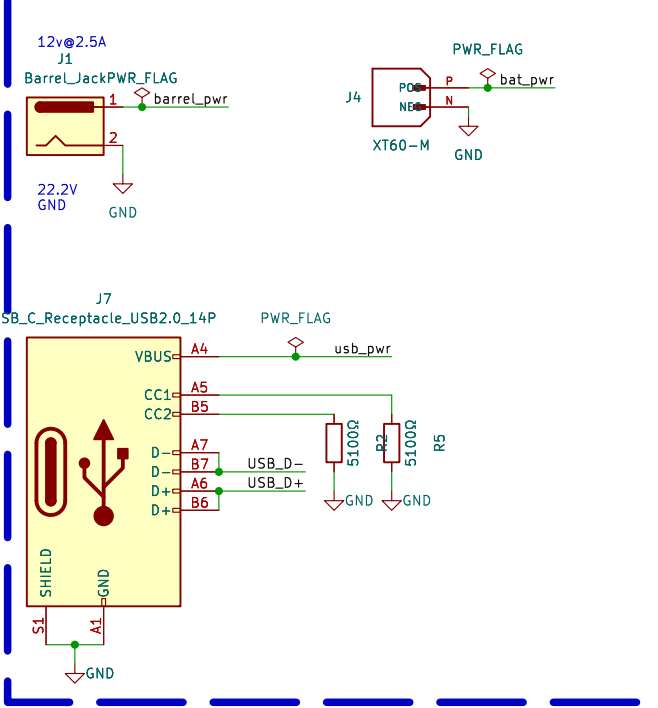


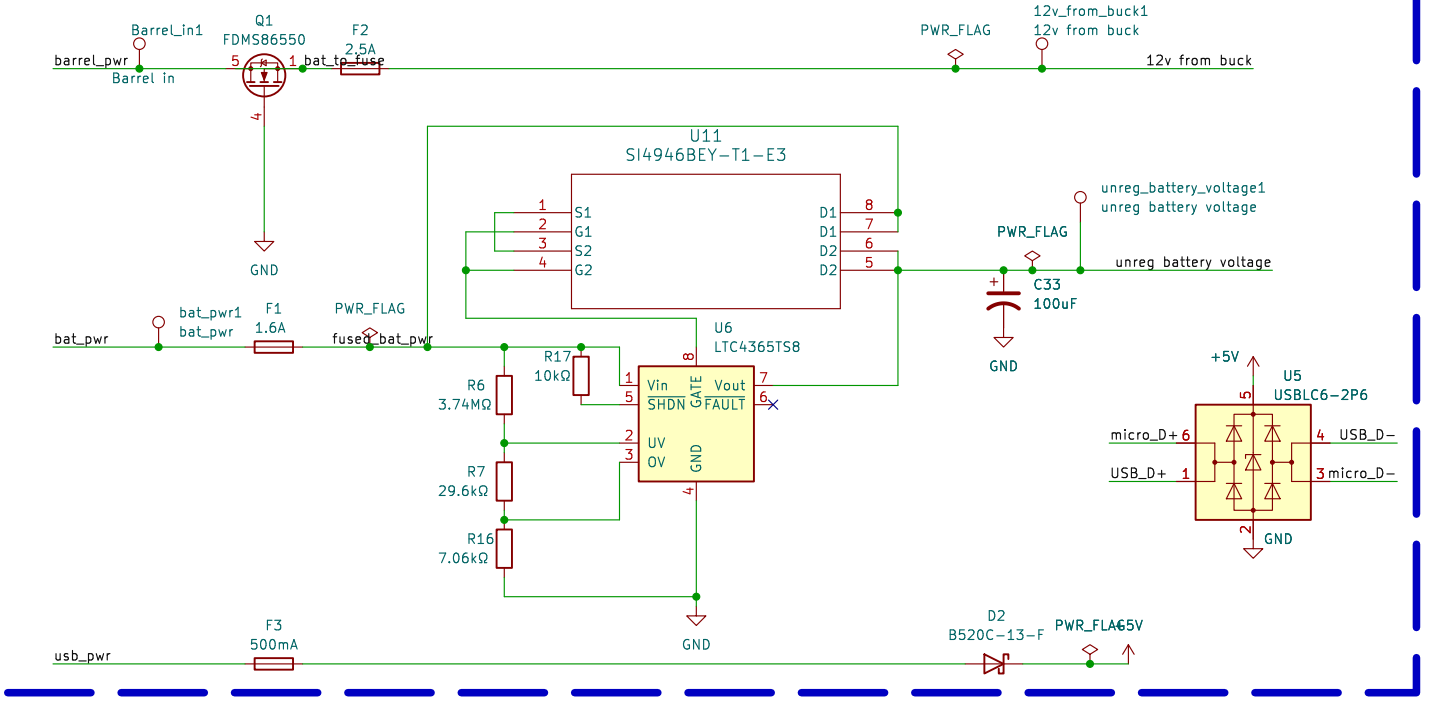
Telemetry Tracker PCB

Power

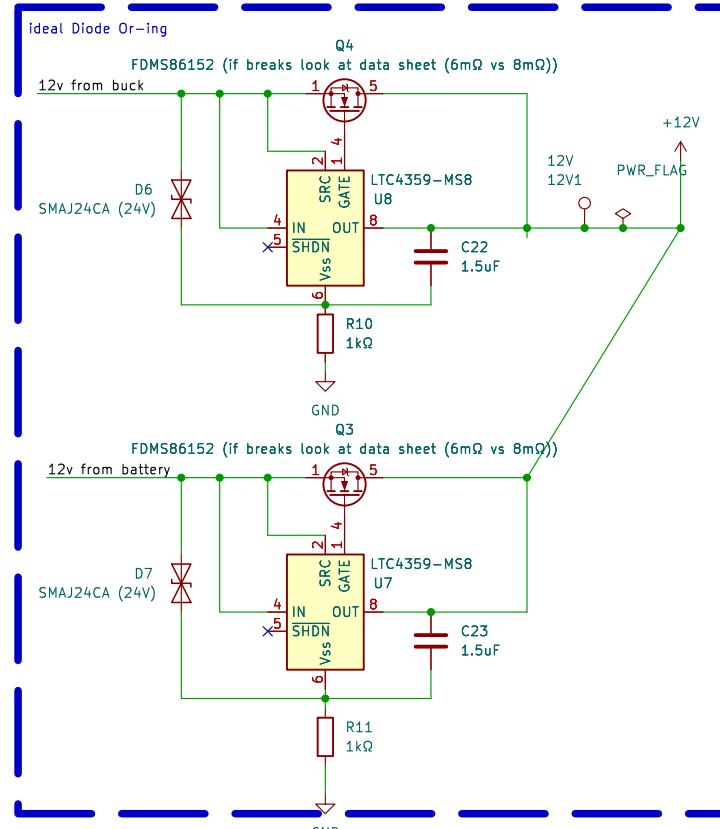
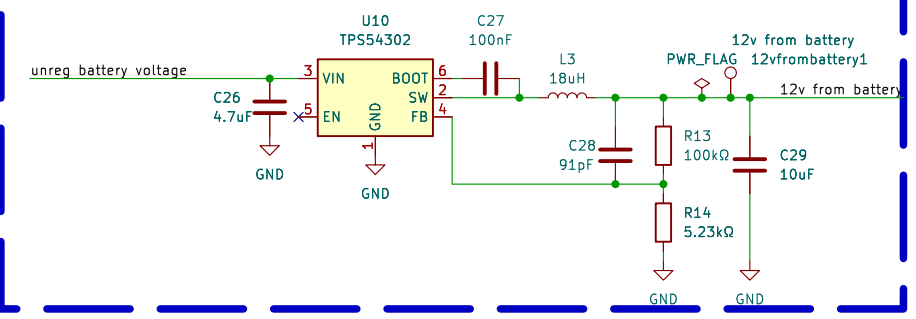
Power In



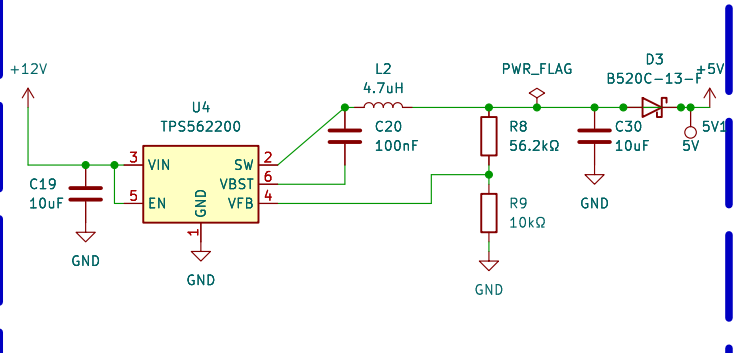
Protection Circuits



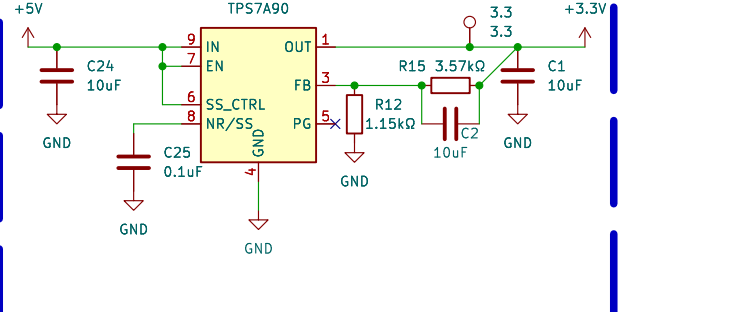
battery voltage -> 12v stepdown buck



12 -> 5v stepdown buck



5V -> 3.3v stepdown LDO

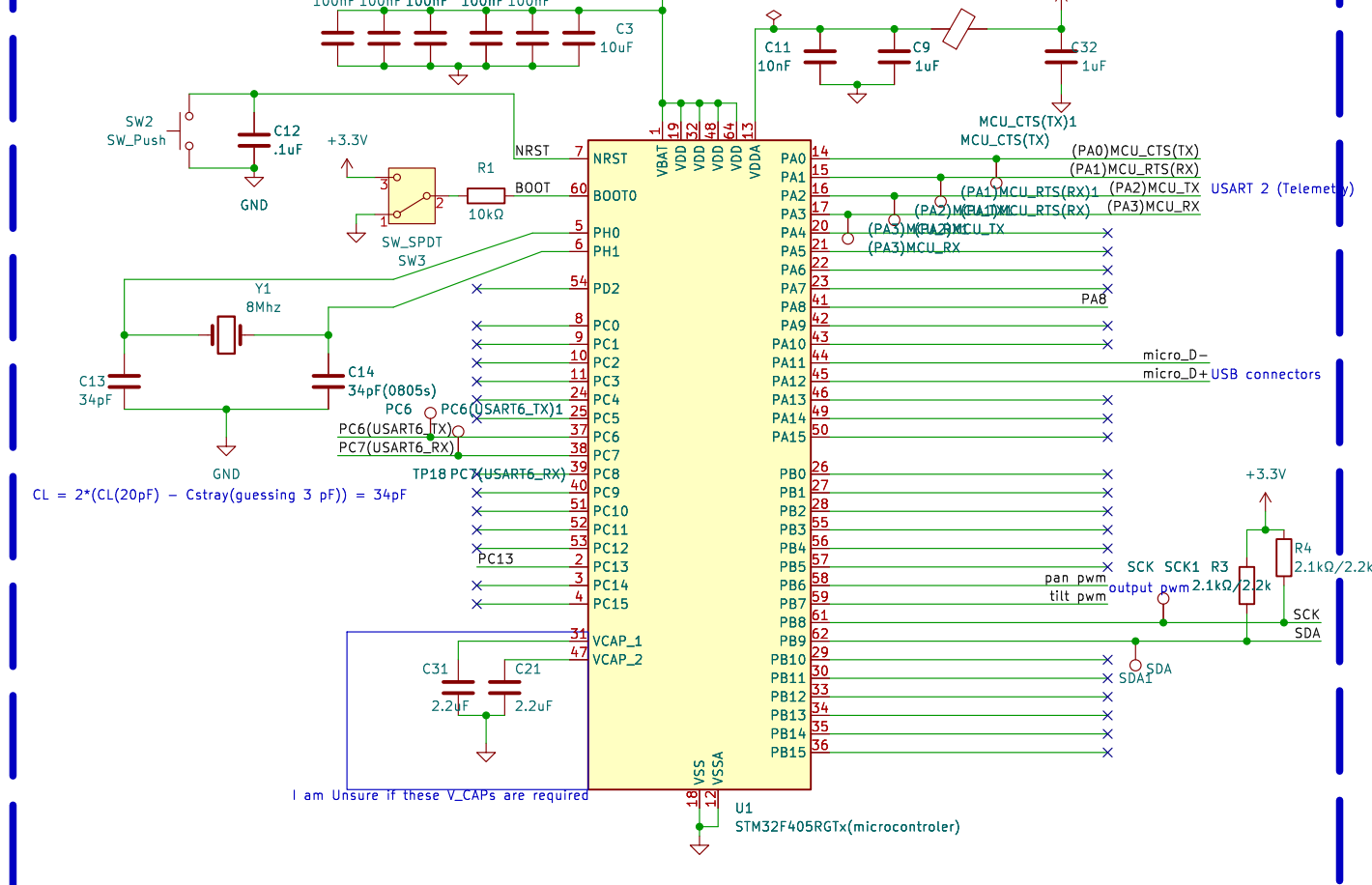


Mounting Holes

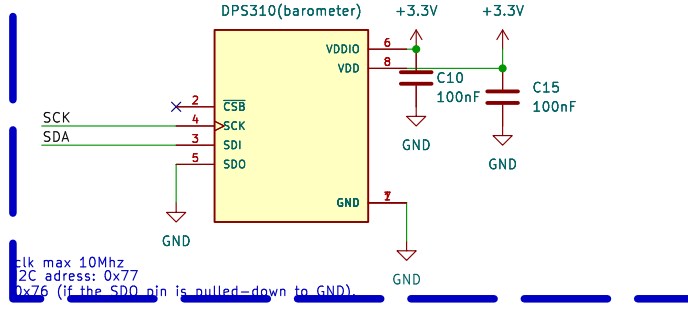


Control

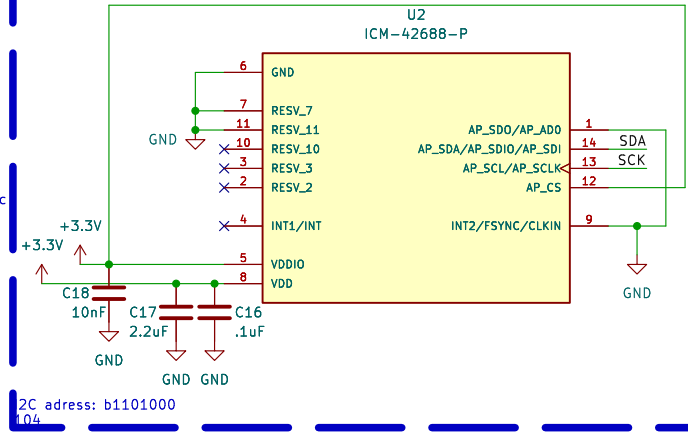
MCU



Barometer



IMU



Output

PWM out pins(specialized pins)

