

Saturdays.Al Copenhagen

1st Machine Learning meetup

Agenda

- 1. The Team
- 2. Objective
- 3. Overall Process.
- 4. Some Lessons Learned for future.



Team

Sana Ullah Khan
Business Analytics
MsC student at DTU.



Charles Maina
MSC Business
Management.
Lund University.

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Majid Khan
Comp-science
Blekinge Institute of tech.



Objective

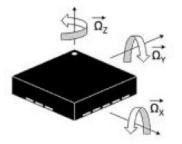
 The goal of this project is to classify the road issues experienced by cycling (potholes, bumps, concrete expansion joints, and storm drain basins) from the 3D accelerometer and gyroscope data.



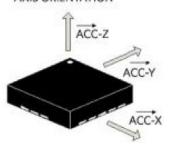


Objective

GYROSCOPE SENSING ANGULAR ORIENTATION



ACCELEROMETER SENSING AXIS ORIENTATION







With our solution we localize and classify road issues

Identify deformation severity of potholes, road cracking, crosswalks and expansion joints, manholes, poor light condition, are essential to improve safety and experience for citizens using the road infrastracture

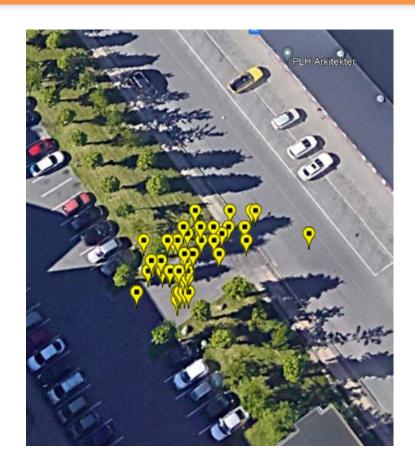


Inspiration:





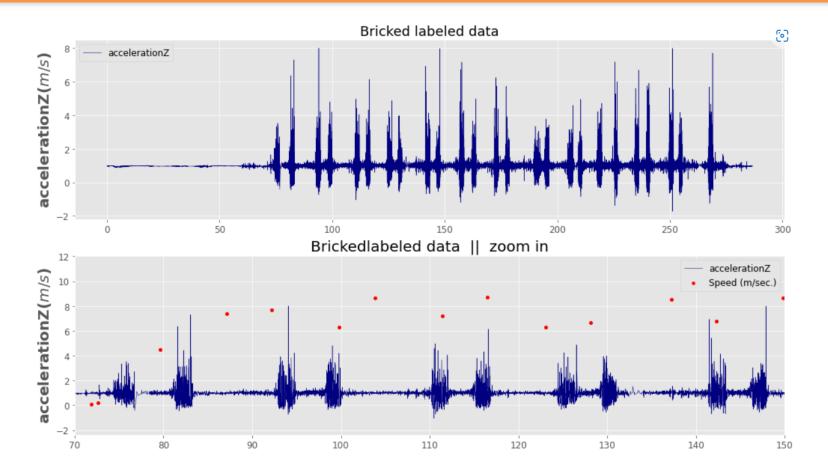
Bricks kml data





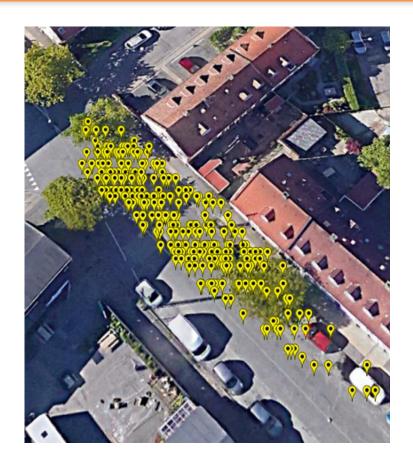


Bricks data plots





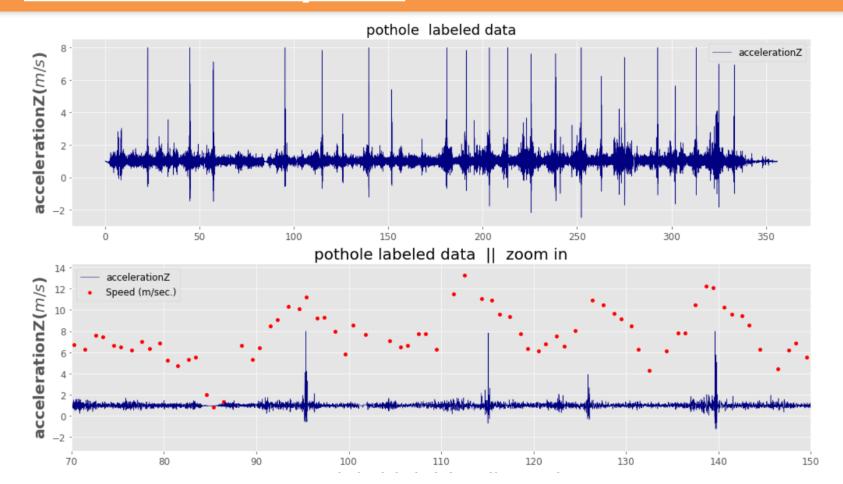
Pothole kml data





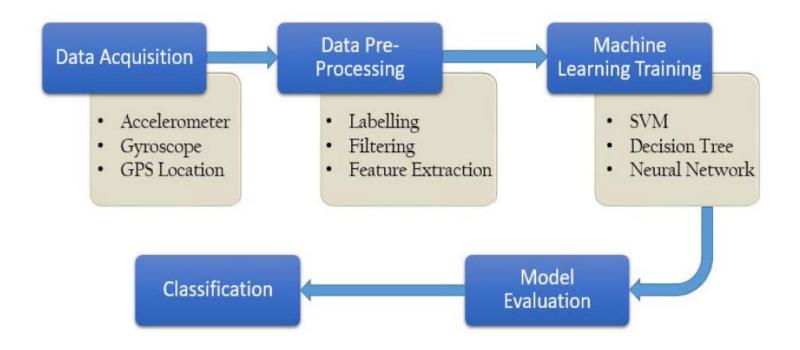


Pothole data plots



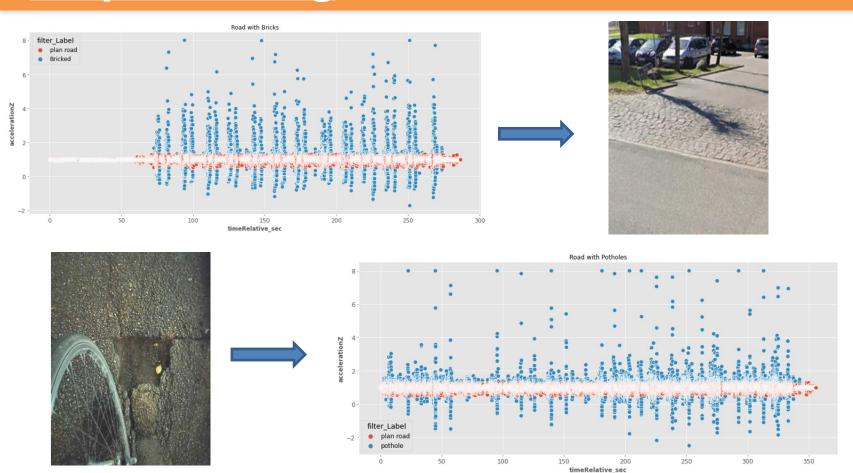


Overall block diagram of the process



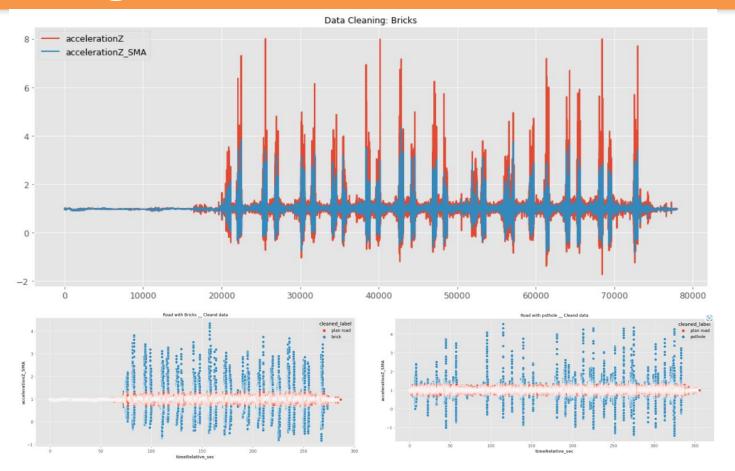


Preprocessing



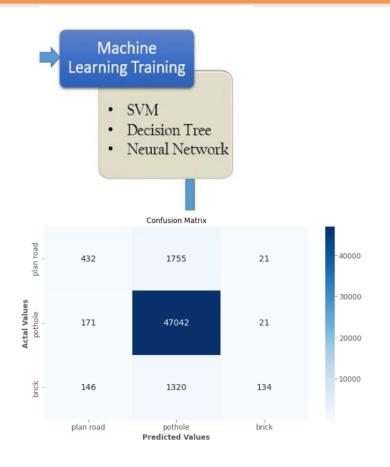


Cleaning with SMA





Machine Learning Training.



Model Evaluation

Confusion Matrix

]]	432	1755	21]
[171	47042	21]
Ī	146	1320	134]]

Accuracy: 0.93

Micro Precision: 0.93 Micro Recall: 0.93 Micro F1-score: 0.93

Macro Precision: 0.76 Macro Recall: 0.43 Macro F1-score: 0.47

Weighted Precision: 0.92 Weighted Recall: 0.93 Weighted F1-score: 0.91

Classification Report

	precision	recall	f1-score	support
Class 1 Class 2	0.58 0.94	0.20 1.00	0.29 0.97	2208 47234
Class 3	0.76	0.08	0.15	1600
accuracy macro avg weighted avg	0.76 0.92	0.43 0.93	0.93 0.47 0.91	51042 51042 51042



Future work:

- Data collection
- Data on continuous road.
- Constant speed is ideal.
- Knowledge about anomaly.
- More advance models.
- More advance data cleaning techniques. i.e fft and interpolating like scipy.interpolate.splrep().
- More advance feature extraction.



