

Substitution in Multiple Integrals

Jacobian Determinant:

Jacobian of the transformation

$$x = g(u, v) \quad y = h(u, v) \quad \text{is}$$

$$J(u, v) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

Converting from cartesian to polar:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$J(r, \theta) = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$$

$$= r \cos^2 \theta + r \sin^2 \theta = r$$

$$\text{So, } dx dy = |J| dr d\theta$$

Cartesian \rightarrow cylindrical.

Jacobian transformation of $x = r \cos \theta$, $y = r \sin \theta$, $z = z$

$$J(r, \theta, z) = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix}$$

$$= \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

Expanding from R_3 ,

$$= r(\cos^2 \theta + \sin^2 \theta) = r \times 1 \\ = r$$

$$\text{So, } dz da dy = |J| r dz dr d\theta$$

Jacobian determinant for spherical coordinate.

$$x = \rho \sin \phi \cos \theta, y = \rho \sin \phi \sin \theta, z = \rho \cos \phi$$

$$J(\rho, \phi, \theta) = \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \phi} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \phi} & \frac{\partial y}{\partial \theta} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \phi} & \frac{\partial z}{\partial \theta} \end{vmatrix}$$

$$= \begin{vmatrix} \sin \phi \cos \theta & \rho \cos \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \cos \phi \sin \theta & \rho \sin \phi \cos \theta \\ \cos \phi & -\rho \sin \phi & 0 \end{vmatrix}$$

Expanding from R_3 ,

$$\begin{aligned} & \cos \phi (\rho \cos \phi \cos \theta \times \rho \sin \phi \cos \theta + \rho \cos \phi \sin \theta \times \rho \sin \phi \sin \theta) \\ & + \rho \sin \phi (\rho \sin \phi \cos \theta \times \sin \phi \cos \theta + \sin \phi \sin \theta \times \rho \sin \phi \sin \theta) \end{aligned}$$

$$= \cos \phi (\rho^2 \sin \phi \cos^2 \theta + \rho^2 \cos \phi \sin^2 \theta) + \rho \sin \phi (\rho \sin^2 \phi \cos^2 \theta + \rho \sin^2 \phi \sin^2 \theta)$$

$$= \{ \cos \phi \times \rho^2 \sin \phi \cos \phi (\cos^2 \theta + \sin^2 \theta) \} + \{ \rho \sin \phi \times \rho \sin^2 \phi (\cos^2 \theta + \sin^2 \theta) \}$$

$$= \rho^2 \cos^2 \phi \sin \phi + \rho^2 \sin^3 \phi \\ = \rho^2 \sin \phi$$

$$\text{So, } \int dz dy dx = \int \rho^2 \sin \phi d\rho d\phi d\theta$$

$$\text{eg: } x = h(u, v, w), y = g(u, v, w), z = k(u, v, w)$$

$$\iiint f(x, y, z) dx dy dz \\ = \iiint_a F(u, v, w) |J(u, v, w)| du dv dw$$

$$= \iiint_a F(r, \theta, \phi) r dr d\theta d\phi$$

$$= \iiint_a F(r, \phi, \theta) \rho^2 \sin \phi d\rho d\phi d\theta$$

Q.17: Evaluate $\int_0^3 \int_0^4 \int_{y/2}^{y/2+1} \left(\frac{2x-y}{2} + \frac{z}{3} \right) dx dy dz$ by applying the transformation.

$$u = \frac{2x-y}{2}, v = \frac{y}{2}, w = \frac{z}{3} \text{ and integrating}$$

over ~~the~~ appropriate region in uvw space.

Solⁿ:

Given,

$$\int_0^3 \int_0^4 \int_{y/2}^{y/2+1} \left(\frac{2x-y}{2} + \frac{z}{3} \right) dx dy dz$$

and transformation,

$$u = \frac{2x-y}{2}, v = \frac{y}{2}, w = \frac{z}{3}$$

Now,

$$u = \frac{2x-y}{2}$$

$$y = 2v$$

$$\text{or } 2u = 2x - 2v$$

$$\text{or } 2u = 2x - 2v$$

$$\text{or } x = u + v$$

$$z = 3w.$$

Again,

$$|J| = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

$$\frac{\partial x}{\partial u} = \frac{\partial (u+v)}{\partial u} = 1 \quad \frac{\partial y}{\partial u} = \frac{\partial (2v)}{\partial u} = 0$$

$$\frac{\partial z}{\partial u} = \frac{\partial (3w)}{\partial u} = 0 \quad \frac{\partial x}{\partial v} = \frac{\partial (u+v)}{\partial v} = 1$$

$$\frac{\partial y}{\partial v} = \frac{\partial (2v)}{\partial v} = 2 \quad \frac{\partial z}{\partial v} = \frac{\partial (3w)}{\partial v} = 0$$

$$\frac{\partial x}{\partial w} = \frac{\partial (u+v)}{\partial w} = 0 \quad \frac{\partial y}{\partial w} = \frac{\partial (2v)}{\partial w} = 0 \quad \frac{\partial z}{\partial w} = \frac{\partial (3w)}{\partial w} = 3$$

So,

$$|J| = \begin{vmatrix} 1 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{vmatrix} = 6$$

Now,

xyz eqⁿ

uvw eqⁿ

simplified form

$$x = y/2$$

$$u+v = v$$

$$u = 0$$

$$x = y/2 + 1$$

$$u+v = v+1$$

$$u = 1$$

$$y = 0$$

$$2v = 0$$

$$v = 0$$

$$y = 4$$

$$2v = 4$$

$$v = 2$$

$$z = 0$$

$$3w = 0$$

$$w = 0$$

$$z = 3$$

$$3w = 3$$

$$w = 1$$

So,

$$\int_0^3 \int_0^4 \int_{y/2}^{y/2+1} \left(\frac{2x-y}{2} + \frac{z}{3} \right) dx dy dz = \int_0^1 \int_0^2 \int_0^1 (u+w) \cdot 6 du dv dw$$

$$= 6 \int_0^1 \int_0^2 \int_0^1 (u+w) du dv dw.$$

$$\begin{aligned}
 &= 6 \int_0^1 \int_0^2 \left(\frac{u^2 + vw}{2} \right)^2 dv dw \\
 &= 6 \int_0^1 \int_0^2 \left(\frac{1}{2} + w \right) dv dw \\
 &= 6 \int_0^1 \left(\frac{v}{2} + vw \right)_0^2 dw \\
 &= 6 \int_0^1 (1 + 2w) dw \\
 &= 6 \left(w + w^2 \right)_0^1 \\
 &= 6(1+1) = 12
 \end{aligned}$$

(x): Steps to solve:

- (i): Find x, y, z in terms of u, v, w .
- (ii): Find Jacobian determinant.
- (iii): xyz eq^s, uvw eq^s, simplified form table. Relating with integral range to find new range.
- (iv): write the transformed integral
- (v): solving integral.

{Q}: Evaluate:

$$(i): \int_0^{2\pi} \int_0^1 \int_{-1/2}^{1/2} (r^2 \sin^2 \theta + 3z^2) dz dr d\theta$$

Sol.

$$\begin{aligned}
 &= \int_0^{2\pi} \int_0^1 \left[r^2 \sin^2 \theta z + \frac{3z^3}{3} \right]_{-1/2}^{1/2} dr d\theta \\
 &= \int_0^{2\pi} \int_0^1 \left\{ \left(r^2 \sin^2 \theta \times \frac{1}{2} + \frac{(1/2)^3}{3} \right) - \left(r^2 \sin^2 \theta \times \left(-\frac{1}{2} \right) + \frac{(-1/2)^3}{3} \right) \right\} dr d\theta \\
 &= \int_0^{2\pi} \int_0^1 \left(\frac{r^2 \sin^2 \theta}{2} + \frac{1}{24} + \frac{r^2 \sin^2 \theta}{2} + \frac{1}{24} \right) dr d\theta \\
 &= \int_0^{2\pi} \int_0^1 \left(r^2 \sin^2 \theta + \frac{1}{12} \right) dr d\theta \\
 &= \int_0^{2\pi} \left(\frac{r^3}{3} \sin^2 \theta + \frac{r}{12} \right)_0^1 d\theta \\
 &= \int_0^{2\pi} \left(\frac{\sin^2 \theta}{3} + \frac{1}{12} \right) d\theta \\
 &= \int_0^{2\pi} \frac{\sin^2 \theta}{3} d\theta + \int_0^{2\pi} \frac{1}{12} d\theta = \int_0^{2\pi} \left[\frac{\theta}{12} \right]_0^{2\pi} + \int_0^{2\pi} \frac{\sin^2 \theta}{3} d\theta \\
 &= \frac{2\pi}{12} + \frac{1}{3 \times 2} \int_0^{2\pi} (1 - \cos 2\theta) d\theta = \frac{\pi}{6} + \frac{1}{6} \left[\int_0^{2\pi} 1 \cdot d\theta - \int_0^{2\pi} \cos 2\theta d\theta \right]
 \end{aligned}$$

$$= \frac{\pi}{6} + \frac{1}{6} \times 2\pi - \frac{1}{6} \times [\cos 4\pi - \cos 0]$$

$$= \frac{\pi}{6} + \frac{2\pi}{6} = \frac{3\pi}{6} = \frac{\pi}{2}$$

