Orchestrating position estimation protocols in randomly deployed WSNs

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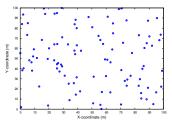
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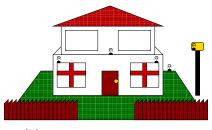


What are Randomly Deployed WSNs?

- ▶ Nodes are placed randomly over a field.
- ▶ It also encompasses deployments made at convenience.



(a) Example random deployment of nodes



(b) Example home surveillance deployment

Characteristics

- ▶ Nodes determine the best route to the sink.
- Often are easier to deploy.
- ▶ In case of a battery run-out, nodes can be replaced.

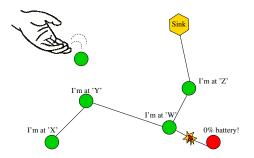


Figure: Replacing nodes

Applications

Because of their ease of deployment, are often used for:

- Volcano activity monitoring.
 - Very dangerous or difficult places for deployment.
- Forest fire detection.
 - Very big areas.

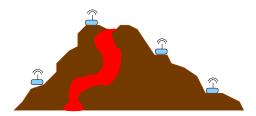


Figure: Volcano monitoring example

Pro's and Con's of random deployments

Pro's:

- Allows rapid deployment.
- Reach very restrictive or dangerous places.
- Allows fast network reinforcement.

Con's:

- It is difficult to trace the metrics.
- Position of the nodes is not know a priori.
- Localization often decreases network lifetime.

Node Localization

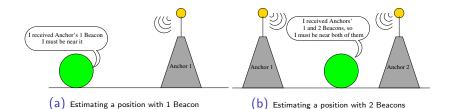
To make metrics traceable:

- 1. All nodes are equipped with GPS modules.
 - 1.1 Decreasing network lifetime due to the modules ↓.
 - 1.2 Increasing the size and weight of the nodes \downarrow .
 - 1.3 Augmenting the required budget ↓.
 - 1.4 Very low estimation error ↑.
- 2. Some nodes use GPS modules
 - 2.1 Nodes derive a position estimation from Anchors: increased estimation error ↓.
 - 2.2 Additional workload is added to the nodes (estimation) ↓.
 - 2.3 Added network traffic (*Beacons*) containing location information ↓.
 - 2.4 Cheaper and scalable approach \(\frac{1}{2} \).



Estimating Position by Reference

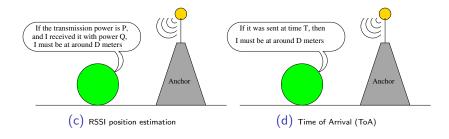
- ► Any *Unknown* node (unaware of its position) may derive an estimation from Beacons.
- Beacons packets contain the position of the sender.



▶ Applications may tolerate different levels of estimation errors.

Making Range Estimations

- Use the propagation characteristics of Beacons
 - ▶ Derive a straight line estimation to the transmitter.



Localization Protocols

Range-free

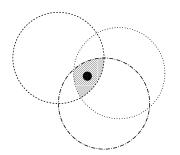


Figure: Bounding-Box example

Range-based

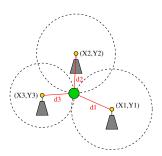


Figure: Lateration example

Range-free and Range-based

Range-free protocols:

- Only consider the effective connection with Anchors.
- Usually consume less battery.
- Error is subject to the number of connections to Anchors.

Range-based protocols:

- Use ranging techniques to constrain the estimation.
- Increased battery consumption related to the ranging technique.
- Error is usually reduced due to the availability of more data.



Locating Nodes

- Applications dictate the maximum estimation error.
- Protocol performance is limited by the network-environmanetal conditions surrounding each node:
 - # of surrounding Anchors.
 - Network delay.
 - Available throughput.
 - Processing capabilities.
- ▶ **Deployments** may have different **considerations** regarding:
 - Network lifetime.
 - Location accuracy.
 - Traffic overhead.
 - Convergence time.

One protocol cannot perform well in all possible scenarios



Composability

► Combines different protocols to achieve better results.

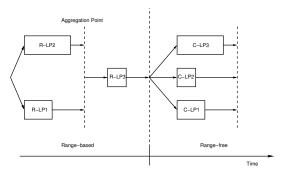


Figure: Composability¹

Composability

- Leverages weaknesses of some protocols with strengths of others.
- Protocols are executed sequentially according to accuracy thresholds.
- Brings some questions:
 - ► How are protocols selected?
 - How are thresholds set?
 - Is it static-sequential execution the way to go?

Is based on:

- Protocol's performance is dependent on the environmental conditions.
- Selected protocols must comply with the deployment considerations.

The Localization Procedure:

- Analyzes the node's environmental conditions.
- ▶ Identifies a suitable set of protocols.

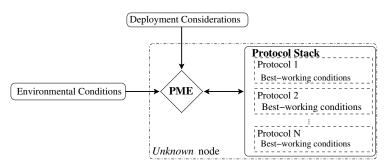


Figure: Localization Procedure

The Pattern Matching Engine (PME):

- ▶ Manages the execution of *characterized*² localization protocols.
- Selects a set of protocols based on the environmental conditions.
- Reorders the execution based on the deployment considerations.



²Their best-working conditions are known.

Evaluation tools

- Bounding-Box and Lateration are tested.
 - Popular.
 - Some of their best-working conditions are known.
 - Range-free and range-based example.
 - ▶ 100 m x 100 m flat surface.

Characteristic	Lateration	Bounding-Box
Env. Conditions	At least 4 Anchors	At least 1 Anchor
Accuracy	2-10 meters	Coarse ³
Energy Consumption	Low	Very Iow⁴

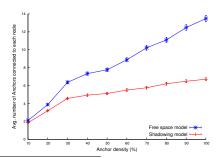


³Location area upper-bounded by *Anchor's* radio range (R).

⁴Can be treated as a discrete problem.

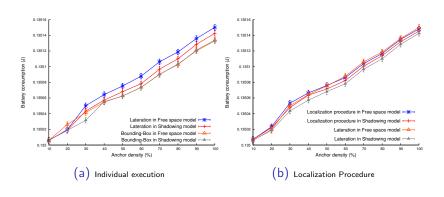
Evaluation tools

- ▶ Modified version of the SENSE simulator⁵
- Deployment considerations: high accuracy and long network lifetime.
- Two channel models: free space and shadowing.



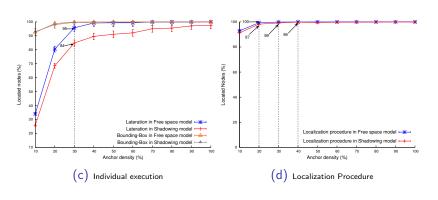
Battery Consumption

Similar battery consumption.



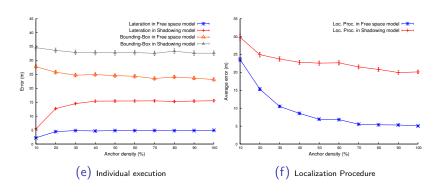
Located Nodes

Increased number of located nodes.



Straigh-line Error

▶ Greater average error than in Lateration-only scenarios.



Remarks

- ▶ Despite of greater error than Lateration:
 - ▶ Number of located nodes is increased.
 - ▶ In the individual execution, these nodes have infinite error.
 - Similar battery consumption.
- A carefully selected set of protocols can work on more scenarios.
- ▶ Allowing node-Beacoming and location information exchange:
 - Centralized protocols.
 - More scenarios: NLoS, anisotropic topologies.

Q&A

Thank you!