```
1 # Replace the average pooling with max-pooling.
2 # Replace the softmax layer with ReLU.
3 # Explore the learning rates.
1 import torch
2 !pip install d2l==1.0.0a0
     Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.8/dist-packages (from requests->d2l==1.0.0a0) (2022.12.
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     Requirement already satisfied: defusedxml in /usr/local/lib/python3.8/dist-packages (from nbconvert->jupyter->d2l==1.0.0a0) (0.7.1)
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    Collecting qtpy>=2.0.1
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                                                          --- 83.6/83.6 KB 4.5 MB/s eta 0:00:00
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     Requirement already satisfied: pycparser in /usr/local/lib/python3.8/dist-packages (from cffi>=1.0.1->argon2-cffi-bindings->argon2-
    Installing collected packages: qtpy, jedi, qtconsole, jupyter, d21
    Successfully installed d21-1.0.0a0 jedi-0.18.2 jupyter-1.0.0 qtconsole-5.4.0 qtpy-2.3.0
1 !pip install matplotlib
2 %matplotlib inline
3 !pip install matplotlib-inline
4 import sys
5 !{sys.executable} -m pip install matplotlib
     Looking in indexes: <a href="https://pypi.org/simple">https://us-python.pkg.dev/colab-wheels/public/simple/</a>
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     Requirement already satisfied: python-dateutil>=2.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (2.8.2)
     Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.8/dist-packages (from python-dateutil>=2.1->matplotlib) (1.15.0)
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```
Looking in indexes: <a href="https://pypi.org/simple">https://us-python.pkg.dev/colab-wheels/public/simple/</a>
    Collecting matplotlib-inline
      Downloading matplotlib_inline-0.1.6-py3-none-any.whl (9.4 kB)
    Requirement already satisfied: traitlets in /usr/local/lib/python3.8/dist-packages (from matplotlib-inline) (5.7.1)
    Installing collected packages: matplotlib-inline
    Successfully installed matplotlib-inline-0.1.6
    Looking in indexes: <a href="https://pypi.org/simple">https://us-python.pkg.dev/colab-wheels/public/simple/</a>
    Requirement already satisfied: matplotlib in /usr/local/lib/python3.8/dist-packages (3.2.2)
    Requirement already satisfied: python-dateutil>=2.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (2.8.2)
    Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (3.0
    Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (1.4.4)
    Requirement already satisfied: numpy>=1.11 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (1.21.6)
    Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (0.11.0)
    Requirement already \ satisfied: \ six>=1.5 \ in \ /usr/local/lib/python 3.8/dist-packages \ (from \ python-dateutil>=2.1->matplotlib) \ (1.15.0)
   4
1 import time
2 import numpy as np
3 import torch
4 import torchvision
5 from torchvision import transforms
6 from torch import nn
7 from d2l import torch as d2l
8 from torch.optim import lr_scheduler
1 def LeNet(num_classes=10):
      net = nn.Sequential(nn.LazyConv2d(6, kernel_size=5, padding=2),
            nn.ReLU().
            nn.MaxPool2d(kernel_size=2, stride=2),
            nn.LazyConv2d(16, kernel_size=5),
            nn.ReLU(),
            nn.MaxPool2d(kernel_size=2, stride=2),
            nn.Flatten(),
            nn.Linear(400, 120),
            nn.ReLU(),
            nn.Linear(120, 84),
            nn.ReLU(),
            nn.Linear(84, num_classes))
      return net
1 def train(model, train_loader, test_loader, num_epochs, loss_fn, trainer):
      animator = d21.Animator(xlabel='epoch', xlim=[0, num_epochs], legend=['train loss', 'train accuracy', 'test accuracy'])
      for epoch in range(num_epochs):
          metric = d21.Accumulator(3)
          for i, (X, y) in enumerate(train_loader):
              net.train()
              trainer.zero_grad()
              y_hat = net(X)
              1 = loss_fn(y_hat, y)
              1.backward()
              trainer.step()
              with torch.no_grad():
                  metric.add(1 * X.shape[0], d21.accuracy(y_hat, y), X.shape[0])
              train_loss = metric[0] / metric[2]
              train_acc = metric[1] / metric[2]
              if (i + 1) \% 50 == 0:
                  animator.add(epoch + i / len(train_loader),
                               (train_loss, train_acc, None))
          test_acc = d21.evaluate_accuracy_gpu(model, test_loader)
          animator.add(epoch+1, (None, None, test_acc))
      print(f'train loss {train_loss:.3f}, train accuracy {train_acc:.3f}, 'f'test accuracy {test_acc:.3f}')
1 loss = nn.CrossEntropyLoss()
2 batch_size = 256
3 \text{ num epochs} = 10
4 lr=0.001
1 train_loader, test_loader = d21.load_data_fashion_mnist(batch_size=batch_size)
2 net= LeNet(num_classes=10)
3 trainer = torch.optim.Adam(net.parameters(), lr=lr)
```

Downloading http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3-ubyte.gz $Downloading \ \underline{http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3-ubyte.gz \ to \ .../data/FashionMNIST/raw/train-images-idx3-ubyte.gz \ to \ .../data/Fashio$ 26421880/26421880 [00:03<00:00, 14073814.10it/s]

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 $Downloading \ \ \underline{http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-labels-idx1-ubyte.gz} \ \ to \ \ ../data/FashionMNIST/raw/train-labels-idx1-ubyte.gz$

100% 29515/29515 [00:00<00:00, 145783.22it/s]

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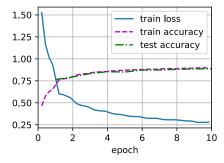
Extracting ../data/FashionMNIST/raw/t10k-labels-idx1-ubyte.gz to ../data/FashionMNIST/raw

/usr/local/lib/python3.8/dist-packages/torch/utils/data/dataloader.py:554: UserWarning: This DataLoader will create 4 worker processes i warnings.warn(_create_warning_msg(

/usr/local/lib/python3.8/dist-packages/torch/nn/modules/lazy.py:180: UserWarning: Lazy modules are a new feature under heavy development warnings.warn('Lazy modules are a new feature under heavy development

1 train(net, train_loader, test_loader, num_epochs, loss, trainer)

train loss 0.280, train accuracy 0.897, test accuracy 0.888



- # Measuring and comparing theoretical computation complexity (number of operations and parameters size)
- pip install torchinfo

Looking in indexes: https://us-python.pkg.dev/colab-wheels/public/simple/

Collecting torchinfo

Downloading torchinfo-1.7.2-py3-none-any.whl (22 kB)

Installing collected packages: torchinfo Successfully installed torchinfo-1.7.2

from torchinfo import summary

3 model = LeNet()

1 2

4 batch_size = 256

summary(model, input_size=(batch_size, 1, 28, 28)) 5

Layer (type:depth-idx)	Output Shape	Param #
======================================	======================================	
⊢Conv2d: 1-1	[256, 6, 28, 28]	156
ReLU: 1-2	[256, 6, 28, 28]	
-MaxPool2d: 1-3	[256, 6, 14, 14]	
├─Conv2d: 1-4	[256, 16, 10, 10]	2,416
⊢ReLU: 1-5	[256, 16, 10, 10]	
⊢MaxPool2d: 1-6	[256, 16, 5, 5]	
⊢Flatten: 1-7	[256, 400]	
⊢Linear: 1-8	[256, 120]	48,120
⊢ReLU: 1-9	[256, 120]	
⊢Linear: 1-10	[256, 84]	10,164
⊢ReLU: 1-11	[256, 84]	
-Linear: 1-12	[256, 10]	850

Total params: 61,706 Trainable params: 61,706 Non-trainable params: 0 Total mult-adds (M): 108.30

Input size (MB): 0.80

Forward/backward pass size (MB): 13.35 Params size (MB): 0.25 Estimated Total Size (MB): 14.40
