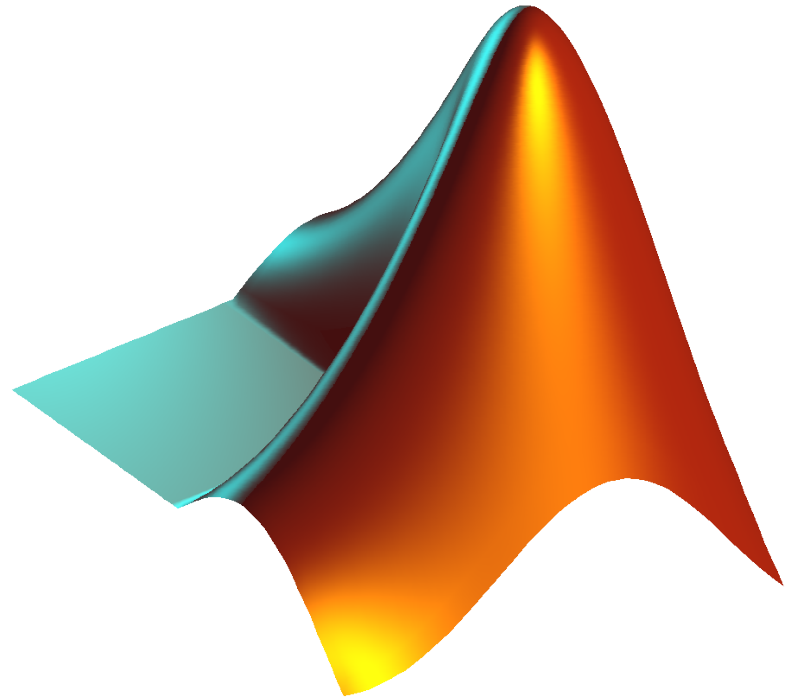


StatOD MATLAB Overview

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MATLAB is a vectorized programming language

Which would you prefer?

C/C++

```
for( i=0; i<3; i++ ){  
    for( j=0; j<3; j++ ){  
        for( k=0; k<3; k++ ){  
            out[i][j] += A[i][k]*B[k][j];  
        }  
    }  
}
```

MATLAB

```
out = A*B;
```



Many MATLAB commands have a vectorized implementation

MATLAB

```
x = 1:1:10;  % x = [ 1, 2, 3, 4, 5, 6, 7, 8, 9, 10 ];  
  
x_sqrt = sqrt(x);  
  
x_sin = sin(x);  
  
x_log = log10(x);  
  
and many others...
```

Some vectorized programming requires a little extra thought than other languages

Root Mean Square (RMS)

$$x_{rms} = \sqrt{\frac{\sum_{i=1}^n x_i^2}{n}}$$

(bad) MATLAB

```
acc_sum = 0.0;  
for i = 1:length(x)  
    acc_sum = acc_sum + x(i)*x(i);  
end  
  
x_rms = sqrt( acc_sum/length(x) );
```

Some vectorized programming requires a little extra thought than other languages

Root Mean Square (RMS)

$$x_{rms} = \sqrt{\frac{\sum_{i=1}^n x_i^2}{n}}$$

(better) MATLAB

```
x_rms = sqrt(sum(x.*x)/length(x));
```



MATLAB is inefficient with loops (for multiple reasons)

Inefficient MATLAB

```
x = 1:1:100;  
for i = 1:length(x)  
    y(i) = sqrt(x(i));  
end
```

Better MATLAB

```
x = 1:1:100;  
y = zeros(size(x));  
for i = 1:length(x)  
    y(i) = sqrt(x(i));  
end
```



Use fprintf() to write to the screen (or a file)

MATLAB fprintf()

```
x = 1:1:10;  
for i = 1:length(x)  
    fprintf('x(%2d) = %g\n', i, x(i));  
end
```

MATLAB fprintf() To File

```
x = 1:1:10;  
fid = fopen('output.txt', 'w');  
for i = 1:length(x)  
    fprintf(fid, 'x(%2d) = %g\n', i, x(i));  
end
```



Field widths can be specified using format identifiers

%X.Ye : X is minimum field width, Y is the number of decimal places to display

Now for some examples...

my_var = 12345.67891011...

%9.3f **12345.679**

%8.1f **>>>>→** **_12345.7**

%2.3f **12345.679**



Here are some general programming tips...

Include comments!!!

Keep units consistent (e.g. angles in radians)

Function and variable names should be descriptive

“Derivative” or “Integrator” are too generic

two_body(), two_body_J2(), two_body_J2drag(), etc.



What we're going to cover:

General MATLAB Introduction

ode45() (and the odeXX suite of integrators)

Symbolic Toolbox

reshape()



MATLAB includes a suite of tools to help solve the ‘initial value problem’

Given: \vec{x}_0

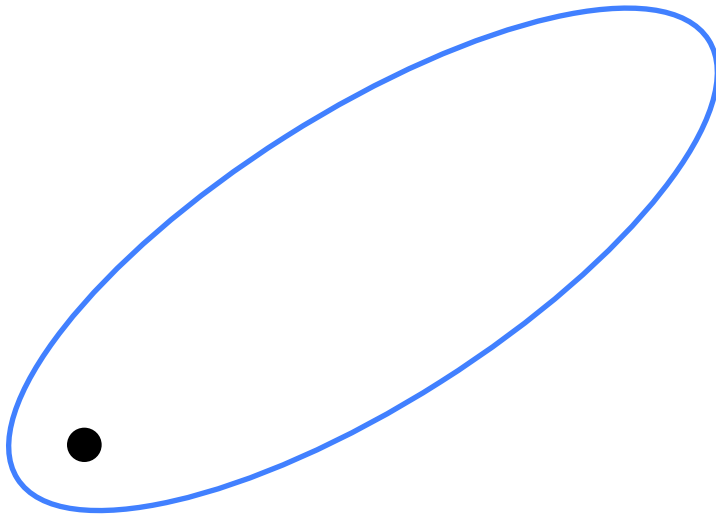
What is: \vec{x}_t

General description of odeXX() suite:

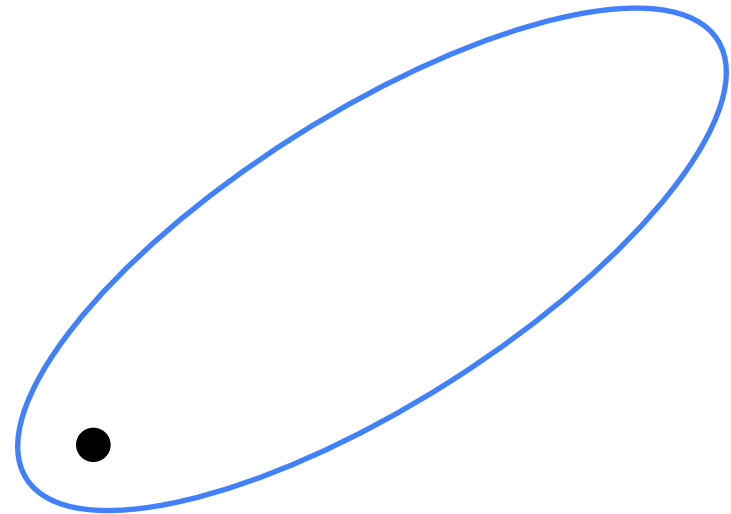
**Shampine and Reichelt, “The MATLAB ODE Suite,”
SIAM Journal of Scientific Computing, v. 18, p. 1-22,
1997.**

Most integrators are either fixed-step or variable step

Fixed Step:



Variable Step:



Why do we want to use a variable step integrator?



odeXX() Suite

Suite of numerical integration routines

The XX refers to the order of the scheme used
ode45() compares a 4th order to a 5th order to
determine time step

Higher order **does not necessarily provide**
higher accuracy
reentry problem (problem becomes “stiff”)

ode45() is fine for this course

Need to set the integration tolerance to select the time step

MATLAB

```
tol = 1e-13    % states match at least 13 digits  
  
options = odeset( 'RelTol', tol );  
  
[time,state] = ode45( @two_body, [time0, timeF], ...  
                      x0, options );
```

**Make sure you pass
the options to ode45()!!**



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The symbolic toolbox provides tools for the manipulation of equations

MATLAB

```
syms x y z

radius = sqrt( x^2 + y^2 + z^2 );

vec = [ x; y; z ];

drdx = diff( radius, x ); % dR/dx

radius = int( drdx, 'x' );

radius = int( drdx, 'x', 0, 1 );

drdv = jacobian( radius, vec );
```




Use fprintf() to get the symbolic A matrix into your code

MATLAB: Store A Matrix

```
fid = fopen('A_matrix.txt', 'w');
for i = 1:length(A(:,1))
    for j = 1:length(A(1,:))
        if( A(i,j) ~= 0 )
            fprintf(fid, 'A(%d,%d)=%s;\n', ...
                    i, j, char(A(i,j)));
        end
    end
    fprintf(fid, '\n');
end
fclose(fid);
```



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reshape() is used to easily change the dimensions of a matrix

MATLAB: reshape() Example

```
>> x = [ 1, 2; 3, 4 ];  
  
>> y = reshape( x, 4,1 );  
  
y =  
    1  
    3  
    2  
    4
```

reshape() cannot change the number of elements in the variable

Used to convert Φ from a matrix to a vector, thus it can be easily propagated in ode45()