```
1 # Replace the average pooling with max-pooling.
2 # Replace the softmax layer with ReLU.
3 # Adjust the number of output channels (width of each layer).
1 import torch
2 !pip install d2l==1.0.0a0
     Requirement already satisfied: idna<3,>=2.5 in /usr/local/lib/python3.8/dist-packages (from requests->d2l==1.0.0a0) (2.10)
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     Requirement already satisfied: tornado>=4.2 in /usr/local/lib/python3.8/dist-packages (from ipykernel->jupyter->d2l==1.0.0a0) (6.2)
     Requirement already satisfied: ipython>=5.0.0 in /usr/local/lib/python3.8/dist-packages (from ipykernel->jupyter->d2l==1.0.0a0) (7.
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     Requirement already satisfied: prompt-toolkit!=3.0.0,!=3.0.1,<3.1.0,>=2.0.0 in /usr/local/lib/python3.8/dist-packages (from jupyter
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     Requirement already satisfied: pandocfilters>=1.4.1 in /usr/local/lib/python3.8/dist-packages (from nbconvert->jupyter->d2l==1.0.0a
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     Requirement already satisfied: jupyter-core in /usr/local/lib/python3.8/dist-packages (from nbconvert->jupyter->d2l==1.0.0a0) (5.2.
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    Collecting qtpy>=2.0.1
       Downloading QtPy-2.3.0-py3-none-any.whl (83 kB)
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    Installing collected packages: qtpy, jedi, qtconsole, jupyter, d2l
    Successfully installed d21-1.0.0a0 jedi-0.18.2 jupyter-1.0.0 qtconsole-5.4.0 qtpy-2.3.0
1 !pip install matplotlib
2 %matplotlib inline
3 !pip install matplotlib-inline
4 import sys
5 !{sys.executable} -m pip install matplotlib
     Looking in indexes: <a href="https://pypi.org/simple">https://us-python.pkg.dev/colab-wheels/public/simple/</a>
    Requirement already satisfied: matplotlib in /usr/local/lib/python3.8/dist-packages (3.2.2)
     Requirement already satisfied: numpy>=1.11 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (1.21.6)
    Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (3.0
     Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (0.11.0)
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     Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (1.4.4)
     Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.8/dist-packages (from python-dateutil>=2.1->matplotlib) (1.15.0)
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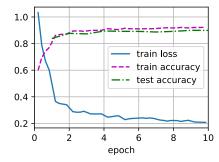
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23 24

```
Looking in indexes: <a href="https://pypi.org/simple">https://us-python.pkg.dev/colab-wheels/public/simple/</a>
   Collecting matplotlib-inline
      Downloading matplotlib_inline-0.1.6-py3-none-any.whl (9.4 kB)
    Requirement already satisfied: traitlets in /usr/local/lib/python3.8/dist-packages (from matplotlib-inline) (5.7.1)
   Installing collected packages: matplotlib-inline
    Successfully installed matplotlib-inline-0.1.6
    Looking in indexes: <a href="https://pypi.org/simple">https://us-python.pkg.dev/colab-wheels/public/simple/</a>
    Requirement already satisfied: matplotlib in /usr/local/lib/python3.8/dist-packages (3.2.2)
    Requirement already satisfied: python-dateutil>=2.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (2.8.2)
    Requirement already satisfied: numpy>=1.11 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (1.21.6)
    Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (3.0
    Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (0.11.0)
    Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.8/dist-packages (from matplotlib) (1.4.4)
   Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.8/dist-packages (from python-dateutil>=2.1->matplotlib) (1.15.0)
   4
1 import time
2 import numpy as np
3 import torch
4 import torchvision
5 from torchvision import transforms
6 from torch import nn
7 from d2l import torch as d2l
8 from torch.optim import lr_scheduler
1 def LeNet(num_classes=10):
      net = nn.Sequential(nn.LazyConv2d(30, kernel_size=5, padding=2),
            nn.ReLU().
            nn.MaxPool2d(kernel_size=2, stride=2),
           nn.LazyConv2d(60, kernel_size=5),
            nn.ReLU(),
           nn.MaxPool2d(kernel_size=2, stride=2),
           nn.Flatten(),
           nn.Linear(1500, 120),
            nn.ReLU(),
            nn.Linear(120, 84),
            nn.ReLU(),
            nn.Linear(84, num_classes))
      return net
1 def train(model, train_loader, test_loader, num_epochs, loss_fn, trainer):
      animator = d21.Animator(xlabel='epoch', xlim=[0, num_epochs], legend=['train loss', 'train accuracy', 'test accuracy'])
      for epoch in range(num_epochs):
         metric = d21.Accumulator(3)
         for i, (X, y) in enumerate(train_loader):
             net.train()
              trainer.zero_grad()
              y_hat = net(X)
              1 = loss_fn(y_hat, y)
              1.backward()
              trainer.step()
              with torch.no_grad():
                  metric.add(1 * X.shape[0], d21.accuracy(y_hat, y), X.shape[0])
              train_loss = metric[0] / metric[2]
              train_acc = metric[1] / metric[2]
              if (i + 1) \% 50 == 0:
                  animator.add(epoch + i / len(train_loader),
                               (train_loss, train_acc, None))
          test_acc = d21.evaluate_accuracy_gpu(model, test_loader)
          animator.add(epoch+1, (None, None, test_acc))
      print(f'train loss {train_loss:.3f}, train accuracy {train_acc:.3f}, 'f'test accuracy {test_acc:.3f}')
1 loss = nn.CrossEntropyLoss()
2 batch_size = 256
3 \text{ num epochs} = 10
4 lr=0.01
1 train_loader, test_loader = d21.load_data_fashion_mnist(batch_size=batch_size)
2 net= LeNet(num_classes=10)
3 trainer = torch.optim.Adam(net.parameters(), lr=lr)
```

```
Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx2">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx2</a>
Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3</a>
                                                                        26421880/26421880 [00:01<00:00, 29041318.25it/s]
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/usr/local/lib/python3.8/dist-packages/torch/utils/data/dataloader.py:554: UserWarning:
   warnings.warn(_create_warning_msg(
/usr/local/lib/python3.8/dist-packages/torch/nn/modules/lazy.py:180: UserWarning: Lazy m
   warnings.warn('Lazv modules are a new feature under heavv development '
```

- 1 train(net, train_loader, test_loader, num_epochs, loss, trainer)
- rain loss 0.209, train accuracy 0.921, test accuracy 0.899



- 1 # Measuring and comparing theoretical computation complexity (number of operations and parameters size)
- 1 pip install torchinfo

Looking in indexes: https://us-python.pkg.dev/colab-wheels/public/simple/ Collecting torchinfo

Downloading torchinfo-1.7.2-py3-none-any.whl (22 kB)
Installing collected packages: torchinfo
Successfully installed torchinfo-1.7.2

- 1 from torchinfo import summary
- 3 model = LeNet()

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- 4 batch_size = 256
- 5 summary(model, input_size=(batch_size, 1, 28, 28))

		=======================================
Layer (type:depth-idx)	Output Shape	Param #
		=======================================
Sequential	[256, 10]	
├─Conv2d: 1-1	[256, 30, 28, 28]	780
ReLU: 1-2	[256, 30, 28, 28]	
─MaxPool2d: 1-3	[256, 30, 14, 14]	
├─Conv2d: 1-4	[256, 60, 10, 10]	45,060
⊢ReLU: 1-5	[256, 60, 10, 10]	
⊢MaxPool2d: 1-6	[256, 60, 5, 5]	
─Flatten: 1-7	[256, 1500]	
⊢Linear: 1-8	[256, 120]	180,120
⊢ReLU: 1-9	[256, 120]	
⊢Linear: 1-10	[256, 84]	10,164
⊢ReLU: 1-11	[256, 84]	
⊢Linear: 1-12	[256, 10]	850

Total params: 236,974 Trainable params: 236,974 Non-trainable params: 0 Total mult-adds (G): 1.36

.....

Input size (MB): 0.80

Forward/backward pass size (MB): 60.90 Params size (MB): 0.95 Estimated Total Size (MB): 62.65
