Practical Machine Learning Course Project

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Introduction

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement - a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it.

In this project, our goal will be to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. The goal of this project is to predict the manner in which they did the exercise.

Loading required packages

```
library(caret)
```

```
## Warning: package 'caret' was built under R version 3.4.3
```

```
## Loading required package: lattice
```

```
## Loading required package: ggplot2
```

```
library(rpart)
library(rpart.plot)
```

```
## Warning: package 'rpart.plot' was built under R version 3.4.3
```

```
library(RColorBrewer)
library(rattle)
```

```
## Warning: package 'rattle' was built under R version 3.4.2
```

```
## Rattle: A free graphical interface for data science with R.
## Version 5.1.0 Copyright (c) 2006-2017 Togaware Pty Ltd.
## Type 'rattle()' to shake, rattle, and roll your data.
```

```
library(randomForest)
```

```
## Warning: package 'randomForest' was built under R version 3.4.3
```

```
## randomForest 4.6-12
```

```
## Type rfNews() to see new features/changes/bug fixes.
```

```
##
## Attaching package: 'randomForest'
```

```
## The following object is masked from 'package:rattle':
##
##     importance
```

```
## The following object is masked from 'package:ggplot2':
##
##     margin
```

Load training and testing data

```
#loading the training data
download.file("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv", destfile = "pml-t

#loading the testing data
download.file("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv", destfile = "pml-te

#Read the training data and replace empty values by NA
trainingData <- read.csv("pml-training.csv", sep=",", header=TRUE, na.strings = c("NA","",'#DIV/0!'))
testingData <- read.csv("pml-testing.csv", sep=",", header=TRUE, na.strings = c("NA","",'#DIV/0!'))
```

Looking at the data

```
#structure of training data
str(trainingData)
```

```
## 'data.frame':    19622 obs. of  160 variables:
##  $ X                       : int  1 2 3 4 5 6 7 8 9 10 ...
##  $ user_name               : Factor w/ 6 levels "adelmo","carlitos",..: 2 2 2 2 2 2 2 2 2 2 ...
##  $ raw_timestamp_part_1    : int  1323084231 1323084231 1323084231 1323084232 1323084232 1323084232 1
##  $ raw_timestamp_part_2    : int  788290 808298 820366 120339 196328 304277 368296 440390 484323 484
##  $ cvtd_timestamp          : Factor w/ 20 levels "02/12/2011 13:32",..: 9 9 9 9 9 9 9 9 9 9 ...
##  $ new_window              : Factor w/ 2 levels "no","yes": 1 1 1 1 1 1 1 1 1 1 ...
##  $ num_window              : int  11 11 11 12 12 12 12 12 12 12 ...
##  $ roll_belt               : num  1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
##  $ pitch_belt              : num  8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
##  $ yaw_belt                : num  -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
##  $ total_accel_belt        : int  3 3 3 3 3 3 3 3 3 3 ...
##  $ kurtosis_roll_belt      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ kurtosis_picth_belt     : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ kurtosis_yaw_belt       : logi  NA NA NA NA NA NA ...
##  $ skewness_roll_belt      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_roll_belt.1    : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_yaw_belt       : logi  NA NA NA NA NA NA ...
##  $ max_roll_belt           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_picth_belt          : int  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_yaw_belt            : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_roll_belt           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_pitch_belt          : int  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_yaw_belt            : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_roll_belt     : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_pitch_belt    : int  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_yaw_belt      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ var_total_accel_belt    : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ avg_roll_belt           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ stddev_roll_belt        : num  NA NA NA NA NA NA NA NA NA NA ...
```

```
##  $ var_roll_belt          : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ avg_pitch_belt         : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ stddev_pitch_belt      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ var_pitch_belt         : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ avg_yaw_belt           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ stddev_yaw_belt        : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ var_yaw_belt           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ gyros_belt_x           : num  0 0.02 0 0.02 0.02 0.02 0.02 0.02 0.02 0.03 ...
##  $ gyros_belt_y           : num  0 0 0 0 0.02 0 0 0 0 0 ...
##  $ gyros_belt_z           : num  -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
##  $ accel_belt_x           : int  -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
##  $ accel_belt_y           : int  4 4 5 3 2 4 3 4 2 4 ...
##  $ accel_belt_z           : int  22 22 23 21 24 21 21 21 24 22 ...
##  $ magnet_belt_x          : int  -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
##  $ magnet_belt_y          : int  599 608 600 604 600 603 599 603 602 609 ...
##  $ magnet_belt_z          : int  -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
##  $ roll_arm               : num  -128 -128 -128 -128 -128 -128 -128 -128 -128 -128 ...
##  $ pitch_arm              : num  22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
##  $ yaw_arm                : num  -161 -161 -161 -161 -161 -161 -161 -161 -161 -161 ...
##  $ total_accel_arm        : int  34 34 34 34 34 34 34 34 34 34 ...
##  $ var_accel_arm          : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ avg_roll_arm           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ stddev_roll_arm        : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ var_roll_arm           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ avg_pitch_arm          : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ stddev_pitch_arm       : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ var_pitch_arm          : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ avg_yaw_arm            : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ stddev_yaw_arm         : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ var_yaw_arm            : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ gyros_arm_x            : num  0 0.02 0.02 0.02 0 0.02 0 0.02 0.02 0.02 ...
##  $ gyros_arm_y            : num  0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
##  $ gyros_arm_z            : num  -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
##  $ accel_arm_x            : int  -288 -290 -289 -289 -289 -289 -289 -289 -288 -288 ...
##  $ accel_arm_y            : int  109 110 110 111 111 111 111 111 109 110 ...
##  $ accel_arm_z            : int  -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
##  $ magnet_arm_x           : int  -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
##  $ magnet_arm_y           : int  337 337 344 344 337 342 336 338 341 334 ...
##  $ magnet_arm_z           : int  516 513 513 512 506 513 509 510 518 516 ...
##  $ kurtosis_roll_arm      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ kurtosis_picth_arm     : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ kurtosis_yaw_arm       : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_roll_arm      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_pitch_arm     : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_yaw_arm       : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_roll_arm           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_picth_arm          : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_yaw_arm            : int  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_roll_arm           : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_pitch_arm          : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_yaw_arm            : int  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_roll_arm     : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_pitch_arm    : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_yaw_arm      : int  NA NA NA NA NA NA NA NA NA NA ...
```

```
##  $ roll_dumbbell           : num  13.1 13.1 12.9 13.4 13.4 ...
##  $ pitch_dumbbell          : num  -70.5 -70.6 -70.3 -70.4 -70.4 ...
##  $ yaw_dumbbell            : num  -84.9 -84.7 -85.1 -84.9 -84.9 ...
##  $ kurtosis_roll_dumbbell  : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ kurtosis_picth_dumbbell : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ kurtosis_yaw_dumbbell   : logi  NA NA NA NA NA NA ...
##  $ skewness_roll_dumbbell  : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_pitch_dumbbell : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ skewness_yaw_dumbbell   : logi  NA NA NA NA NA NA ...
##  $ max_roll_dumbbell       : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_picth_dumbbell      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ max_yaw_dumbbell        : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_roll_dumbbell       : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_pitch_dumbbell      : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ min_yaw_dumbbell        : num  NA NA NA NA NA NA NA NA NA NA ...
##  $ amplitude_roll_dumbbell : num  NA NA NA NA NA NA NA NA NA NA ...
##   [list output truncated]
```

```
#structure of testing data
str(testingData)
```

```
## 'data.frame':    20 obs. of  160 variables:
##  $ X                       : int  1 2 3 4 5 6 7 8 9 10 ...
##  $ user_name               : Factor w/ 6 levels "adelmo","carlitos",..: 6 5 5 1 4 5 5 5 2 3 ...
##  $ raw_timestamp_part_1    : int  1323095002 1322673067 1322673075 1322832789 1322489635 1322673149 1
##  $ raw_timestamp_part_2    : int  868349 778725 342967 560311 814776 510661 766645 54671 916313 38428
##  $ cvtd_timestamp          : Factor w/ 11 levels "02/12/2011 13:33",..: 5 10 10 1 6 11 11 10 3 2 ...
##  $ new_window              : Factor w/ 1 level "no": 1 1 1 1 1 1 1 1 1 1 ...
##  $ num_window              : int  74 431 439 194 235 504 485 440 323 664 ...
##  $ roll_belt               : num  123 1.02 0.87 125 1.35 -5.92 1.2 0.43 0.93 114 ...
##  $ pitch_belt              : num  27 4.87 1.82 -41.6 3.33 1.59 4.44 4.15 6.72 22.4 ...
##  $ yaw_belt                : num  -4.75 -88.9 -88.5 162 -88.6 -87.7 -87.3 -88.5 -93.7 -13.1 ...
##  $ total_accel_belt        : int  20 4 5 17 3 4 4 4 4 18 ...
##  $ kurtosis_roll_belt      : logi  NA NA NA NA NA NA ...
##  $ kurtosis_picth_belt     : logi  NA NA NA NA NA NA ...
##  $ kurtosis_yaw_belt       : logi  NA NA NA NA NA NA ...
##  $ skewness_roll_belt      : logi  NA NA NA NA NA NA ...
##  $ skewness_roll_belt.1    : logi  NA NA NA NA NA NA ...
##  $ skewness_yaw_belt       : logi  NA NA NA NA NA NA ...
##  $ max_roll_belt           : logi  NA NA NA NA NA NA ...
##  $ max_picth_belt          : logi  NA NA NA NA NA NA ...
##  $ max_yaw_belt            : logi  NA NA NA NA NA NA ...
##  $ min_roll_belt           : logi  NA NA NA NA NA NA ...
##  $ min_pitch_belt          : logi  NA NA NA NA NA NA ...
##  $ min_yaw_belt            : logi  NA NA NA NA NA NA ...
##  $ amplitude_roll_belt     : logi  NA NA NA NA NA NA ...
##  $ amplitude_pitch_belt    : logi  NA NA NA NA NA NA ...
##  $ amplitude_yaw_belt      : logi  NA NA NA NA NA NA ...
##  $ var_total_accel_belt    : logi  NA NA NA NA NA NA ...
##  $ avg_roll_belt           : logi  NA NA NA NA NA NA ...
##  $ stddev_roll_belt        : logi  NA NA NA NA NA NA ...
##  $ var_roll_belt           : logi  NA NA NA NA NA NA ...
##  $ avg_pitch_belt          : logi  NA NA NA NA NA NA ...
##  $ stddev_pitch_belt       : logi  NA NA NA NA NA NA ...
##  $ var_pitch_belt          : logi  NA NA NA NA NA NA ...
```

```
##  $ avg_yaw_belt           : logi  NA NA NA NA NA NA ...
##  $ stddev_yaw_belt        : logi  NA NA NA NA NA NA ...
##  $ var_yaw_belt           : logi  NA NA NA NA NA NA ...
##  $ gyros_belt_x           : num  -0.5 -0.06 0.05 0.11 0.03 0.1 -0.06 -0.18 0.1 0.14 ...
##  $ gyros_belt_y           : num  -0.02 -0.02 0.02 0.11 0.02 0.05 0 -0.02 0 0.11 ...
##  $ gyros_belt_z           : num  -0.46 -0.07 0.03 -0.16 0 -0.13 0 -0.03 -0.02 -0.16 ...
##  $ accel_belt_x           : int  -38 -13 1 46 -8 -11 -14 -10 -15 -25 ...
##  $ accel_belt_y           : int  69 11 -1 45 4 -16 2 -2 1 63 ...
##  $ accel_belt_z           : int  -179 39 49 -156 27 38 35 42 32 -158 ...
##  $ magnet_belt_x          : int  -13 43 29 169 33 31 50 39 -6 10 ...
##  $ magnet_belt_y          : int  581 636 631 608 566 638 622 635 600 601 ...
##  $ magnet_belt_z          : int  -382 -309 -312 -304 -418 -291 -315 -305 -302 -330 ...
##  $ roll_arm               : num  40.7 0 0 -109 76.1 0 0 0 -137 -82.4 ...
##  $ pitch_arm              : num  -27.8 0 0 55 2.76 0 0 0 11.2 -63.8 ...
##  $ yaw_arm                : num  178 0 0 -142 102 0 0 0 -167 -75.3 ...
##  $ total_accel_arm        : int  10 38 44 25 29 14 15 22 34 32 ...
##  $ var_accel_arm          : logi  NA NA NA NA NA NA ...
##  $ avg_roll_arm           : logi  NA NA NA NA NA NA ...
##  $ stddev_roll_arm        : logi  NA NA NA NA NA NA ...
##  $ var_roll_arm           : logi  NA NA NA NA NA NA ...
##  $ avg_pitch_arm          : logi  NA NA NA NA NA NA ...
##  $ stddev_pitch_arm       : logi  NA NA NA NA NA NA ...
##  $ var_pitch_arm          : logi  NA NA NA NA NA NA ...
##  $ avg_yaw_arm            : logi  NA NA NA NA NA NA ...
##  $ stddev_yaw_arm         : logi  NA NA NA NA NA NA ...
##  $ var_yaw_arm            : logi  NA NA NA NA NA NA ...
##  $ gyros_arm_x            : num  -1.65 -1.17 2.1 0.22 -1.96 0.02 2.36 -3.71 0.03 0.26 ...
##  $ gyros_arm_y            : num  0.48 0.85 -1.36 -0.51 0.79 0.05 -1.01 1.85 -0.02 -0.5 ...
##  $ gyros_arm_z            : num  -0.18 -0.43 1.13 0.92 -0.54 -0.07 0.89 -0.69 -0.02 0.79 ...
##  $ accel_arm_x            : int  16 -290 -341 -238 -197 -26 99 -98 -287 -301 ...
##  $ accel_arm_y            : int  38 215 245 -57 200 130 79 175 111 -42 ...
##  $ accel_arm_z            : int  93 -90 -87 6 -30 -19 -67 -78 -122 -80 ...
##  $ magnet_arm_x           : int  -326 -325 -264 -173 -170 396 702 535 -367 -420 ...
##  $ magnet_arm_y           : int  385 447 474 257 275 176 15 215 335 294 ...
##  $ magnet_arm_z           : int  481 434 413 633 617 516 217 385 520 493 ...
##  $ kurtosis_roll_arm      : logi  NA NA NA NA NA NA ...
##  $ kurtosis_picth_arm     : logi  NA NA NA NA NA NA ...
##  $ kurtosis_yaw_arm       : logi  NA NA NA NA NA NA ...
##  $ skewness_roll_arm      : logi  NA NA NA NA NA NA ...
##  $ skewness_pitch_arm     : logi  NA NA NA NA NA NA ...
##  $ skewness_yaw_arm       : logi  NA NA NA NA NA NA ...
##  $ max_roll_arm           : logi  NA NA NA NA NA NA ...
##  $ max_picth_arm          : logi  NA NA NA NA NA NA ...
##  $ max_yaw_arm            : logi  NA NA NA NA NA NA ...
##  $ min_roll_arm           : logi  NA NA NA NA NA NA ...
##  $ min_pitch_arm          : logi  NA NA NA NA NA NA ...
##  $ min_yaw_arm            : logi  NA NA NA NA NA NA ...
##  $ amplitude_roll_arm     : logi  NA NA NA NA NA NA ...
##  $ amplitude_pitch_arm    : logi  NA NA NA NA NA NA ...
##  $ amplitude_yaw_arm      : logi  NA NA NA NA NA NA ...
##  $ roll_dumbbell          : num  -17.7 54.5 57.1 43.1 -101.4 ...
##  $ pitch_dumbbell         : num  25 -53.7 -51.4 -30 -53.4 ...
##  $ yaw_dumbbell           : num  126.2 -75.5 -75.2 -103.3 -14.2 ...
##  $ kurtosis_roll_dumbbell : logi  NA NA NA NA NA NA ...
```

```
##  $ kurtosis_picth_dumbbell : logi  NA NA NA NA NA NA ...
##  $ kurtosis_yaw_dumbbell   : logi  NA NA NA NA NA NA ...
##  $ skewness_roll_dumbbell  : logi  NA NA NA NA NA NA ...
##  $ skewness_pitch_dumbbell : logi  NA NA NA NA NA NA ...
##  $ skewness_yaw_dumbbell   : logi  NA NA NA NA NA NA ...
##  $ max_roll_dumbbell       : logi  NA NA NA NA NA NA ...
##  $ max_picth_dumbbell      : logi  NA NA NA NA NA NA ...
##  $ max_yaw_dumbbell        : logi  NA NA NA NA NA NA ...
##  $ min_roll_dumbbell       : logi  NA NA NA NA NA NA ...
##  $ min_pitch_dumbbell      : logi  NA NA NA NA NA NA ...
##  $ min_yaw_dumbbell        : logi  NA NA NA NA NA NA ...
##  $ amplitude_roll_dumbbell : logi  NA NA NA NA NA NA ...
##   [list output truncated]
```

Our data consists of 19622 values of 160 variables.

Cleaning the data

We partition our training data into two

```
partTrain <- createDataPartition(trainingData$classe, p=0.6, list=FALSE)
myTrainData <- trainingData[partTrain, ]
myTestData <- trainingData[-partTrain, ]
dim(myTrainData); dim(myTestData)
```

```
## [1] 11776   160
```

```
## [1] 7846  160
```

To clean the data, we 1.)Remove variables having zero variance. 2.)Remove the first column of myTrainData and myTestData data sets. 3.)Remove variables with more than 60% missing values.

```
#Remove zero variance variables
novar <- nearZeroVar(myTrainData, saveMetrics=TRUE)
myTrainData <- myTrainData[,novar$nzv==FALSE]

novar <- nearZeroVar(myTestData, saveMetrics=TRUE)
myTestData <- myTestData[,novar$nzv==FALSE]

#Remove the first column of the myTrainData data set
myTrainData <- myTrainData[c(-1)]

#Clean variables with more than 60% missing values
trainData <- myTrainData
for(i in 1:length(myTrainData)) {
    if( sum( is.na( myTrainData[, i] ) ) /nrow(myTrainData) >= .7) {
        for(j in 1:length(trainData)) {
            if( length( grep(names(myTrainData[i]), names(trainData)[j]) ) == 1)  {
                trainData <- trainData[ , -j]
            }
        }
    }
}

# Set back to the original variable name
myTrainData <- trainData
```

```
rm(trainData)

#Transform the myTestData and testingData data sets
cleanData1 <- colnames(myTrainData)
cleanData2 <- colnames(myTrainData[, -58])  # remove the classe column
myTestData <- myTestData[cleanData1]         # allow only variables in myTestData that are also in myTr
testingData <- testingData[cleanData2]             # allow only variables in testingData that are also

dim(myTestData)
```

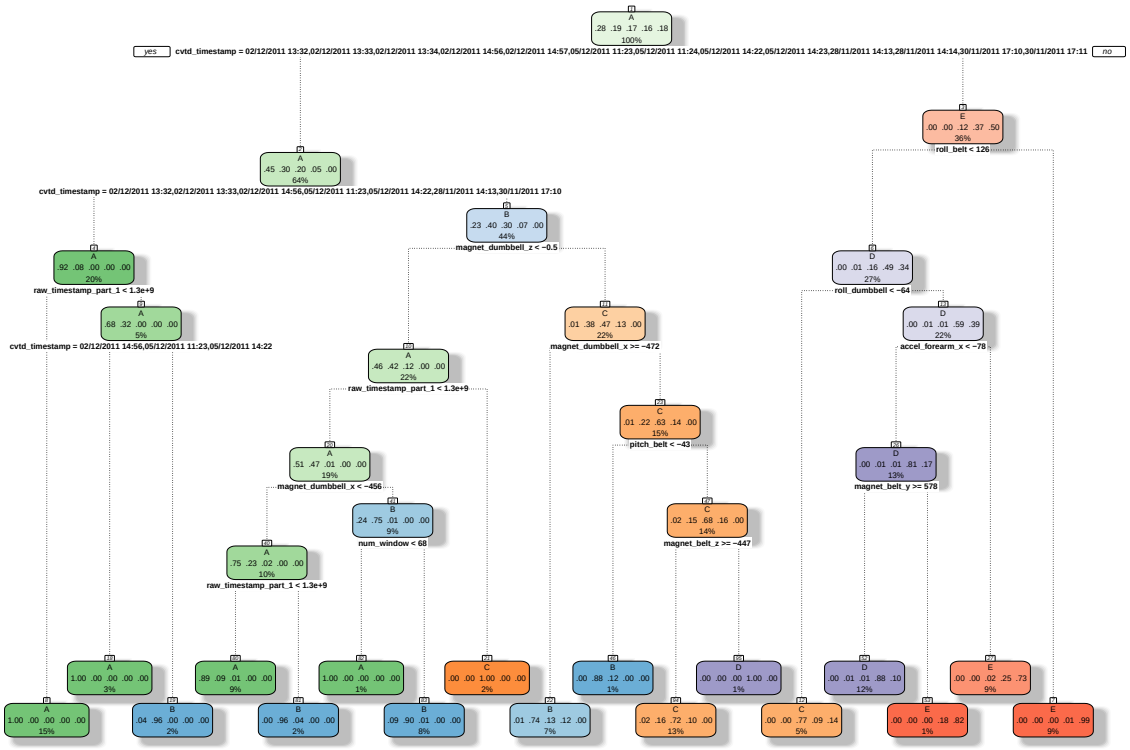
```
## [1] 7846   58
```

```
#Coerce the data into the same type
for (i in 1:length(testingData) ) {
  for(j in 1:length(myTrainData)) {
    if( length( grep(names(myTrainData[i]), names(testingData)[j]) ) == 1)  {
      class(testingData[j]) <- class(myTrainData[i])
    }
  }
}

# To get the same class between testing and myTraining
testingData <- rbind(myTrainData[2, -58] , testingData)
testingData <- testingData[-1,]
```

Prediction with decision trees

```
set.seed(3)
dtmodel <- rpart(classe ~ ., data=myTrainData, method="class")
fancyRpartPlot(dtmodel)
```



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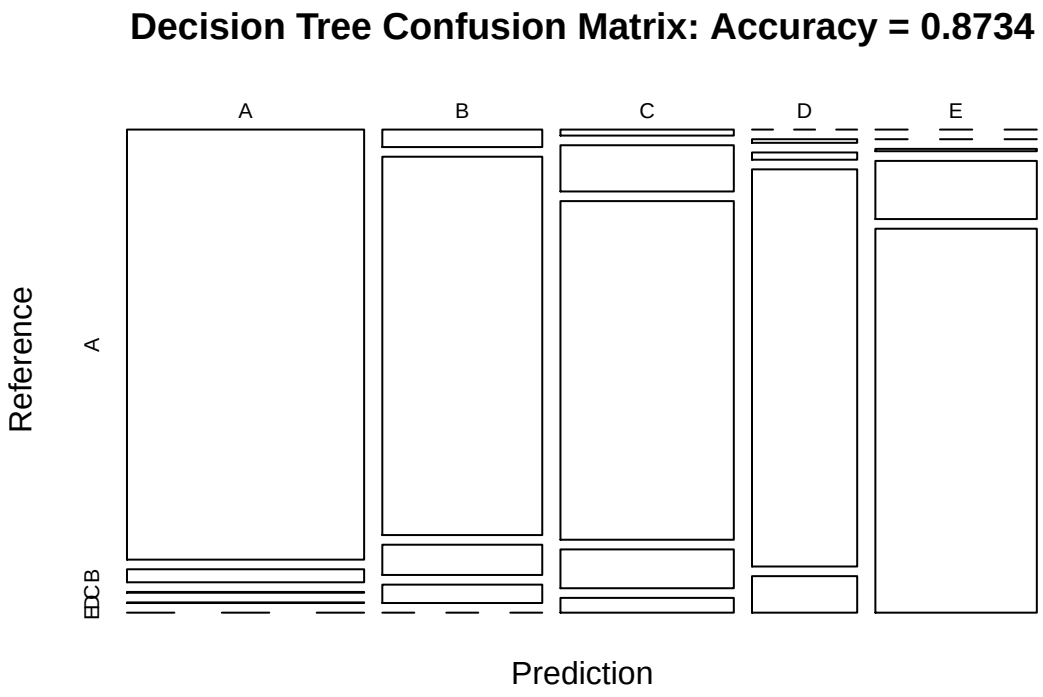
```
predictionsdt <- predict(dtmodel, myTestData, type = "class")
cmtree <- confusionMatrix(predictionsdt, myTestData$classe)
cmtree
```

```
## Confusion Matrix and Statistics
##
##           Reference
## Prediction    A    B    C    D    E
##          A 2151   65    4    3    0
##          B   59 1276  102   62    0
##          C   22  169 1238  142   54
##          D    0    8   16  881   81
##          E    0    0    8  198 1307
##
## Overall Statistics
##
##                Accuracy : 0.8734
##                  95% CI : (0.8659, 0.8807)
##     No Information Rate : 0.2845
##     P-Value [Acc > NIR] : < 2.2e-16
##
##                   Kappa : 0.8399
##  Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##                      Class: A Class: B Class: C Class: D Class: E
```

```
## Sensitivity            0.9637   0.8406   0.9050   0.6851   0.9064
## Specificity            0.9872   0.9648   0.9403   0.9840   0.9678
## Pos Pred Value         0.9676   0.8512   0.7618   0.8935   0.8638
## Neg Pred Value         0.9856   0.9619   0.9791   0.9410   0.9787
## Prevalence             0.2845   0.1935   0.1744   0.1639   0.1838
## Detection Rate         0.2742   0.1626   0.1578   0.1123   0.1666
## Detection Prevalence   0.2833   0.1911   0.2071   0.1257   0.1928
## Balanced Accuracy      0.9754   0.9027   0.9226   0.8345   0.9371
```

```
plot(cmtree$table, col = cmtree$byClass, main = paste("Decision Tree Confusion Matrix: Accuracy =", rou
```



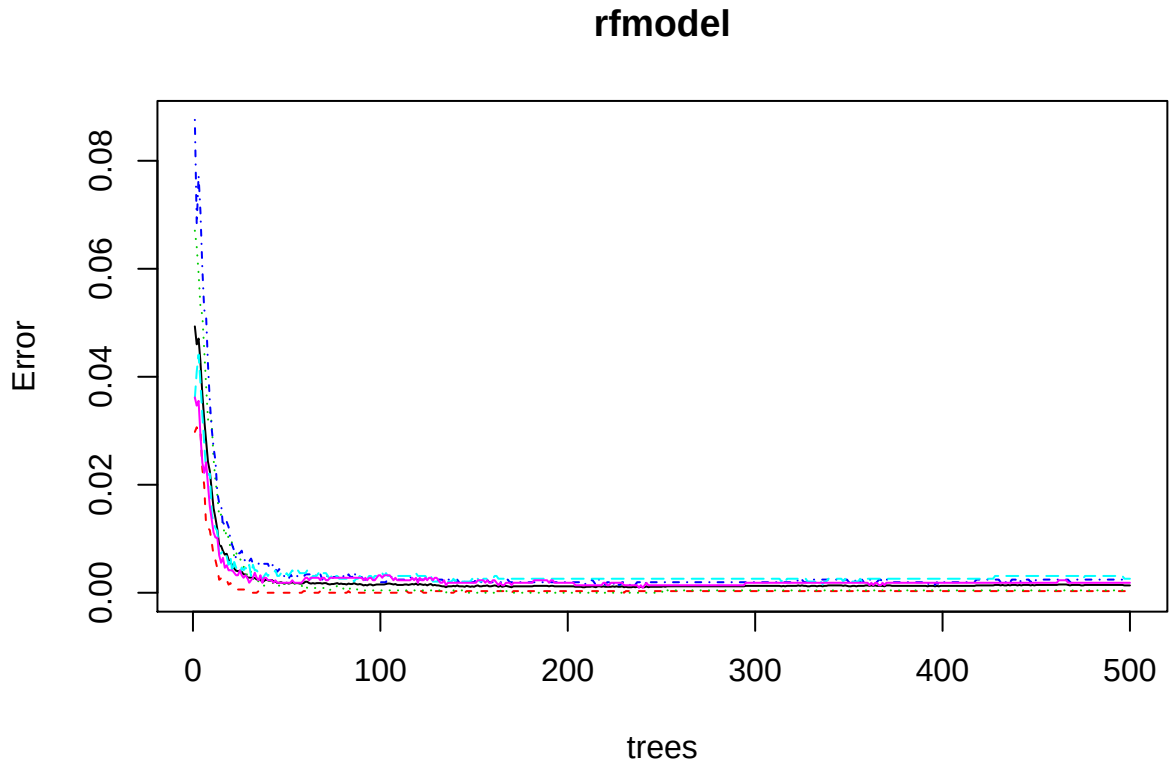
Prediction using Random Forest

```
set.seed(1)
rfmodel <- randomForest(classe ~ ., data=myTrainData)
prediction1 <- predict(rfmodel, myTestData, type = "class")
cm <- confusionMatrix(prediction1, myTestData$classe)
cm
```

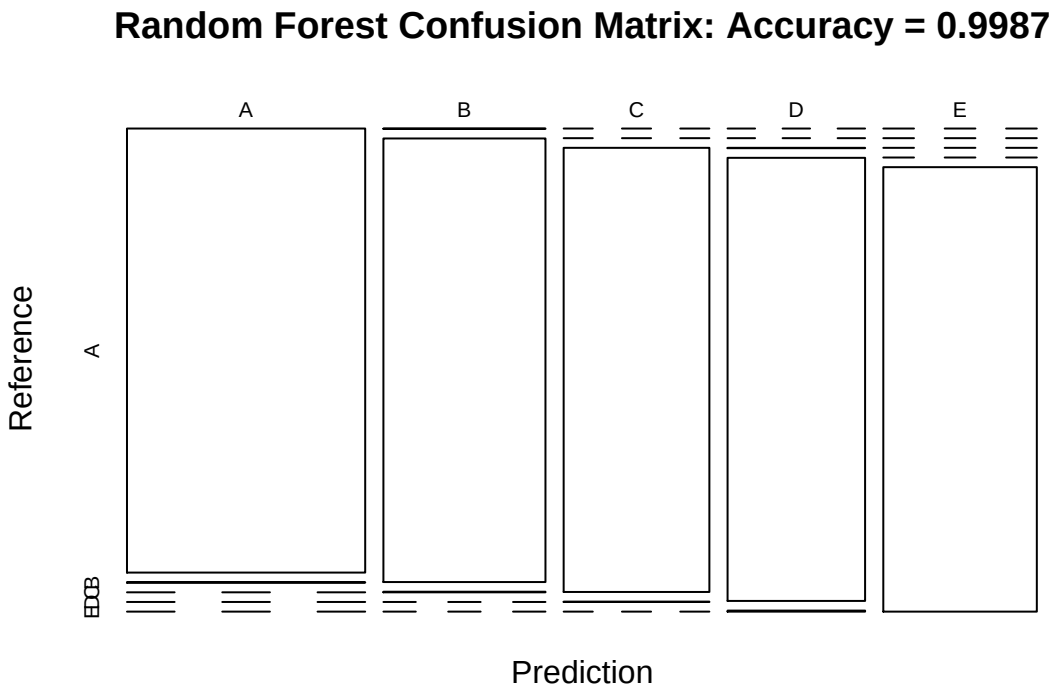
```
## Confusion Matrix and Statistics
##
##           Reference
## Prediction    A    B    C    D    E
##          A 2231    2    0    0    0
##          B    1 1516    2    0    0
##          C    0    0 1365    1    0
```

```
##          D    0    0    1 1285    3
##          E    0    0    0    0 1439
##
## Overall Statistics
##
##                Accuracy : 0.9987
##                  95% CI : (0.9977, 0.9994)
##     No Information Rate : 0.2845
##     P-Value [Acc > NIR] : < 2.2e-16
##
##                   Kappa : 0.9984
##  Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##                      Class: A Class: B Class: C Class: D Class: E
## Sensitivity            0.9996   0.9987   0.9978   0.9992   0.9979
## Specificity            0.9996   0.9995   0.9998   0.9994   1.0000
## Pos Pred Value         0.9991   0.9980   0.9993   0.9969   1.0000
## Neg Pred Value         0.9998   0.9997   0.9995   0.9998   0.9995
## Prevalence             0.2845   0.1935   0.1744   0.1639   0.1838
## Detection Rate         0.2843   0.1932   0.1740   0.1638   0.1834
## Detection Prevalence   0.2846   0.1936   0.1741   0.1643   0.1834
## Balanced Accuracy      0.9996   0.9991   0.9988   0.9993   0.9990
```

```
plot(rfmodel)
```



```
plot(cm$table, col = cmtree$byClass, main = paste("Random Forest Confusion Matrix: Accuracy =", round(cm
```



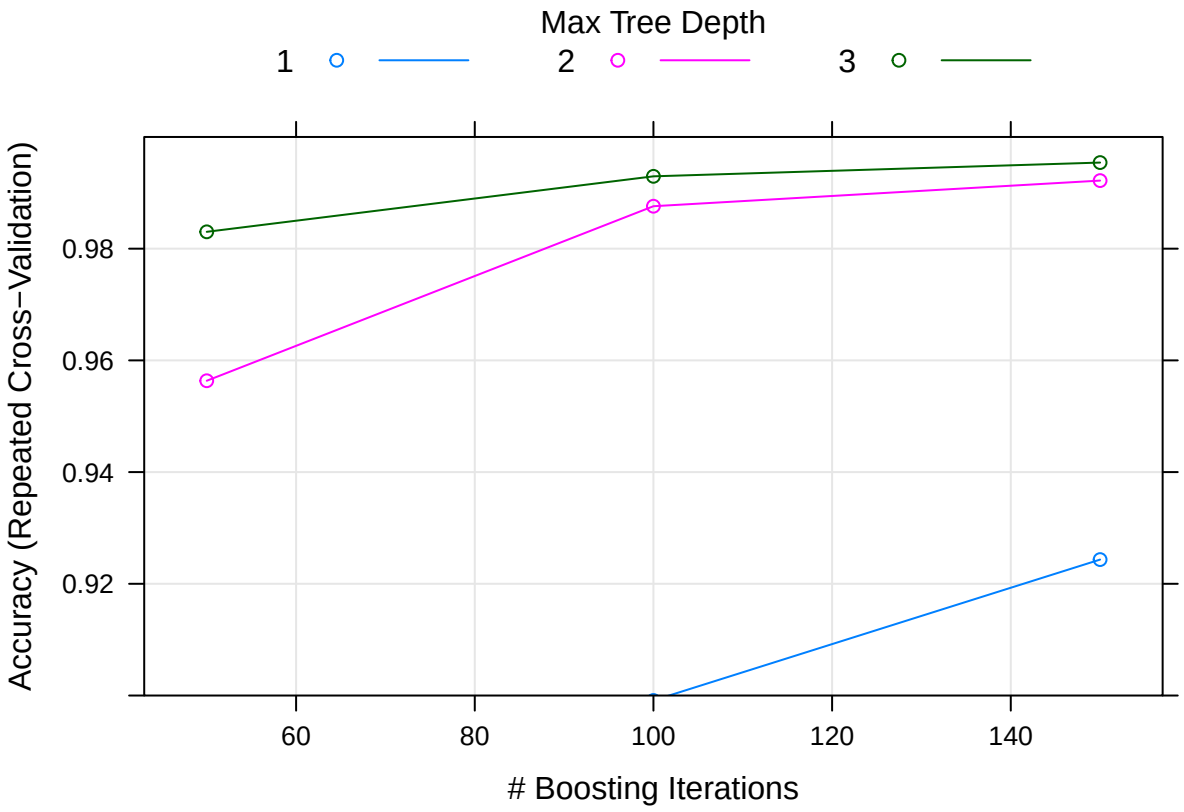
Prediction with generalization booster

```
set.seed(2)
fitControl <- trainControl(method = "repeatedcv",
                           number = 5,
                           repeats = 1)

gbmmodel <- train(classe ~ ., data=myTrainData, method = "gbm",
                  trControl = fitControl,
                  verbose = FALSE)


gbmFinModel <- gbmmodel$finalModel

gbmPrediction <- predict(gbmmodel, newdata=myTestData)
gbmAccuracy <- confusionMatrix(gbmPrediction, myTestData$classe)
gbmAccuracy
```

```
## Confusion Matrix and Statistics
##
##           Reference
## Prediction    A    B    C    D    E
```

```
##          A 2229    4    0    0    0
##          B    3 1507    2    0    0
##          C    0    5 1356    1    0
##          D    0    2   10 1283    0
##          E    0    0    0    2 1442
##
## Overall Statistics
##
##                Accuracy : 0.9963
##                  95% CI : (0.9947, 0.9975)
##     No Information Rate : 0.2845
##     P-Value [Acc > NIR] : < 2.2e-16
##
##                   Kappa : 0.9953
##  Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##                      Class: A Class: B Class: C Class: D Class: E
## Sensitivity            0.9987   0.9928   0.9912   0.9977   1.0000
## Specificity            0.9993   0.9992   0.9991   0.9982   0.9997
## Pos Pred Value         0.9982   0.9967   0.9956   0.9907   0.9986
## Neg Pred Value         0.9995   0.9983   0.9981   0.9995   1.0000
## Prevalence             0.2845   0.1935   0.1744   0.1639   0.1838
## Detection Rate         0.2841   0.1921   0.1728   0.1635   0.1838
## Detection Prevalence   0.2846   0.1927   0.1736   0.1651   0.1840
## Balanced Accuracy      0.9990   0.9960   0.9952   0.9979   0.9998
```

```
plot(gbmmodel, ylim=c(0.9, 1))
```



Predicting results on test data

Random Forests gave an Accuracy in the myTesting dataset of 99.82%, which was more accurate that what I got from the Decision Trees or GBM. The expected out-of-sample error is 100-99.82 = 0.18%.

```
prediction2 <- predict(rfmodel, testingData, type = "class")
prediction2
```

```
##  1 21  3  4  5  6  7  8  9 10 11 12 13 14 15 16 17 18 19 20
##  B  A  B  A  A  E  D  B  A  A  B  C  B  A  E  E  A  B  B  B
## Levels: A B C D E
```