

# Homework 1 EE519.

## Problem 1.

(a) Sol:

$$\Rightarrow |y[n]| = \left| \sum_{k=-\infty}^{\infty} h_k[n] x[k] \right| \dots \text{eq(1)}$$

Now, assume  $|x[n]| \leq B_x < \infty, \forall n$   
i.e.,  $x[n]$  is a bounded input.

$\Rightarrow$  eq(1) can be represented as follows

$$\begin{aligned} |y[n]| &= \left| \sum_{k=-\infty}^{\infty} h_k[n] x[k] \right| \\ &\leq \sum_{k=-\infty}^{\infty} |h_k[n]| |x[k]| \\ &\leq B_x \cdot \sum_{k=-\infty}^{\infty} |h_k[n]| \dots \text{eq(2)} \end{aligned}$$

$$\textcircled{1} \text{ If } \sum_{k=-\infty}^{\infty} |h_k[n]| < \infty$$

Then  $|y[n]| < \infty$

$$\textcircled{2} \text{ If BIBO stable } \Rightarrow \sum_{k=-\infty}^{\infty} |h_k[n]| < \infty \forall n?$$

$$\Leftrightarrow \text{If } \sum_{k=-\infty}^{\infty} |h_k[n]| = \infty \exists n \text{ then non BIBO stable}$$

If  $h_k[n] = 1 \Rightarrow$  non BIBO stable  
such  $n$  exists.

$\Rightarrow$  by  $\textcircled{1}$  &  $\textcircled{2}$  statements

The system is BIBO stable

iff and only iff  $\sum_{k=-\infty}^{\infty} |h_k[n]| < \infty$   
 $\forall n$

$\therefore$  Q.E.D.

(b) It is worth reminding  
of meaning of causality

$\Rightarrow$  Causality: For  $\forall k > n$ ,  $y[n]$  is  
independent on  $x[k]$

$\Rightarrow$  for  $k > n$ ,  $h[n-k] = 0 = h_k[n]$

Let's see if each case  $\textcircled{1}$  &  $\textcircled{2}$  below  
satisfy causality.  
definition of

$\textcircled{1}$  If  $h_k[n] = 0$  for  $n < k$

$\Rightarrow y[n]$  is determined regardless  $x[n]$   
for  $n < k$

$\Rightarrow$  meaning it is causal

$\textcircled{2}$  If causal

$\Rightarrow y[n]$  is independent on  $x[n]$   
for  $n < k$

$\Rightarrow$  meaning  $h_k[n]$  for  $n < k$  has  
to be zero.

$\Rightarrow$  By  $\textcircled{1}$  &  $\textcircled{2}$  case,

the system is causal iff and only  
iff  $h_k[n] = 0$  for  $n < k$

Q.E.D.

## Problem 2.

$$(a) y[n] = \sin(2\pi x[n])$$

sol)

(i) linear?

$$\text{Let } x_1[n] \mapsto y_1[n]$$

$$x_2[n] \mapsto y_2[n]$$

$$\& x_1[n] + x_2[n] \mapsto y_3[n]$$

For a system to be a linear system  
 $y_3[n]$  should be equal to  $y_1[n] + y_2[n]$

$$\Rightarrow y_1[n] = \sin(2\pi x_1[n])$$

$$y_2[n] = \sin(2\pi x_2[n])$$

$$\Rightarrow y_3[n] = \sin(2\pi (x_1[n] + x_2[n]))$$

$$\neq y_1[n] + y_2[n]$$

$\therefore$  Non-linear system.

(1)



(Ti) Time invariant?

Let  $x[n] \rightarrow y[n]$

$x_1[n] \rightarrow y_1[n]$

Where  $x_1[n] = x[n-n_0]$

$\Rightarrow$  see if  $y_1[n] = y[n-n_0]$

$$\textcircled{1} y[n-n_0] = \sin(2\pi x[n-n_0])$$

$$\textcircled{2} y_1[n] = \sin(2\pi x_1[n]) \\ = \sin(2\pi x[n-n_0])$$

$$\Rightarrow y_1[n] = \sum_{k=n-n_0}^{n+n_0} x_1[k]$$

$$y_2[n] = \sum_{k=n-n_0}^{n+n_0} x_2[k]$$

$$y_3[n] = \sum_{k=n-n_0}^{n+n_0} x_3[k]$$

$$= \sum_{k=n-n_0}^{n+n_0} (x_1[k] + x_2[k])$$

$$= y_1[n] + y_2[n]$$

$\Rightarrow$  Linear System

$$\Rightarrow y[n-n_0] = y_1[n]$$

$\therefore$  Time Invariant system

(ii) Time invariant

Let  $x[n] \rightarrow y[n]$

$x_1[n] = x[n-n_1] \rightarrow y_1[n]$

(iii) Causal?

$y[n] = \sin(2\pi x[n])$  is not

depending on future value of  $x[n]$

$\Rightarrow$  causal system

see if  $x[n] = y[n-n_1]$

$$\Rightarrow y[n] = \sum_{k=n-n_0}^{n+n_0} x[k] \Rightarrow y[n-n_1] = \sum_{k=n-n_1-n_0}^{n-n_1+n_0} x[k] \dots \textcircled{1}$$

(iv) BIBO stable?

For all possible real values for  $x[n]$

$\Rightarrow y[n]$  is within  $-1$  &  $1$

$\Rightarrow$  BIBO stable system

$$\textcircled{2} y_1[n] = \sum_{k=n-n_0}^{n+n_0} x_1[k]$$

$$= \sum_{k=n-n_0}^{n+n_0} x[k-n_1]$$

$\textcircled{1}$  &  $\textcircled{2}$  are eventually same

Therefore

$$y_1[n] = y[n-n_1]$$

$\Rightarrow$  Time-Invariant system

$$(b) y[n] = \sum_{k=n-n_0}^{n+n_0} x[k]$$

(i) Linear?

Let  $x_1[n] \rightarrow y_1[n]$

$x_2[n] \rightarrow y_2[n]$

$x_3[n] = x_1[n] + x_2[n] \rightarrow y_3[n]$

see if  $y_3[n] = y_1[n] + y_2[n]$

(iii) Causal

$y[n]$  is dependent on future value of  $x[n]$

e.g.  $y[n]$  determined by  $x[n+n_0]$  where  $n_0 > 0$

$\Rightarrow$  Non causal

(2)

(IV) BIBO Stable?

$$\text{If } |x_1[k]| \leq B_k < \infty$$

$$\Rightarrow y_1[n] = \sum_{k=n-n_0}^{n+n_0} x_1[k] \\ \leq \sum_{k=n-n_0}^{n+n_0} B_k < \infty$$

because sum of finite terms.

$\Rightarrow$  BIBO stable system

(C)  $y[n] = n x[n]$

(i) Linear?

Let  $x_1[n] \xrightarrow{H} y_1[n]$

$x_2[n] \xrightarrow{H} y_2[n]$

$x_3[n] = x_1[n] + x_2[n] \xrightarrow{H} y_3[n]$

see if  $y_3[n] = y_1[n] + y_2[n]$

$\Rightarrow y_3[n] = n x_3[n] = n (x_1[n] + x_2[n])$  ... ①

$y_1[n] + y_2[n] = n x_1[n] + n x_2[n]$  ... ②

$\Rightarrow$  ① = ②  $\Rightarrow y_3[n] = y_1[n] + y_2[n]$

$\Rightarrow$  linear system

(ii) Time Invariant?

Let  $x[n] \xrightarrow{H} y[n]$

$x_1[n] = x[n-n_0] \xrightarrow{H} y_1[n]$

see if  $y_1[n] = y[n-n_0]$

$y[n-n_0] = (n-n_0) x[n-n_0]$  ... ①

$y_1[n] = n x_1[n]$

$= n x[n-n_0]$  ... ②

①  $\neq$  ②  $\Rightarrow$  Non time invariant

(iii) Causal?

$y[n]$  only depends on current value of  $x[n]$

$\Rightarrow$  Causal

(iv) BIBO stable?

Counter example

$n \rightarrow \infty \Rightarrow y[n] \rightarrow \infty$  even though  $x[n] < \infty$

$\Rightarrow$  Non BIBO stable.

(d)  $y[n] = 0.5^{n-1} x[n-1]$

sol:

(i) Linear?

Let  $x_1[n] \rightarrow y_1[n] = 0.5^{n-1} x_1[n-1]$

$x_2[n] \rightarrow y_2[n] = 0.5^{n-1} x_2[n-1]$

$x_3[n] = x_1[n] + x_2[n] \rightarrow y_3[n] = 0.5^{n-1} (x_3[n-1])$   
 $= 0.5^{n-1} (x_1[n-1] + x_2[n-1])$  ... ①

what is  $y_1[n] + y_2[n]$

$\Rightarrow y_1[n] + y_2[n] = 0.5^{n-1} x_1[n-1]$

$+ 0.5^{n-1} x_2[n-1]$

$= 0.5^{n-1} (x_1[n-1] + x_2[n-1])$

$=$  ①

$\Rightarrow y_3[n] = y_1[n] + y_2[n]$

$\Rightarrow$  Linear system.

(ii) Time invariant?

Let  $x[n] \rightarrow y[n] = 0.5^{n-1} x[n-1]$

$x_1[n] \rightarrow y_1[n] = 0.5^{n-1} x_1[n-1]$

$= x[n-n_0] = 0.5^{n-n_0-1} x[n-n_0-1]$

is  $y_1[n] = y[n-n_0]$ ?



$$\Rightarrow y[n-n_0] = 0.5^{n-n_0-1} x[n-1-n_0]$$

$$\neq y[n]$$

$\Rightarrow$  Non time invariant.

(iii) Causal?

$y[n]$  only depends on past

value of  $x[n]$ .

$\Rightarrow$  Causal system

(iv) BIBO stable?

$$0.5^{n-1} \leq B < \infty \text{ for } \forall n$$

$$\text{let } |x[n]| \leq B_x < \infty \text{ for } \forall n \text{ (Bounded input)}$$

$$\Rightarrow y[n] = 0.5^{n-1} x[n-1] \leq 0.5^{n-1} |x[n-1]| \leq B \cdot B_x < \infty$$

$\Rightarrow$  Bounded Output

$\Rightarrow$  BIBO stable system.

Problem 3.

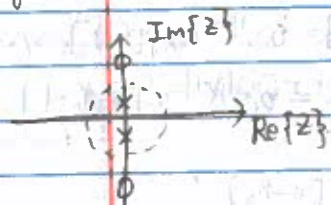
(a) (i) All-pass system

We can tell if a system is

an all-pass system by checking

If all poles & zeros are conjugate reciprocal to each other

(x)



all pass filter's zero pole plot

(ii) minimum phase system

We can call a system

a minimum phase system

If all zeros & poles of system are in the unit circle.

(b) Causal LTI

$$H(z) = \frac{(1+0.2z^{-1})(1-0.2z^{-2})}{1+0.8z^{-2}}$$

$$\Rightarrow = \frac{(1+0.2z^{-1})(1-3z^{-1})(1+3z^{-1})}{(1-0.9z^{-1})(1+0.9z^{-1})}$$

can be decomposed as follows

$$= \frac{(1+0.2z^{-1})(1+\frac{1}{3}z^{-1})(1-\frac{1}{3}z^{-1})}{(1-0.9z^{-1})(1+0.9z^{-1})} \times \frac{(1+3z^{-1})(1-3z^{-1})}{(1+\frac{1}{3}z^{-1})(1-\frac{1}{3}z^{-1})}$$

$$= H_{\text{apn}}(z) \times H_{\text{ap}}(z)$$

$$\Rightarrow H_{\text{apn}}(z) = \frac{(1+0.2z^{-1})(1+\frac{1}{3}z^{-1})(1-\frac{1}{3}z^{-1})}{(1-0.9z^{-1})(1+0.9z^{-1})}$$

$$H_{\text{ap}}(z) = \frac{(1+3z^{-1})(1-3z^{-1})}{(1+\frac{1}{3}z^{-1})(1-\frac{1}{3}z^{-1})}$$

(A)

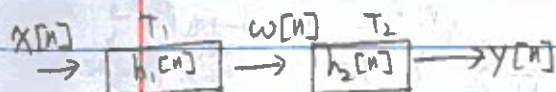


#### Problem 4

(a)

Sol)

LTI system



$$\Rightarrow y[n] = w[n] \oplus h_2[n] \dots (1)$$

$$w[n] = x[n] \oplus h_1[n] \dots (2)$$

by (1) & (2)

$$\Rightarrow y[n] = x[n] \oplus h_1[n] \oplus h_2[n]$$

$$= x[n] \oplus (h_1[n] \oplus h_2[n])$$

$$= x[n] \oplus h[n]$$

$$\Rightarrow h[n] = h_1[n] \oplus h_2[n]$$

(b) Let's use definition of convolution

$$\Rightarrow h_1[n] \oplus h_2[n] = \sum_{k=-\infty}^{\infty} h_1[k] h_2[n-k]$$

$$\text{Let } n-k=k'$$

$$\Rightarrow \sum_{k'=-\infty}^{\infty} h_1[n-k'] h_2[k']$$

$$\text{Let } k'=k$$

$$\Rightarrow \sum_{k=-\infty}^{\infty} h_1[n-k] h_2[k]$$

$$= h_2[n] \oplus h_1[n]$$

$$\Rightarrow h_2[n] \oplus h_1[n] = h_1[n] \oplus h_2[n]$$

(c)

$$H(z) = \left( \sum_{r=0}^M b_r z^{-r} \right) \left( \frac{1}{1 - \sum_{k=1}^N a_k z^{-k}} \right)$$

$$= H_1(z) H_2(z)$$

Sol)

$$\Rightarrow \frac{Y(z)}{X(z)} = \left( \sum_{r=0}^M b_r z^{-r} \right) \left( \frac{1}{1 - \sum_{k=1}^N a_k z^{-k}} \right)$$

$$= \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_M z^{-M}}{1 - (a_1 z^{-1} + a_2 z^{-2} + \dots + a_N z^{-N})}$$

$$\Rightarrow Y(z) \{ 1 - (a_1 z^{-1} + a_2 z^{-2} + \dots + a_N z^{-N}) \}$$

$$= X(z) \{ b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_M z^{-M} \}$$

inverse z-transform

$\Rightarrow$  Difference equation of the system

$$Y[n] - a_1 Y[n-1] - a_2 Y[n-2] - \dots - a_N Y[n-N]$$

$$= b_0 X[n] + b_1 X[n-1] + b_2 X[n-2] + \dots + b_M X[n-M]$$

#### Problem 5.

(a)

Sol) Let

$$\tilde{X}[k] = \sum_{m=-\infty}^{\infty} x[m] e^{-j \frac{2\pi}{N} km} \dots e^{j\theta(1)}$$

$$\tilde{X}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] e^{j \frac{2\pi}{N} kn} \dots e^{j\theta(2)}$$

plug in eq(1) to (2)

$\Rightarrow$  continue on the next

page.



$$\Rightarrow \hat{X}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \left( \sum_{m=-\infty}^{\infty} x[m] e^{-j \frac{2\pi}{N} km} \right) \cdot e^{j \frac{2\pi}{N} kn}$$

Assume all summations converge.

$$= \sum_{m=-\infty}^{\infty} x[m] \cdot \frac{1}{N} \sum_{k=0}^{N-1} e^{-j \frac{2\pi}{N} k(m-n)}$$

This term has a special representation

$$\Rightarrow \frac{1}{N} \sum_{k=0}^{N-1} e^{j \frac{2\pi}{N} k(m-n)} = \begin{cases} 1 & \text{for } m=n+1N \\ & r, n \text{ together} \\ 0 & \text{otherwise} \end{cases}$$

$$\Rightarrow \text{Let } m=n+1N$$

$$\Rightarrow rN = m-n$$

$$\Rightarrow r = \frac{m-n}{N} \Rightarrow r \text{'s range also } [-\infty, \infty]$$

$$\Rightarrow \sum_{r=-\infty}^{\infty} x[n+rN] \cdot 1$$

$$\therefore \hat{X}[n] = \sum_{r=-\infty}^{\infty} x[n+rN]$$

Q.E.D.

(b)

Sol

$$Y(e^{j\omega}) = \sum_{n=-\infty}^{\infty} y[n] e^{-j\omega n}$$

$$= \sum_{n=-\infty}^{\infty} x[nM] e^{-j\omega n}$$

$$\text{Let } nM=k$$

$$= \sum_{k=-\infty}^{\infty} x[k] \delta[\langle k \rangle_M] e^{-j\omega k/M}$$

$$\text{Let } k=n$$

$$= \sum_{n=-\infty}^{\infty} x[n] \delta[\langle n \rangle_M] e^{-j\omega n/M}$$

$$\text{Fact } \frac{1}{M} \sum_{k=0}^{M-1} e^{j \frac{2\pi}{M} kn} = \begin{cases} 1 & \text{for } n=0M \\ 0 & \text{for } n \neq 0M \end{cases}$$

use fact

$$= \sum_{n=-\infty}^{\infty} x[n] \cdot \frac{1}{M} \sum_{k=0}^{M-1} e^{j \frac{2\pi}{M} kn} \cdot e^{-j\omega n}$$

$$= \frac{1}{M} \sum_{k=0}^{M-1} \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} e^{j \frac{2\pi}{M} kn}$$

$$= \frac{1}{M} \sum_{k=0}^{M-1} X(e^{j(\omega - \frac{2\pi}{M} k)})$$

Q.E.D.

Problem 6.

(a) Please see my source code

TA my report / or you can see matlab files as well

(b)

$$r[n] = \begin{cases} 1 & 0 \leq n \leq L-1 \\ 0 & \text{otherwise} \end{cases}$$

$$= u[n] - u[n-L]$$

$$R(e^{j\omega}) = \sum_{n=-\infty}^{\infty} r[n] e^{-j\omega n}$$

$$= \sum_{n=0}^{\infty} u[n] - \sum_{n=0}^{\infty} u[n-L] \quad \downarrow \quad \left( \sum_{n=-\infty}^{\infty} u[n] = \frac{1}{1-e^{-j\omega}} \right)$$

$$= \frac{1}{1-e^{-j\omega}} - e^{-j\omega L} \cdot \left( \frac{1}{1-e^{-j\omega}} \right) \quad \oplus \text{DTFT shift property}$$

$$= \frac{1}{(1-e^{-j\omega})} \cdot (1-e^{-j\omega L})$$

$$= \frac{(e^{+j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}) \cdot e^{-j\frac{\omega}{2}}}{(e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}) \cdot e^{-j\frac{\omega}{2}}}$$

$$= \frac{\sin(\omega L/2)}{\sin(\omega/2)} \cdot e^{-j\omega(L-1)/2}$$

Q.E.D.

(c) Euler's formula

⊕ Plotting part is in my report.

$$\rightarrow d_b[n] = \sin\left(2\pi \cdot 941 \cdot \frac{1}{8000} \cdot n\right) + \sin\left(2\pi \cdot 1336 \cdot \frac{1}{8000} \cdot n\right)$$

(c)

When  $L=31$ , height of the mainlobe increases & number of positions of the points where the magnitude is equal to 0 increases as well.

$$= \sin(0.7391n) + \sin(1.0493n)$$

$$d_s[n] = \sin\left(2\pi \cdot 697 \cdot \frac{1}{8000} n\right) + \sin\left(2\pi \cdot 1336 \cdot \frac{1}{8000} n\right) \\ = \sin(0.5474n) + \sin(1.0493n)$$

In theory, as  $L$  increases,

maximum of  $|R(e^{j\omega})|$  is  $L$

As we observe,  $\max |R(e^{j\omega})| = 24$  with  $L=24$

&  $\max |R(e^{j\omega})| = 31$  with  $L=31$ .

Also, as  $L$  increases

term  $\omega L/2$  increases

meaning frequency of zero increases.

Therefore, pattern we could find in (c) & (b) agrees with theory.

(b) please check my answer in the report.

(c) & (e)

please check my report.

problem 7.

(a) sol)

$$d(t) = \sin(\omega_1 t) + \sin(\omega_2 t) \\ = \sin(2\pi f_1 t) + \sin(2\pi f_2 t) \\ (\because \omega = 2\pi f \text{ [rad/sec]})$$

$$\rightarrow d[n] = d(nT_s) \quad (\because t = nT_s)$$

$$\text{where } T_s = \frac{1}{8000}, f_s = 8000 \text{ Hz}$$

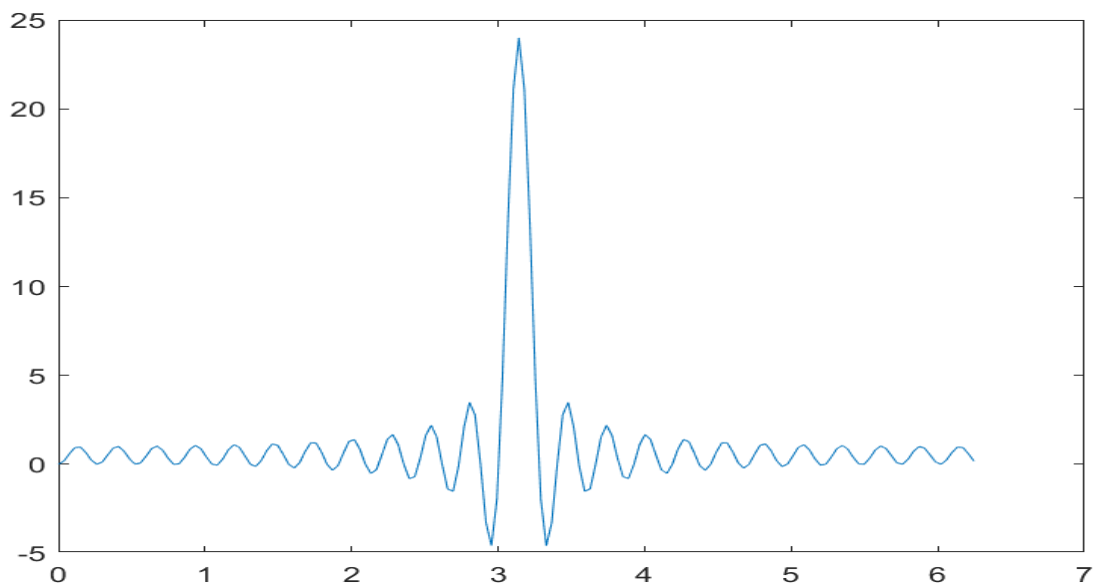


Problem6

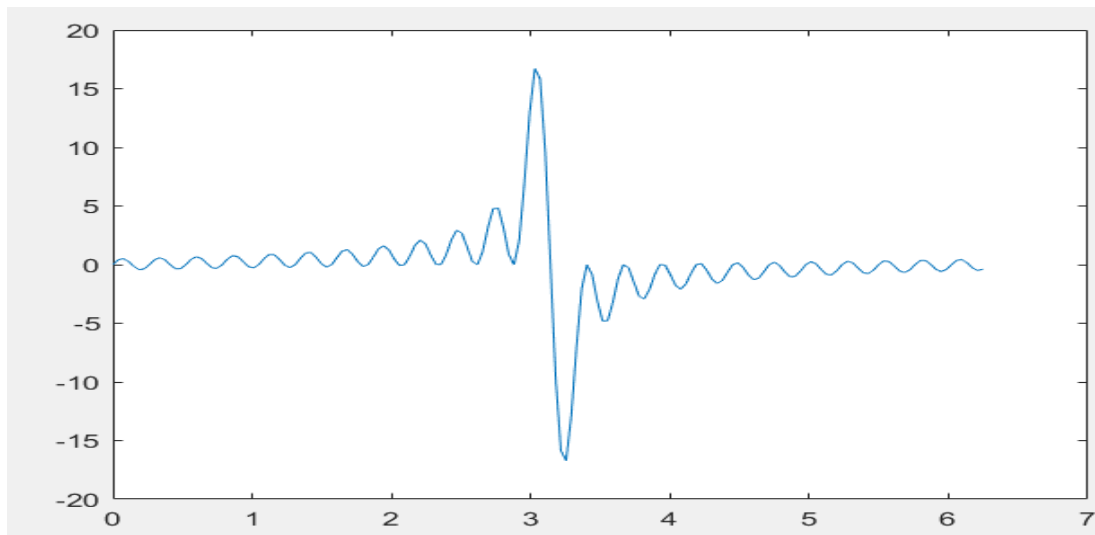
(b)

$$L = 24, N = 7 \times L$$

(1) Real part of R

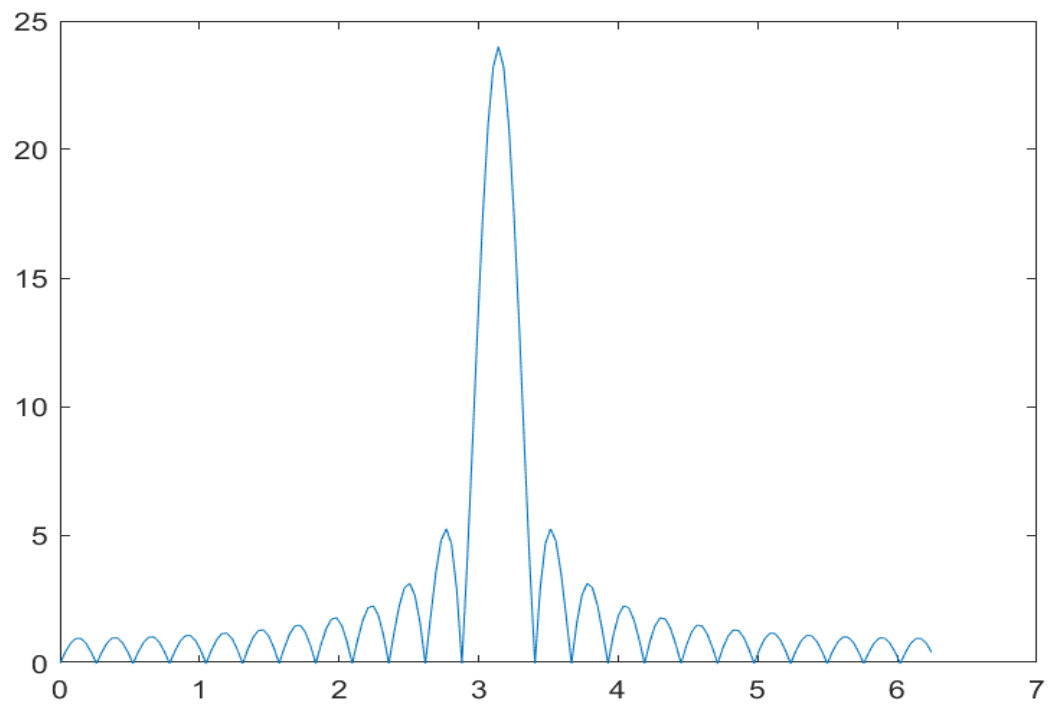


(2) Imaginary Part



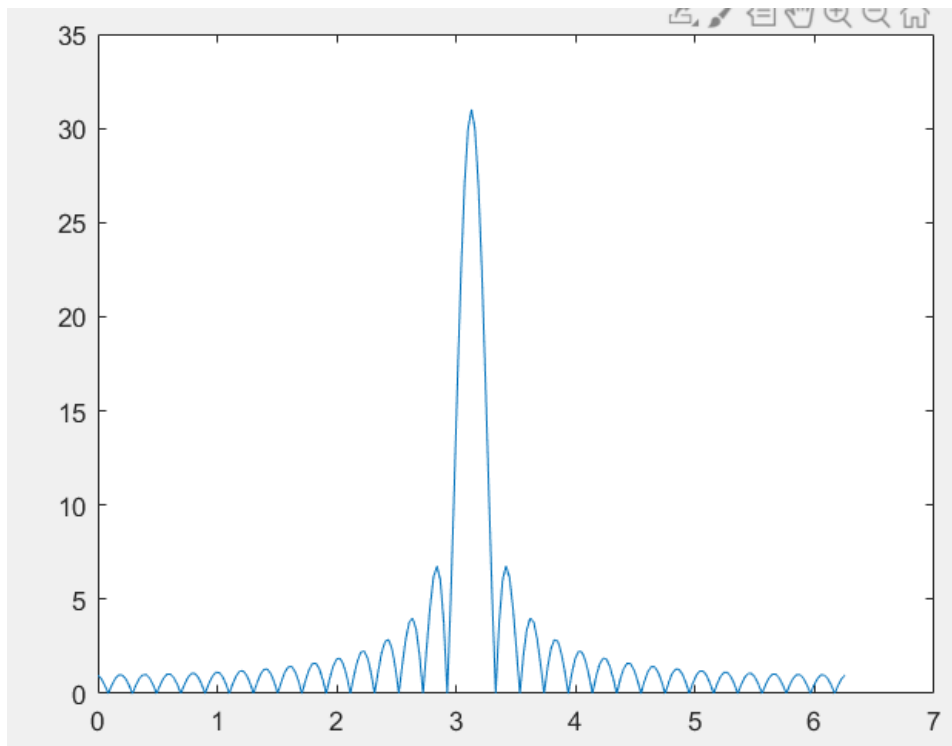


(3) Magnitude part



(c)

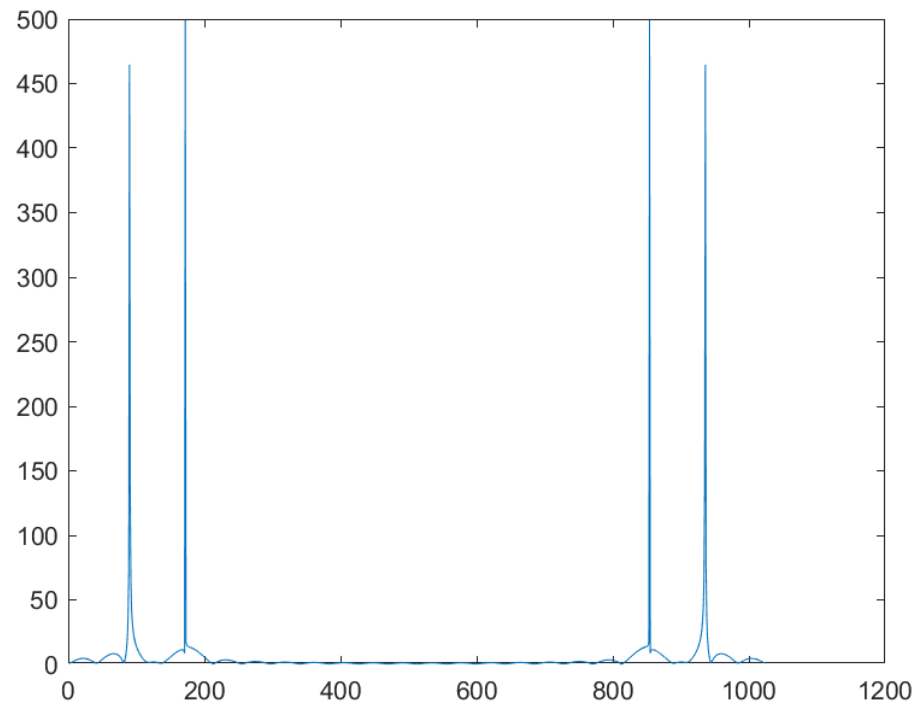
$L = 31, N = 7 \times L$



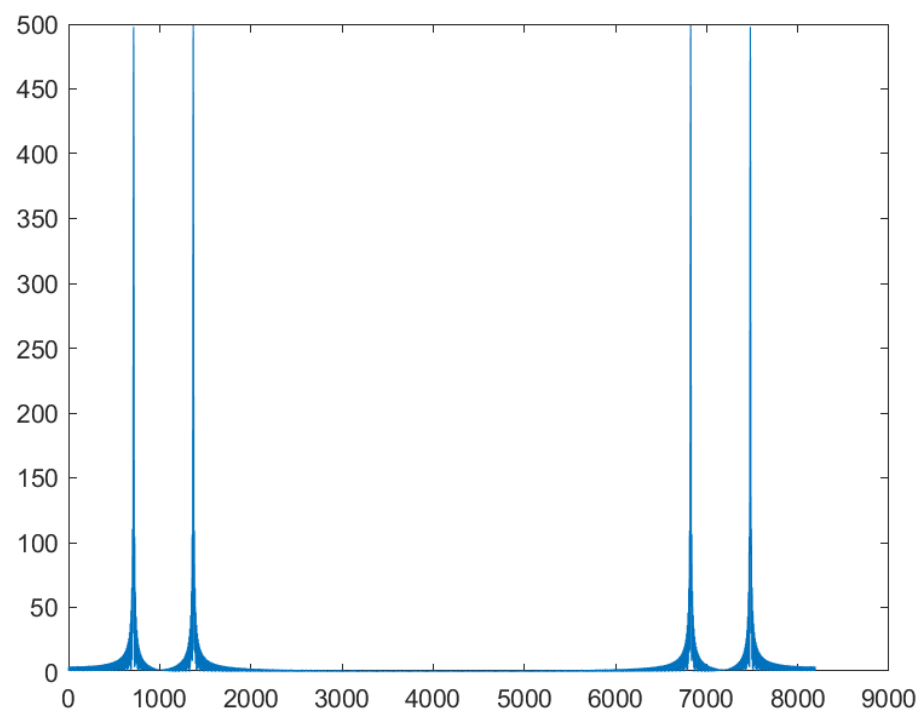
Problem7.

(b)

$N = 2^{10}$



$N = 2^{13}$





As we can observe, the case  $N = 2^{13}$  has fine resolution. Two peaks become closer with  $N = 2^{13}$ . Also, the results seem 4 Dirac pulses for each  $N$ , but not exactly the same. This is because length of  $N$  is finite.

(d)

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Please check my audio file, USCID.wav

(e)

Decoded numbers (Sig1) = 584730

Decoded numbers (Sig2) = 66874129

Decoded numbers (Sig3) = 50037