Parallel Reinforcement Learning (Q-Learning)

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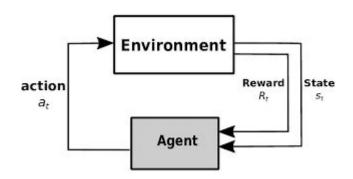
Q-Learning

Q-learning is a **Reinforcement Learning** (RL) method that deals with the problem of learning to **control autonomous agents**. The learning process works based on interactions by **trial and error** with a dynamic environment which provides **reward** signals for each **action** the agent executes.

Bellman equation in Q-value form:

$$Q^{\pi}(s,a) = \mathbb{E}[r_{t+1} + \lambda r_{t+2} + \lambda^2 r_{t+3} + \dots | s,a]$$

= $\mathbb{E}_{s'}[r + \lambda Q^{\pi}(s',a')|s,a]$



Q-learning Algorithm

```
Initialize (with 0's or random values) Q(s,a) for all s ∈ S and for all a ∈ A(s)
Repeat (for each episode)
Initialize s
Repeat (for each step episode):
Choose a from s using a policy derived from Q (e.g., ∈-greedy)
Take actiona, observe resultant state s' and the reward r.
Q(s,a) ← Q(s,a) + α[r + γ max<sub>a</sub>,Q(s',a') - Q(s,a)]
Greedy algorithm
S ← s';
until s is terminal
```

```
s: Sate.
a: Action.
r: Reward.
alpha: Learning rate parameter.
gamma: Decay rate (future reward discount) parameter.
```

Q-table

 A table with the Q value for every <S, A> pair.

OpenMPI (multi processors)

Initialized

Q-Table		Actions								
Q-12	ible			East (2)	West (3)	Pickup (4)	Dropoff (5)			
		0	0	0	0	0	0			
			·							
		•	•		•	•				
States	327	0	0	0	0	0	0			
		•	•	•		•				
		0	0	0	0	0	0			



	Q-Table		Actions							
			South (0)	North (1)	East (2)	West (3)	Pickup (4)	Dropoff (5)		
			0	0	0	0	0	0		
			·							
						•_				
St	tates	328	-2.30108105	-1.97092076	-2.30357004	-2.205 839	-10.3607344	-8.5583017		
			•	. 🔻			•			
		499	9.96984239	4.02706992	12.96022777	29	3.32877873	3.38230603		

Objectives

- Select the RL problem for performance comparison.
- Parallelize Q-learning by splitting the Q-table.
- Find an efficient way of information exchange.
- Compare its performance with serial code.
- Compare the performance for a different number of processors.