

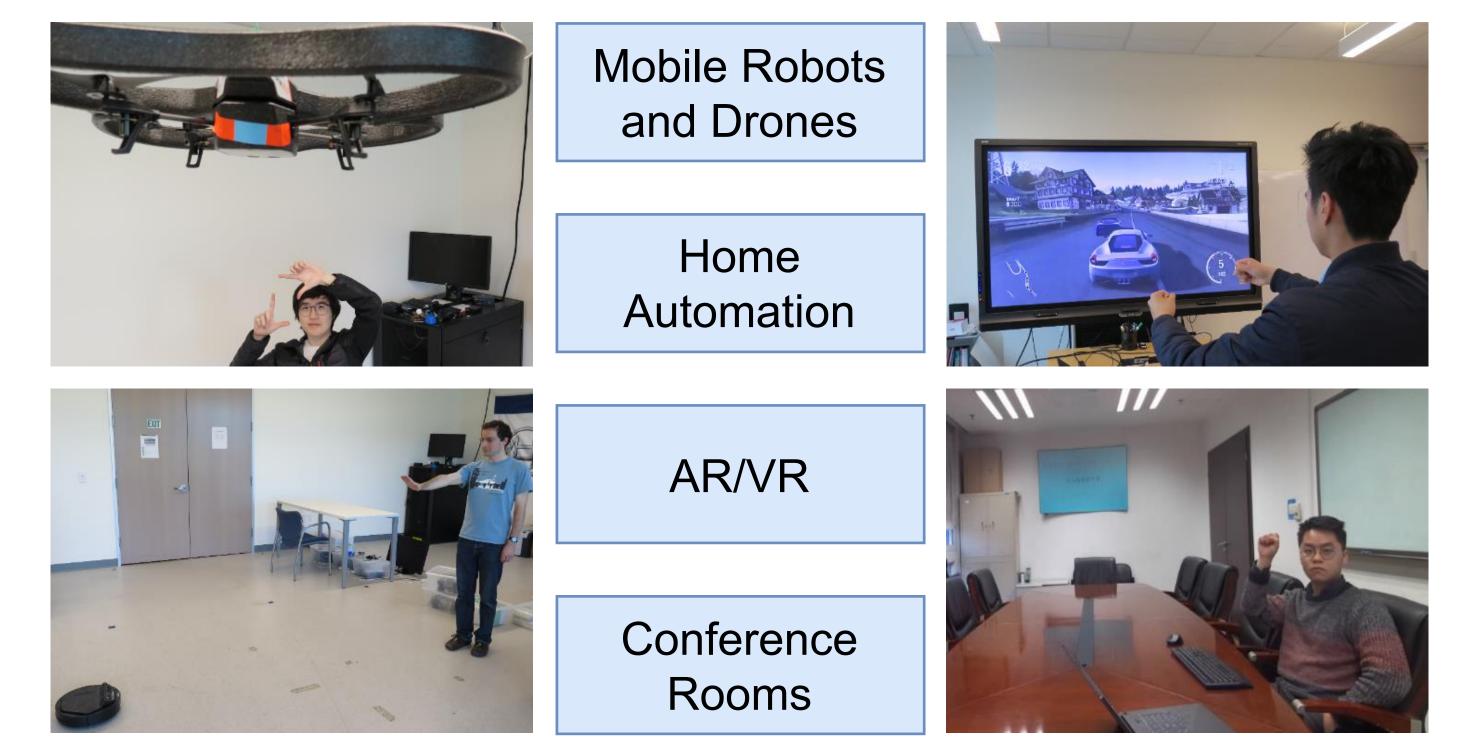
# Long-Distance Gesture Recognition using Dynamic Neural Networks

[ILLINOIS

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#### Motivation



- Gestures are a natural interface for communication between humans and machines
- Provide a convenient and contact-less way to communicate with robots

## Challenges in Long Distance Recognition

Gesturing subject is small



3D CNNs down sample input

Features might lose too much gesture informati on

Higher resolution video requires more compute, bandwidth!

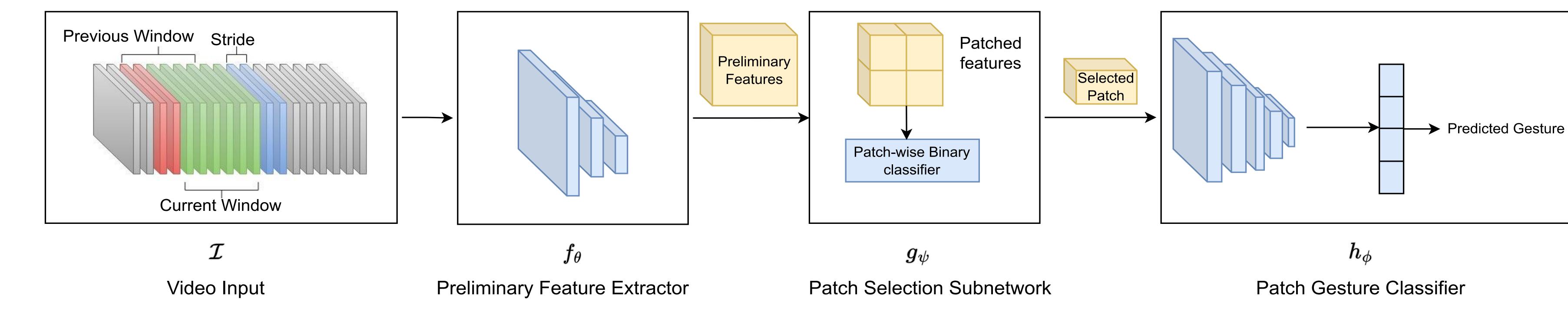
### Use Spatially Dynamic Neural networks

Can adapt computational graph to input at run-time

Discard background features

Preserve gesturing subject features

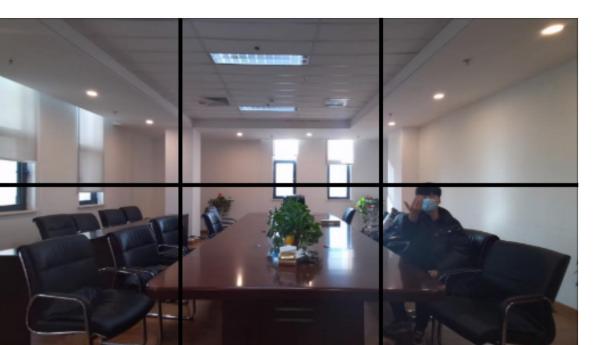
## **Proposed Spatially Dynamic Neural Network**



#### **Binary Gesture Classifier**

- Core of Patch selection subnetwork
- Predicts if input patch features contain subject
- Trained using rough subject location annotations

# **Preliminary Features** No Gesture

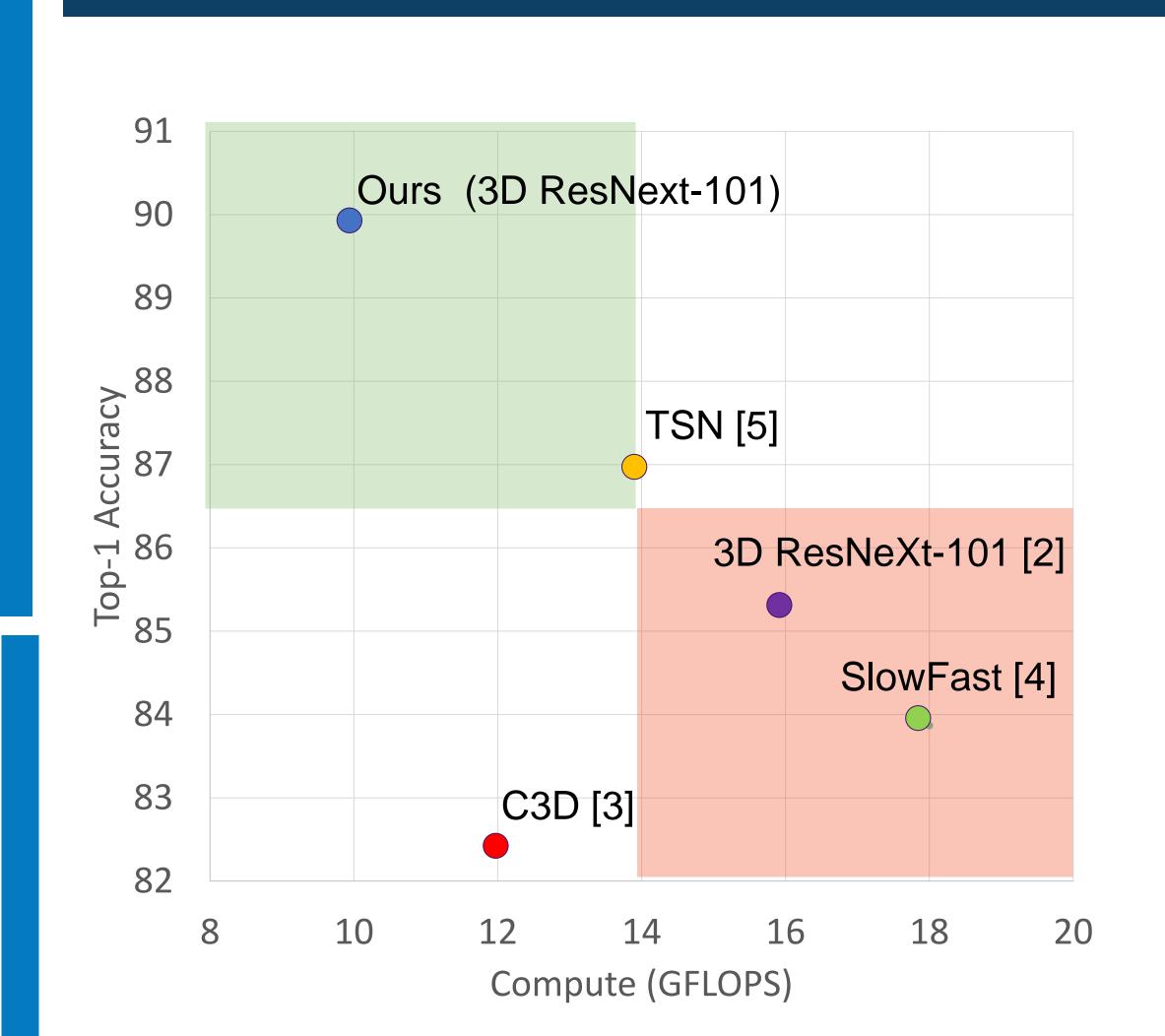


Selected Patch

Discarded Patches

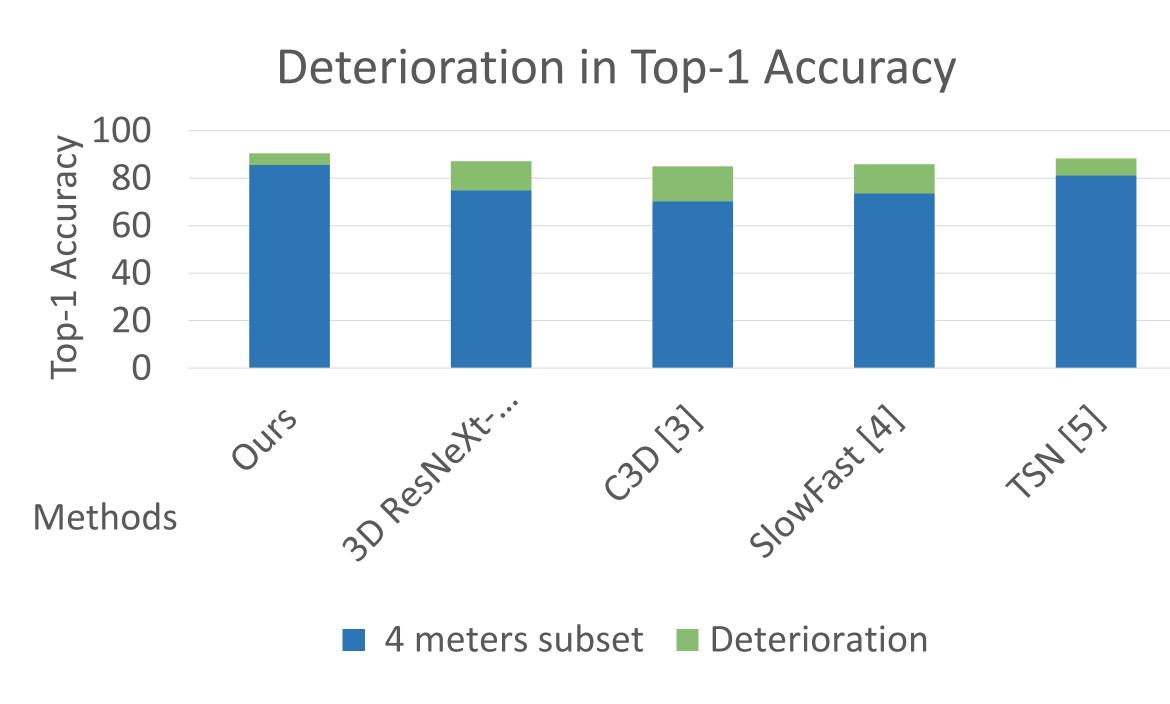


 $L = L_{h_{\phi}} + \lambda L_{g_{\psi}}$   $L_{h_{\phi}}$  = Cross entropy for Gesture Recognition  $L_{g_{\eta}}$  = Cross entropy for Patch Selection



Method	Compute (GFLOPS)	•
Ours (3D MobileNet)	1.5	76.68
3D MobileNet [6]	1.5	65.33

# **Experimental Results**



Num of patches (m x n)	Compute (GFLOPS)	Accuracy %
1 x 2	26	86.48
2 x 2	18	88.67
2 x 3	10	89.94

- Lower compute & Better performance compared to state-ofthe-art
- Lower performance deterioration with distance
- Smaller patches improve accuracy, efficiency

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