

## Contents

- First, Load and Parse Observation Data
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- Initialize Variables
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```
% function Xstar0 = BatchProcess()
% Compute new xhat
% Looks for functions to return:
%   G
%   Htilde
% Inside of /Filters/BatchTools.m

clc; clear all; close all; format compact; tic
warning off MATLAB:nearlySingularMatrix
```

## First, Load and Parse Observation Data

```
load('Observations.mat');
t_obs      = obs(:,1);
station    = obs(:,2);
rho_obs    = obs(:,3);
rhodot_obs = obs(:,4);
```

## Pre-Allocations

```
x      = zeros(length(obs));
y      = x;
z      = x;
xdot   = x;
ydot   = x;
zdot   = x;
Xsite1 = x;
Ysite1 = x;
Zsite1 = x;
Xsite2 = x;
Ysite2 = x;
Zsite2 = x;
Xsite3 = x;
Ysite3 = x;
Zsite3 = x;
Phi     = cell(1,length(obs));
y_res   = zeros(2,length(obs));
Xsite   = x;
Ysite   = x;
```

```
Zsite = x;
theta = x;
```

## Initialize Variables

```
% Calculations for rho, rhodot. Put into bigger function sometime
%-----
findrhostar = @(x,y,z,Xsite,Ysite,Zsite,theta) sqrt(x^2+y^2+z^2+Xsite^2+Ysite^2+Zsite^2);
findrhodotstar = @(x,y,z,xdot,ydot,zdot,Xsite,Ysite,Zsite,theta,theta_dot,rho) (x*xdot + y*ydot + z*zdot +
    +(xdot*Ysite - ydot*Xsite)*sin(theta) + theta_dot*(x*Ysite - y*Xsite)*cos(theta))/rho;
%-----

% System Constants
%-----
Phi_Init = eye(18,18);
tol = 1e-13;
uE = 3.986004415e14; % m^3/s^2
J2 = 1.082626925638815e-3; % []
Cd = 2; % []
theta_dot = 7.29211585530066e-5; % rad/s
time = t_obs;
%-----

% Information
%-----
sigma_rho = 0.01; % rms std
sigma_rhodot = 0.001; % rms std
R = [sigma_rho^2 , 0 ; ...
     0 , sigma_rhodot^2];
W = inv(R);
Pbar0 = diag([1e6,1e6,1e6,1e6,1e6,1e6,1e20,1e6,1e6,1e-10,1e-10,1e-10,1e6,1e6,1e6,1e6]);
%-----

% Initial Conditions
%-----
RV_Init = [757700,5222607.0,4851500.0,2213.21,4678.34,-5371.30];
Station_Init= [-5127510.0 , -3794160.0 , 0.0 , ... %101
               3860910.0 , 3238490.0 , 3898094.0 , ... %337
               549505.0 , -1380872.0 , 6182197.0 ]; %394
Const_Init = [uE , J2 , Cd ];
%-----

% Form Initialization State
%-----
Xstar0 = [RV_Init , Const_Init , Station_Init , reshape(Phi_Init,1,length(Phi_Init)^2)]';
```

```

%-----

% Initial xbar0, or a-priori state deviation from reference trajectory
%-----
xbar0      = zeros(18,1);
%-----

```

## Perform Batch Loop

```

num_iterations = 1;
for ii = 1:num_iterations

    % Dynamical Integration
    %-----
    tol_mat      = ones(size(Xstar0)) .* tol;
    options      = odeset('RelTol',tol,'AbsTol',tol,'OutputFcn',@odetpbar);

    [time,StatePhi] = ode45(@StateDeriv_WithPhi,time,Xstar0,options);
    %-----

    % Batch Processing Part
    %-----
    Lam = inv(Pbar0);
    N    = Pbar0\xbar0; % same as inv(pobar)*xbar0
    N_orig = N;
    Lam_orig=Lam;

    % Reform Phi Matrix
    %-----
    for jj = 1:length(time)
        Phi      = reshape(StatePhi(jj,19:end),size(Phi_Init));
        Xstar     = StatePhi(:,1:18);
        x         = Xstar(:,1);
        y         = Xstar(:,2);
        z         = Xstar(:,3);
        xdot      = Xstar(:,4);
        ydot      = Xstar(:,5);
        zdot      = Xstar(:,6);
        Xsite1    = Xstar(:,10);
        Ysite1    = Xstar(:,11);
        Zsite1    = Xstar(:,12);
        Xsite2    = Xstar(:,13);
        Ysite2    = Xstar(:,14);
        Zsite2    = Xstar(:,15);
    end
end

```

```

Xsite3 = Xstar(:,16);
Ysite3 = Xstar(:,17);
Zsite3 = Xstar(:,18);

%-----

%
parfor jj = 1:length(rho_obs)
    theta(jj) = theta_dot*time(jj);
    Htilde = zeros(2,18);
    % Check Stations
    %-----
    %Station 1
    if station(jj) == 101
        Xsite(jj) = Xsite1(jj);    Ysite(jj)=Ysite1(jj);    Zsite(jj)=Zsite1(jj);
        % Find H Tilde
        %-----
        Htilde = FindHtilde(Xsite(jj),Ysite(jj),Zsite(jj),theta(jj),theta_dot,x(jj),xdot);
        %-----
        Htilde = [Htilde , zeros(2,6)];

    end

    %Station 2
    if station(jj) == 337
        Xsite(jj) = Xsite2(jj);    Ysite(jj)=Ysite2(jj);    Zsite(jj)=Zsite2(jj);
        % Find H Tilde
        %-----
        Htilde = FindHtilde(Xsite(jj),Ysite(jj),Zsite(jj),theta(jj),theta_dot,x(jj),xdot);
        %-----
        Htilde = [Htilde(:,1:9) , zeros(2,3), Htilde(:,10:12),zeros(2,3)];

    end

    %Station 3
    if station(jj) == 394
        Xsite(jj) = Xsite3(jj);    Ysite(jj)=Ysite3(jj);    Zsite(jj)=Zsite3(jj);
        % Find H Tilde
        %-----
        Htilde = FindHtilde(Xsite(jj),Ysite(jj),Zsite(jj),theta(jj),theta_dot,x(jj),xdot);
        %-----
        Htilde = [Htilde(:,1:9),zeros(2,6),Htilde(:,10:12)];

    end
    %-----

```

```

% Map To Epoch
%-----
H{jj}    = Htilde*Phi;
%-----

% Cumulate INFORMATION?? Matrix
%-----
Lam       = Lam + H{jj}'*W*H{jj};
%-----

% Put into FindG
%-----
rhostar   = findrhostar(x(jj),y(jj),z(jj),Xsite(jj),Ysite(jj),Zsite(jj),theta(jj));
rhodotstar= findrhodotstar(x(jj),y(jj),z(jj),xdot(jj),ydot(jj),zdot(jj),Xsite(jj),Y
%-----

% Find Observation Deviations
%-----
ystar      = [rhostar;rhodotstar];
y_res(:,jj) = [rho_obs(jj);rhodot_obs(jj)] - ystar;
%-----

% Cumulate SOMETING?? Matrix
%-----
N          = N + H{jj}'*W*y_res(:,jj);
%-----

end
fprintf('RMS of rho is : %3.5f \n',rms(y_res(1,:)))
fprintf('RMS of rhodot is : %3.5f \n',rms(y_res(2,:)))
% Find New State Deviation
%-----
xhat0     = Lam\N;
%-----

% Update Best Guess of Initial Conditions
%-----
Xstar0    = [Xstar0(1:18) + xhat0; (reshape(Phi_Init,length(Phi_Init)^2,1))];
%-----

% Update a-priori State Deviation
%-----
xbar0     = xbar0 - xhat0;
%-----

```

```

figure(1)
subplot(num_iterations,2,2*ii-1)
plot(y_res(1,:))
ylabel('rho residues')
xlabel('observation number')

subplot(num_iterations,2,2*ii)
plot(y_res(2,:))
ylabel('rho residues')
xlabel('observation number')

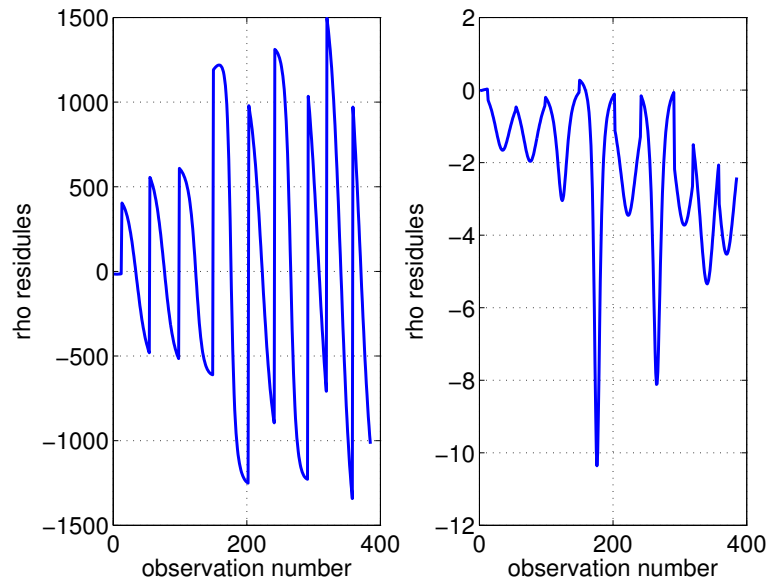
end

fprintf('\n\nRunning Time for Batch Processor : %3.5f\n\n',toc)

ODE integration: 100%      [.....]
Integration time: 3.1912
RMS of rho is : 732.74831
RMS of rhodot is : 2.90017

Running Time for Batch Processor : 4.44755

```



## Display Outputs

```
SumHtWH = Lam - Lam_orig;
SumHtWy = N - N_orig;

fprintf('Sum of H''WH is :\n')
printMatrix(SumHtWH,27,10);
fprintf('\n\n\n Sum of H''Wy is :\n')
printMatrix(SumHtWy,15,5);

fprintf('\n\n\n Output of xhat0 is :\n')
printMatrix(xhat0,27,10)

Sum of H'WH is :
      15642892.2139638532      96445342.0481109023
87553862.2093564719      39035426229.8915863037
85380621054.4556427002      -89456061116.4034271240
-1.5954227562      286051153800621.4375000000
-7713897.2730123671      94424.1960645709
-55744.7939965413      1837092.6939293954
678092.1290839665      638409.6495227553
-1277860.1201436382      733971.6775837080
635723.5618613327      123510.5898856849
      96445342.0481109023      647567086.6741099358
591096262.6015053988      261992453682.0038146973
568653301031.6795654297      -602809745181.2003173828
-10.7016510482      1995728895595858.5000000000
-52282664.0776869431      -773424.0039953113
1432595.0899111021      10595645.8622289877
7392018.3361077625      1308575.5194160349
-8711564.5189841464      6309531.7304992266
1145230.3956329017      -266474.1940985713
      87553862.2093564868      591096262.6015053988
545069191.1156791449      239589749865.7162170410
517506233589.1514892578      -554569933689.5238037109
-9.8035792463      1834580284670072.5000000000
-48506619.6265168786      -402655.1210385546
1045048.6870896441      8376683.0559452018
7194081.2672169982      1587982.6929616374
-8729815.9775514472      6065287.8468057951
1084368.6505893399      -273346.3020820002
      39035426229.8915939331      261992453682.0038452148
239589749865.7162170410      106661554804651.4062500000
230019289585374.4687500000      -244305773049970.0625000000
-4332.9515060860      803726582978524416.0000000000
-21168772678.9310188293      -50859313.7735307217
```

302043238.1972026825	4288498976.4752812386	
2916254082.3784904480	611717806.8690390587	
-3472182365.3918185234	2884955908.2518606186	
206458670.4745006561	-225374609.3335765600	
85380621054.4556274414	568653301031.6795654297	
517506233589.1514892578	230019289585374.4687500000	
500449734561211.2500000000	-528426575793172.3750000000	
-9393.3837935608	1745988440697024256.0000000000	
-45491258336.3640747070	-690061915.6090250015	
1311456344.9984645844	9736126092.6784706116	
6209844895.7019824982	1224063166.9970550537	
-7345835814.4685678482	5408488696.8719940186	
1469890745.0940928459	-83278163.7571291327	
-89456061116.4034271240	-602809745181.2001953125	
-554569933689.5236816406	-244305773049970.0625000000	
-528426575793172.3125000000	564925217977991.5000000000	
9992.9746072029	-1868777680042144768.0000000000	
49351823593.8733901978	453804529.4006270766	
-1186627512.8099844456	-8815559900.1859703064	
-7155118427.5747156143	-1442785596.3882243633	
8473696896.6845960617	-6211919135.8050832748	
-1275868107.9849932194	227040169.4953751564	
-1.5954227562	-10.7016510482	
-9.8035792463	-4332.9515060860	
-9393.3837935608	9992.9746072029	
0.0000001772	-33071416.4047614485	0.8680775739
0.0105353831	-0.0212645324	-0.1670443062
-0.1240245340	-0.0250132771	
0.1466430480	-0.1057804599	-0.0238949898
0.0031677740		
286051153800621.4375000000	1995728895595858.5000000000	
1834580284670072.5000000000	803726582978524544.0000000000	
1745988440697024000.0000000000	-1868777680042144512.0000000000	
-33071416.4047614485	6357520838113366114304.0000000000	
-162933815454797.0937500000	-5176617560516.4169921875	
8224474829224.8125000000	27349691260043.2031250000	
27574275176521.5312500000	81037364953.2355957031	
-27206535197374.7304687500	19159599168762.6289062500	
3598318516081.8442382812	-805207179437.5408935547	
-7713897.2730123661	-52282664.0776869431	
-48506619.6265168637	-21168772678.9310188293	
-45491258336.3640747070	49351823593.8733901978	
0.8680775739	-162933815454797.1250000000	4712675.9088873239
4607.5040727804	-47211.4081440844	
-617765.3808566579	-571670.9101045745	
-87065.8866727704	691156.4551380392	



-593635.2690462477	36198.6465750722	
59945.3954439472		
94424.1960645709	-773424.0039953114	
-402655.1210385547	-50859313.7735307217	
-690061915.6090250015	453804529.4006271362	
0.0105353831	-5176617560516.4169921875	4607.5040727804
301411.2586326599	-238883.2131691568	
13355.2193051041	0.0000000000	
0.0000000000	0.0000000000	0.0000000000
0.0000000000	0.0000000000	
-55744.7939965413	1432595.0899111023	
1045048.6870896443	302043238.1972027421	
1311456344.9984645844	-1186627512.8099844456	
-0.0212645324	8224474829224.8115234375	
-47211.4081440844	-238883.2131691568	
382196.5541191101	-5925.9028849073	
0.0000000000	0.0000000000	0.0000000000
0.0000000000	0.0000000000	0.0000000000
1837092.6939293954	10595645.8622289877	
8376683.0559452018	4288498976.4752812386	
9736126092.6784706116	-8815559900.1859703064	
-0.1670443062	27349691260043.2031250000	
-617765.3808566579	13355.2193051041	
-5925.9028849073	547491.3019981384	
0.0000000000	0.0000000000	0.0000000000
0.0000000000	0.0000000000	0.0000000000
678092.1290839666	7392018.3361077616	
7194081.2672169982	2916254082.3784904480	
6209844895.7019824982	-7155118427.5747156143	
-0.1240245340	27574275176521.5351562500	
-571670.9101045745	0.0000000000	
0.0000000000	0.0000000000	443985.4002217269
-187039.8461420266	-202932.9174915103	
0.0000000000	0.0000000000	0.0000000000
638409.6495227553	1308575.5194160349	
1587982.6929616374	611717806.8690390587	
1224063166.9970550537	-1442785596.3882243633	
-0.0250132771	81037364953.2366943359	
-87065.8866727704	0.0000000000	
0.0000000000	0.0000000000	-187039.8461420266
489429.5398828702	-185546.2470719735	
0.0000000000	0.0000000000	0.0000000000
-1277860.1201436382	-8711564.5189841483	
-8729815.9775514472	-3472182365.3918190002	
-7345835814.4685678482	8473696896.6845960617	
0.1466430480	-27206535197374.7382812500	691156.4551380392

0.0000000000	0.0000000000	0.0000000000
-202932.9174915103	-185546.2470719735	
467743.5986754843	0.0000000000	
0.0000000000	0.0000000000	
733971.6775837080	6309531.7304992266	
6065287.8468057951	2884955908.2518606186	
5408488696.8719940186	-6211919135.8050832748	
-0.1057804599	19159599168762.6289062500	
-593635.2690462477	0.0000000000	
0.0000000000	0.0000000000	0.0000000000
0.0000000000	0.0000000000	477457.6594665953
-145787.8075451687	-99770.1215443975	
635723.5618613327	1145230.3956329024	
1084368.6505893404	206458670.4745006561	
1469890745.0940928459	-1275868107.9849936962	
-0.0238949898	3598318516081.8452148438	
36198.6465750722	0.0000000000	
0.0000000000	0.0000000000	0.0000000000
0.0000000000	0.0000000000	-145787.8075451687
666808.3371934118	208656.0639778854	
123510.5898856849	-266474.1940985713	
-273346.3020820001	-225374609.3335765600	
-83278163.7571291327	227040169.4953751564	
0.0031677740	-805207179437.5407714844	59945.3954439472
0.0000000000	0.0000000000	0.0000000000
0.0000000000	0.0000000000	0.0000000000
-99770.1215443974	208656.0639778854	
76408.2371207681		

Sum of H'Wy is :

5486061547.19810

36584442778.58514

33408872159.34251

14834824166248.30859

32158626582387.25391

-34086624652357.96484

-604.98783

112317807659114768.00000

-2948644630.17576

-27771434.44241

67040528.11551

603470756.22806

400176817.76198

91700586.30273

```
-484097205.11321
369071814.20939
75465589.38682
-13494689.60293
```

```
Output of xhat0 is :
-0.0363025898
-0.2741066153
-0.1808766575
0.0409349622
0.0327483949
-0.0147530394
-9463442.1830325481
-0.0000006574
0.1475547229
0.0000018632
0.0000013787
-0.0000002538
-10.5636296834
9.9833774037
5.7943247874
-5.7819128352
2.3443688041
1.5124575876
```