

EAFIT UNIVERSITY
IT AND SYSTEMS DEPARTMENT
FINAL PROJECT
Third report

Objective: Implementation of the second batch of numerical methods seen until this point in the semester, including the additional ones.

Course: Numerical analysis.

Teacher: Edwar Samir Posada Murillo.

Semester: 2020-2.

Due date for the Third report: Wednesday November 11.

Project name: Numerical views.

Project Repository: [Link Repo](#)

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Report description: We will write the pseudocode of each method followed by an example execution. The code can be found on the repository link cited above

1 Methods

Algorithm 1: Incremental search

```
input : f: function to find root of,  
        X0: first root approximation,  
        Delta: delta(x),  
        N: maximum number of iterations,  
  
if ( $y=0$ ) then  
    | x0 is root;  
else  
    |  $x1 \leftarrow [x0 \text{ } \textit{delta}]$   
    |  $y1 \leftarrow [f(x1)]$   
    |  $\textit{counter} \leftarrow [1]$   
while  $y1 * y0 > 0$  and  $\textit{counter} < n$  do do  
    |  $x0 \leftarrow [x1]$   
    |  $y0 \leftarrow [y1]$   
    |  $x1 \leftarrow [x0 + \textit{delta}]$   
    |  $y1 \leftarrow [f(x1)]$   
    |  $\textit{counter} \leftarrow \textit{counter} + 1$   
if ( $y1==0$ ) then  
    | x1 is root;  
else  
    | if ( $y1 * y0 < 0$ ) then  
    | |  $[x0,x1]$  define an interval;  
    | else  
    | | print("didn't find interval in N iterations")
```

Algorithm 2: Extra method Muller

input : function f , root approximation 1 x_0 , root approximation 2 x_1 , root approximation 3 x_2 , tolerance tol , Maximum number of iterations N

output: root approximation

$$h1 = x1 - x0$$

$$h2 = x2 - x1$$

$$t1 = (f(x1) - f(x0))/h1$$

$$t2 = (f(x2) - f(x1))/h2$$

$$d = (t2 - t1)/(h2 + h1)$$

for $i \leftarrow 3$ **to** N **do**

$$b = t2 + h2 * d$$

$$D = (b^2 - 4 * f(x2) * d)^{1/2}$$

if $abs(b - D) < abs(b + D)$ **then**

$$| E = b + D;$$

else

$$| E = b - D$$

$$h = (-2 * f(x2))/E$$

$$e = x$$

$$x = x2 + h$$

$$e = abs(e - x)$$

if $abs(e) \leq tol$ **then**

break;

$$x0 = x1$$

$$x1 = x2$$

$$x2 = x$$

$$h1 = x1 - x0$$

$$h2 = x2 - x1$$

$$t1 = (f(x1) - f(x0))/h1$$

$$t2 = (f(x2) - f(x1))/h2$$

$$d = (t2 - t1)/(h2 + h1)$$

Algorithm 3: Vandermonde

input : x, y

output: Polynomial coefficients, Vandermonde polynom

Repeat

Repeat

$$A(j,i) = X(j)^{(n-i)}$$

until($j < n$)

until($i < n$)

print: (Reverse A)*y

Algorithm 4: Newton Divided difference

input : vector x_0, x_1, \dots, x_n , vector values $f(x_0)$; a point to evaluate

output: Divided differences $F_{0,0} \dots F_{n,n}$

Step 1

for $i=0, \dots, n$ **do**

 Set $F_{i,0} = f(x_i)$

Step 2

for $i=1, \dots, n$ **do**

for $j=1, 2, \dots, i$ **do**

 Set $F_{i,j} = (F_{i,j-1} - F_{i-1,j-1}) / (x_i - x_{i-j})$

 End ;

Output $(F_{0,0}, \dots, F_{i,i}, \dots, F_{n,n})$

STOP

Algorithm 5: Lagrange

input : vector x_0, x_1, \dots, x_n , vector values $f(x_0)$; a point to evaluate

output: P Lagrange polynomial $P(x)$ evaluated at z

Step 1

Initialize variables. Set P_z equal zero. Set n to the number of pairs of points (x, y) . Set L to be the all ones vector of length n

Step 2

for $i=1, 2, \dots, n$ **do**

 Step 3

for $j=1, 2, \dots, i$ **do**

 Step 4

if $i = j$ **then** $L_i = (z - x_j) / (x_i - x_j) * L_i$ **then**

 break ;

 Step 5

$P_z = (L_i * y_i + P_z)$

Step 6 Output P_z . STOP

Algorithm 6: Neville

input : Numbers x_0, x_1, \dots, x_n , values $f(x_0), f(x_1), \dots, f(x_n)$

output: the table Q with $p(x) = Q_{n,n}$

Step 1

for $i=1, 2, \dots, n$ **do**

for $j=1, 2, \dots, i$ **do**

Set $Q(i,j) = ((x - x_{i-j})Q_{i,j-1} - (x - x_i)Q_{i-1,j-1}) / (x_i - x_{i-j})$

Step 2

Output(Q);

STOP

Algorithm 7: Simple LU

input : nxn matrix A, column vector b
output: solution vector x

if (*A is not square*) or (*size of A and size of b are not computable*) **then**
| break ;
if $\det(A) = 0$ **then**
| break ;
 $A \leftarrow LU$
 $z \leftarrow \text{progressiveSustitution}([L \ b])$
 $x \leftarrow \text{RegressiveSustitution}([U \ z])$

Algorithm 8: Partial Pivoting LU

input : nxn matrix A, column vector b
output: solution vector x

if (*A is not square*) or (*size of A and size of b are not computable*) **then**
| break ;
if $\det(A) = 0$ **then**
| break ;
 $PA \leftarrow LU$
 $z \leftarrow \text{progressiveSustitution}([L \ P * b])$
 $x \leftarrow \text{RegressiveSustitution}([U \ z])$

Algorithm 9: SOR

input : nxn matrix A, column vector b, initial aproximation X0, weighing factor w, tolerance, maximum iterations Nmax
output: solution vector x, final number of iterations iter, error err

$A \leftarrow D - L - U$
 $T \leftarrow (D - w * L)^{-1} * ((1 - w) * D + w * U)$
 $C \leftarrow w * (D - w * L)^{-1} * b$
 $xant \leftarrow x0$
 $count \leftarrow 0$
 $error = 100$
while $error > tolerance$ and $counter < nmax$ **do**
| $xact = T * xant + C$
| $error = norm(xant - xact)$
| $xant = xact;$
| $cont = cont + 1;$
 $x = xact$
 $iter = cont$
 $err = error$

Algorithm 10: Gauss-Seidel

input : nxn matrix A, column vector b, initial aproximation X0, weighing factor w, tolerance, maximum iterations Nmax

output: solution vector x, final number of iterations iter, error err

$$A \leftarrow D - L - U$$

$$T \leftarrow (D - L)^{-1} * U$$

$$C \leftarrow (D - L)^{-1} * b$$

$$x_{ant} \leftarrow x_0$$

$$count \leftarrow 0$$

$$error = 100$$

while *error > tolerance and counter < nmax* **do**

$$x_{act} = T * x_{ant} + C$$

$$error = norm(x_{ant} - x_{act})$$

$$x_{ant} = x_{act};$$

$$cont = cont + 1;$$

$$x = x_{act}$$

$$iter = cont$$

$$err = error$$

Algorithm 11: Jacobi

input : nxn matrix A, column vector b, initial aproximation X0, weighing factor w, tolerance, maximum iterations Nmax

output: solution vector x, final number of iterations iter, error err

$$A \leftarrow D - L - U$$

$$T \leftarrow (D)^{-1} * (L + U)$$

$$C \leftarrow (D)^{-1} * b$$

$$x_{ant} \leftarrow x_0$$

$$count \leftarrow 0$$

$$error = 100$$

while *error > tolerance and counter < nmax* **do**

$$x_{act} = T * x_{ant} + C$$

$$error = norm(x_{ant} - x_{act})$$

$$x_{ant} = x_{act};$$

$$cont = cont + 1;$$

$$x = x_{act}$$

$$iter = cont$$

$$err = error$$

Algorithm 12: Crout

input : nxn matrix A, column vector b
output: solution vector x

$L \leftarrow I(n)$
 $U \leftarrow I(n)$
for $i \leftarrow 1$ **to** $n - 1$ **do**
 for $j \leftarrow i$ **to** n **do**
 $L_{j,i} \leftarrow A_{j,i} - \text{dot}(L(j, 1 : i - 1), U(1 : i - 1, i)')$
 for $j \leftarrow i + 1$ **to** n **do**
 $U_{i,j} \leftarrow A_{i,j} - \text{dot}(L(i, 1 : i - 1), U(1 : i - 1, j)')$
 $L[n, n] = A[n, n] - \text{dot}(L[n, 1 : n - 1], U[1 : n - 1, n]')$
 $z = \text{progressiveSubstitution}([L \ b]);$
 $x = \text{regressiveSubstitution}([U \ z]);$

Algorithm 13: Cholesky

input : nxn matrix A, column vector b, initial approximation X0, weighing factor w, tolerance, maximum iterations Nmax
output: solution vector x

$L \leftarrow I(n)$
 $U \leftarrow I(n)$
for $i \leftarrow 1$ **to** $n - 1$ **do**
 $L_{i,i} \leftarrow \sqrt{A_{i,i} - \text{dot}(L(i, 1 : i - 1), U(1 : i - 1, i)')}$
 $U_{i,i} \leftarrow L_{i,i}$
 for $j \leftarrow i + 1$ **to** n **do**
 $L[j, i] = (A[j, i] - \text{dot}(L[j, 1 : i - 1], U[1 : i - 1, i]')) / U(i, i);$
 $U[i, j] = (A[i, j] - \text{dot}(L[i, 1 : i - 1], U[1 : i - 1, j]')) / L[i, i];$
 $L[n, n] = A[n, n] - \text{dot}(L[n, 1 : n - 1], U[1 : n - 1, n]')$
 $z = \text{progressiveSubstitution}([L \ b]);$
 $x = \text{regressiveSubstitution}([U \ z]);$

2 Evidence

INCREMENTAL SEARCHES

Results:

There is a root of f in [-2.5 , -2.0]

There is a root of f in [-1.0 , -0.5]

There is a root of f in [0.5 , 1.0]

There is a root of f in [2.0 , 2.5]

There is a root of f in [4.0 , 4.5]

There is a root of f in [5.0 , 5.5]

There is a root of f in [7.0 , 7.5]

There is a root of f in [8.0 , 8.5]

There is a root of f in [10.0 , 10.5]

There is a root of f in [11.5 , 12.0]

There is a root of f in [13.5 , 14.0]

There is a root of f in [14.5 , 15.0]

There is a root of f in [16.5 , 17.0]

There is a root of f in [17.5 , 18.0]

There is a root of f in [19.5 , 20.0]

There is a root of f in [21.0 , 21.5]

There is a root of f in [22.5 , 23.0]

There is a root of f in [24.0 , 24.5]

There is a root of f in [26.0 , 26.5]

There is a root of f in [27.0 , 27.5]

There is a root of f in [29.0 , 29.5]

There is a root of f in [30.0 , 30.5]

There is a root of f in [32.0 , 32.5]

There is a root of f in [33.5 , 34.0]

There is a root of f in [35.0 , 35.5]

There is a root of f in [36.5 , 37.0]

There is a root of f in [38.5 , 39.0]

There is a root of f in [39.5 , 40.0]

There is a root of f in [41.5 , 42.0]

There is a root of f in [43.0 , 43.5]

There is a root of f in [44.5 , 45.0]

Muller Method

```
Muller method
iter|      x0      |      x1      |      x2      |      Root      |      E
  0 | -1.000000e+00 |  0.000000e+00 |  1.000000e+00 | -2.220446e-16 |
  1 | -1.000000e+00 |  0.000000e+00 |  1.000000e+00 | -2.220446e-16 |
  2 |  0.000000e+00 |  1.000000e+00 | -2.220446e-16 | -2.220446e-16 |  0.000000e+00
A root aproximation was found at -2.220446049250313e-16
```

Figure 2: Proof of Muller Method

Doolittle

```
24 [0.5251077877274448, 0.25545768216313536, -0.41047969902650905, -0.2816585612350974]
25 [0.5251083414671069, 0.25545801583827094, -0.4104799594870898, -0.281658892623501]
26 [0.5251086734271935, 0.25545821587239254, -0.4104801156299903, -0.2816590912867551]
27 [0.5251088724331645, 0.25545833579037724, -0.41048020923573025, -0.2816592103829217]
28 [0.5251089917347855, 0.25545840767972766, -0.41048026535121496, -0.28165928177960226]
29 [0.5251090632546336, 0.25545845077650514, -0.4104802989917548, -0.28165932458103016]
30 [0.5251091061298989, 0.25545847661249077, -0.41048031915884275, -0.2816593502399575]
```

Figure 3: Proof of Doolittle

Jacobi

```
| 42 | 1.5e-06 | 0.525106 | 0.255457 | -0.410479 | -0.281657
| 43 | 1.1e-06 | 0.525107 | 0.255457 | -0.410479 | -0.281658
| 44 | 8.7e-07 | 0.525107 | 0.255457 | -0.410479 | -0.281658
| 45 | 6.5e-07 | 0.525108 | 0.255458 | -0.410480 | -0.281658
| 46 | 4.9e-07 | 0.525108 | 0.255458 | -0.410480 | -0.281659
| 47 | 3.7e-07 | 0.525108 | 0.255458 | -0.410480 | -0.281659
| 48 | 2.8e-07 | 0.525109 | 0.255458 | -0.410480 | -0.281659
| 49 | 2.1e-07 | 0.525109 | 0.255458 | -0.410480 | -0.281659
| 50 | 1.6e-07 | 0.525109 | 0.255458 | -0.410480 | -0.281659
| 51 | 1.2e-07 | 0.525109 | 0.255458 | -0.410480 | -0.281659
| 52 | 9.0e-08 | 0.525109 | 0.255458 | -0.410480 | -0.281659
```

Figure 4: Proof of Jacobi

Vandermonde

```
Vandermonde Matrix:
[[-1.  1. -1.  1.]
 [ 0.  0.  0.  1.]
 [27.  9.  3.  1.]
 [64. 16.  4.  1.]]
Polynomial coefficients: [-1.1417  5.825 -5.5333  3.   ]
Vandermonde polynom:
-1.1416666666666666 *x^ 3 +
5.8249999999999999 *x^ 2 +
-5.5333333333333332 *x^ 1 +
3.0 *x^ 0 +
```

Figure 5: Proof of Vandermonde

Newton Divided Difference

```
Newton's polynomial coefficients:
[ 15.5 -12.5  3.5417 -1.1417]
Newton's Divided Difference Table
[[ 15.5  0.  0.  0. ]
 [ 3. -12.5  0.  0. ]
 [ 8.  1.6667  3.5417  0. ]
 [ 1. -7. -2.1667 -1.1417]]
Newton's polynom:
-1.1416666666666667*x*(x - 3.0)*(x + 1.0) + 3.5416666666666667*x*(x + 1.0) - 12.5*x
+ 3.0
Newton's simple polynom::
-1.1416666666666667*x**3 + 5.825*x**2 - 5.533333333333333*x + 3.0
```

Figure 6: Proof of Newton Divided Difference

Lagrange

```

Lagrange interpolating polynomials:
L0 -0.05*x**3 + 0.35*x**2 - 0.6*x
L1 0.0833333333333333*x**3 - 0.5*x**2 + 0.416666666666667*x + 1.0
L2 -0.0833333333333333*x**3 + 0.25*x**2 + 0.333333333333333*x
L3 0.05*x**3 - 0.1*x**2 - 0.15*x
Lagrange polynom
15.5*L0+3.0*L1+8.0*L2+1.0*L3

```

Figure 7: Proof of Lagrange

Spline Linear

Lineal tracers coefficients

$-12.5 \leftrightarrow 3.0$
 $1.66667 \leftrightarrow 3.0$
 $-7.0 \leftrightarrow 29.0$

Lineal tracers

$3.0 - 12.5*x$
 $1.6666666666666667*x + 3.0$
 $29.0 - 7.0*x$

Figure 8: Proof of Spline Linear

Spline Square

Cuadratic tracers coefficients

```
0.0 <-> -12.5 <-> 3.0
4.72222 <-> -12.5 <-> 3.0
-22.83333 <-> 152.83333 <-> -245.0
```

Cuadratic tracers

```
3.0 - 12.5*x
4.722222222222222*x**2 - 12.5*x + 3.0
-22.83333333333333*x**2 + 152.8333333333333*x - 245.0
```

Figure 9: Proof of Spline Square

Spline Cubic

Cubic tracers coefficients

```
2.53333 <-> 7.6 <-> -7.43333 <-> 3.0
-1.52222 <-> 7.6 <-> -7.43333 <-> 3.0
2.03333 <-> -24.4 <-> 88.56667 <-> -93.0
```

Cubic tracers

```
2.533333333333333*x**3 + 7.6*x**2 - 7.433333333333333*x + 3.0
-1.522222222222222*x**3 + 7.6*x**2 - 7.433333333333333*x + 3.0
2.033333333333333*x**3 - 24.4*x**2 + 88.56666666666667*x - 93.0
```

Figure 10: Proof of Spline Cubic

Neville

```
[[15.5, None, None, None], [3.0, 3.0 - 12.5*x, None, None], [8.0,
1.666666666666667*x + 3.0, -0.25*(3.0 - 12.5*x)*(x - 3.0) + 0.25*(x +
1.0)*(1.666666666666667*x + 3.0), None], [1.0, 29.0 - 7.0*x, 0.25*x*(29.0 -
7.0*x) - 0.25*(x - 4.0)*(1.666666666666667*x + 3.0), -0.2*(x - 4.0)*(-0.25*(3.0 -
12.5*x)*(x - 3.0) + 0.25*(x + 1.0)*(1.666666666666667*x + 3.0)) + 0.2*(x +
1.0)*(0.25*x*(29.0 - 7.0*x) - 0.25*(x - 4.0)*(1.666666666666667*x + 3.0))]]
-1.141666666666667*x**3 + 5.825*x**2 - 5.533333333333333*x + 3.0
```

Figure 11: Proof of Neville

LU Simple

Simple LU

Stage 0

4.000	-1.000	0.000	3.000
1.000	15.500	3.000	8.000
0.000	-1.300	-4.000	1.100
14.000	5.000	-2.000	30.000

Stage 1

4.000	-1.000	0.000	3.000
0.000	15.750	3.000	7.250
0.000	-1.300	-4.000	1.100
0.000	8.500	-2.000	19.500

L:

1.000	0.000	0.000	0.000
0.250	1.000	0.000	0.000
0.000	0.000	1.000	0.000
3.500	0.000	0.000	1.000

U:

4.000	-1.000	0.000	3.000
0.000	15.750	3.000	7.250
0.000	0.000	0.000	0.000
0.000	0.000	0.000	0.000

Stage 2

4.000	-1.000	0.000	3.000
0.000	15.750	3.000	7.250
0.000	0.000	-3.752	1.698
0.000	0.000	-3.619	15.587

L:

1.000	0.000	0.000	0.000
0.250	1.000	0.000	0.000
0.000	-0.083	1.000	0.000
3.500	0.540	0.000	1.000

U:

4.000	-1.000	0.000	3.000
0.000	15.750	3.000	7.250
0.000	0.000	-3.752	1.698
0.000	0.000	0.000	0.000

Stage 3

4.000	-1.000	0.000	3.000
0.000	15.750	3.000	7.250
0.000	0.000	-3.752	1.698
0.000	0.000	0.000	13.949

L:

1.000	0.000	0.000	0.000
0.250	1.000	0.000	0.000
0.000	-0.083	1.000	0.000

LU Partial Pivot

Partial Pivot

Stage 0

4.000	-1.000	0.000	3.000
1.000	15.500	3.000	8.000
0.000	-1.300	-4.000	1.100
14.000	5.000	-2.000	30.000

Stage 1

L:

1.000	0.000	0.000	0.000
0.071	1.000	0.000	0.000
0.000	0.000	1.000	0.000
0.286	0.000	0.000	1.000

A:

14.000	5.000	-2.000	30.000
0.000	15.143	3.143	5.857
0.000	-1.300	-4.000	1.100
0.000	-2.429	0.571	-5.571

P:

0.000	0.000	0.000	1.000
0.000	1.000	0.000	0.000
0.000	0.000	1.000	0.000
1.000	0.000	0.000	0.000

L:

1.000	0.000	0.000	0.000
0.071	1.000	0.000	0.000
0.000	0.000	1.000	0.000
0.286	0.000	0.000	1.000

U:

14.000	5.000	-2.000	30.000
0.000	15.143	3.143	5.857
0.000	0.000	0.000	0.000
0.000	0.000	0.000	-5.571

Stage 2

L:

1.000	0.000	0.000	0.000
0.071	1.000	0.000	0.000
0.000	-0.086	1.000	0.000
0.286	-0.160	0.000	1.000

A:

14.000	5.000	-2.000	30.000
0.000	15.143	3.143	5.857
0.000	0.000	-3.730	1.603
0.000	0.000	1.075	-4.632

P:

0.000	0.000	0.000	1.000
0.000	1.000	0.000	0.000
0.000	0.000	1.000	0.000

P:

0.000	0.000	0.000	1.000
0.000	1.000	0.000	0.000
0.000	0.000	1.000	0.000
1.000	0.000	0.000	0.000

L:

1.000	0.000	0.000	0.000
0.071	1.000	0.000	0.000
0.000	-0.086	1.000	0.000
0.286	-0.160	0.000	1.000

U:

14.000	5.000	-2.000	30.000
0.000	15.143	3.143	5.857
0.000	0.000	-3.730	1.603
0.000	0.000	0.000	-4.632

Stage 3

L:

1.000	0.000	0.000	0.000
0.071	1.000	0.000	0.000
0.000	-0.086	1.000	0.000
0.286	-0.160	-0.288	1.000

A:

14.000	5.000	-2.000	30.000
0.000	15.143	3.143	5.857
0.000	0.000	-3.730	1.603
0.000	0.000	0.000	-4.170

P:

SOR

SOR						
iter	E					
0		0.000000e+00	0.000000e+00	0.000000e+00	0.000000e+00	
1	6.162414e-01	3.750000e-01	6.048387e-02	-4.044859e-01	-2.680696e-01	
2	3.183688e-01	5.117597e-01	3.419762e-01	-4.500492e-01	-3.046960e-01	
3	1.453273e-01	5.901442e-01	2.352284e-01	-3.903364e-01	-3.085937e-01	
4	1.098156e-01	5.153065e-01	2.815263e-01	-4.443708e-01	-2.712363e-01	
5	7.360179e-02	5.280600e-01	2.439088e-01	-3.836051e-01	-2.833615e-01	
6	4.309603e-02	5.212175e-01	2.551253e-01	-4.244577e-01	-2.793986e-01	
7	2.128919e-02	5.243866e-01	2.580027e-01	-4.037994e-01	-2.822520e-01	
8	1.074326e-02	5.270911e-01	2.525138e-01	-4.126297e-01	-2.822292e-01	
9	6.899037e-03	5.236550e-01	2.581368e-01	-4.109464e-01	-2.810727e-01	
10	5.517942e-03	5.261806e-01	2.536968e-01	-4.091465e-01	-2.821289e-01	
11	4.227797e-03	5.244410e-01	2.563803e-01	-4.117903e-01	-2.813184e-01	
12	2.849285e-03	5.254053e-01	2.550853e-01	-4.095027e-01	-2.818461e-01	
13	1.690326e-03	5.250312e-01	2.555134e-01	-4.110729e-01	-2.815844e-01	
14	8.831839e-04	5.250844e-01	2.555475e-01	-4.101965e-01	-2.816734e-01	
15	4.363164e-04	5.251707e-01	2.553365e-01	-4.105686e-01	-2.816738e-01	
16	2.698699e-04	5.250488e-01	2.555621e-01	-4.104927e-01	-2.816371e-01	
17	2.155237e-04	5.251531e-01	2.553888e-01	-4.104310e-01	-2.816789e-01	
18	1.666535e-04	5.250830e-01	2.554967e-01	-4.105317e-01	-2.816460e-01	
19	1.138496e-04	5.251215e-01	2.554428e-01	-4.104415e-01	-2.816669e-01	
20	6.816800e-05	5.251055e-01	2.554613e-01	-4.105042e-01	-2.816562e-01	
21	3.592628e-05	5.251084e-01	2.554617e-01	-4.104686e-01	-2.816601e-01	
22	1.771948e-05	5.251115e-01	2.554538e-01	-4.104842e-01	-2.816599e-01	
23	1.064441e-05	5.251068e-01	2.554626e-01	-4.104806e-01	-2.816585e-01	
24	8.426540e-06	5.251109e-01	2.554557e-01	-4.104785e-01	-2.816602e-01	
25	6.571071e-06	5.251081e-01	2.554601e-01	-4.104823e-01	-2.816589e-01	
26	4.537825e-06	5.251097e-01	2.554579e-01	-4.104788e-01	-2.816597e-01	
27	2.747051e-06	5.251090e-01	2.554587e-01	-4.104813e-01	-2.816593e-01	
28	1.462035e-06	5.251091e-01	2.554586e-01	-4.104799e-01	-2.816594e-01	
29	7.201971e-07	5.251093e-01	2.554583e-01	-4.104805e-01	-2.816594e-01	
30	4.207385e-07	5.251091e-01	2.554587e-01	-4.104804e-01	-2.816594e-01	
31	3.293455e-07	5.251092e-01	2.554584e-01	-4.104803e-01	-2.816594e-01	
32	2.588758e-07	5.251091e-01	2.554586e-01	-4.104804e-01	-2.816594e-01	
33	1.807148e-07	5.251092e-01	2.554585e-01	-4.104803e-01	-2.816594e-01	
34	1.105975e-07	5.251092e-01	2.554585e-01	-4.104804e-01	-2.816594e-01	
35	5.945865e-08	5.251092e-01	2.554585e-01	-4.104803e-01	-2.816594e-01	

Figure 14: Proof of SOR

Cholesky

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Cholesky
Stage 0

  4.000  -1.000  0.000  3.000
  1.000  15.500  3.000  8.000
  0.000  -1.300  -4.000  1.100
 14.000  5.000  -2.000 30.000

Stage 1

L:

( 2.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.500+ 0.000j) ( 1.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j) ( 0.000+ 0.000j)
( 7.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j)

U:

( 2.000+ 0.000j) ( -0.500+ 0.000j) ( 0.000+ 0.000j) ( 1.500+ 0.000j)
( 0.000+ 0.000j) ( 1.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j)

Stage 2

L:

( 2.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.500+ 0.000j) ( 3.969+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( -0.328+ 0.000j) ( 1.000+ 0.000j) ( 0.000+ 0.000j)
( 7.000+ 0.000j) ( 2.142+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j)

U:

( 2.000+ 0.000j) ( -0.500+ 0.000j) ( 0.000+ 0.000j) ( 1.500+ 0.000j)
( 0.000+ 0.000j) ( 3.969+ 0.000j) ( 0.756+ 0.000j) ( 1.827+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j)

Stage 3

L:

( 2.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.500+ 0.000j) ( 3.969+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( -0.328+ 0.000j) ( 0.000+ 1.937j) ( 0.000+ 0.000j)
( 7.000+ 0.000j) ( 2.142+ 0.000j) ( 0.000+ 1.868j) ( 1.000+ 0.000j)

U:

( 2.000+ 0.000j) ( -0.500+ 0.000j) ( 0.000+ 0.000j) ( 1.500+ 0.000j)
( 0.000+ 0.000j) ( 3.969+ 0.000j) ( 0.756+ 0.000j) ( 1.827+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 1.937j) ( 0.000+ -0.877j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 1.000+ 0.000j)

Stage 4

L:

( 2.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.500+ 0.000j) ( 3.969+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j)
( 0.000+ 0.000j) ( -0.328+ 0.000j) ( 0.000+ 1.937j) ( 0.000+ 0.000j)
( 7.000+ 0.000j) ( 2.142+ 0.000j) ( 0.000+ 1.868j) ( 3.735+ 0.000j)

U:

( 2.000+ 0.000j) ( -0.500+ 0.000j) ( 0.000+ 0.000j) ( 1.500+ 0.000j)
( 0.000+ 0.000j) ( 3.969+ 0.000j) ( 0.756+ 0.000j) ( 1.827+ 0.000j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 1.937j) ( 0.000+ -0.877j)
( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 0.000+ 0.000j) ( 3.735+ 0.000j)

After applying progressive and regressive substitution
X:
(275993036322204239822896234495.000+ 0.000j)
(170125478496320516419793977344.000+ 0.000j)
(-140893391633949672754055741440.000+ -0.000j)
(-31128222264165469229139623936.000+ 0.000j)

```

Figure 15: Proof of Cholesky