

Or S implements X, Y, Z

\* This is the minimum requirement, S might implement many more interfaces.

ABC is a generic class that contains generic type of objects S.

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Overloaded functions

B 5 (a) (i) They have the same signature except for the param. list.

i.e. ~~return type~~ <sup>or</sup> ~~number~~ <sup>types</sup> of arguments or both will be the same, just

(ii) Function body is redefined.

(iii) Library functions can be overloaded too  
(saw one in stack overflow)

(iv) Constructors can be overload, but not destructors

(v) using :  
void f1(int &x);  
void f1(int x);  
} involving by  
int x = 10;  
f1(x);

(vi) Overloaded functions have different addresses.  
(for obvious reasons) can cause  
ambiguity

```

5b) int& f()
{
    return x;
}

```

here  
`int a = f();` is the same as  
 (works as) `a = x;`  
 working as r-value.

again, ~~int~~ `f() = a;` is also possible,  
~~if int~~ it is like `x = a;` working as l-value

5c) Bitwise copy; copy constructor is called

Includes address/  
 ref. copy too which  
 Sometimes causes  
 Various problems

- where at the declaration statement
- When object is passed by value to a function as an argument
- When a func. returns an object & received by a same class's obj.

6a) class Frame body should be given a forward declaration or the body MUST be given at the beginning.

In the Frame class:

adding the following two functions:

```

void setWidth(int x){
    width = x;
}

```



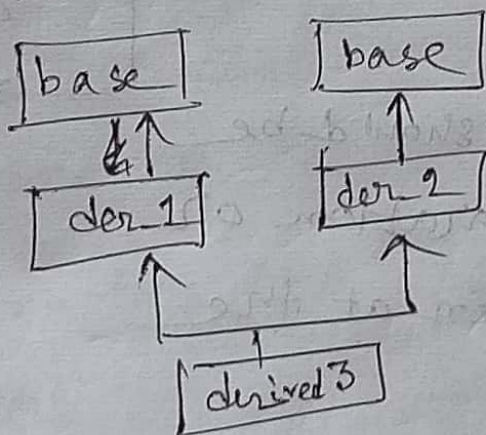
```
void setLength (int x) {
    length = x;
}
```

In the ~~ptr~~ Photo class; adding the following operator overloading def<sup>n</sup>.

```
frame operator+(int x) {
    frame f;
    f.setWidth(this->getWidth()+x);
    f.setLength(this->getLength()+x);
    return f;
}
```

Code: [github.com/Idtida01/TF-Codes-1-2-Aree/main](https://github.com/Idtida01/TF-Codes-1-2-Aree/main)

6(b) Yes, it is possible,



Now derived 3 has 2 copies (more than 2 is also possible) of base class

```
class base {
public: int x;
};
```

```
class der_1 : public base {
```

```
public:
    int y;
};
```

```
class der_2: public base
{
public:
    int z;
};
```

```
class derived3: public der_1, public der_2
{
public:
    int t;
};
```

```
int main() {
    derived3 obj;
    obj.x = 100; // will be an ambiguous assignment
}
```

To avoid this: using

```
① class der_1: virtual public base {
// class der_1: virtual public base {
```

or, ① obj.der\_1::x = 100; // OK  
obj.der\_2::x = 200; // OK



7a) [Kindly go through the slides please]

7b) (i): 1st parameter is a stream, we don't have access to the stream objects, so they are external entities to the class. So they must be either friends of the concerning class or a public method.

(ii) cout can be used, but naming conventions will be violated. [I know a little about the answer to the current Q]

8a) Inc. signatures to be added in the Fraction class:

public:

friend Fraction& operator++(Fraction& fr);

~~void~~ setX(int x);

void setY(int y);

Definitions:

Fraction& operator++(Fraction& fr) {

fr.setX(~~x+1~~); fr.setX(fr.getX()+1);

fr.setY(fr.getY()+1);

return fr;

}

void Fraction::setX(int x) {

{ this->x = x;

```
void Fraction::setY(int y) {
    this->y = y;
}
```

8(b) → Out of syllabus.

(c) If we want to count the number of objects <sup>of the class</sup> present in the current execution time, we can have a static member variable, like this (↓)

```
class hello {
    static int count = 0;
    hello() {
        ++count;
    }
    ~hello() {
        to --count;
    }
};
```