

broadcast ephemeris algorithm

Interface Control Document

Table 20-II. Ephemeris Data Definitions

M_0	Mean Anomaly at Reference Time
Δn	Mean Motion Difference From Computed Value
e	Eccentricity
$(A)^{1/2}$	Square Root of the Semi-Major Axis
$(\text{OMEGA})_0$	Longitude of Ascending Node of Orbit Plane at Weekly Epoch
i_0	Inclination Angle at Reference Time
ω	Argument of Perigee
OMEGADOT	Rate of Right Ascension
IDOT	Rate of Inclination Angle
C_{uc}	Amplitude of the Cosine Harmonic Correction Term to the Argument of Latitude
C_{us}	Amplitude of the Sine Harmonic Correction Term to the Argument of Latitude
C_{rc}	Amplitude of the Cosine Harmonic Correction Term to the Orbit Radius
C_{rs}	Amplitude of the Sine Harmonic Correction Term to the Orbit Radius
C_{ic}	Amplitude of the Cosine Harmonic Correction Term to the Angle of Inclination
C_{is}	Amplitude of the Sine Harmonic Correction Term to the Angle of Inclination
t_{oe}	Reference Time Ephemeris (reference paragraph 20.3.4.5)
IODE	Issue of Data (Ephemeris)

Table 20-III. Ephemeris Parameters

Parameter	No. of Bits**	Scale Factor (LSB)	Effective Range***	Units
IODE	8			(see text)
C _{rs}	16*	2 ⁻⁵		meters
Δn	16*	2 ⁻⁴³		semi-circles/sec
M ₀	32*	2 ⁻³¹		semi-circles
C _{uc}	16*	2 ⁻²⁹		radians
e	32	2 ⁻³³	0.03	dimensionless
C _{us}	16*	2 ⁻²⁹		radians
(A) ^{1/2}	32	2 ⁻¹⁹		meters ^{1/2}
t _{oe}	16	2 ⁴	604,784	seconds
C _{ic}	16*	2 ⁻²⁹		radians
(OMEGA) ₀	32*	2 ⁻³¹		semi-circles
C _{is}	16*	2 ⁻²⁹		radians
i ₀	32*	2 ⁻³¹		semi-circles
C _{rc}	16*	2 ⁻⁵		meters
ω	32*	2 ⁻³¹		semi-circles
OMEGADOT	24*	2 ⁻⁴³		semi-circles/sec
IDOT	14*	2 ⁻⁴³		semi-circles/sec
<p>* Parameters so indicated shall be two's complement, with the sign bit (+ or -) occupying the MSB;</p> <p>** See Figure 20-1 for complete bit allocation in subframe;</p> <p>*** Unless otherwise indicated in this column, effective range is the maximum range attainable with indicated bit allocation and scale factor.</p>				

Table 20-IV. Elements of Coordinate Systems (sheet 1 of 3)

$$\mu = 3.986005 \times 10^{14} \text{ meters}^3/\text{sec}^2$$

WGS 84 value of the earth's universal gravitational parameter

$$\dot{\Omega}_e = 7.2921151467 \times 10^{-5} \text{ rad/sec}$$

WGS 84 value of the earth's rotation rate

$$A = \left(\sqrt{A} \right)^2$$

Semi-major axis

$$n_0 = \sqrt{\frac{\mu}{A^3}}$$

Computed mean motion (rad/sec)

$$t_k = t - t_{oe}^*$$

Time from ephemeris reference epoch

$$n = n_0 + \Delta n$$

Corrected mean motion

$$M_k = M_0 + nt_k$$

Mean anomaly

* t is GPS system time at time of transmission, i.e., GPS time corrected for transit time (range/speed of light). Furthermore, t_k shall be the actual total time difference between the time t and the epoch time t_{oe} , and must account for beginning or end of week crossovers. That is, if t_k is greater than 302,400 seconds, subtract 604,800 seconds from t_k . If t_k is less than -302,400 seconds, add 604,800 seconds to t_k .

Table 20-IV. Elements of Coordinate Systems (sheet 2 of 3)

$$M_k = E_k - e \sin E_k$$

Kepler's Equation for Eccentric Anomaly
(may be solved by iteration)(radians)

$$v_k = \tan^{-1} \left\{ \frac{\sin v_k}{\cos v_k} \right\}$$

True Anomaly

$$= \tan^{-1} \left\{ \frac{\sqrt{1-e^2} \sin E_k / (1 - e \cos E_k)}{(\cos E_k - e) / (1 - e \cos E_k)} \right\}$$

$$E_k = \cos^{-1} \left\{ \frac{e + \cos v_k}{1 + e \cos v_k} \right\}$$

Eccentric Anomaly

$$\Phi_k = v_k + \omega$$

Argument of Latitude

$$\delta u_k = c_{us} \sin 2\Phi_k + c_{uc} \cos 2\Phi_k$$

$$\delta r_k = c_{rs} \sin 2\Phi_k + c_{rc} \cos 2\Phi_k$$

$$\delta i_k = c_{is} \sin 2\Phi_k + c_{ic} \cos 2\Phi_k$$

Argument of Latitude Correction

Radius Correction

Inclination Correction

} Second Harmonic Perturbations

$$u_k = \Phi_k + \delta u_k$$

Corrected Argument of Latitude

$$r_k = A(1 - e \cos E_k) + \delta r_k$$

Corrected Radius

$$i_k = i_0 + \delta i_k + (\text{IDOT}) t_k$$

Corrected Inclination

Table 20-IV. Elements of Coordinate Systems (sheet 3 of 3)

$$\left. \begin{aligned} x_k' &= r_k \cos u_k \\ y_k' &= r_k \sin u_k \end{aligned} \right\}$$

Positions in orbital plane.

$$\Omega_k = \Omega_0 + (\dot{\Omega} - \dot{\Omega}_e) t_k - \dot{\Omega}_e t_{oe}$$

Corrected longitude of ascending node.

$$\left. \begin{aligned} x_k &= x_k' \cos \Omega_k - y_k' \cos i_k \sin \Omega_k \\ y_k &= x_k' \sin \Omega_k + y_k' \cos i_k \cos \Omega_k \\ z_k &= y_k' \sin i_k \end{aligned} \right\}$$

Earth-fixed coordinates.

20.3.3.4.3.2 Parameter Sensitivity. The sensitivity of the SV's antenna phase center position to small perturbations in most ephemeris parameters is extreme. The sensitivity of position to the parameters $(A)^{1/2}$, C_{rc} and C_{rs} is about one meter/meter. The sensitivity of position to the angular parameters is on the order of 10^8 meters/semicircle, and to the angular rate parameters is on the order of 10^{12} meters/semicircle/second. Because of this extreme sensitivity to angular perturbations, the value of π used in the curve fit is given here. π is a mathematical constant, the ratio of a circle's circumference to its diameter. Here π is taken as

$$\pi = 3.1415926535898.$$