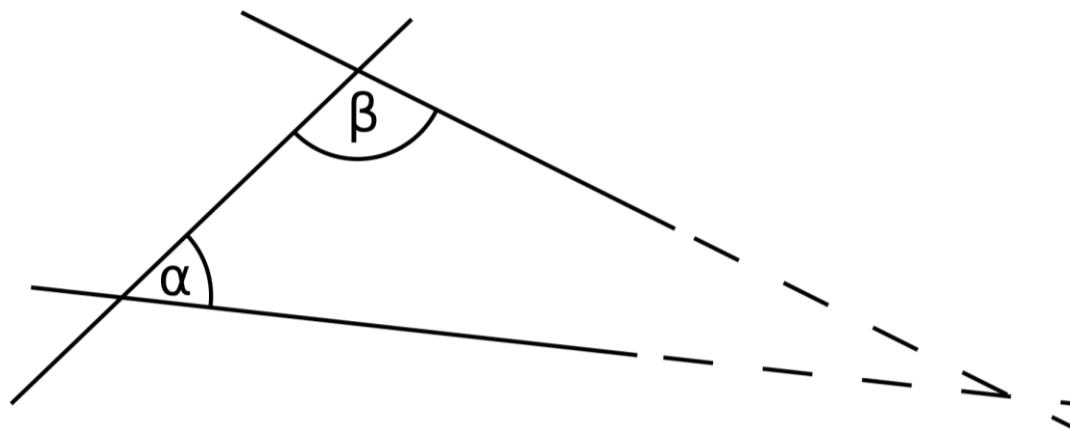
Origins of non-Euclidean geometry

Euclid's 5 postulates:

1. *A straight-line segment can be drawn joining any two points.*
2. *Any straight-line segment can be extended indefinitely in a straight line.*
3. *Given any straight lines segment, a circle can be drawn having the segment as radius and one endpoint as center.*
4. *All Right Angles are congruent.*
5. *If two lines are drawn which intersect a third in such a way that the sum of the inner angles on one side is less than two Right Angles, then the two lines inevitably must intersect each other on that side if extended far enough. This postulate is equivalent to what is known as the Parallel Postulate.*

Origins of non-Euclidean geometry

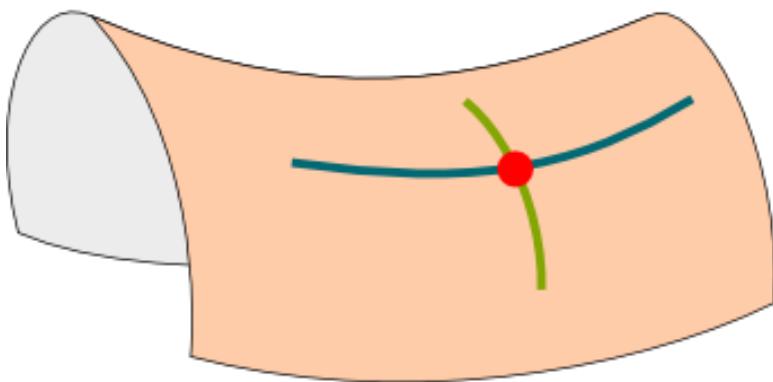
Euclid's 5th postulate:



Did Euclid make a mistake by making it a postulate? Shouldn't it be a theorem?

Curving space

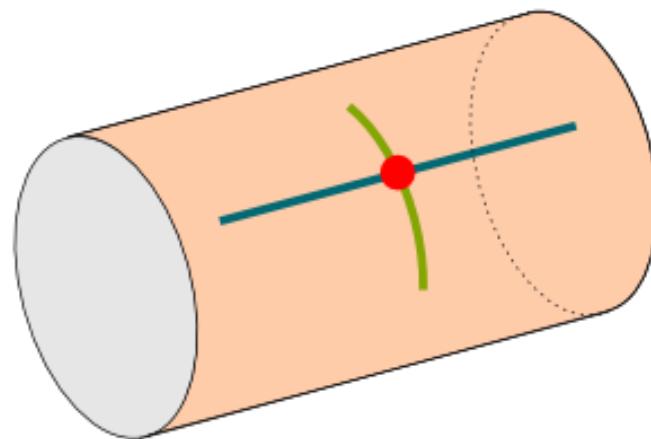
Extremal directions curve
in opposite directions



Negative Curvature

current research

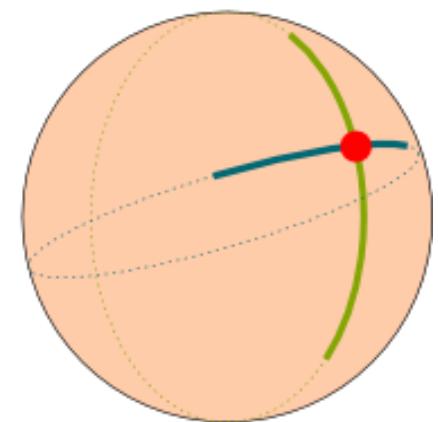
One extremal direction
has zero curvature



Zero Curvature

usually we are here

Extremal directions curve
in the same directions



Positive Curvature

this has been done in DL

Hyperspherical deep learning

About spherical deep learning

Many real-world problems have data that lie on a sphere.

climate/weather modelling, world-wide patterns, 360 degree cameras, ...

Even in standard neural networks, we often rely on spherical operations.

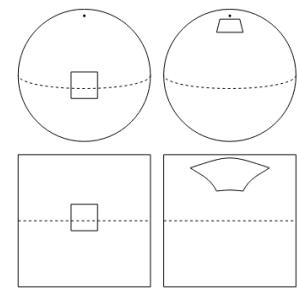
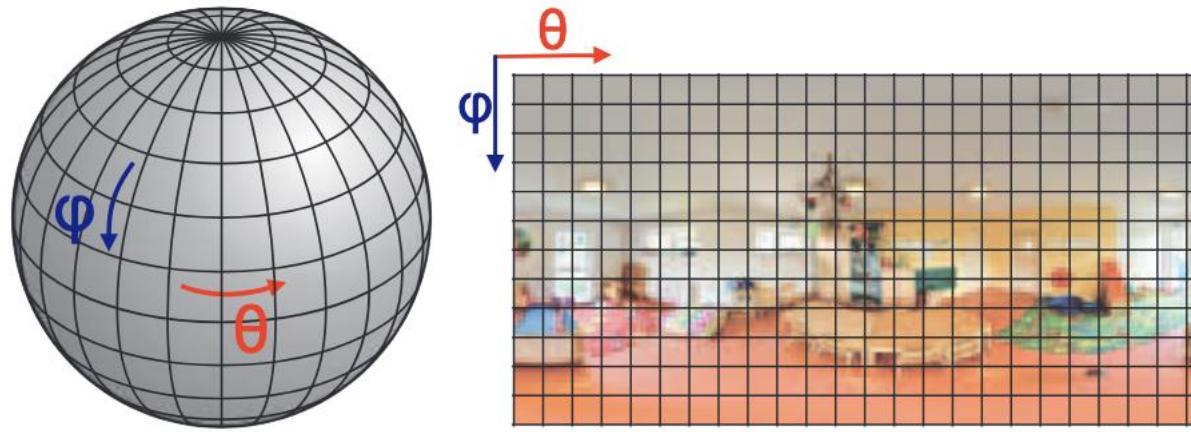
Cosine similarity!

L2 data normalization

Classifiers

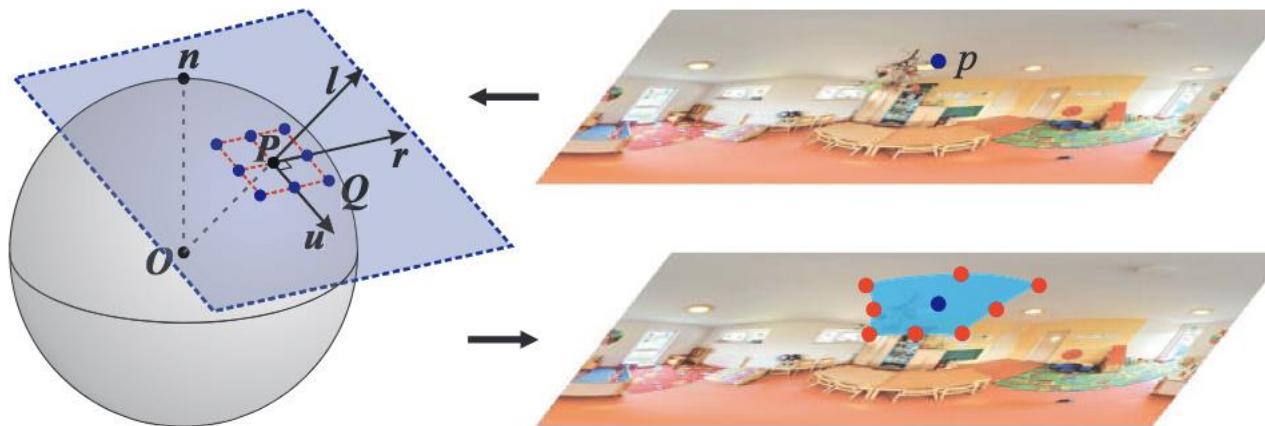
In standard networks, a spherical perspective can bring new insights.

Deep learning on spherical inputs



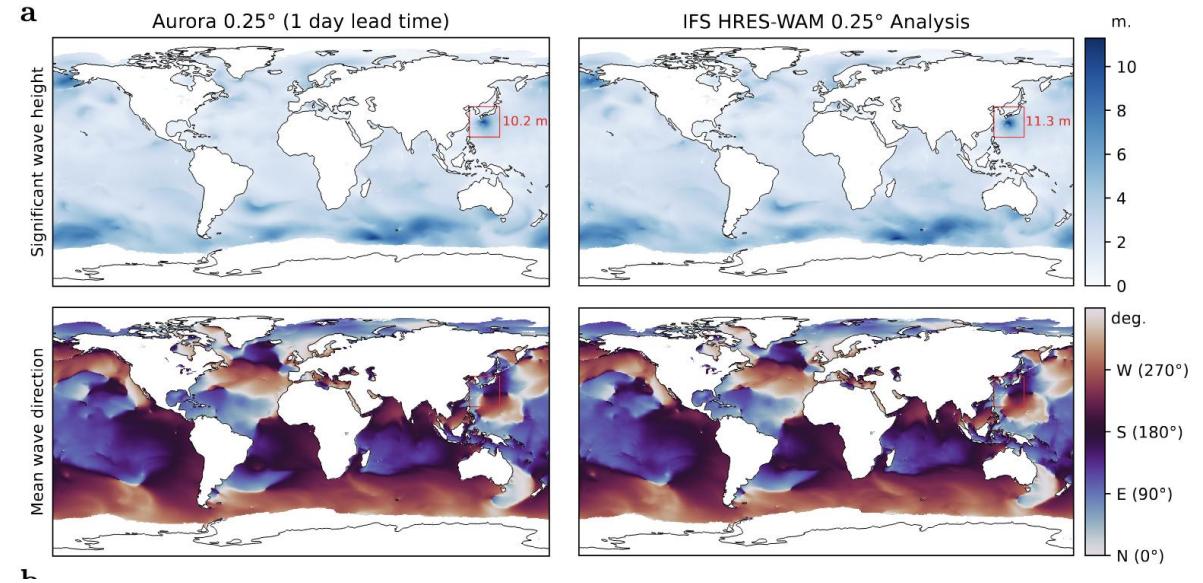
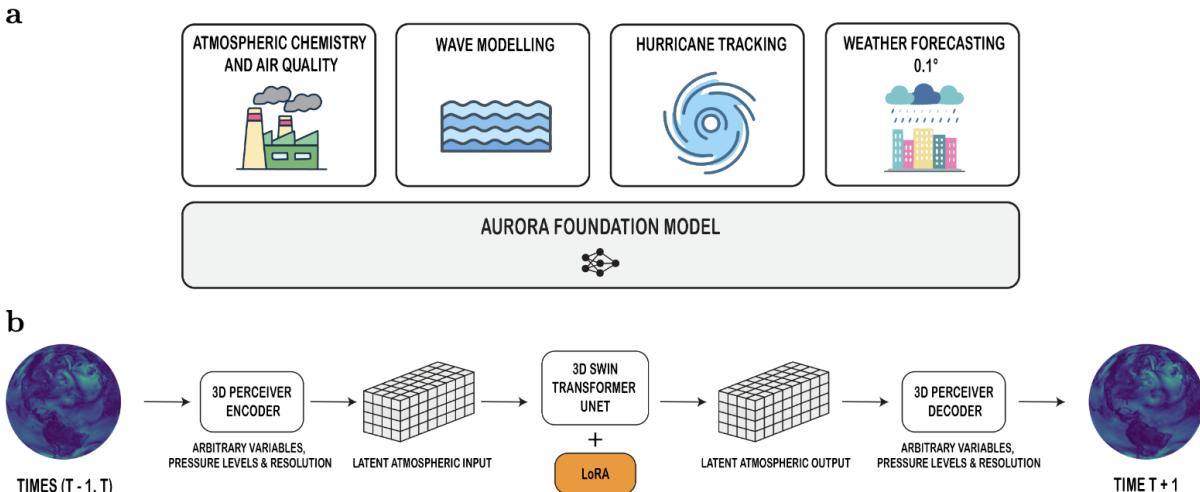
Cohen et al. (2018)

the baseline solution for spherical image is to transform them in a normal image.the amount of information in top left corner and another is not the same



Zhao et al. (2018)

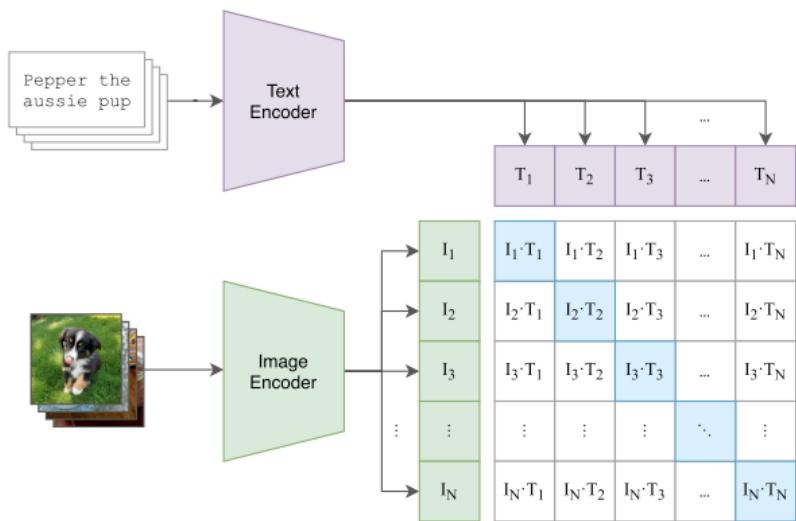
Yet spherical distortion can also be ignored



Spherical losses are everywhere in deep learning

“On the Surprising Behavior of Distance Metrics in High Dimensional Space” – Aggarwal et al. (2001)

“What is the nearest neighbor in high-dimensional spaces?” – Hinneburg et al. (2000)



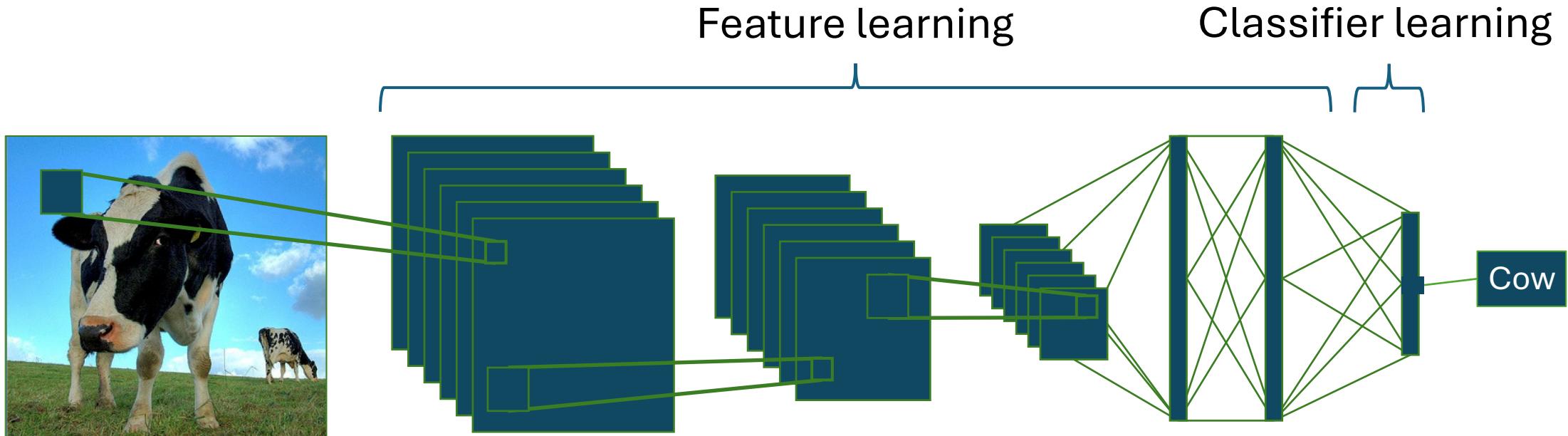
```
# extract feature representations of each modality
I_f = image_encoder(I) #[n, d_i]
T_f = text_encoder(T) #[n, d_t]

# joint multimodal embedding [n, d_e]
I_e = l2_normalize(np.dot(I_f, W_i), axis=1)
T_e = l2_normalize(np.dot(T_f, W_t), axis=1)

# scaled pairwise cosine similarities [n, n]
logits = np.dot(I_e, T_e.T) * np.exp(t)

# symmetric loss function
labels = np.arange(n)
loss_i = cross_entropy_loss(logits, labels, axis=0)
loss_t = cross_entropy_loss(logits, labels, axis=1)
loss = (loss_i + loss_t)/2
```

Classifiers in deep networks are spherical



Recall this decoupling from before.

If we think of classifiers as angularly separated, what makes an optimal classifier?

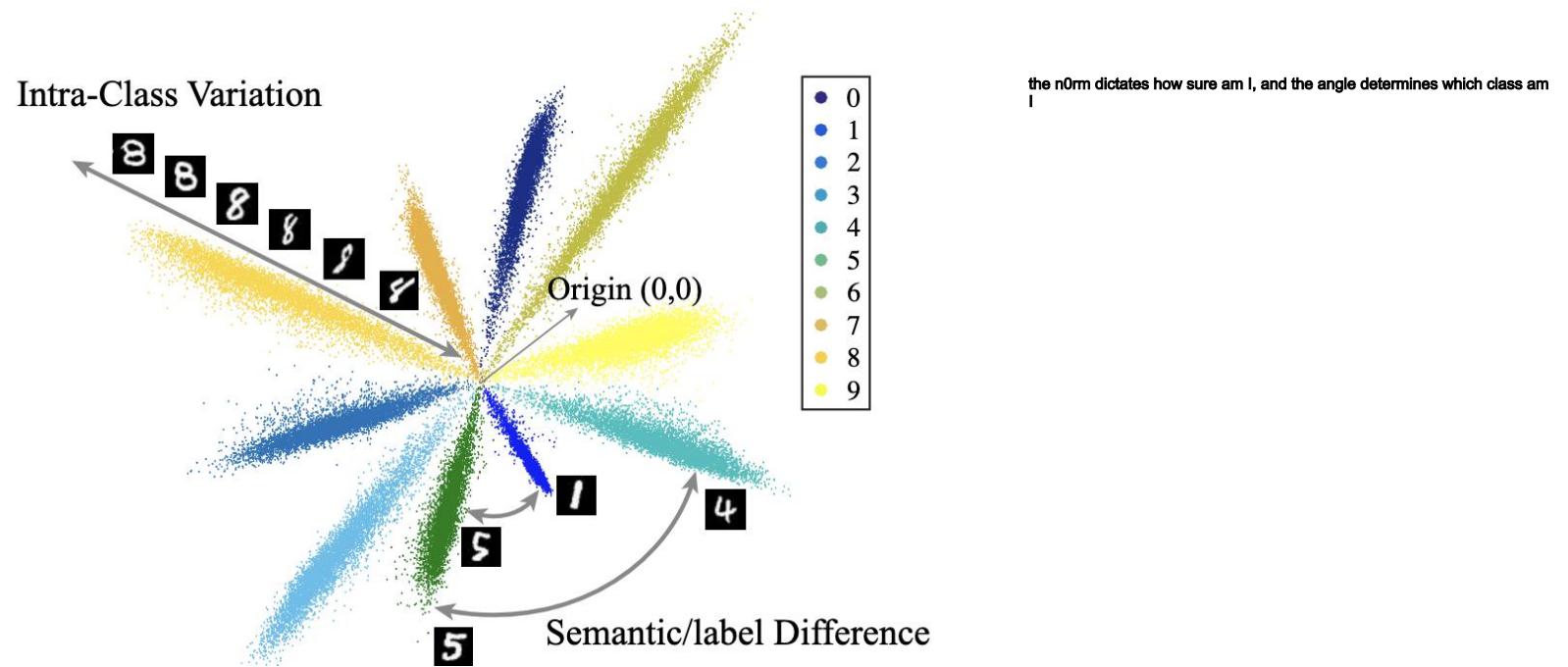
Decoupled Networks – Liu et al. (2018)

classification is decoupled

Each class-specific classifier is a vector in the last layer of the network.

Similarity to sample is given by the dot-product.

Hence: high similarity of classifier and sample point in the same direction!



Maximum Class Separation – Kasarla et al. (2022)

If classes are separated by angles, there is a theoretical optimal last layer.

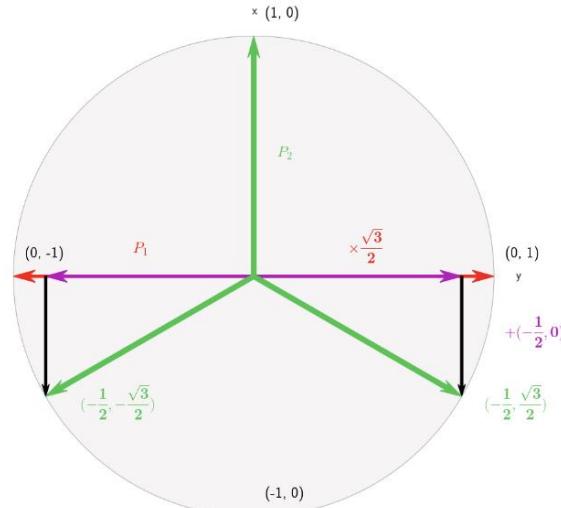
Separate all classes uniformly on the hypersphere.

General problem known as Tammes problem.

Specifically, for N classes in N-1 space, there is a solution:

$$P_1 = \begin{pmatrix} 1 & -1 \end{pmatrix} \in \mathbb{R}^{1 \times 2}$$

$$P_k = \left(\mathbf{0} \quad \sqrt{1 - \frac{1}{k^2}} \mathbf{1}^T \right) \in \mathbb{R}^{k \times (k+1)}$$

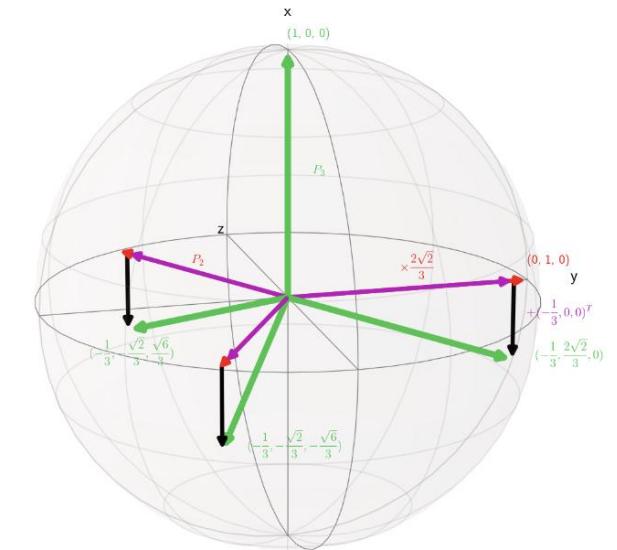


(a) Recursive update from 2 to 3 classes.

since deep learning is just representation learning + classification, if I find a way to determine exactly to maximize the distance between classes in the hypersphere, deep learning becomes only representation learning

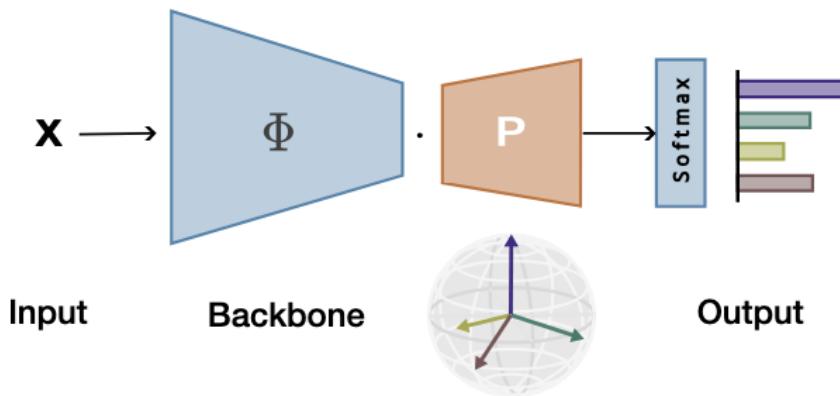
what is the downside?

This is good only if the classes have to be perfectly equalized, (so represent a perfect accuracy) but in the reality classes are non equal, and that has to be taken into account



(b) Recursive update from 3 to 4 classes.

Maximum Class Separation – Kasarla et al. (2022)



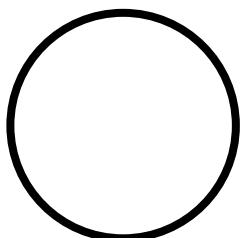
	Resnet-50				Resnet-152			
	top 1		top 5		top 1		top 5	
	Base	+ Ours	Base	+ Ours	Base	+ Ours	Base	+ Ours
Imagenet	73.2	74.8	92.4	94.9	77.9	78.5	94.3	95.1
Imagenet-LT	43.8	47.3	70.4	73.6	48.3	49.7	73.9	74.8

	Imbalance factor			Imbalance factor						
	0.1	0.02	0.01	0.1	0.02	0.01				
	LDAM-SGD	55.05	43.85	39.87	MiSLAS (stage 1)	58.36	44.69	40.29		
+ This paper	57.72	45.14	42.02	+2.67	+1.29	+2.20	+1.27	+0.96	+0.27	
LDAM-DRW	57.45	47.56	42.37	MiSLAS (stage 2)	61.93	52.53	48.00			
+ This paper	58.37	48.02	43.19	+ This paper	63.52	53.36	48.42	+1.59	+0.83	+0.42

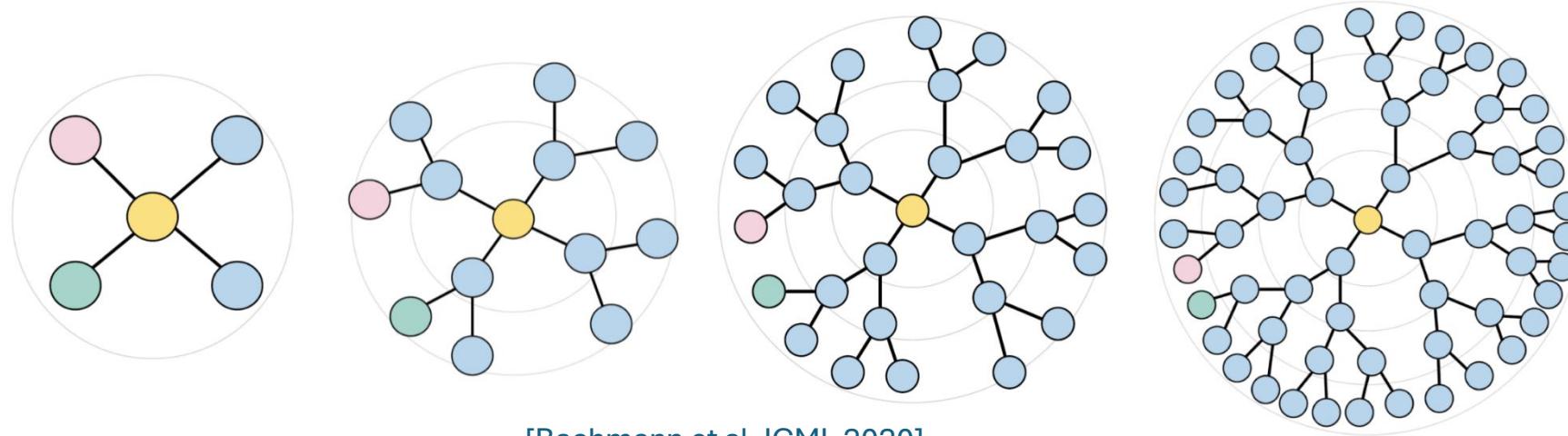
	CIFAR-100					CIFAR-10				
	-	0.2	0.1	0.02	0.01	-	0.2	0.1	0.02	0.01
ConvNet	56.70	45.97	40.34	27.35	16.59	86.68	79.47	73.90	51.40	43.67
+ This paper	57.05	46.59	40.44	28.27	18.40	86.76	79.63	75.88	55.25	48.05
	+0.35	+0.62	+0.10	+0.92	+1.81	+0.08	+0.16	+1.98	+3.85	+4.38
ResNet-32	75.77	65.74	58.98	42.71	35.02	94.63	88.17	83.10	68.64	56.98
+ This paper	76.54	66.01	60.54	45.12	38.85	95.09	91.42	88.16	77.02	69.70
	+0.77	+0.27	+1.56	+2.41	+3.83	+0.46	+3.25	+5.06	+8.38	+12.72

Hyperbolic deep learning

The geometry of hierarchies


$$v = \pi r^2$$

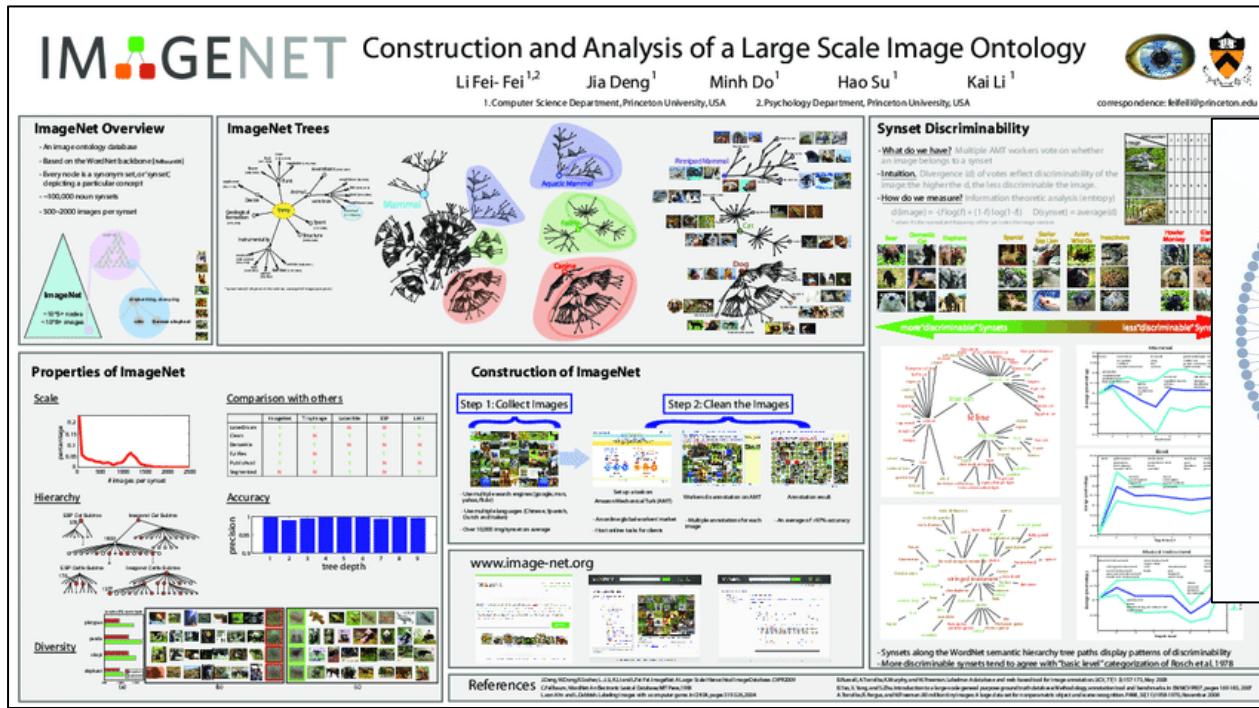
Euclidean space and hierarchies are a mismatch: linear vs. exponential growth.



What we need is a hierarchical geometry for representation learning!

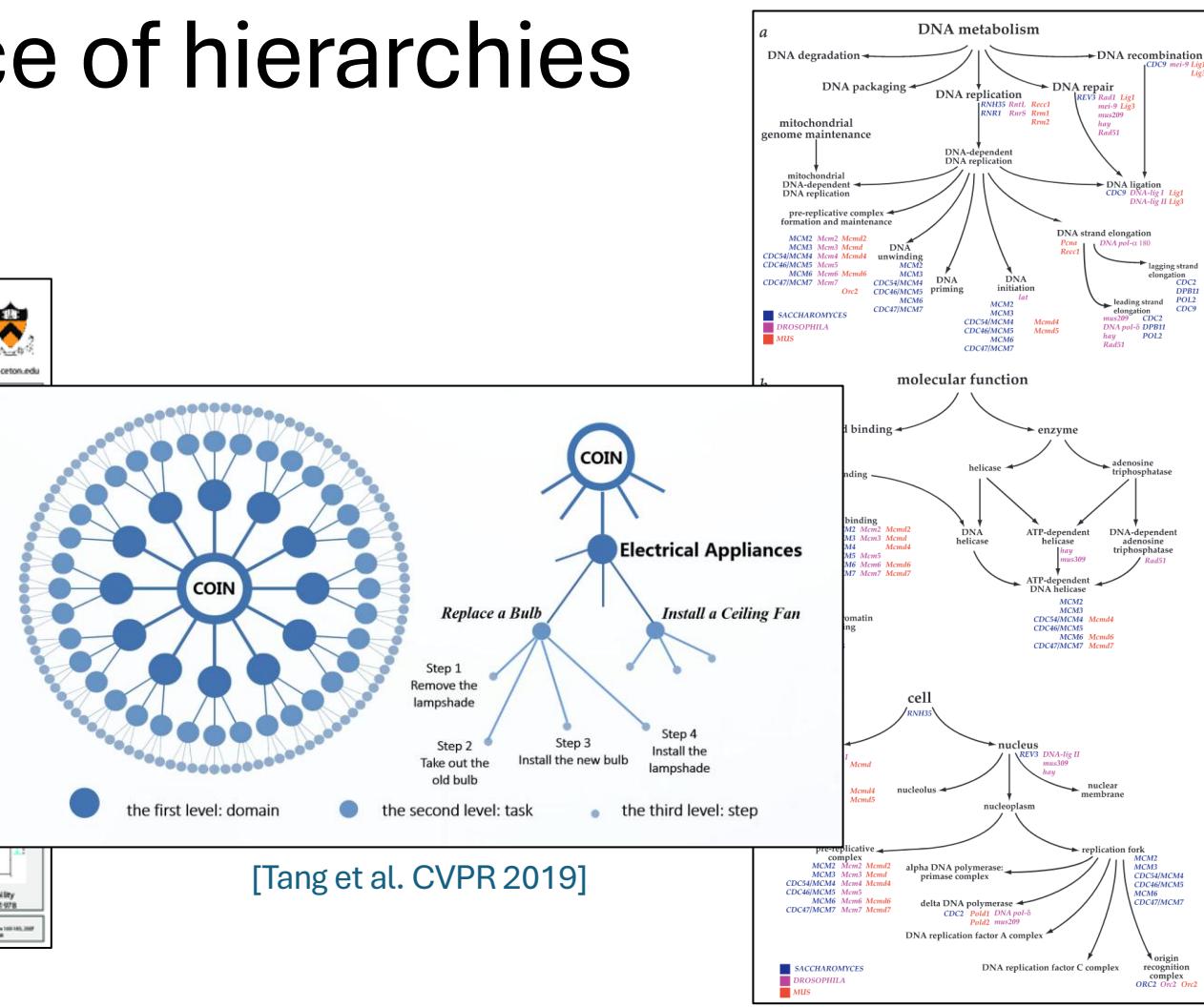
The importance of hierarchies

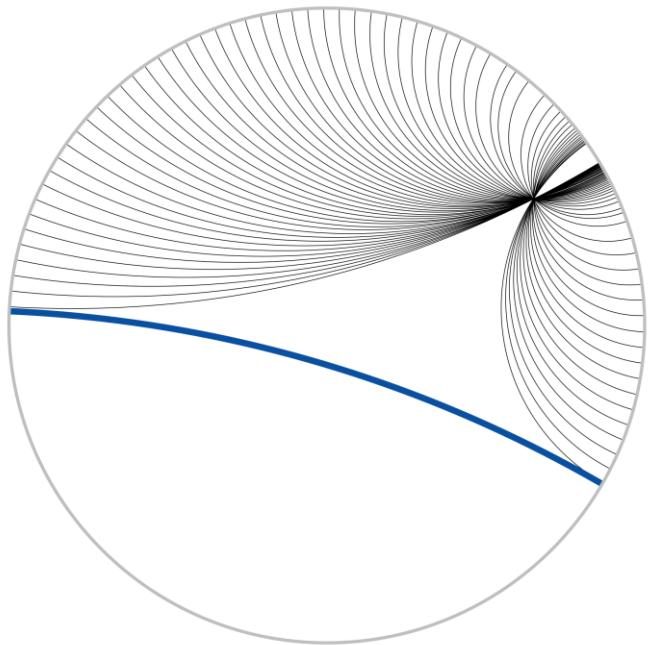
it is everything but independent, it is super organised into a hierarchy



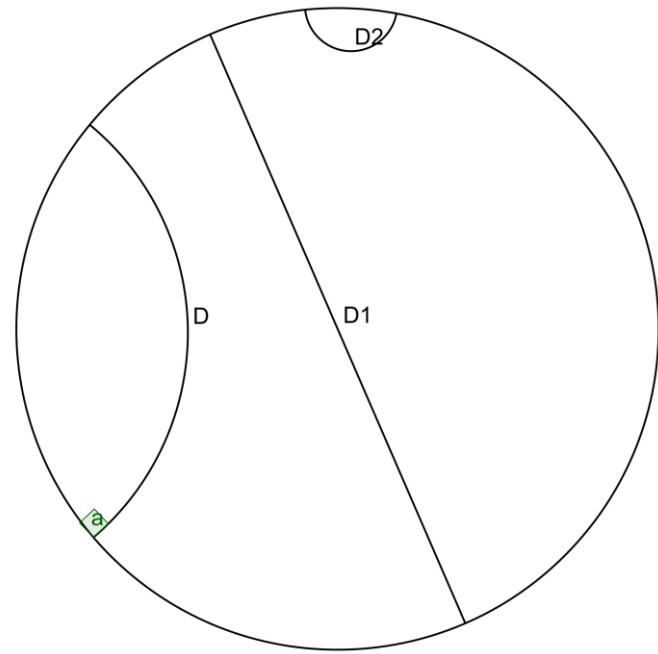
[Li et al. 2009]

Hierarchies allow us to look beyond samples and their individual labels.





Poincaré ball model

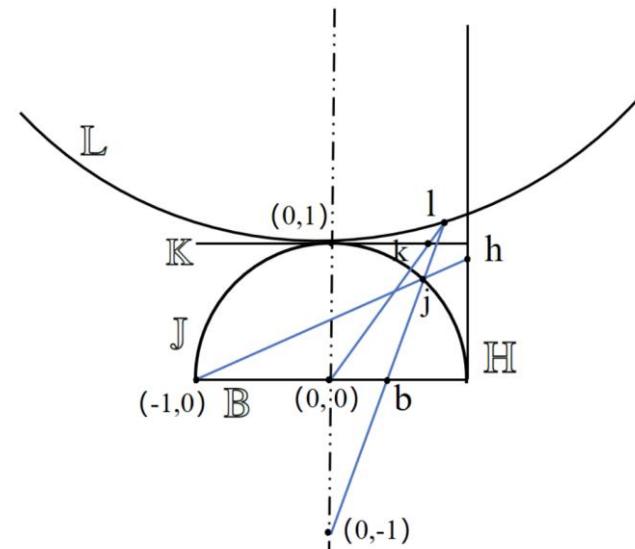
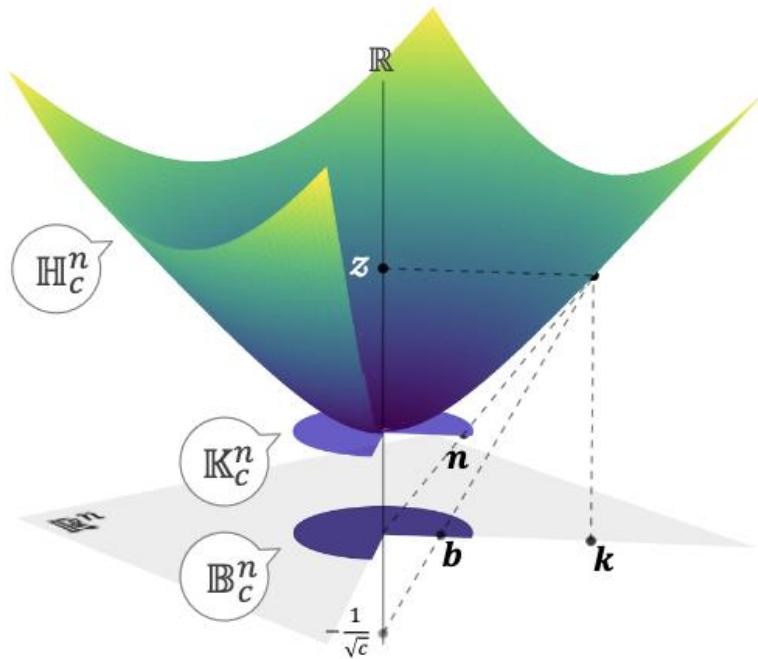


hyperbolic geometry is the natural geometry of hierarchies, I can embed a ?? in hyperbolic geometry so that the number of edges is exactly ?? (0)



Models of hyperbolic geometry

To perform numerical operations, we need to operate in a model of hyperbolic geometry.



Multiple isometric models exist, with different pros and cons for numerical complexity, stability, and visualization prowess.

Numerical operation in Poincaré model

things becomes difficult in low level representations

Points inside unit ball

$$\mathbb{D}^n = \{x \in \mathbb{R}^n : \|x\| < 1\} \quad g_x^{\mathbb{D}} = \lambda_x^2 g^E, \quad \text{where } \lambda_x := \frac{2}{1 - \|x\|^2}$$

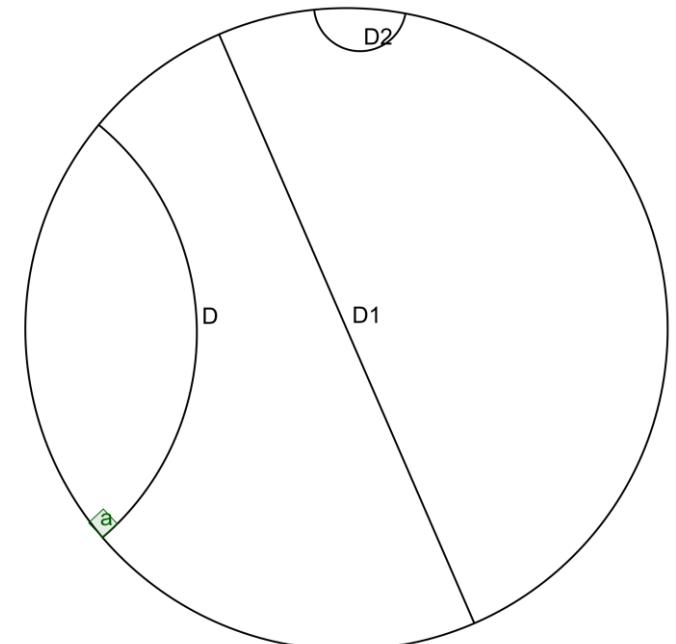
Tensor metric

Distance between two points:

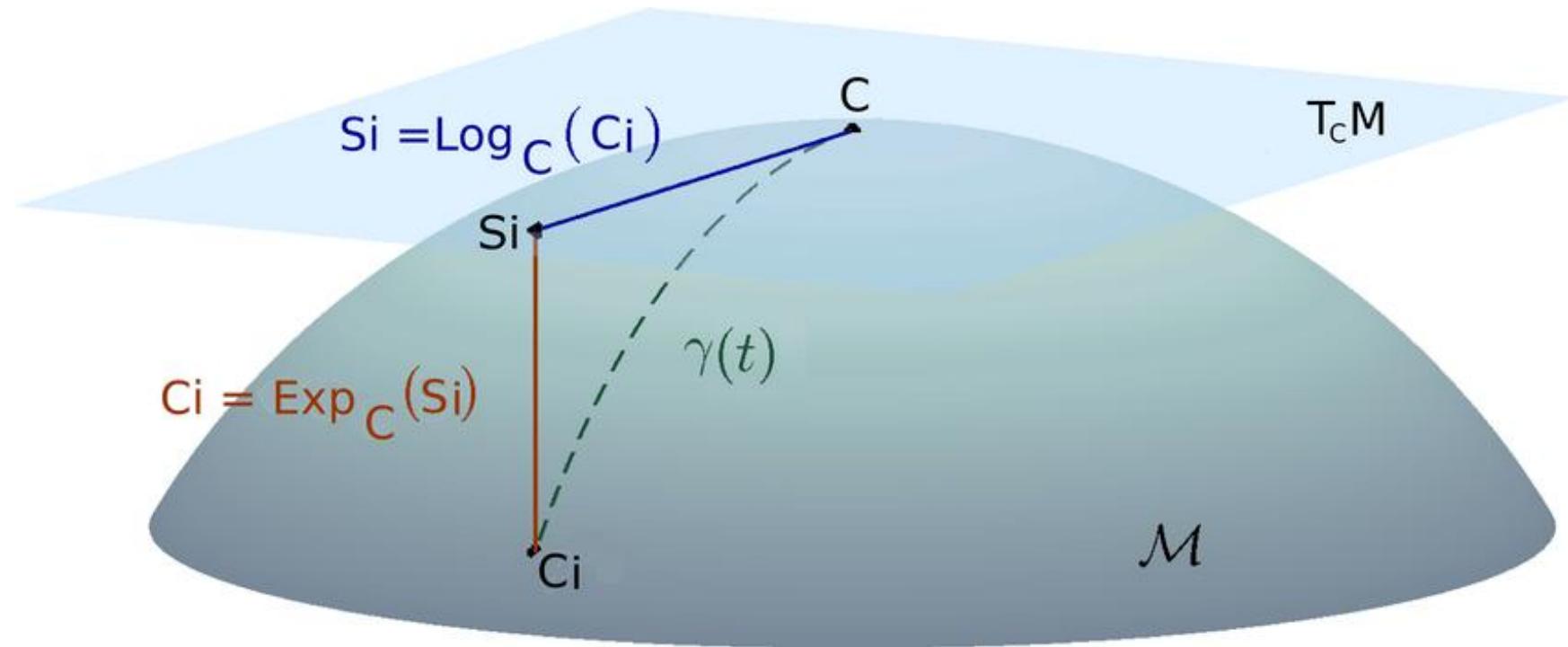
$$d_{\mathbb{D}}(x, y) = \cosh^{-1} \left(1 + 2 \frac{\|x - y\|^2}{(1 - \|x\|^2)(1 - \|y\|^2)} \right)$$

Möbius addition:

$$x \oplus_c y := \frac{(1 + 2c\langle x, y \rangle + c\|y\|^2)x + (1 - c\|x\|^2)y}{1 + 2c\langle x, y \rangle + c^2\|x\|^2\|y\|^2}.$$



From tangent space to Poincaré ball (and back)



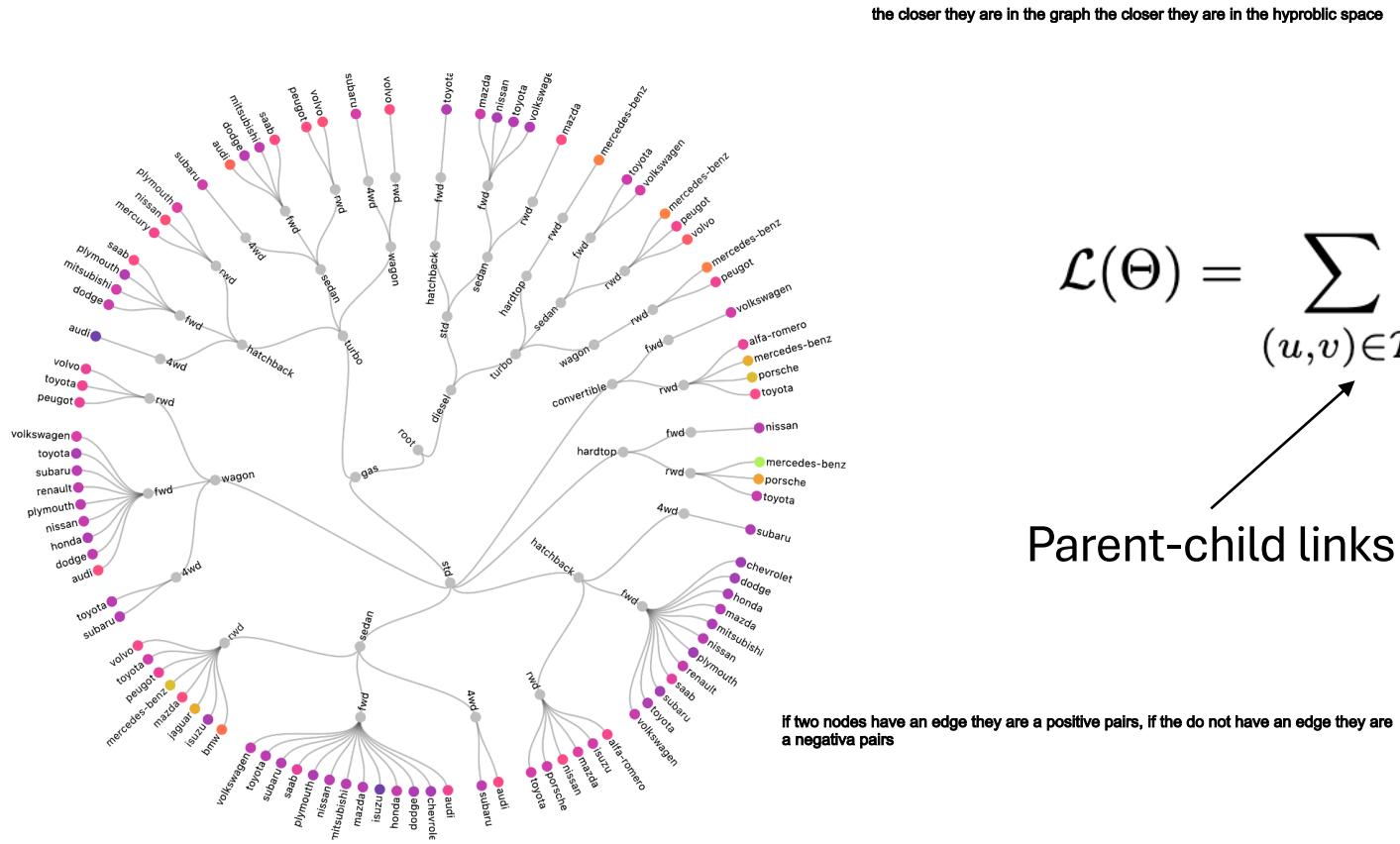
$$\exp_{\mathbf{0}}^c(v) = \tanh(\sqrt{c}\|v\|) \frac{v}{\sqrt{c}\|v\|}$$

$$\log_{\mathbf{0}}^c(y) = \tanh^{-1}(\sqrt{c}\|y\|) \frac{y}{\sqrt{c}\|y\|}$$

First hyperbolic success: Poincaré Embeddings

[Nickel and Kiela. NeurIPS 2017]

Embed nodes as hyperbolic points and optimize with contrastive learning.



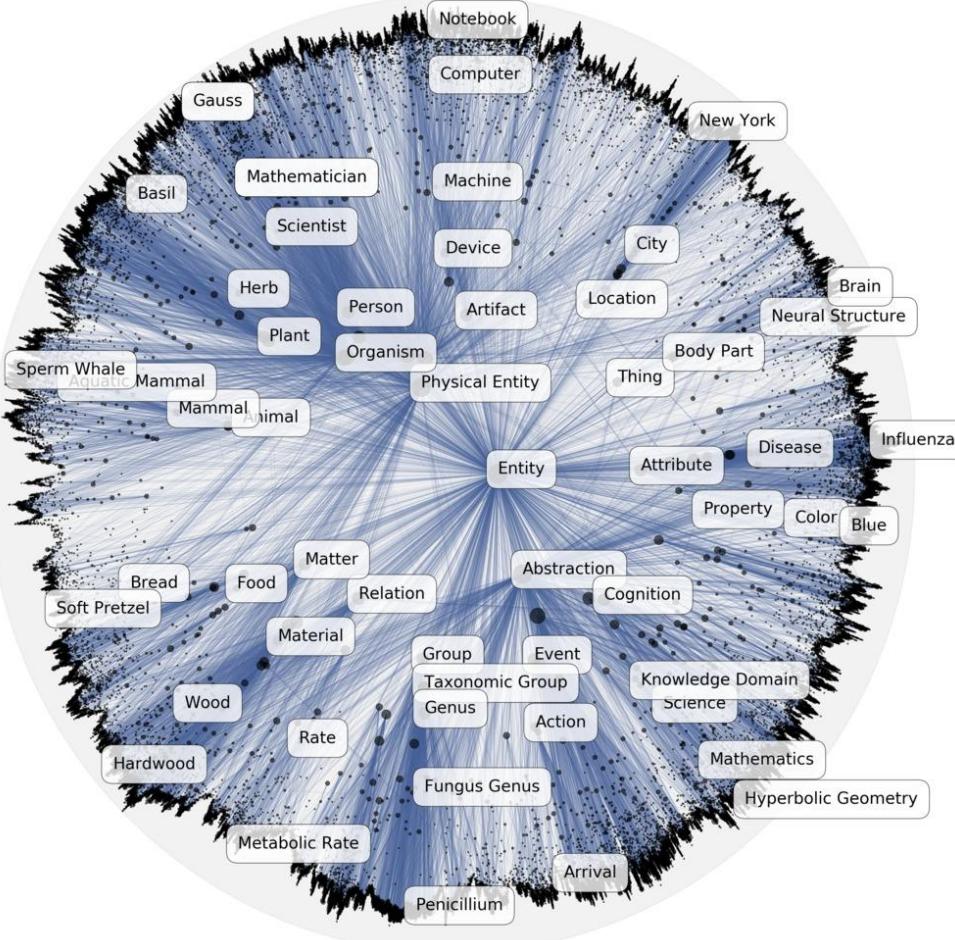
$$\mathcal{L}(\Theta) = \sum_{(u,v) \in \mathcal{D}} \log \frac{e^{-d(u,v)}}{\sum_{v' \in \mathcal{N}(u)} e^{-d(u,v')}},$$

Parent-child links

Hyperbolic distance

Non parent-child links

Poincaré Embeddings



		Dimensionality						
		5	10	20	50	100	200	
WORDNET Reconstruction	Euclidean	Rank	3542.3	2286.9	1685.9	1281.7	1187.3	1157.3
	Euclidean	MAP	0.024	0.059	0.087	0.140	0.162	0.168
WORDNET Link Pred.	Translational	Rank	205.9	179.4	95.3	92.8	92.7	91.0
	Translational	MAP	0.517	0.503	0.563	0.566	0.562	0.565
WORDNET Link Pred.	Poincaré	Rank	4.9	4.02	3.84	3.98	3.9	3.83
	Poincaré	MAP	0.823	0.851	0.855	0.86	0.857	0.87
WORDNET Link Pred.	Euclidean	Rank	3311.1	2199.5	952.3	351.4	190.7	81.5
	Euclidean	MAP	0.024	0.059	0.176	0.286	0.428	0.490
WORDNET Link Pred.	Translational	Rank	65.7	56.6	52.1	47.2	43.2	40.4
	Translational	MAP	0.545	0.554	0.554	0.56	0.562	0.559
WORDNET Link Pred.	Poincaré	Rank	5.7	4.3	4.9	4.6	4.6	4.6
	Poincaré	MAP	0.825	0.852	0.861	0.863	0.856	0.855

Hyperbolic Entailment Cones

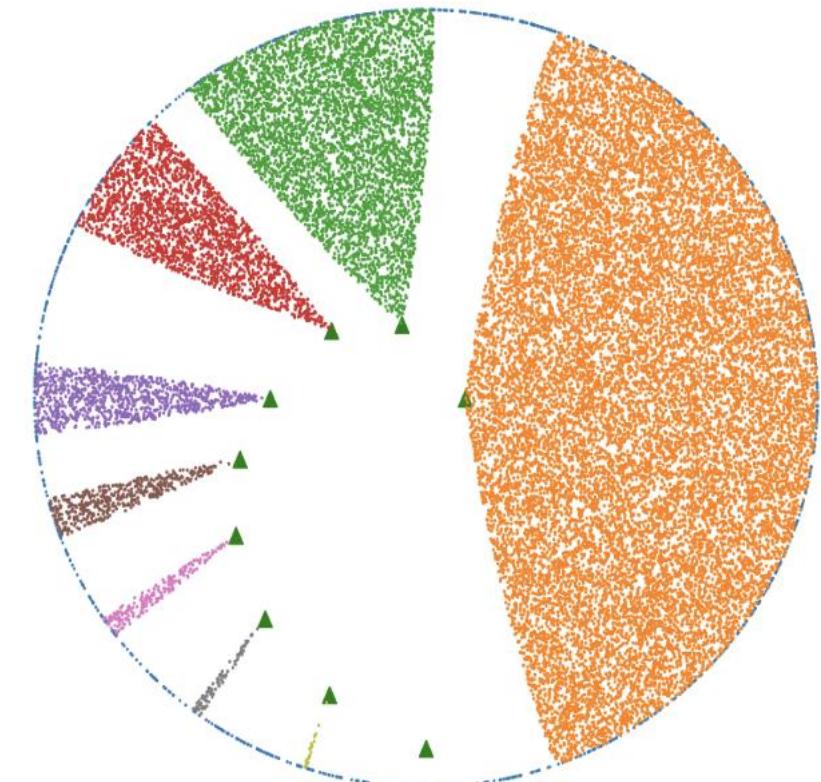
instead of collapse the point in a hyperbolic space we collapse them, for all the parent child relation I want the child to be in the cone of the parent

[Ganea et al. ICML 2018]

Pairwise contrastive learning has trouble enforcing hierarchical depth.
They propose to view points as cones of entailment.

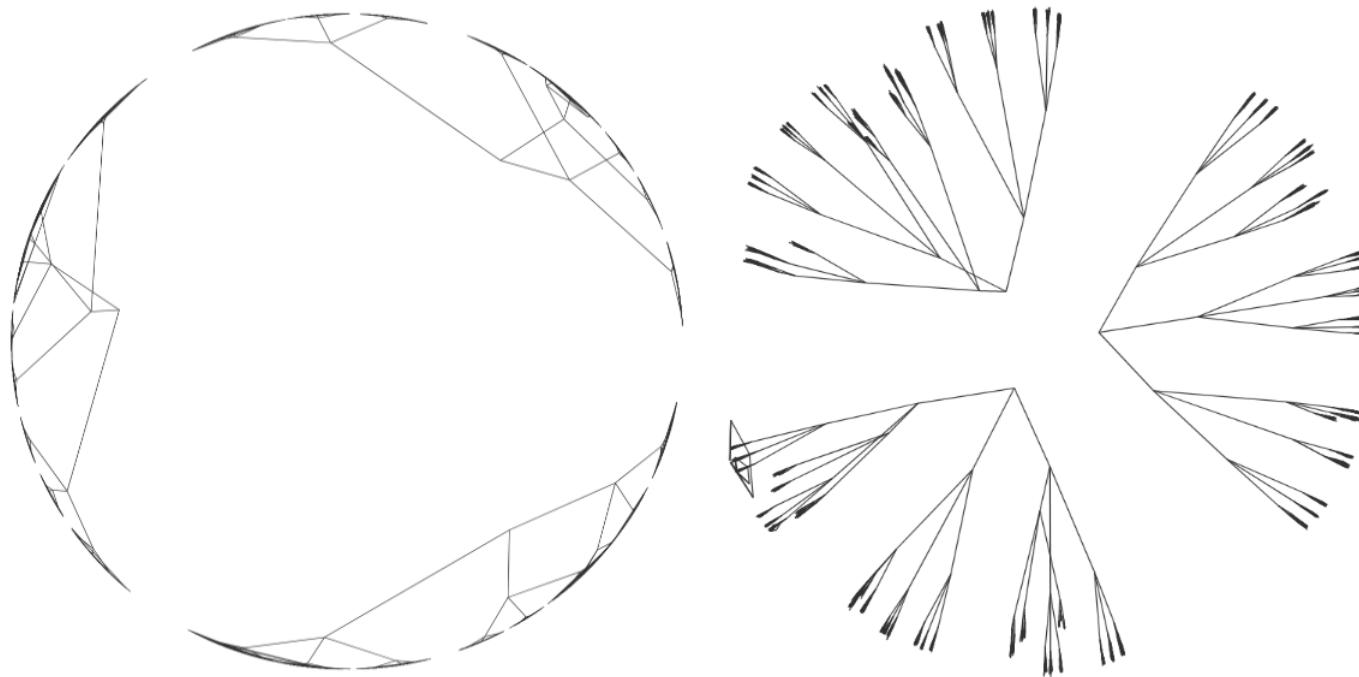
Required properties:

1. Axial symmetry
2. Rotation invariance
3. Aperture of cone is continuous function
4. Nested angular cones preserve partial order



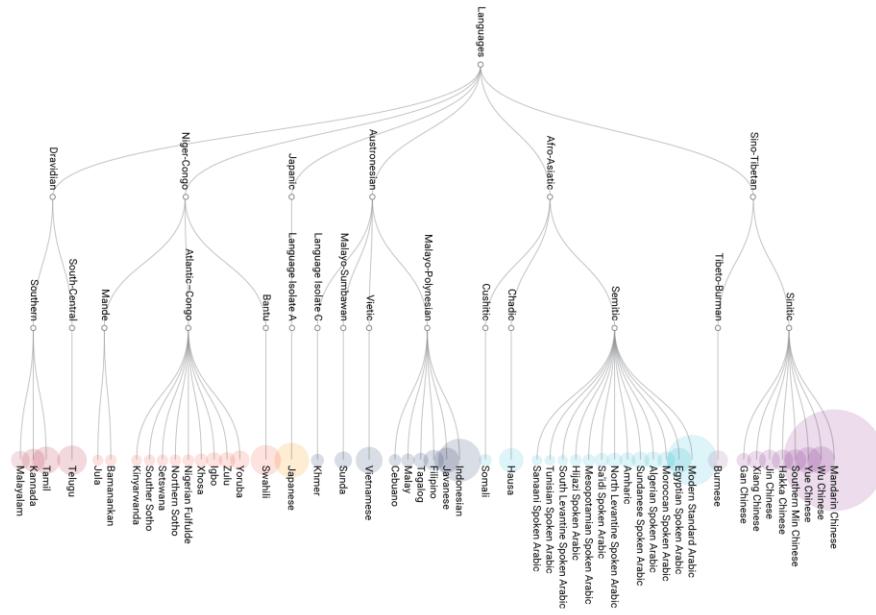
Hyperbolic Entailment Cones

[Ganea et al. ICML 2018]



Poincaré Embeddings (left) vs Hyperbolic Entailment Cones (right)

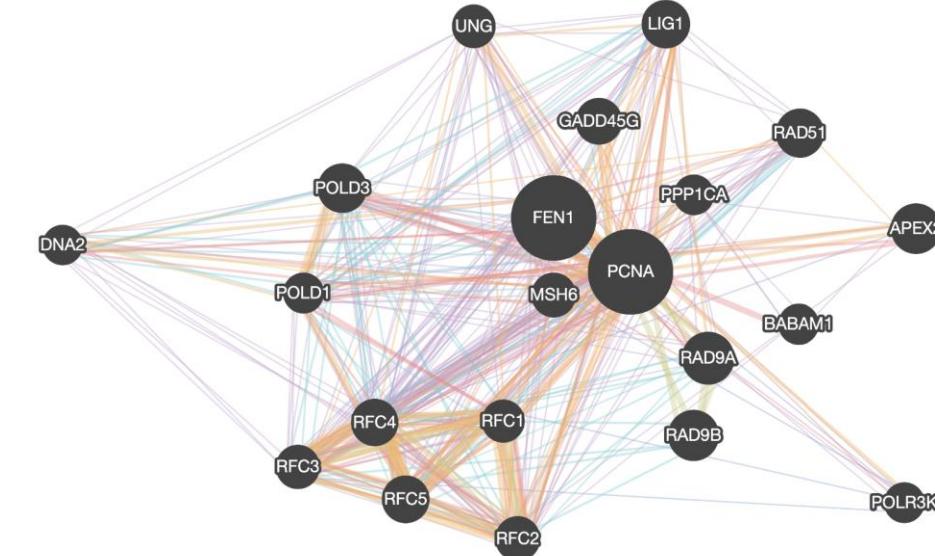
From hierarchies to graphs



Nodes and edges

Embed to preserve edge distances

One layer

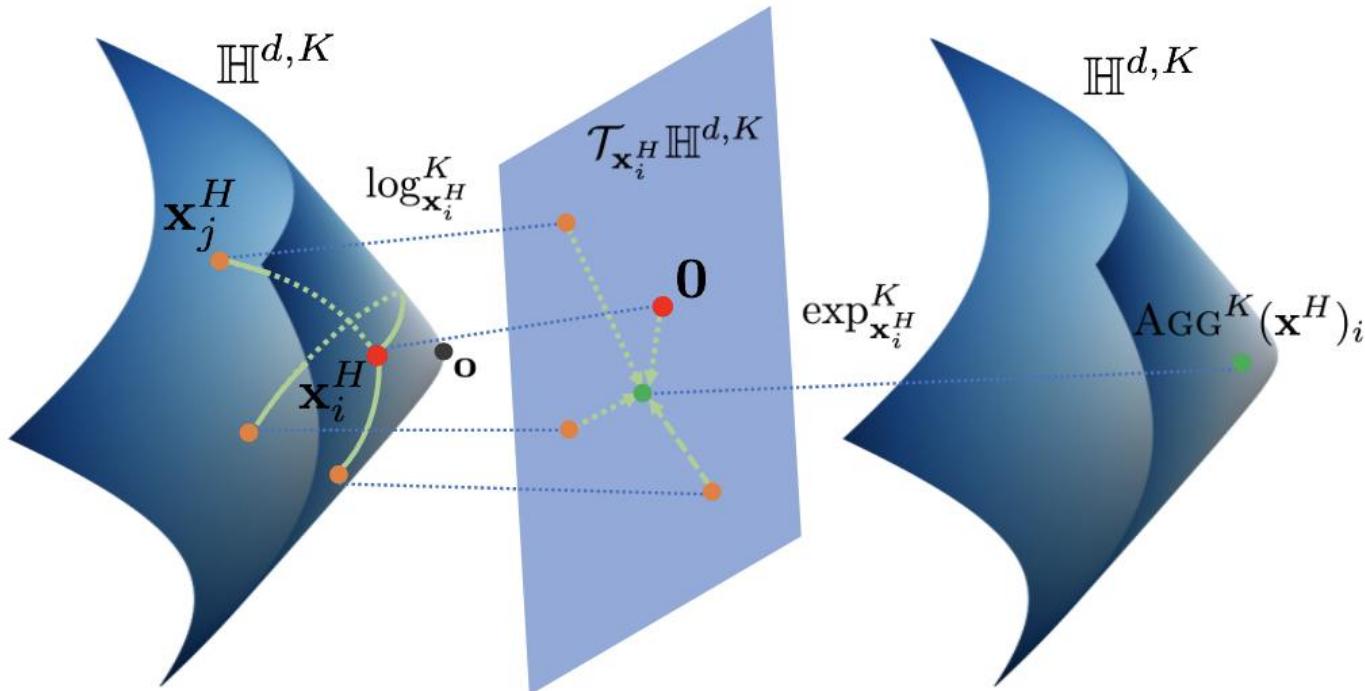


Nodes and edges

Embed for node/edge/graph inference

Multiple layers

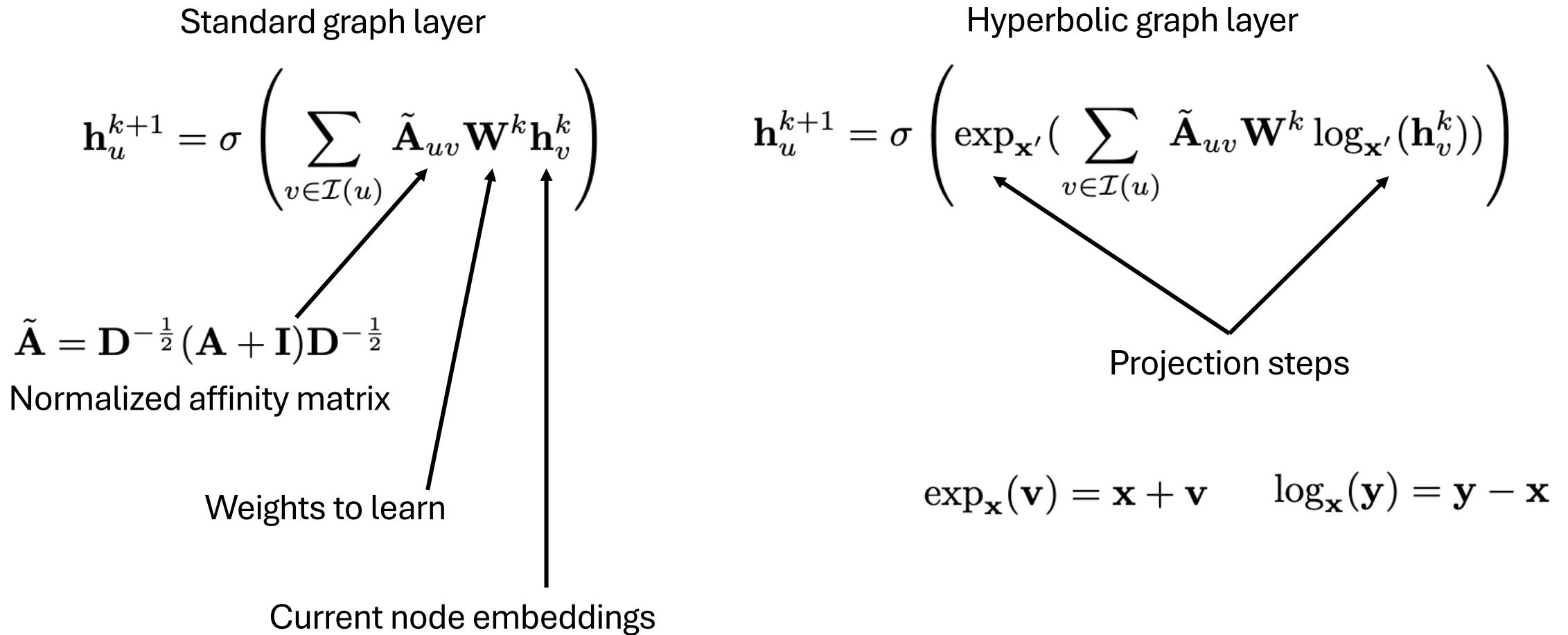
First generation hyperbolic graph networks



Project hyperbolic nodes to Euclidean space, do normal graph layer, project back.

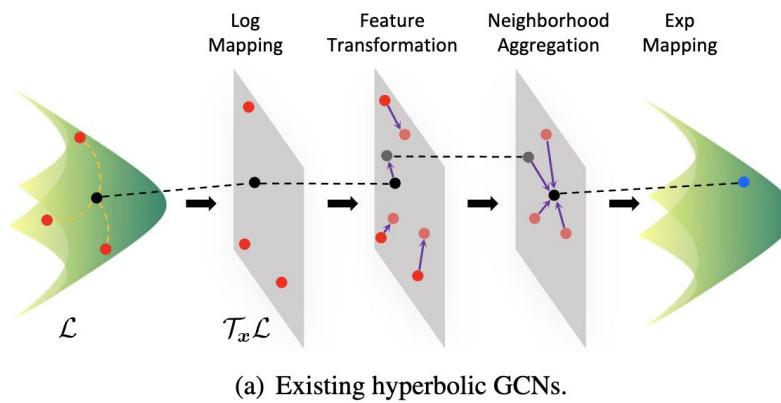
[Chami et al., NeurIPS 2019, Liu et al., NeurIPS
2019]

First generation hyperbolic graph networks



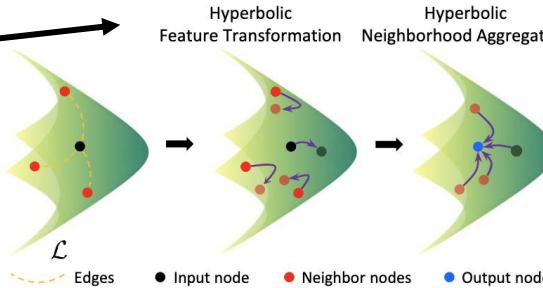
Second generation hyperbolic graph networks

Perform transformations also in hyperbolic space.



(a) Existing hyperbolic GCNs.

Transformations in Lorentz model.



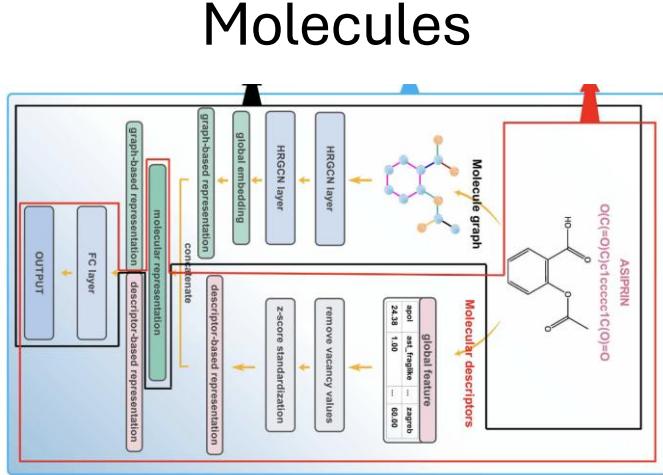
[Dai et al. CVPR 2021]

Aggregation in Klein model.

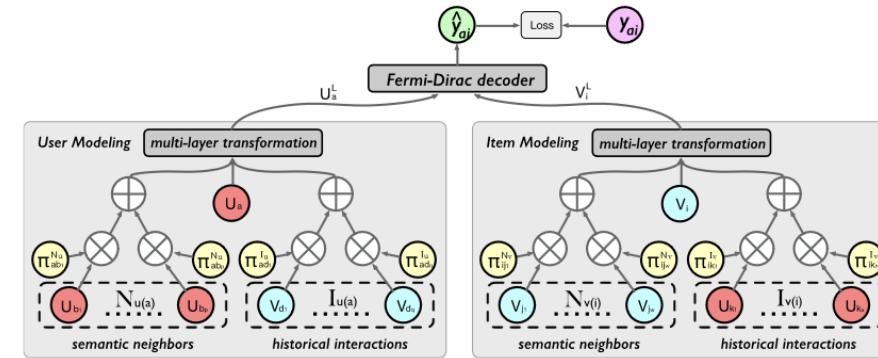
Non-linearities in Poincaré ball model.

Applications of hyperbolic graph networks

[Wu et al. BiB 2021]



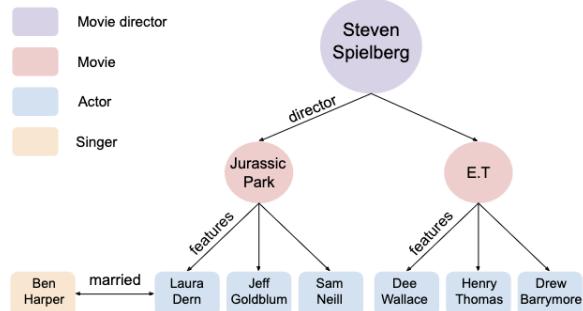
Recommendation systems



[Li et al. TKDE 2023]

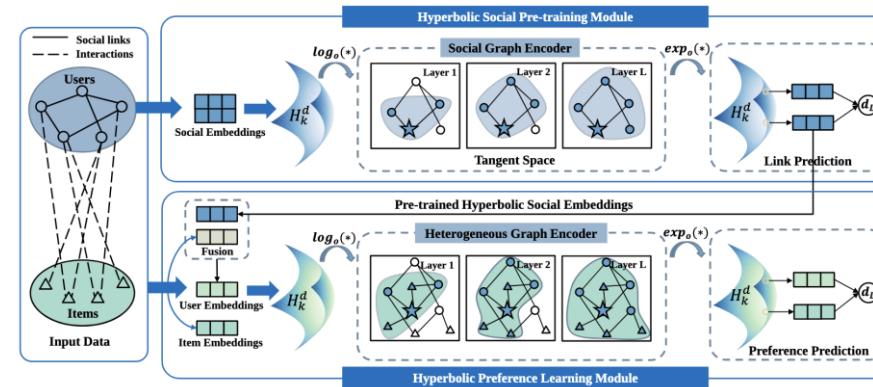
[Chami et al. 2020]

Knowledge graphs



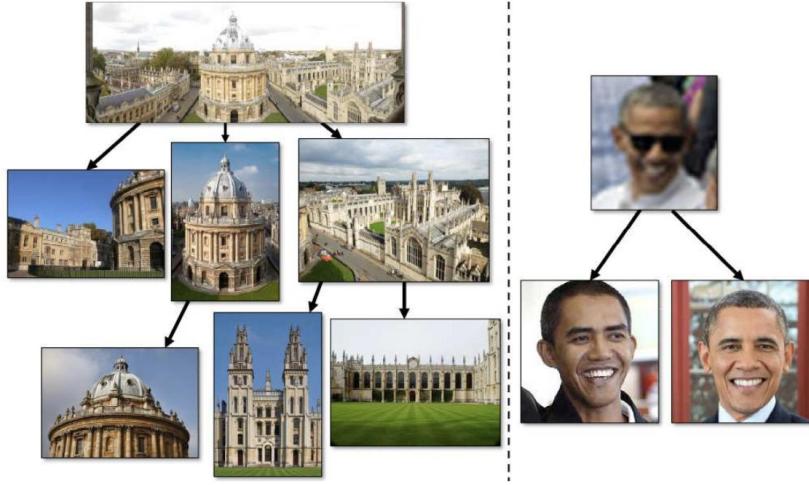
[Yang et al. TKDE 2023]

Social networks

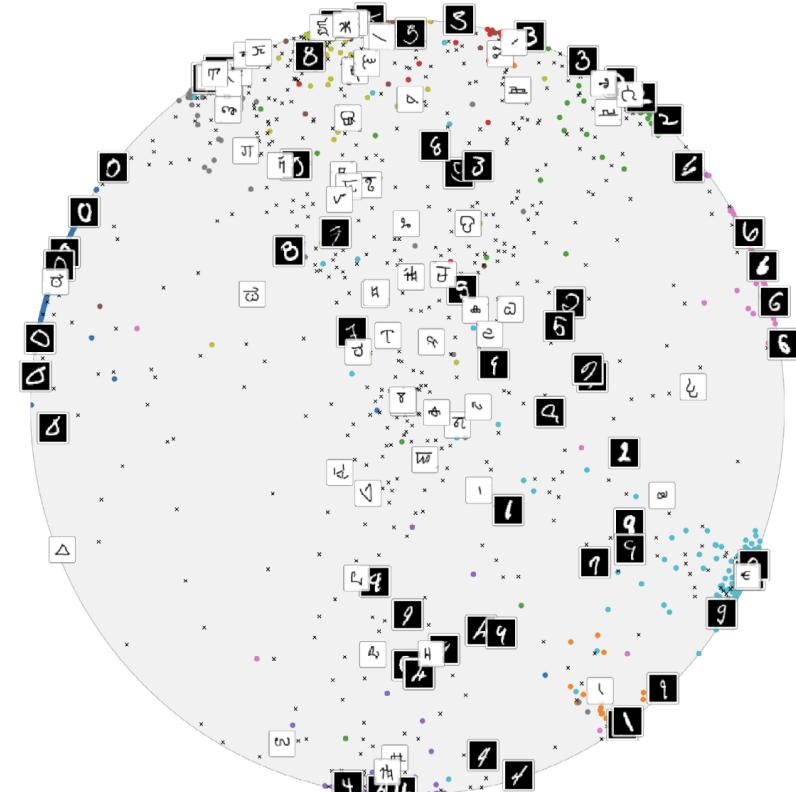


Hyperbolic Image Embeddings

[Khrulkov et al. CVPR 2020]



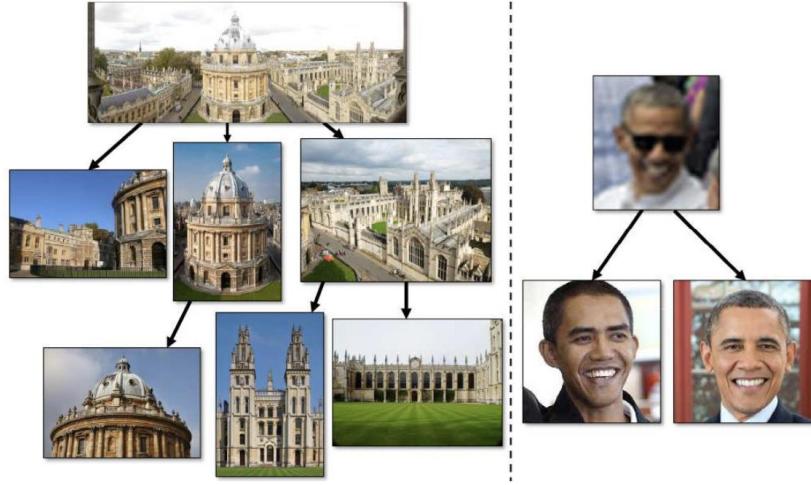
Encoder	Dataset			
	CIFAR10	CIFAR100	CUB	<i>MiniImageNet</i>
Inception v3 [49]	0.25	0.23	0.23	0.21
ResNet34 [14]	0.26	0.25	0.25	0.21
VGG19 [42]	0.23	0.22	0.23	0.17



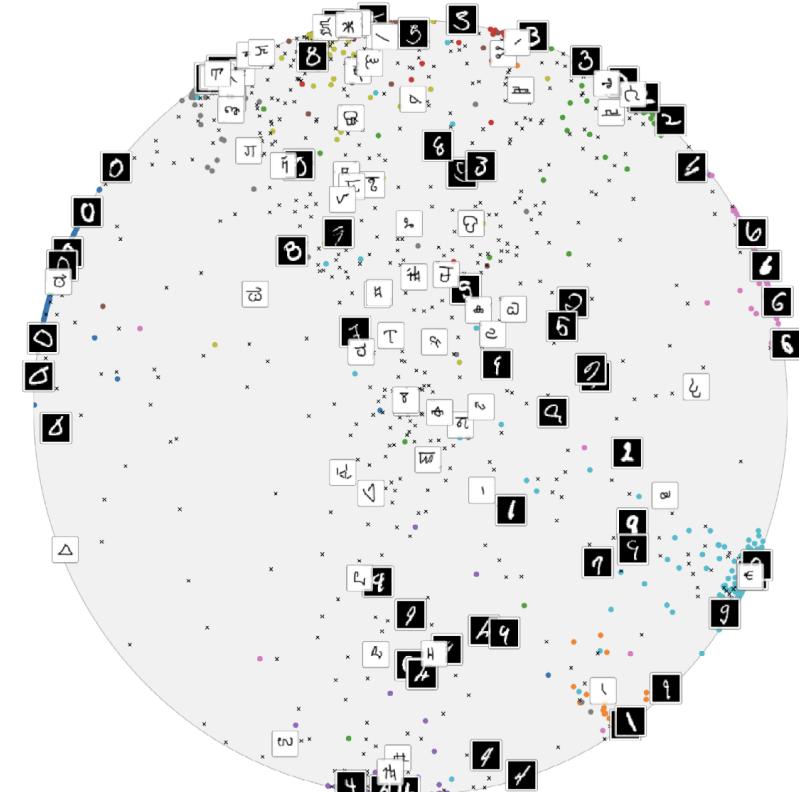
Images are naturally hierarchical, hyperbolic embeddings improve few-shot learning.

Hyperbolic Image Embeddings

[Khrulkov et al. CVPR 2020]



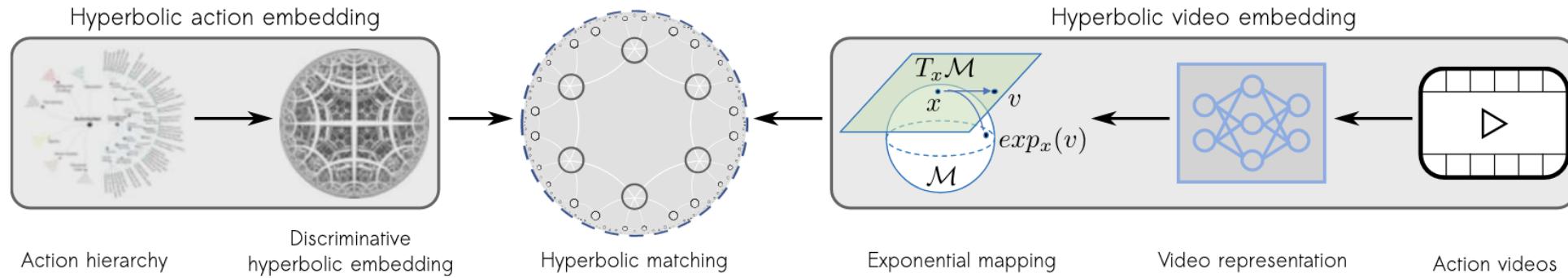
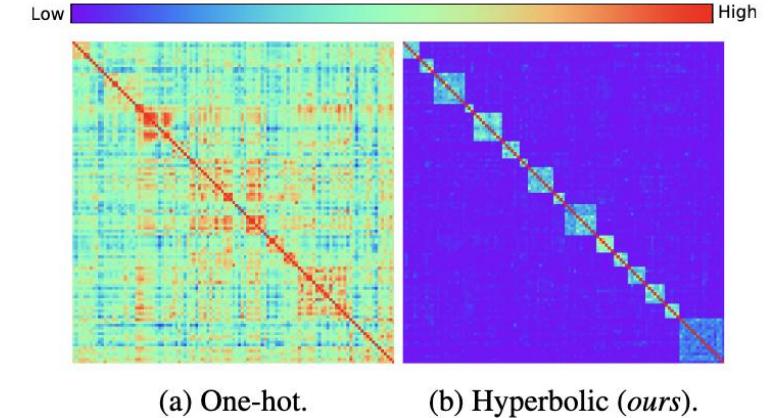
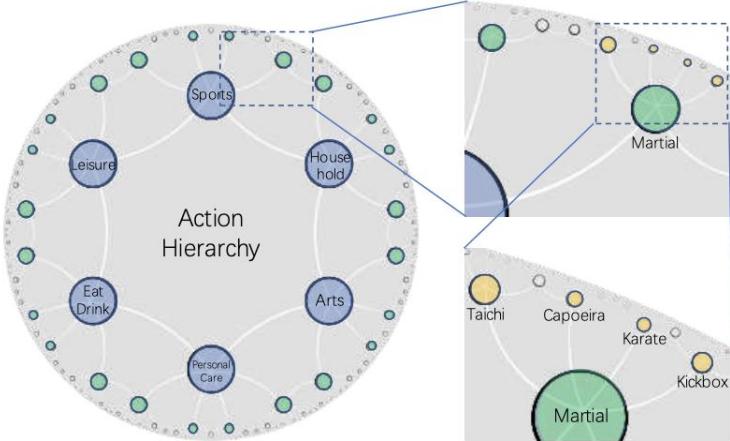
Encoder	Dataset			
	CIFAR10	CIFAR100	CUB	<i>MiniImageNet</i>
Inception v3 [49]	0.25	0.23	0.23	0.21
ResNet34 [14]	0.26	0.25	0.25	0.21
VGG19 [42]	0.23	0.22	0.23	0.17



Images are naturally hierarchical, hyperbolic embeddings improve few-shot learning.

Hyperbolic actions

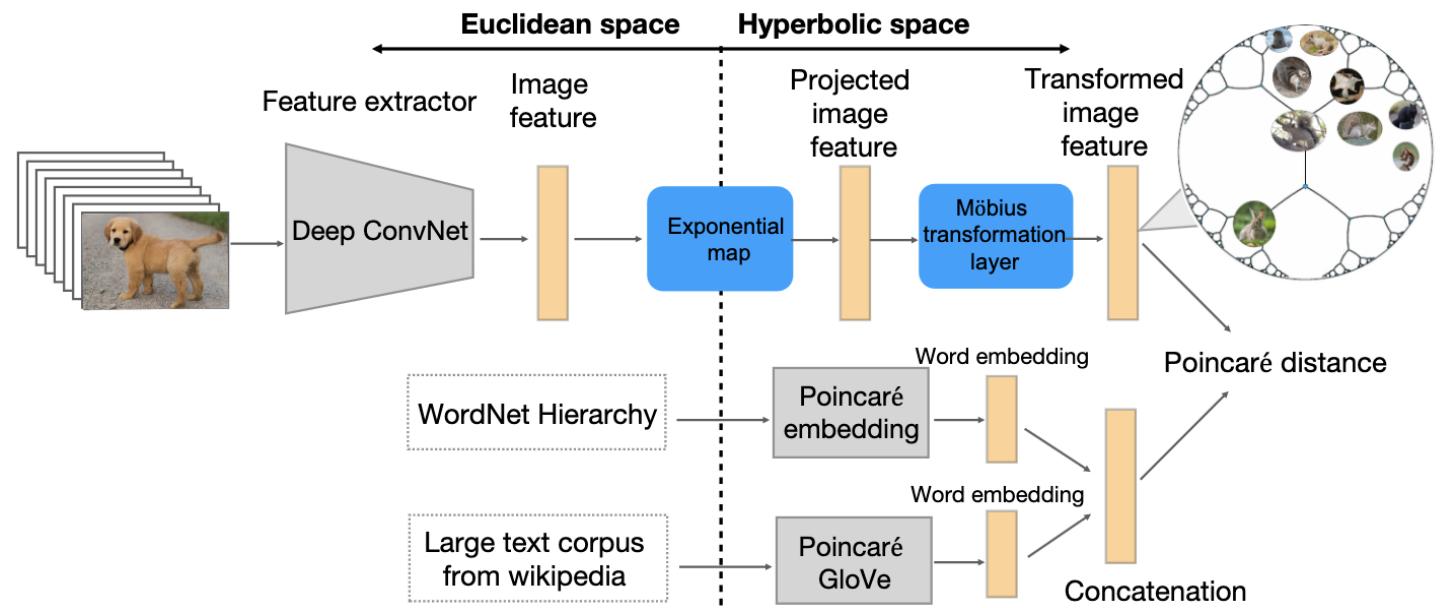
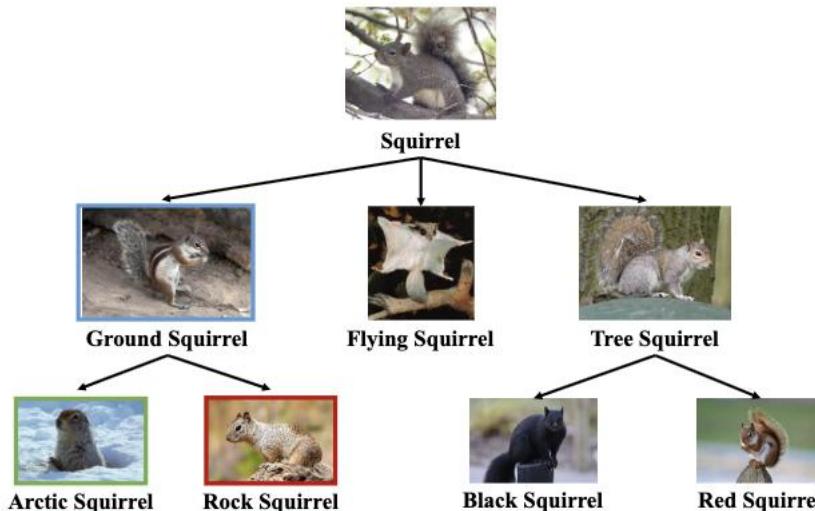
[Long et al.. CVPR 2020]



Videos are naturally hierarchical, hyperbolic embeddings improve action recognition.

Hyperbolic zero-shot learning

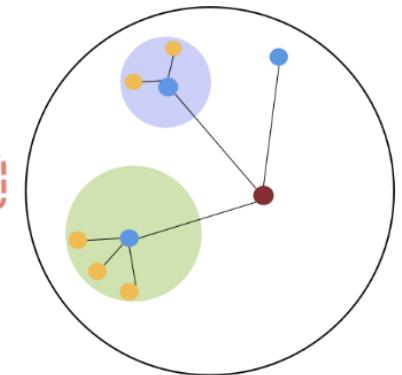
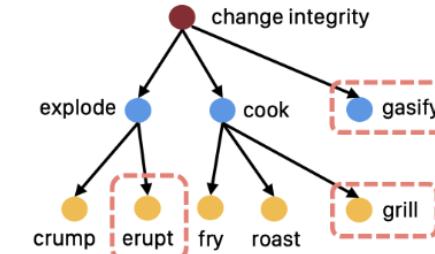
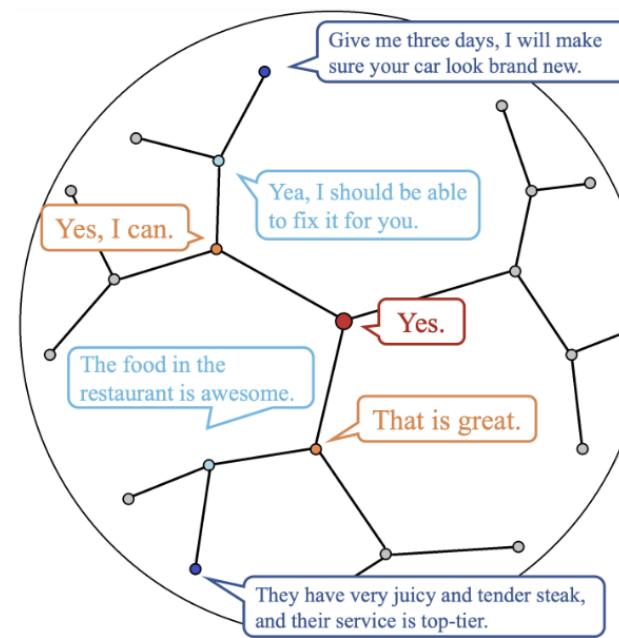
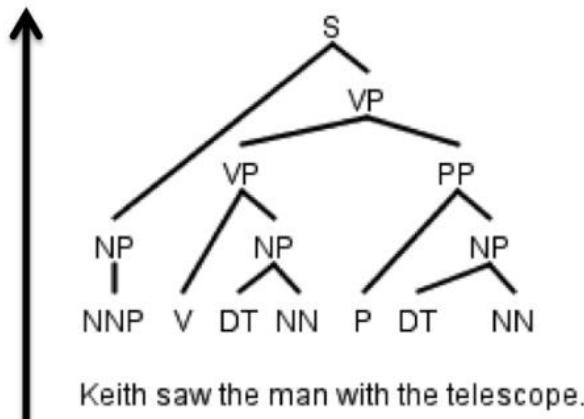
[Liu et al. CVPR 2020]



Semantics is naturally hierarchical, hyperbolic embeddings improve zero-shot recognition.

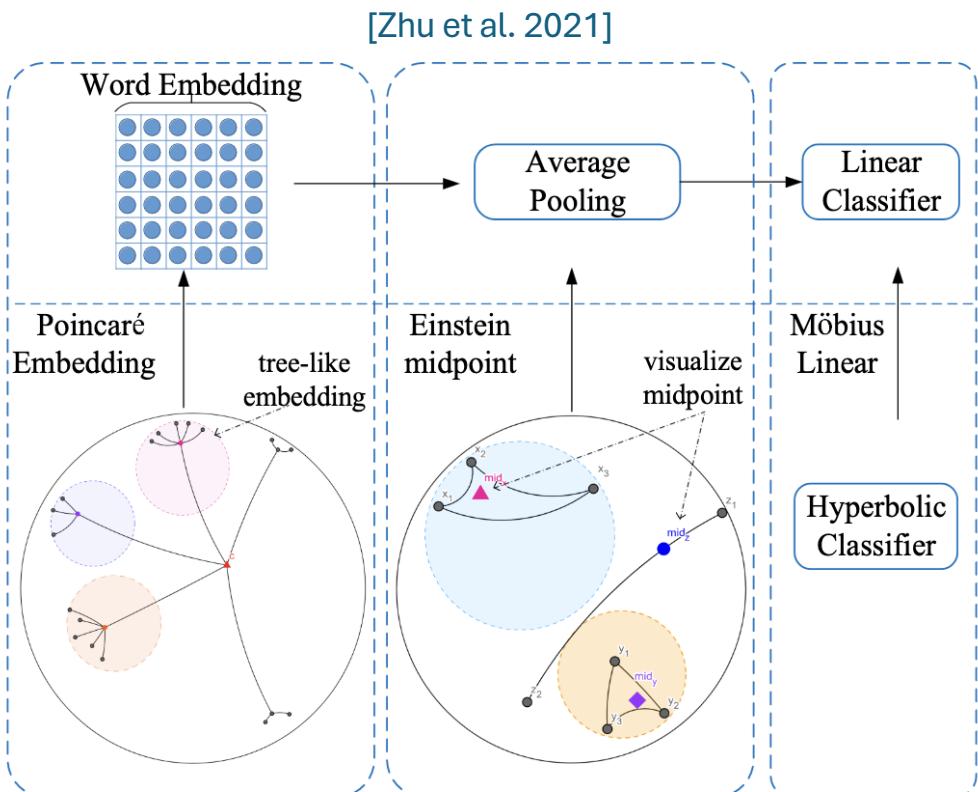
Hyperbolic embeddings for text

Text is well-known to be hierarchical at multiple levels.

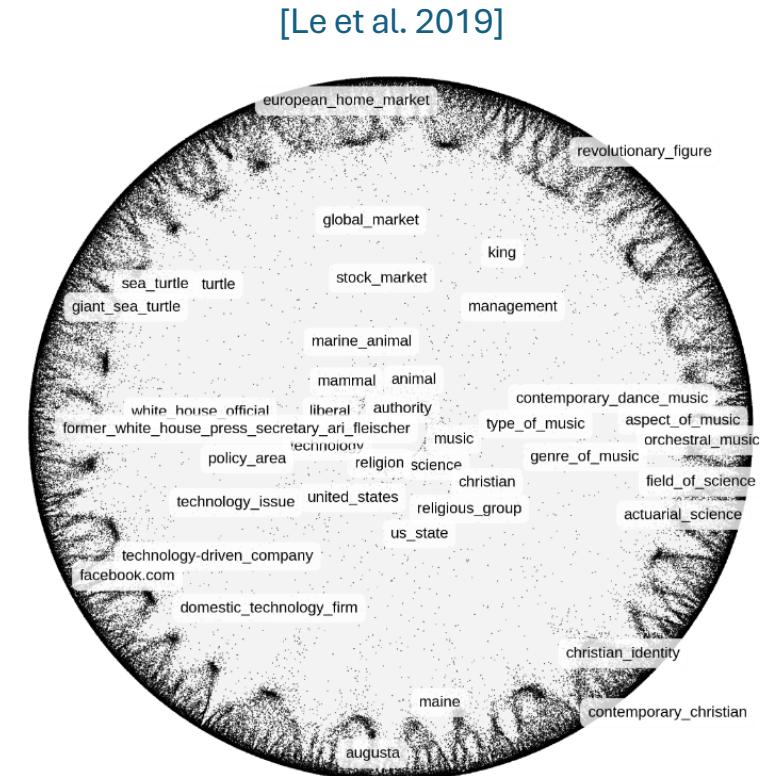


Should representations of text then also be embedded in a hierarchical geometry?

Hyperbolic word embeddings



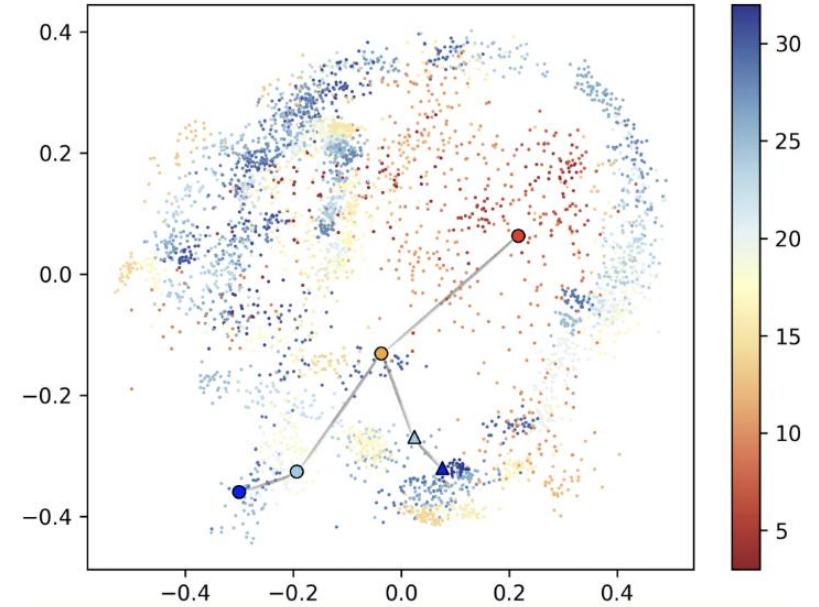
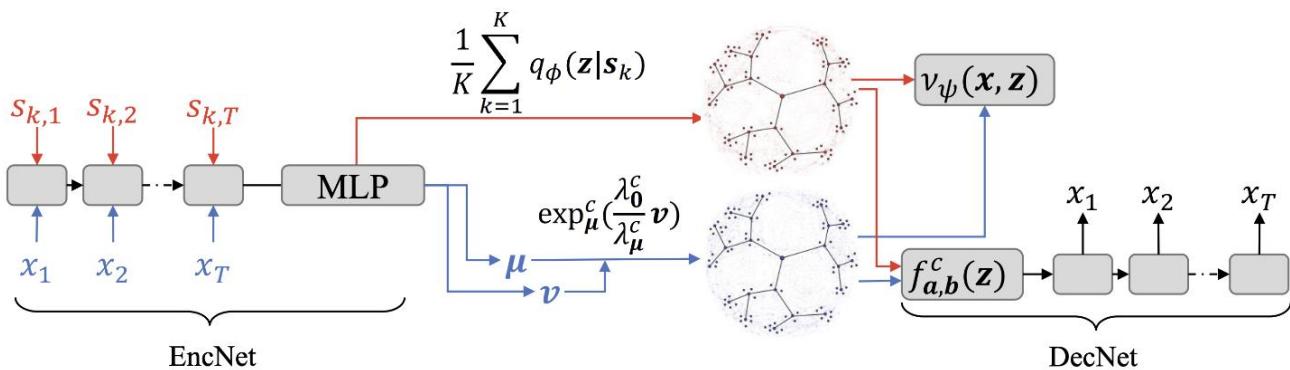
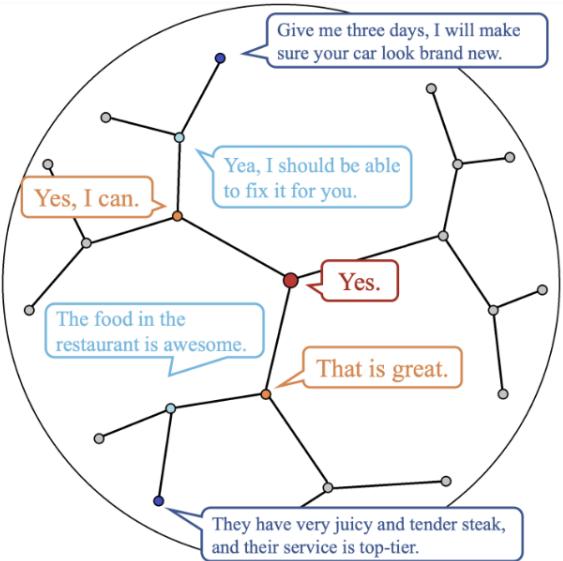
Hyperbolic FastText



Inferring concept hierarchies from text in hyperbolic space

Hyperbolic generation of text

[Dai et al. 2020]



- the national cancer institute ban smoking
- the national cancer institute warns citizens to avoid smoking cigarette
- the national cancer institute claims that smoking cigarette too often would increase the chance of getting lung cancer
- △ the national cancer institute study the effect of chemical in cigarette on different group of workers.
- the national cancer institute also projected that overall u.s. mortality rates from lung cancer should begin to drop in several years if cigarette smoking continues to decrease
- ▲ the national cancer institute report a form of asbestos once used to make cigarette filters has caused a high percentage of cancer deaths among a group of workers exposed to it

Hyperbolic vision-language models

[Desai et al. ICML 2023]

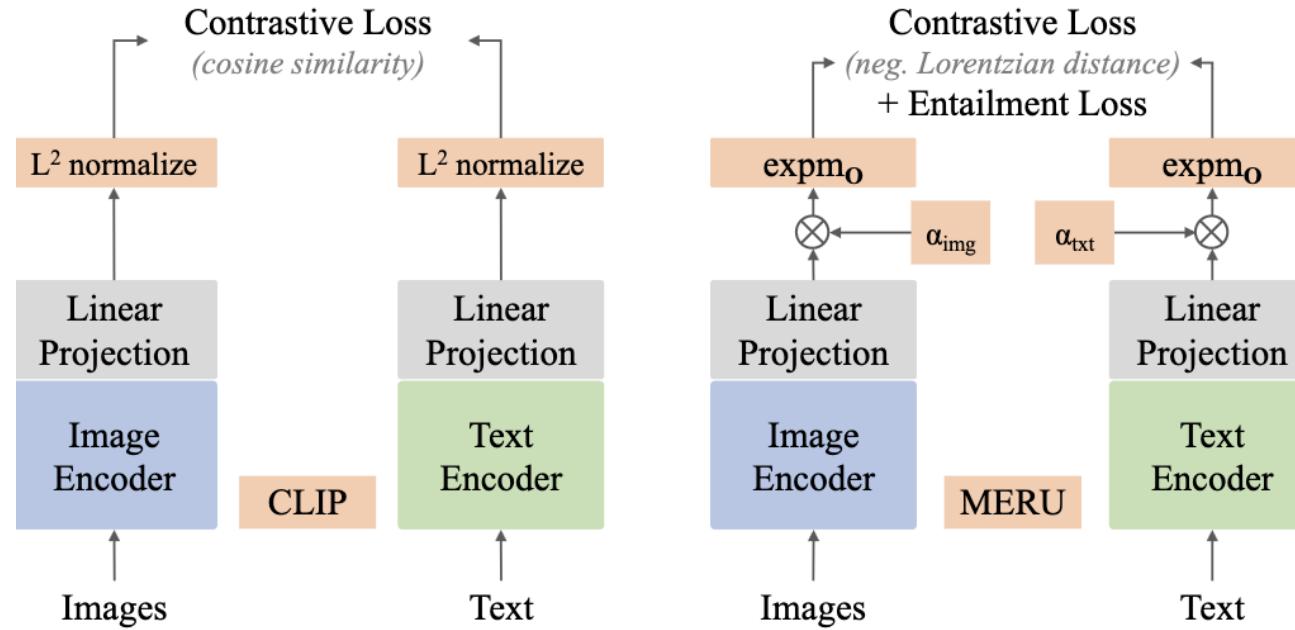


Image-text representation learning wants to collapse image and text embeddings.

Issue 1: image-text asymmetry

Vision-language models explicitly assume that image and text are equal.

Both are points in a shared space, contrastive learning wants to collapse them.

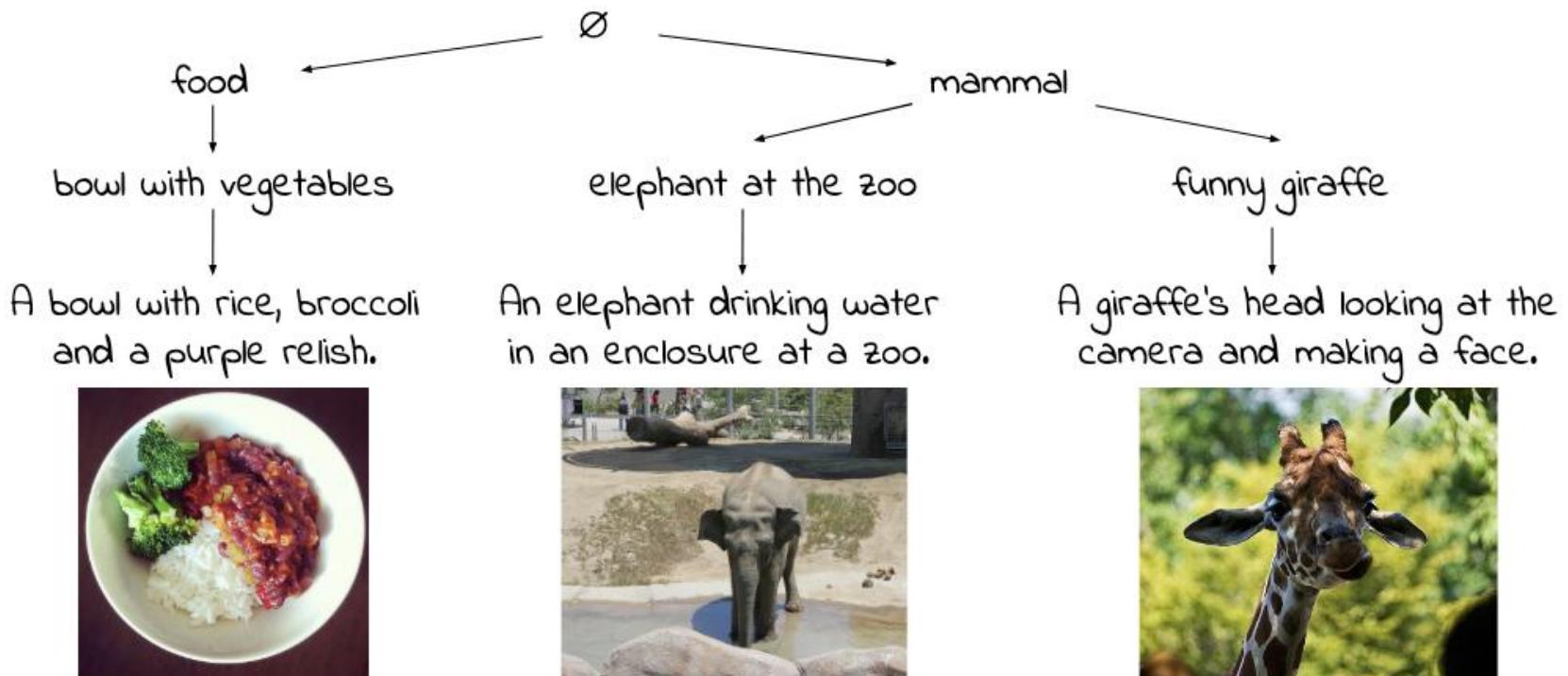
But one sentence does not uniquely define an image.

Text is more general than images.



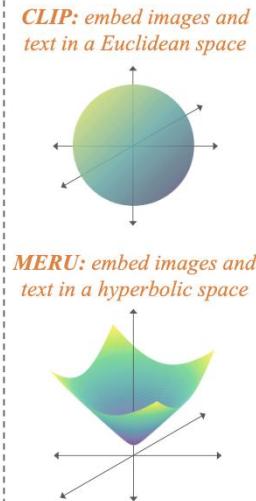
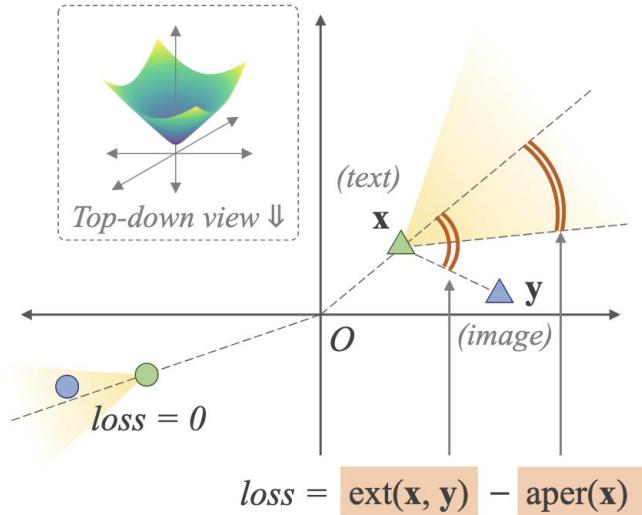
Issue 2: vision-language is hierarchical

"Foundation VLMs exhibit zero-shot hierarchical understanding" – Alper et al. (2024)



Hyperbolic vision-language models

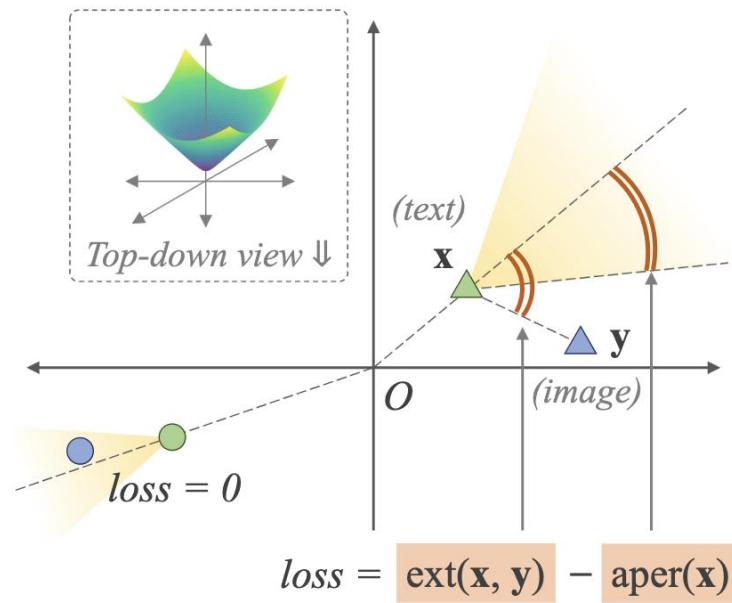
Intuitively, image and text embeddings are unequal!



Hyperbolic entailments allow to model this imbalance
and learn the hierarchical nature of image-text representations.

Entailment as a loss

Main objective: model the asymmetry between image and text.

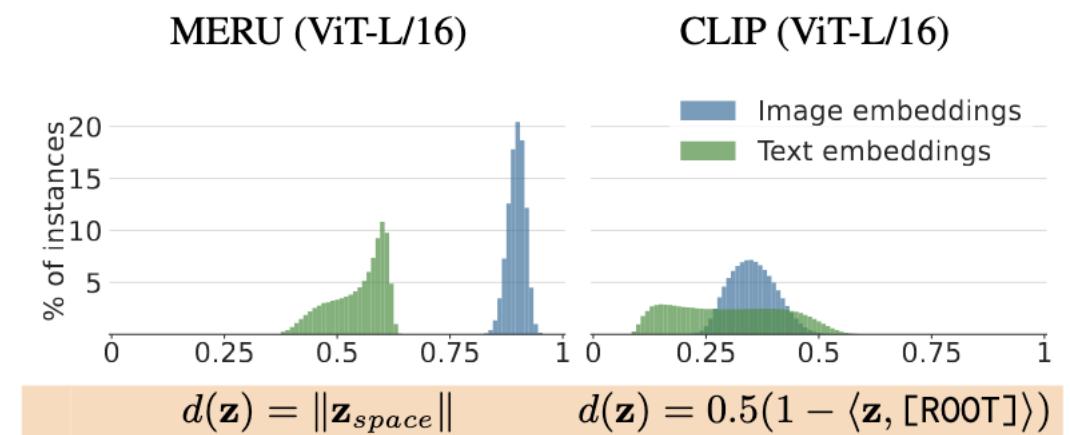


Hyperbolic entailments allow to model this imbalance
and (implicitly) learn the hierarchical nature of image-text representations.

Empirical effect

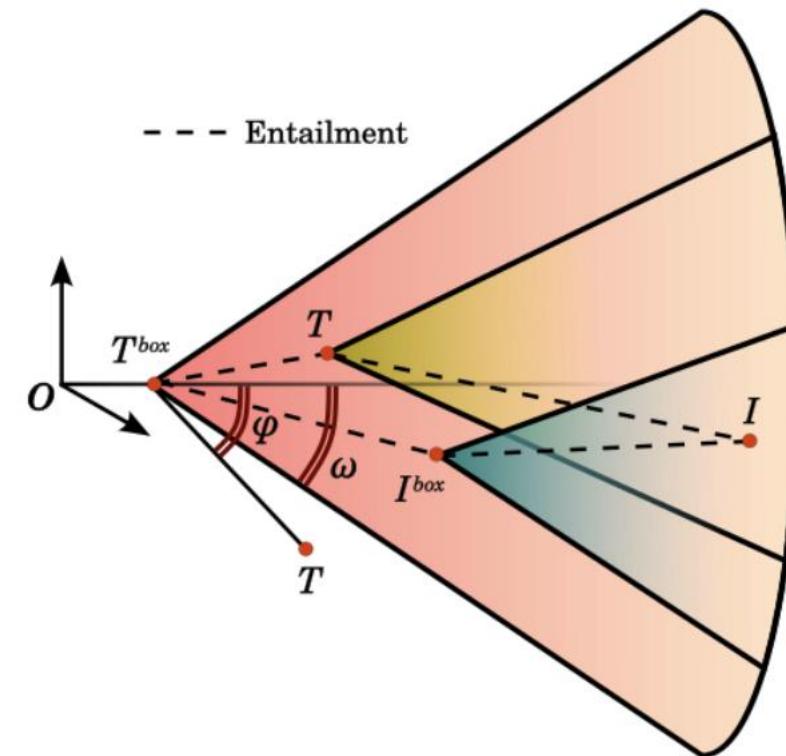
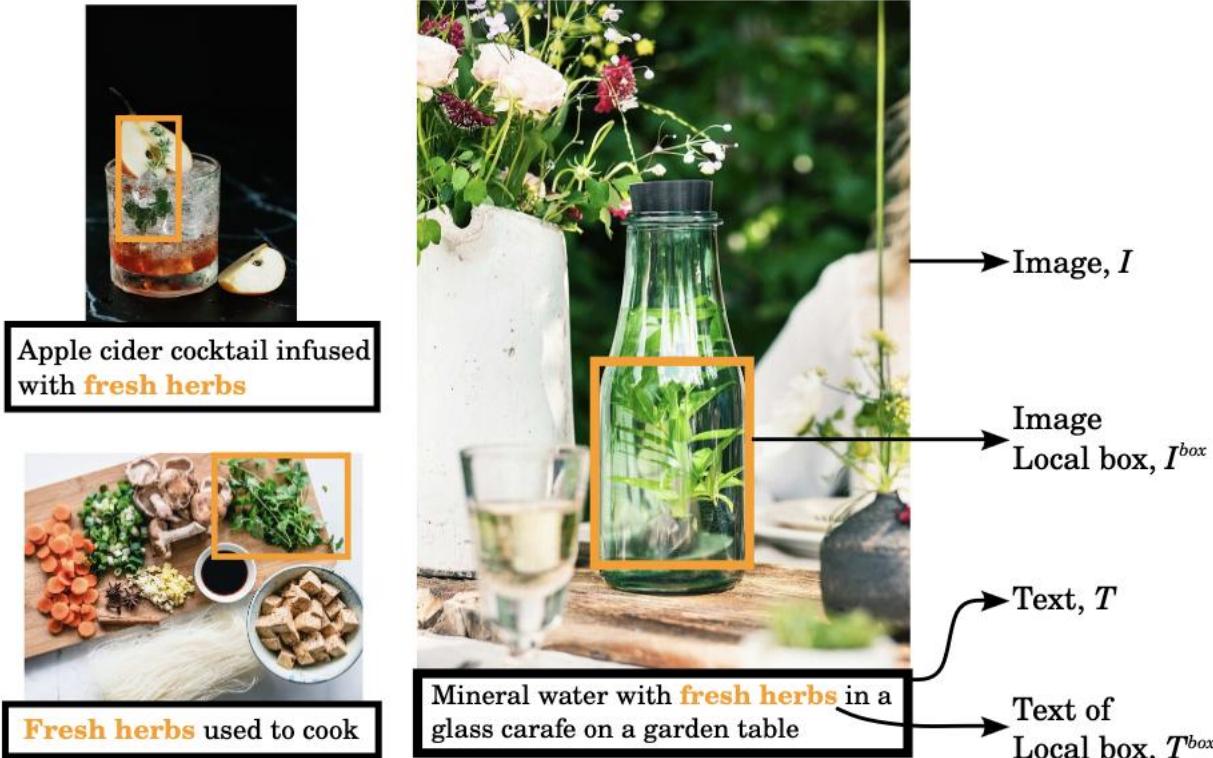
		<i>text → image</i>				<i>image → text</i>			
		COCO		Flickr		COCO		Flickr	
		R5	R10	R5	R10	R5	R10	R5	R10
ViT S/16	CLIP	29.9	40.1	35.3	46.1	37.5	48.1	42.1	54.7
	MERU	30.5	40.9	37.1	47.4	39.0	50.5	43.5	55.2
ViT B/16	CLIP	32.9	43.3	40.3	51.0	41.4	52.7	50.2	60.2
	MERU	33.2	44.0	41.1	51.6	41.8	52.9	48.1	58.9
ViT L/16	CLIP	31.7	42.2	39.0	49.3	40.6	51.3	47.8	58.5
	MERU	32.6	43.0	39.6	50.3	41.9	53.3	50.3	60.6

		Embedding width				
		512	256	128	96	64
COCO <i>text→image</i>	CLIP	31.7	31.8	31.4	29.6	25.7
	MERU	32.6	32.7	32.7	31.0	26.5
COCO <i>image→text</i>	CLIP	40.6	41.0	40.4	37.9	33.3
	MERU	41.9	42.5	42.6	40.5	34.2
ImageNet	CLIP	38.4	38.3	37.9	35.2	30.2
	MERU	38.8	38.8	38.8	37.3	32.3

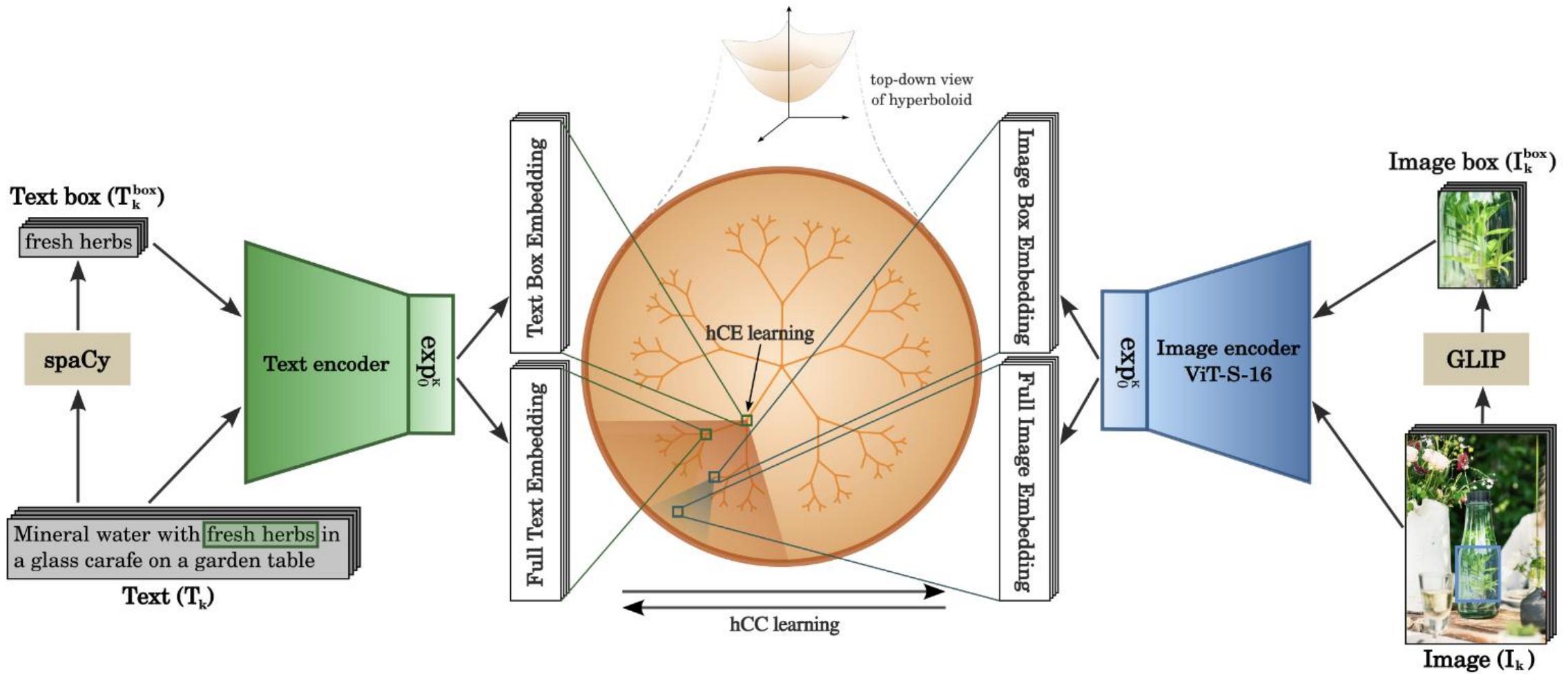


Compositional vision-language models

[Pal et al. ICLR 2025 (oral)]



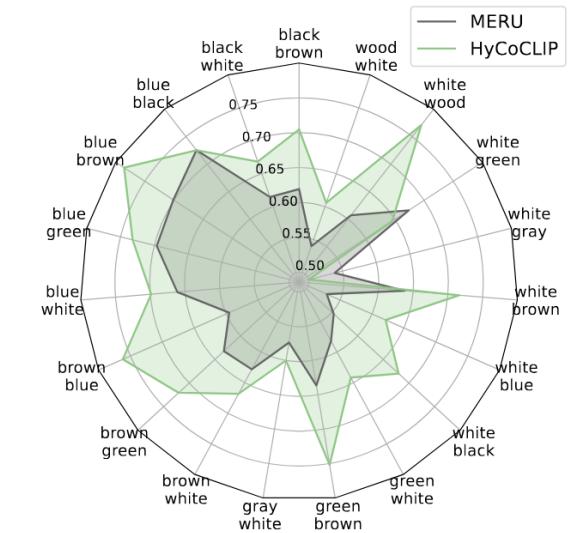
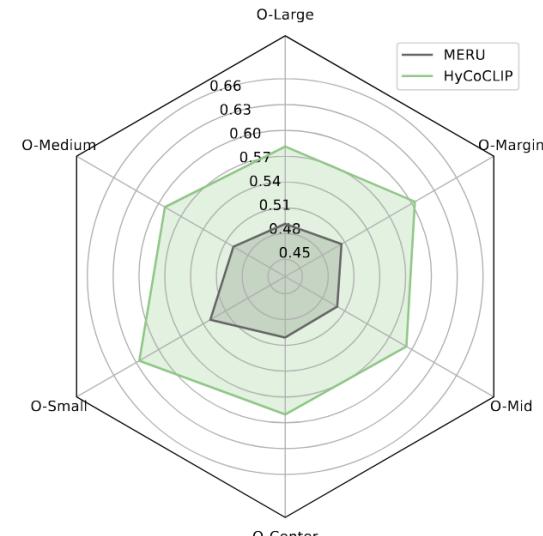
Multi-modal network



Entailment compositions work

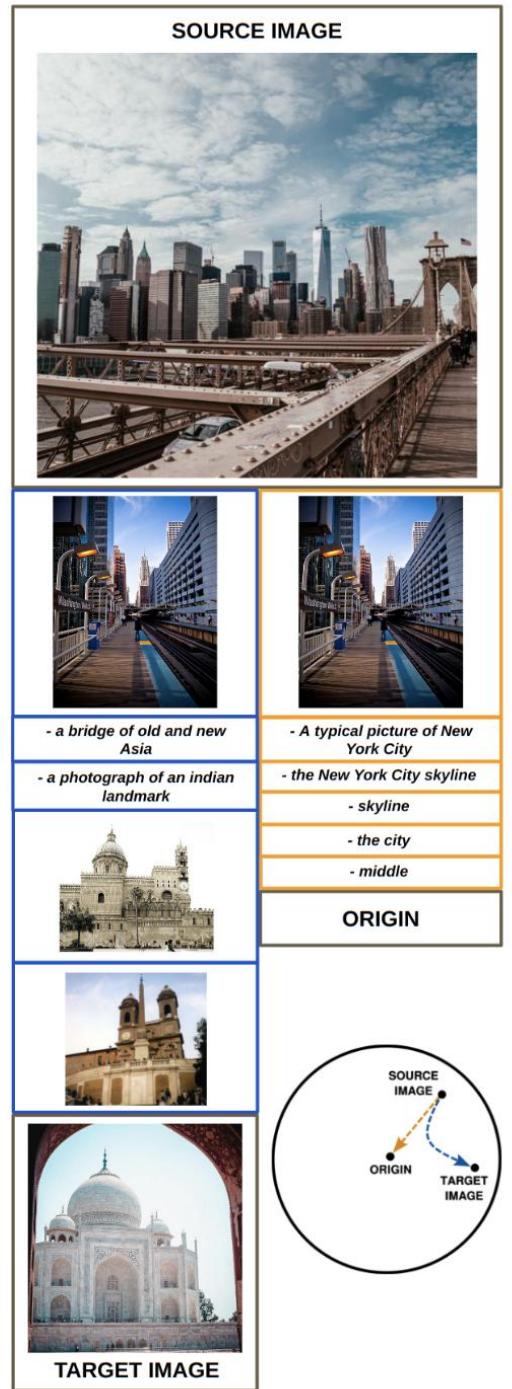
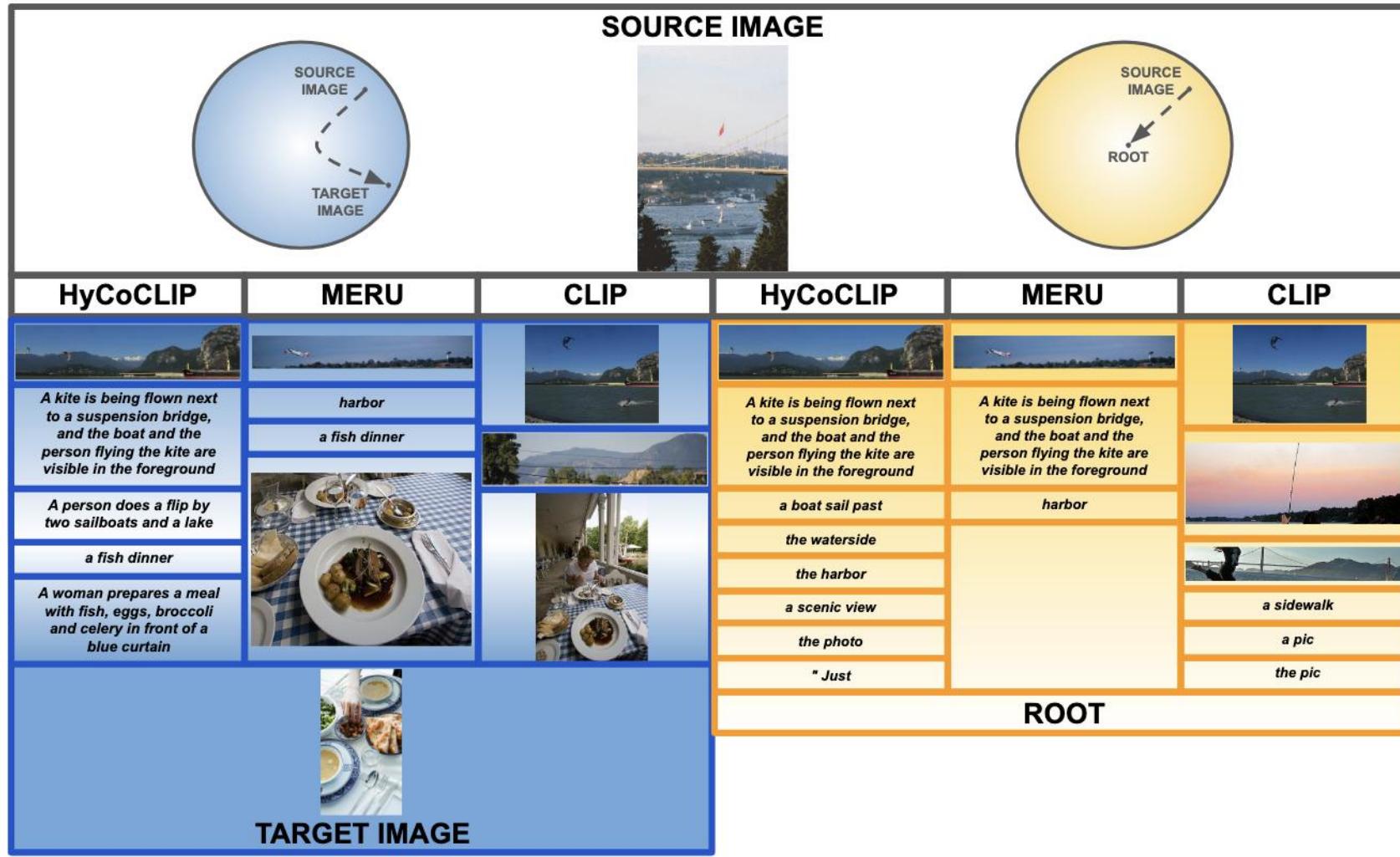
	w/ boxes	samples (M)	General datasets				Fine-grained datasets				Misc. datasets								
			ImageNet	CIFAR-10	CIFAR-100	SUN397	Caltech-101	STL-10	Food-101	CUB	Cars	Aircraft	Pets	Flowers	DTD	EuroSAT	RESISC45		
RedCaps																			
ViT S/16	CLIP [†]	✗	11.4	32.5	66.7	35.8	26.7	60.8	89.8	72.5	29.8	11.1	1.3	72.5	44.9	16.4	30.1	27.7	5.0
	CLIP	✓	11.4 [6.3]	30.2	76.5	42.4	25.8	62.3	89.5	69.6	25.7	8.5	2.2	65.3	38.6	13.6	36.6	28.5	4.6
	MERU [†]	✗	11.4	31.4	65.9	35.2	26.8	58.1	89.3	71.4	29.0	8.3	1.6	71.0	40.9	17.0	29.9	29.3	4.7
	MERU	✓	11.4 [6.3]	29.9	76.4	39.9	26.6	62.3	89.5	68.4	25.4	8.9	1.2	67.2	37.6	13.0	30.5	27.6	4.3
	HyCoCLIP	✓	5.8 [6.3]	31.9	77.4	37.7	27.6	64.5	90.9	71.1	28.8	9.7	1.1	70.5	41.4	13.4	22.7	30.7	4.4
GRIT																			
ViT S/16	CLIP	✗	20.5	36.7	70.2	42.6	49.5	73.6	89.7	44.7	9.8	6.9	2.0	44.6	14.8	22.3	40.7	40.1	5.1
	CLIP	✓	20.5 [35.9]	36.2	84.2	54.8	46.1	74.1	91.6	43.2	11.9	6.0	2.5	45.9	18.1	24.0	32.4	35.5	4.7
	MERU	✗	20.5	35.4	71.2	42.0	48.6	73.0	89.8	48.8	10.9	6.5	2.3	42.7	17.3	18.6	39.1	38.9	5.3
	MERU	✓	20.5 [35.9]	35.0	85.0	54.0	44.6	73.9	91.6	41.1	10.1	5.6	2.2	43.9	15.9	24.5	39.3	33.5	4.8
	HyCoCLIP	✓	20.5 [35.9]	41.7	85.0	53.6	52.5	75.7	92.5	50.2	14.7	8.1	4.2	52.0	20.5	22.3	33.8	45.7	5.2
ViT B/16	CLIP	✗	20.5	40.6	78.9	48.3	53.0	76.7	92.4	48.6	10.0	9.0	3.4	45.9	21.3	23.4	37.1	42.7	5.7
	MERU	✗	20.5	40.1	78.6	49.3	53.0	72.8	93.2	51.5	11.9	8.6	3.7	48.5	21.2	22.2	31.7	44.2	5.6
	HyCoCLIP	✓	20.5 [35.9]	45.8	88.8	60.1	57.2	81.3	95.0	59.2	16.4	11.6	3.7	56.8	23.9	29.4	35.8	45.6	6.5

Vision encoder	Model	w/ boxes	Text retrieval				Image retrieval				Hierarchical metrics					
			COCO		Flickr		COCO		Flickr		WordNet					
			R@5	R@10	R@5	R@10	R@5	R@10	R@5	R@10	TIE(↓)	LCA(↓)	J(↑)	P _H (↑)	R _H (↑)	
ViT S/16	CLIP	✗	69.3	79.1	90.2	95.2	53.7	65.2	81.1	87.9	4.02	2.39	0.76	0.83	0.84	
	CLIP	✓	60.7	71.8	84.2	91.3	47.1	58.6	73.1	82.1	4.03	2.38	0.76	0.83	0.83	
	MERU	✗	68.8	78.8	89.4	94.8	53.6	65.3	80.4	87.5	4.08	2.39	0.76	0.83	0.83	
	MERU	✓	72.7	81.9	83.5	90.1	46.6	58.3	60.0	71.7	4.08	2.39	0.75	0.83	0.83	
	HyCoCLIP	✓	69.5	79.5	89.1	93.9	55.2	66.6	81.5	88.1	3.55	2.17	0.79	0.86	0.85	
ViT B/16	CLIP	✗	71.4	81.5	93.6	96.9	57.4	68.5	83.5	89.9	3.60	2.21	0.79	0.85	0.85	
	MERU	✗	72.3	82.0	93.5	96.2	57.4	68.6	84.0	90.0	3.63	2.22	0.78	0.85	0.85	
	HyCoCLIP	✓	72.0	82.0	92.6	95.4	58.4	69.3	84.9	90.3	3.17	2.05	0.81	0.87	0.87	



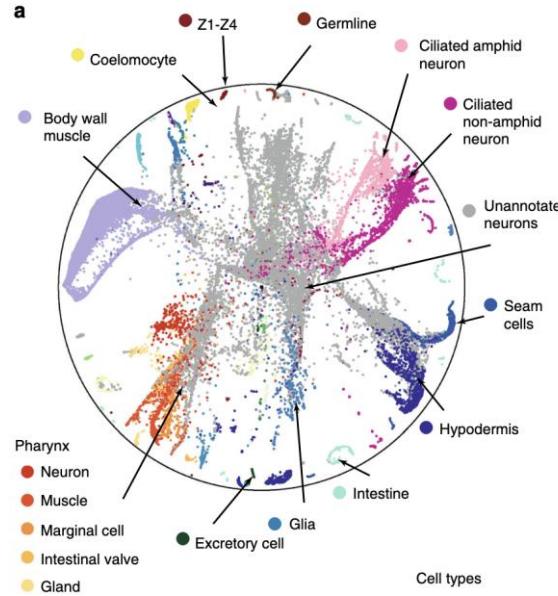
Model	AP
CLIP	51.2
MERU	55.8
RegionCLIP	65.2
HyCoCLIP	68.5

Embedding traversal

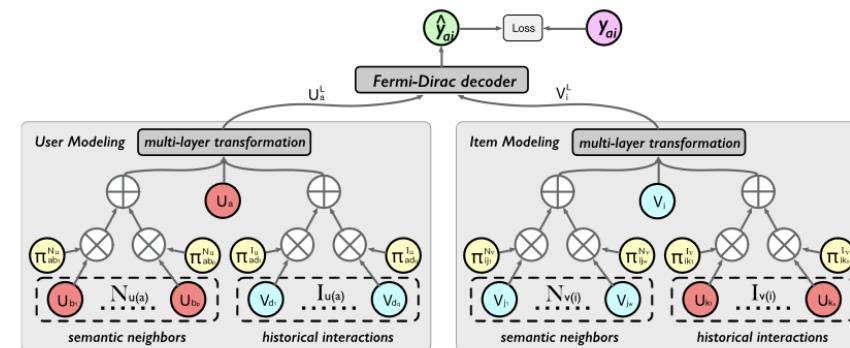


Hyperbolic embeddings for other data types

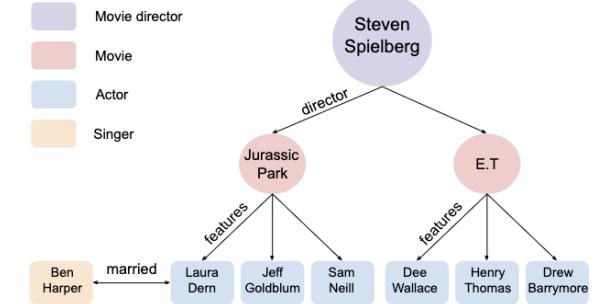
[Klimovskaia et al. Nature Comm. 2020]



[Li et al. TKDD 2023]



[Chami et al. 2020]



Hyperbolic embeddings
of single-cell data.

Hyperbolic recommender systems

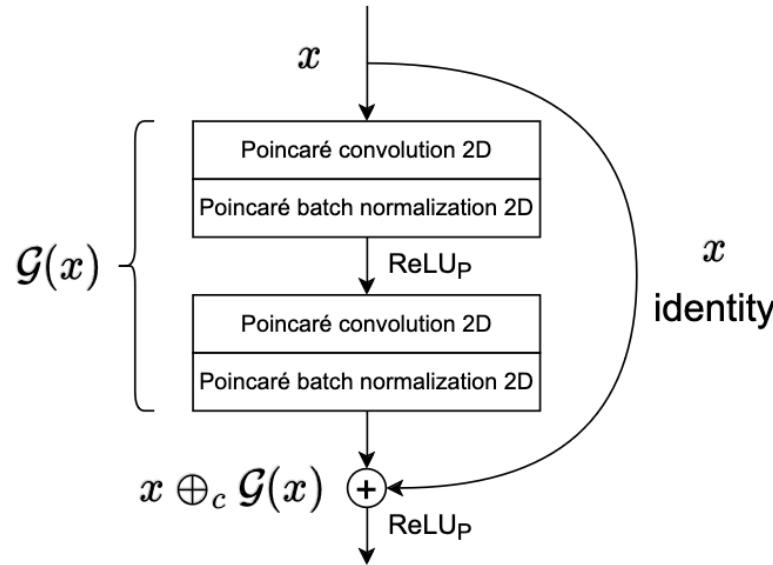
Hyperbolic knowledge graphs

And more for music, 3D skeletons, phylogenetic placement, social networks, clustering...

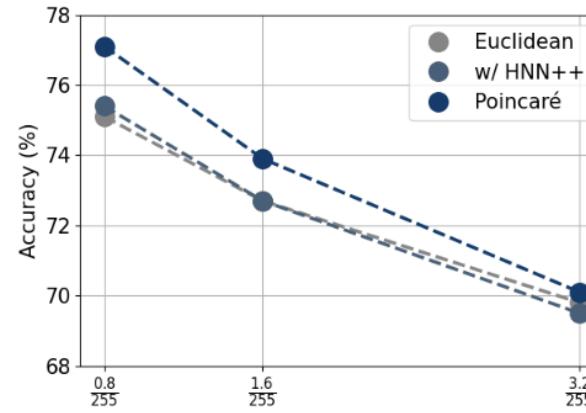
What if every layer becomes hyperbolic?

[van Spengler et al. ICCV 2023]

First convolutional network for images fully in hyperbolic space.



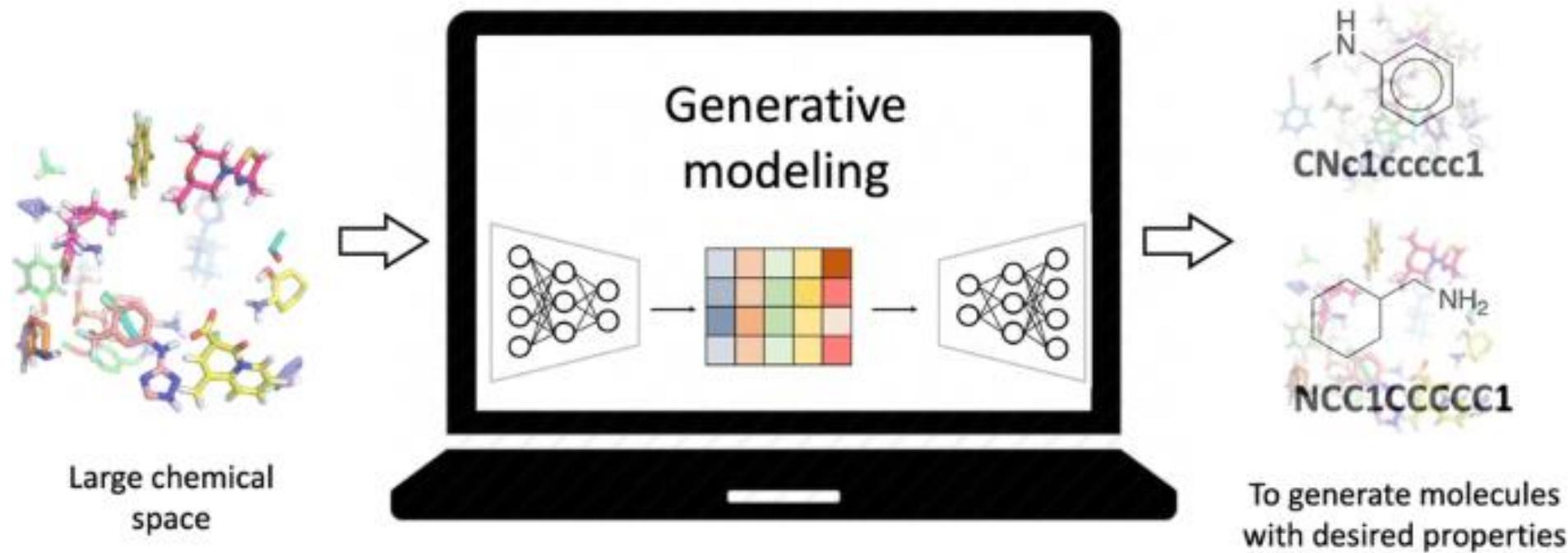
Manifold	CIFAR-10						CIFAR-100						
	FPR95 ↓		AUROC ↑		AUPR ↑		FPR95 ↓		AUROC ↑		AUPR ↑		
	R20	R32	R20	R32	R20	R32	R20	R32	R20	R32	R20	R32	
Places-365	Euclidean	64.2	72.3	84.7	82.0	96.2	95.6	89.5	93.9	62.5	57.9	89.3	87.9
	w/ HNN++	63.8	72.7	79.6	77.7	94.5	94.2	93.2	86.3	63.3	66.6	89.8	91.1
	Poincaré	70.2	70.7	82.3	82.6	95.7	95.9	82.8	83.8	71.5	71.1	92.3	92.2
68.8 73.4 92.8 94.1 99.5 98.8 43.7 54.6 83.7 88.2													
85.5 82.2 96.9 96.1 92.1 88.6 66.4 68.9 91.1 92.0													
85.0 83.6 96.6 96.3 76.9 83.0 76.8 72.6 94.1 92.9													
73.6 77.3 93.2 94.7 98.1 96.0 33.5 42.9 75.9 79.4													
79.6 85.8 94.5 96.6 85.9 77.5 58.9 65.7 86.8 89.0													
82.1 82.3 95.5 95.6 83.9 84.2 67.7 68.8 91.0 91.5													



It works! Also better OOD and adversarial robustness, but scaling remain challenging.

Hyperbolic generative learning

[Bian and Xie, JMM 2021]

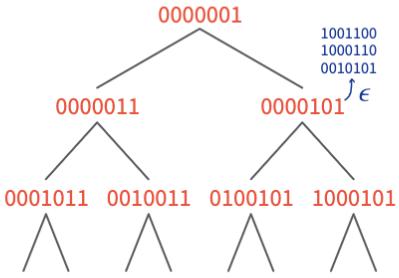


So far, we focused on discriminative learning. What about generation in hyperbolic space?

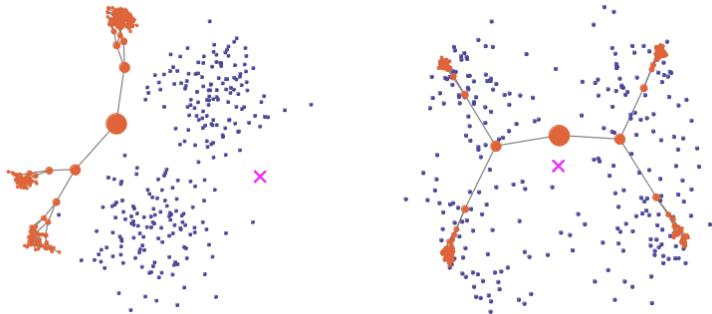
Hyperbolic Variational Autoencoders

[Nagano et al. ICML 2019, Mathieu et al. NeurIPS 2019]

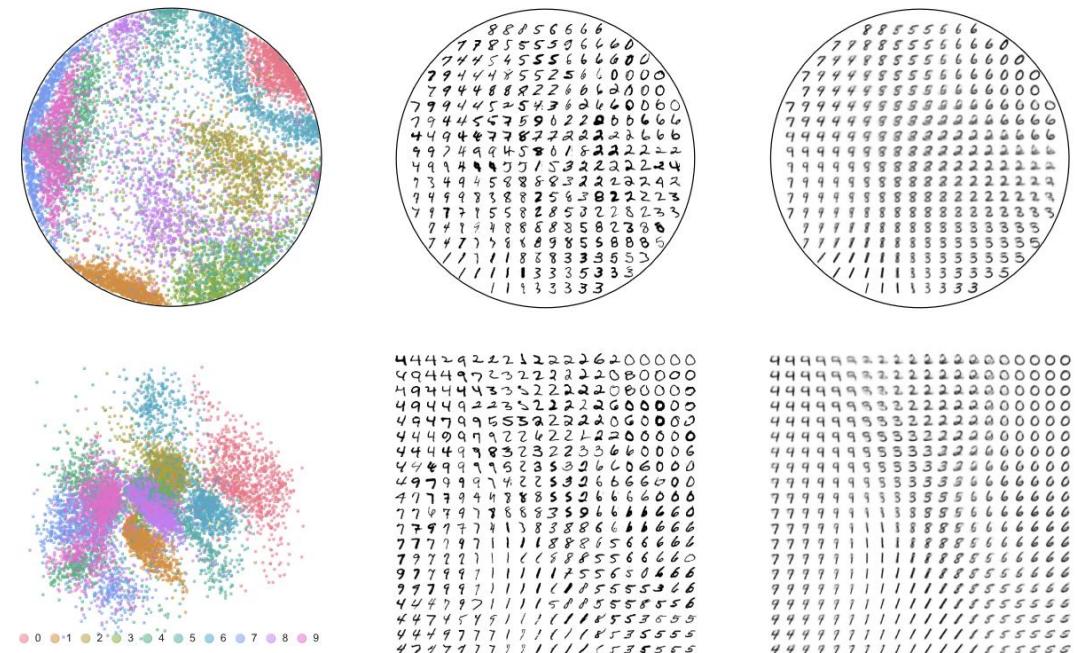
(a) A tree representation of the training dataset



(b) Vanilla VAE ($\beta = 1.0$)



(c) Hyperbolic VAE

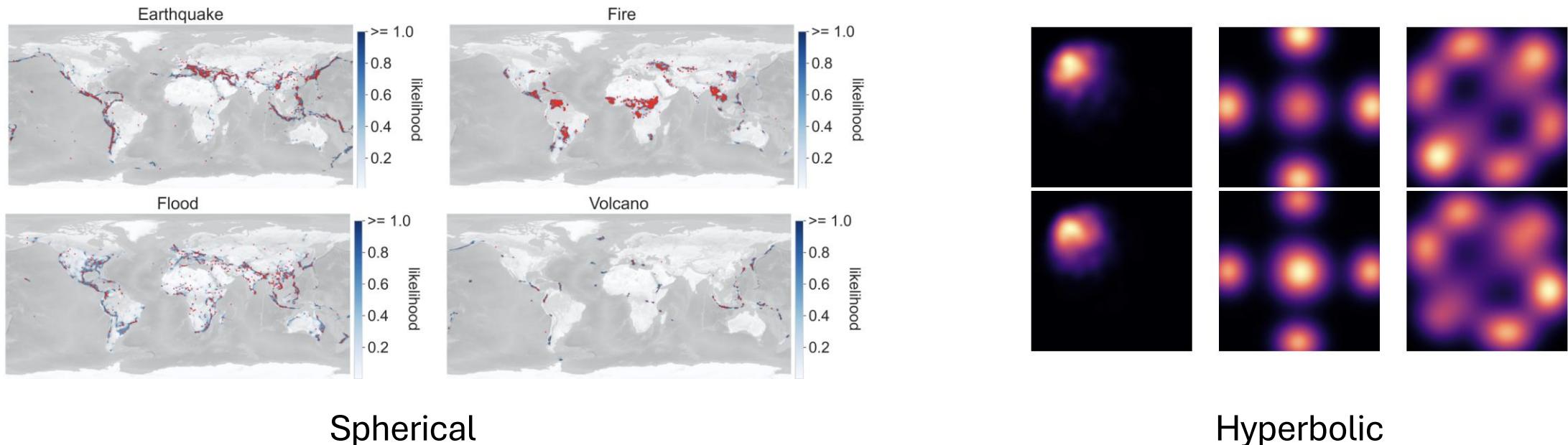


Hyperbolic latent spaces with wrapped normals enable learning latent hierarchical distributions.

Riemannian diffusion models

[Huang et al. NeurIPS 2022]

Generalize diffusion process to any Riemannian manifold.



Allows us to adapt diffusion process to the real underlying data distribution.

The big potential of hyperbolic learning

- Hierarchical learning** model the hierarchies of semantics and data.
- Robust learning** handle new distributions and adversarial samples.
- Low-dimensional learning** hyperbolic space is dense, allowing for smaller networks.
- Brain-like networks** brains are likely hyperbolic, big links with neuroscience

Zhang et al. *Nature Communications* 2022

The grand challenges of hyperbolic learning

Fully hyperbolic learning which hyperbolic model is best? and how to optimize?

Computational challenges numerical stability and speed of computation.

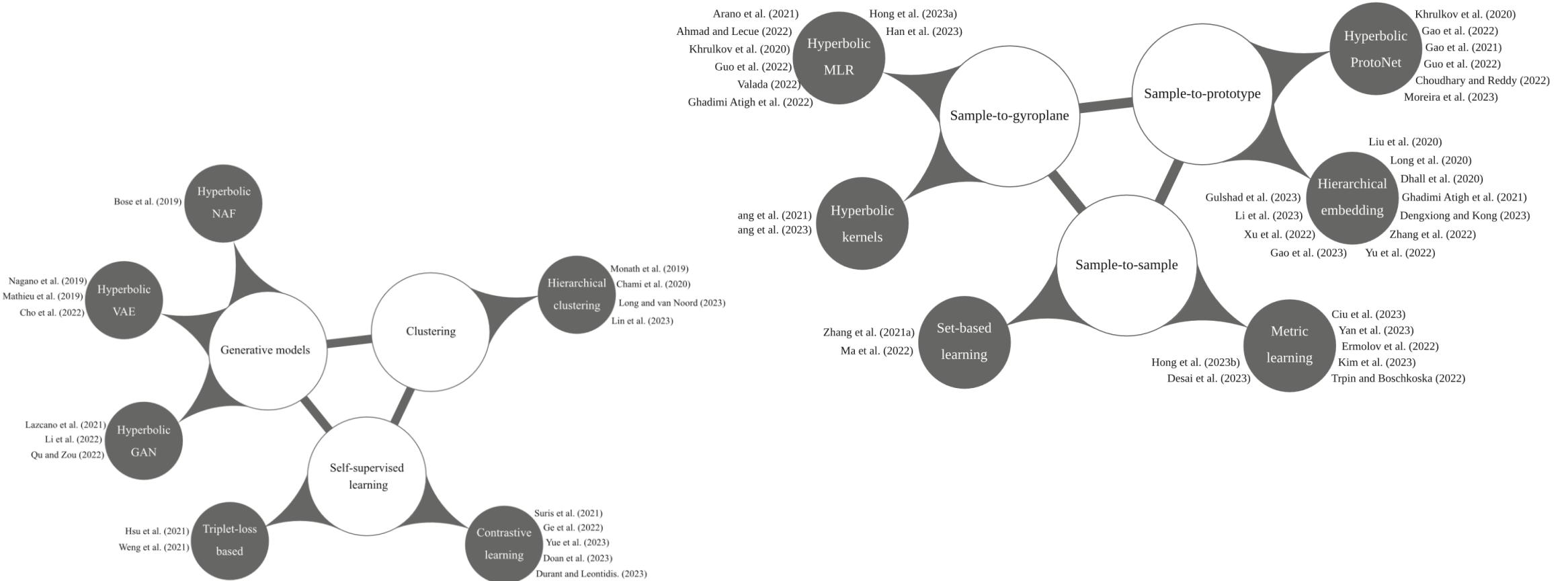
Open source community where is hyperbolic PyTorch?

Learning at scale we need an ImageNet/CLIP moment for hyperbolic learning.

Where to start?

Pascal Mettes, Mina Ghadimi, Martin Keller-Ressel, Jeffrey Gu, Serena Yeung. IJCV 2024

Hyperbolic Deep Learning in Computer Vision: A Survey





Where to start?

Max van Spengler, Philipp Wirth, Pascal Mettes. ACM MM 2024

HypLL: The Hyperbolic Learning Library

```
import hypll.nn as hnn
from hypll.manifolds.poincare_ball import (
    Curvature, PoincareBall
)

ball = PoincareBall(Curvature(1.0))
class HNet(nn.Module):
    def __init__(self):
        super().__init__()
        self.conv1 = hnn.HConvolution2d(3, 6, 5, ball)
        self.pool = hnn.HMaxPool2d(2, ball, 2)
        self.conv2 = hnn.HConvolution2d(6, 16, 5, ball)
        self.fc1 = hnn.HLinear(16 * 5 * 5, 120, ball)
        self.fc2 = hnn.HLinear(120, 84, ball)
        self.fc3 = hnn.HLinear(84, 10, ball)
        self.relu = hnn.HReLU(ball)

    def forward(self, x):
        x = self.pool(self.relu(self.conv1(x)))
        x = self.pool(self.relu(self.conv2(x)))
        x = x.flatten(1)
        x = self.relu(self.fc1(x))
        x = self.relu(self.fc2(x))
        x = self.fc3(x)
        return x
```

```
import torch.nn as nn

class Net(nn.Module):
    def __init__(self):
        super().__init__()
        self.conv1 = nn.Conv2d(3, 6, 5)
        self.pool = nn.MaxPool2d(2, 2)
        self.conv2 = nn.Conv2d(6, 16, 5)
        self.fc1 = nn.Linear(16 * 5 * 5, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.pool(self.relu(self.conv1(x)))
        x = self.pool(self.relu(self.conv2(x)))
        x = x.flatten(1)
        x = self.relu(self.fc1(x))
        x = self.relu(self.fc2(x))
        x = self.fc3(x)
        return x
```

https://github.com/maxvanspengler/hyperbolic_learning_library

Where to start?

Max van Spengler, Philipp Wirth, Pascal Mettes. ACM MM 2024

HypLL: The Hyperbolic Learning Library

```
from hypll.tensors import TangentTensor

for data in trainloader:
    inputs, labels = data

    tangents = TangentTensor(
        inputs, man_dim=1, manifold=ball
    )
    inputs_on_ball = ball.expmap(tangents)

    outputs = hnet(inputs_on_ball)
```

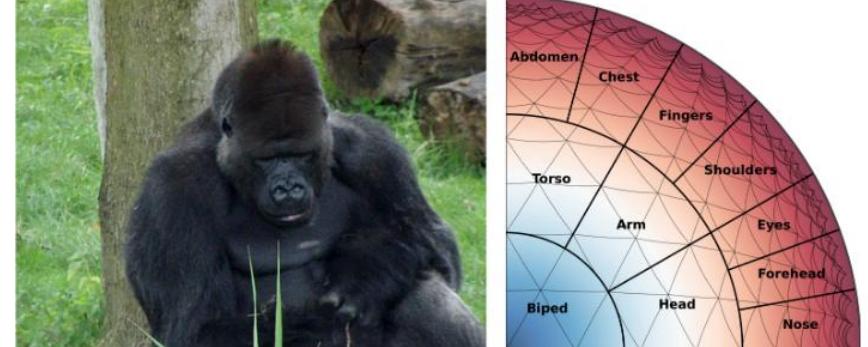
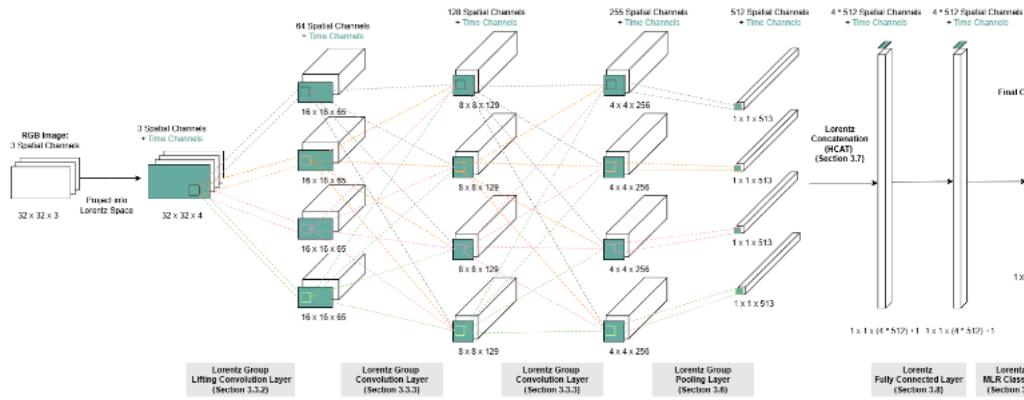
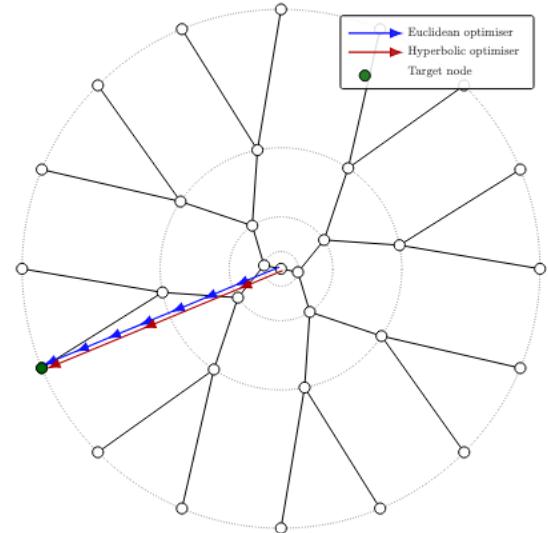
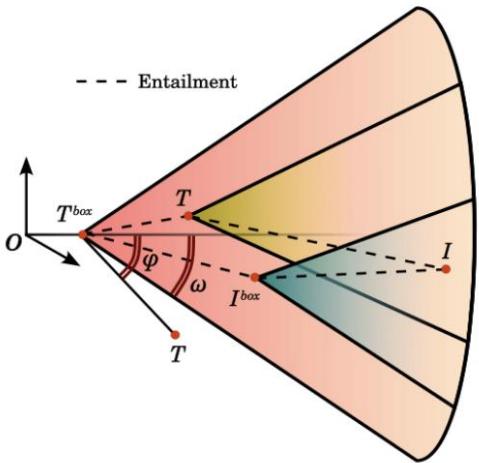
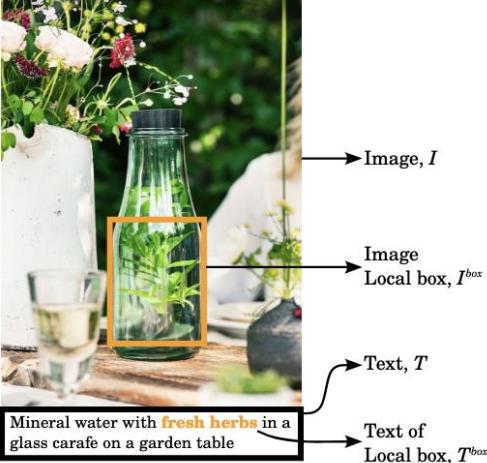
https://github.com/maxvanspengler/hyperbolic_learning_library



Where to start?

<https://www.youtube.com/@hyperboliclearningforcv/playlists>

Interested? Let's write a hyperbolic thesis!



Next lecture

Lecture	Title	Lecture	Title
1	Intro and history of deep learning	2	AutoDiff
3	Deep learning optimization I	4	Deep learning optimization II
5	Convolutional deep learning	6	Attention-based deep learning
7	Graph deep learning	8	From supervised to unsupervised deep learning
9	Multi-modal deep learning	10	Generative deep learning
11	What doesn't work in deep learning	12	Non-Euclidean deep learning
13	Q&A	14	Deep learning for videos