

# LAB-1

Implement a vacuum cleaner agent

Algorithm:-

1) Initialize

Set goal-state =  $\langle 'A' : '0', 'B' : '0' \rangle$

Set cost = 0

2) Input

- Get the current location of vacuum cleaner as 'A' or 'B'
- Get the status of the current location, where '0' means clean and '1' means dirty (status-input)
- Get the status of the other location, where '0' means clean and '1' means dirty (status-input-complement)
- If the vacuum cleaner is at location A:
  - If location A is dirty (status-input == '1')
  - Clean location A (set goal-state['A'] = '0')
  - Increment the cost by 1 for cleaning location A
  - Print the status of cleaning
- If the vacuum cleaner is at location B:
  - If location B is dirty (status-input-complement == '1')
  - Move to location B (increment the cost by 1 for movement)
  - Clean location B (set goal-state['B'] = '0')
  - Increment the cost by 1 for cleaning location B
  - If location B is clean (status-input-complement == '0'):
    - No action needed for location B

- If the vacuum cleaner is at location B:
- If location B is dirty (status-input == '1'):
  - Clean location B (set goal state ['B'] = '0').
  - Increment the cost by 1 for cleaning location B
  - Print the status of cleaning

- If location A is dirty (status-input-complement == '1'):
- Move to location A (increment the cost by 1 for movement).
  - Clean location A (set goal-state ['A'] = '0').
  - Increment the cost by 1 for cleaning location A
  - If location A is clean (status-input-complement == '0'):
  - No action needed for location A

Expected output :-

- Print the final goal-state (both locations should be clean).
- Print the total cost (cleaning & moving actions)

Output :-

Enter Location of Vacuum (A or B) : A

Enter status of A (0 for Clean, 1 for Dirty) : 1

Enter status of other room (0 for clean, 1 for Dirty) : 0

Initial location Condition : ('A' : '0', 'B' : '0')

Vacuum is placed in location A

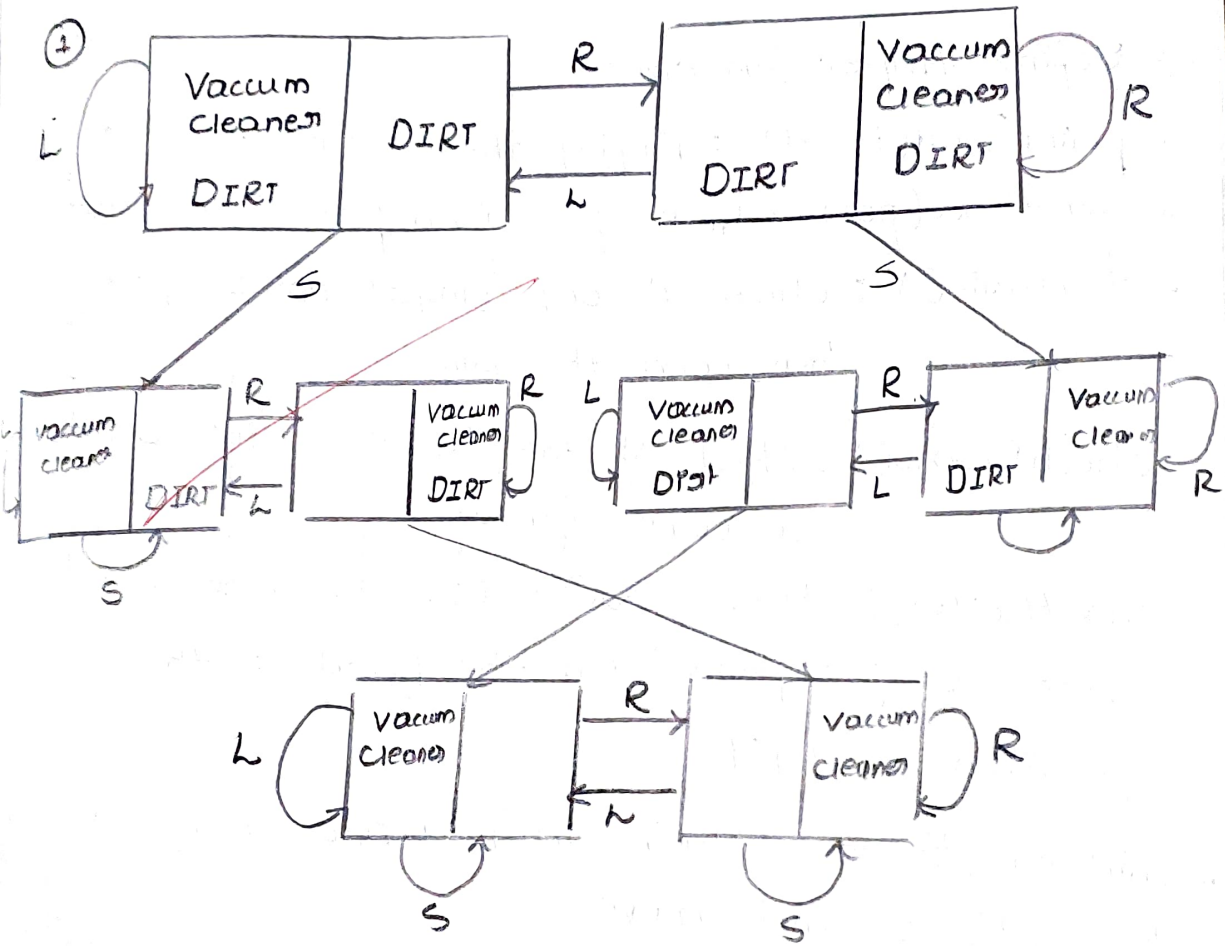
Location A is Dirty

Cost for cleaning A : 1

Location A has been cleaned

Performance Measurement (Total Cost) : 1

## STATE SPACE TREE



# 1) TIC-TAC TOE

## Algorithm

### 1) Initialize Game Board:

- Create an empty board with positions labeled 1-9

### 2) Define Helper Functions:

- printBoard(board) : Display the current board state
- spaceFree(pos) : Check if a given position is empty
- checkWin() : Check if any player (bot or player) has won the game.
- checkDraw() : Check if the board is full without a winner (draw)
- insertLetter(letter, position) : Place a letter ('X' for bot, 'O' for player) on the board if the position is empty.
- minimax(board, isMaximizing) : Minimax algorithm for bot's optimal move

### 3) Main Game Loop:

#### • Player's Turn:

- \* Prompt the player to input a valid position (1-9)
- \* Check if the move results in a win or draw. If so, end the game.

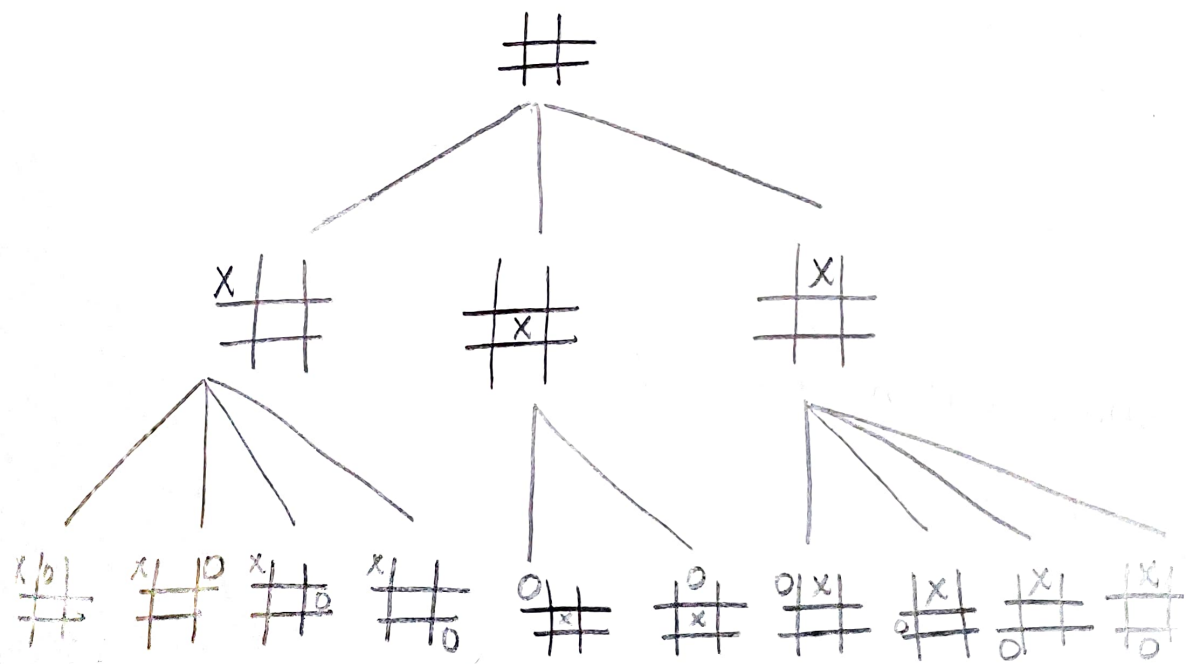
## • Bot's Turn:

- \* Use minimax() to calculate the best move for the bot.
- \* Make the move on the board & check if the bot wins or if the game results in a draw.

## 4) Game End Conditions:

- If a win or draw condition is met, display the result (either 'You win' 'Bot win or 'draw')
- Exit the game loop when the game ends

## STATE SPACE TREE



Output:-

x		

Enter position for 0: 1

Position taken, please pick a different position.

Enter new position: 3

x		0

x		0
x		

Enter position for 0: 7

x		0
x		
0		

x		0
x	x	
0		

Enter position for 0: 6

x		0
x	x	0
0		

x		0
x	x	0
0		x

Bot wins!

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